1.
$$\nabla F(A,B) = \begin{bmatrix} \frac{\partial F}{\partial A} = \frac{1}{N} \sum \frac{1}{1 + \exp(1)} \exp(1) (-y_n \cdot \xi_n) \\ \frac{\partial F}{\partial B} = \frac{1}{N} \sum \frac{1}{1 + \exp(1)} \exp(1) \cdot (-y_n) \end{bmatrix}$$

$$= \begin{bmatrix} \frac{1}{N} \sum p_n (-y_n) \\ \frac{1}{N} \sum p_n \cdot (-y_n) \end{bmatrix}$$

2.
$$H(F) = \begin{bmatrix} \frac{\partial^2 F}{\partial A^2} & \frac{\partial F}{\partial A \partial B} \\ \frac{\partial^2 F}{\partial B \partial A} & \frac{\partial^2 F}{\partial B^2} \end{bmatrix}$$

$$\frac{1}{3A^{2}} = \frac{1}{A} \sum_{n=1}^{\infty} (-y_{n} \cdot z_{n}) \frac{\partial P_{n}}{\partial A}$$
and
$$\frac{\partial P_{n}}{\partial A} = \frac{-y_{n} z_{n} \exp(()[(1+\exp(()-\exp(())]))}{[(1+\exp(())]^{2}]}$$

$$= -yn z_n \cdot P_n \left(\frac{1 + exp()}{1 + exp()} - \frac{exp()}{1 + exp()} \right) = -yn z_n P_n (1 - P_n).$$
So $\frac{\partial^2 F}{\partial A^2} = \frac{1}{N} \sum (-y_n \cdot z_n)^2 P_n (1 - P_n) = \frac{1}{N} \sum z_n^2 P_n (1 - P_n).$

$$\frac{3^{2}F}{3A3B} = \frac{1}{N} \sum_{n=1}^{\infty} (-y_{n}z_{n}) \frac{3P_{n}}{3B}$$
and
$$\frac{3P_{n}}{3B} = \frac{-y_{n} \exp(1[1+\exp(1-\exp(1)])}{[1+\exp(1)]^{2}} = -y_{n} P_{n}(1-P_{n})$$

$$\sqrt{11} \frac{3^2 F}{3BA} = \frac{3^2 F}{3ABB}$$

$$(\overline{l}v)\frac{\partial^2 f}{\partial B^2} = \frac{1}{N}\sum_{i}(-y_n)\frac{\partial P_n}{\partial B} = \frac{1}{N}\sum_{i}P_n(1-P_n).$$

$$3 \cdot e^{-r \| x - x' \|^2} \rightarrow 0 \quad \text{as } r \rightarrow \infty \quad \text{if } x \neq x'$$

$$e^{-r \| x - x' \|^2} = 1 \quad \text{if } x = x'$$

5

$$\beta = (\lambda I + k)^{-1} y = \frac{1}{(\lambda + 1)} y$$

4.
$$et = \frac{1}{M} \sum_{m} (g_{t}(\vec{x_{m}}) - \vec{y_{m}})^{2} = \frac{1}{M} \left[\sum_{j=1}^{2} (\vec{x_{m}}) - 2 \sum_{j=1}^{2} g_{t}(\vec{x_{m}}) \cdot \vec{y_{m}} + \sum_{j=1}^{2} (g_{0}(\vec{x_{m}}) - y_{m})^{2} \right]$$

$$= St - \frac{2}{M} \sum_{j=1}^{2} g_{t}(\vec{x_{m}}) \cdot \vec{y_{m}} + e_{0}$$

To min this least square error, it's equivalent to solve

the problem
$$\begin{bmatrix} g_0(\tilde{x}_1) & g_1(\tilde{x}_1) & \dots & g_T(\tilde{x}_1) \end{bmatrix} \begin{bmatrix} q_0 \\ \vdots \\ g_0(\tilde{x}_m) & \dots & g_T(\tilde{x}_m) \end{bmatrix} \begin{bmatrix} q_0 \\ \vdots \\ q_1 \end{bmatrix} = \begin{bmatrix} \tilde{y}_1 \\ \vdots \\ \tilde{y}_M \end{bmatrix}$$

In linear algebra we know that the or minimizing E-lest satisfies GTG = GTy

if G is linearly independent GG is invertible, or GG Gy if not, or have infinite many solu

We know that
$$|W_1 \times W_2| \ge 2 - x_1 - x_2$$

We know that $|W_1 \times W_2| \ge 2 - x_1 - x_2 = x_1 - x_1 - x_2 = x_1 - x$

The case
$$ii$$
: $\int ht(x) \cdot ht(x') = 1$, $x \in x' \le 0$ or $x' \in x \le 0$

In case
$$\overline{i}\overline{y}$$
: $\begin{cases} ht(x) \cdot ht(x') = 1, & x \leq x' \leq 0 \text{ or } x' \leq x \leq 0 \\ ht(x) \cdot ht(x') = 0, & \text{otherwise} \end{cases}$

We notice that In case is, inner product of ht is min(x,x')

So for each feature, the first M gt=1, gt is corresponding to ht
the remaining gt=0

Including g we excluded before, and set their gt = 0.

We know that
$$\sum_{n} \alpha_{n} y_{n} = 0$$
, so $\frac{1}{2} \sum_{n} \sum_{m} q_{n} q_{m} y_{n} y_{m} k$

$$= \frac{1}{2} \sum_{n} q_{n} y_{n} k \sum_{m} q_{m} y_{m} = 0$$

 $w = \sum \alpha_n y_n \ge n$, $b = y_s - \sum \alpha_n y_n k(x_n, x_s)$ depends on α_n is hence the same.

```
Eout
min Ein=0
                                    0.45
                                    0,45
                                    0,45
                                    6,44
                                    0,44
                                    2.44
                   0,00
                                     0146
           0.125
                    1
                            0,03
                                     0,45
           0125
                   1000
                           02425
                                     0.39
```

 $\lambda = 100$ has min Eih = 0.3125

15. \ Eih Eout

8.01 0.2175 0.26

0.1 0.3125 0.37

1 0.32 0.37

1 0.3225 0.37

1 0.3225 0.37

X=01 has min Ein=0,3125

Since square error is just a upper bound for 0/1 error Ein(g) will roughly smaller than Fin(G) but not always.

16: \ \ = 0.0 | has min Eout = 0.36

Since training data in problem 13 is the time data where we booststup from, Eout (g) = $g \approx \text{Eout}(G)$ but in theory, g is more sensitive to data that's why we use G.