

微分形式梳理

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1 前言

本系列的目的是梳理一下微分形式的一些概念。学习的时候发现这些知识没过几个礼拜就会遗忘，而且记号有些混乱，因此做一下梳理。

2 Differentiable Manifolds

2.1 Differentiable Manifolds

Definition 1 (Differentiable Manifolds). *M is a set (even without topological structure). M is an **n -dimensional differentiable manifold**, if there exists a family of injective maps $f_\alpha : U_\alpha \subset \mathbf{R}^n \rightarrow M$, where all U_α are open sets in \mathbf{R}^n and,*

$$(1) \bigcup_\alpha f_\alpha(U_\alpha) = M$$

(2) for each pair $\alpha \neq \beta$, if $W := f_\alpha(U_\alpha) \cap f_\beta(U_\beta) \neq \emptyset$, then $f_\alpha^{-1}(W)$ and $f_\beta^{-1}(W)$ are also open sets in \mathbf{R}^n , satisfying $f_\alpha^{-1} \circ f_\beta$ and $f_\beta^{-1} \circ f_\alpha$

are differentiable on their own domain (which are open sets by the previous restriction).

Remark 1. A differentiable manifold intrinsically induces a topological structure. A set $A \subset M$ is an open set iff $f_\alpha^{-1}(A \cap f_\alpha(U_\alpha))$ is an open set in \mathbf{R}^n for all α .

It follows that this defines a topology in M and all f_α are homeomorphisms.

Remark 2. If M is born with a topological structure, how can we prove that M is a differentiable manifold while matching its induced topology with its inborn topology (which is often we hope). If we are able to additionally prove that all f_α are homeomorphisms, the induced topology can be fit into the inborn topology.

Remark 3. From now on, to develop calculus, we fix a Hausdorff and second countable n -dim differentiable manifold M .

2.2 Tangent Space

Definition 2 (Differentiable). M, N are differentiable manifolds. $p \in M$. A map $F : M \rightarrow N$ is **differentiable at p** if for the parameterization of p (U_α, f_α) and the parameterization of $F(p)$ (V_α, g_α), $g_\alpha^{-1} \circ F \circ f_\alpha$ is differentiable at $f_\alpha^{-1}(p)$.

It's necessary to check that this definition is independent of the choice of the parameterization.

Definition 3 (tangent space). Fix a point p in M , denote the set of all curves passing p as \mathcal{C} , where a curve passing p is a differentiable map $\gamma : (-\epsilon, \epsilon) \rightarrow M$ with $\gamma(0) = p$. Two curves γ_1, γ_2 are **tangent at p** if for every differentiable function $F : M \rightarrow \mathbf{R}$, $\frac{d}{dt}|_{t=0}(F \circ \gamma_1) = \frac{d}{dt}|_{t=0}(F \circ \gamma_2)$, which is an equivalence relation. The **tangent space of M at p** $T_p M$ is defined by the quotient space of \mathcal{C} under the tangent relation.

Remark 4 (The inspiration). In normal geometry in \mathbf{R}^n , we define tangent vector v of a curve $\gamma(t) = (x^1(t), x^2(t), \dots, x^n(t))$ by letting $v = (x^{1'}(t), x^{2'}(t), \dots, x^{n'}(t))$.

It follows that for every differentiable function $F : \mathbf{R}^n \rightarrow \mathbf{R}$,

$$\begin{aligned} \frac{d}{dt}|_{t=0}(F \circ \gamma)(t) &= \sum_{i=1}^n \partial_i F \cdot x^{i'}(0) \\ &= \left(\sum_{i=1}^n x^{i'}(0) \cdot \frac{\partial}{\partial x^i} \right)(F) \\ &= \frac{\partial}{\partial v} F \end{aligned} \tag{1}$$

which turns out to be the same when two curves have the same tangent vector v , i.e. two curves are tangent.

Remark 5. From Remark 4, we have an explicit definition for $T_p M$. Let D be the set of all differentiable functions $F : M \rightarrow \mathbf{R}$. γ is a curve passing p . The **tangent vector to γ at p** is the map $v : D \rightarrow \mathbf{R}$ defined by

$$vF = \frac{d}{dt}|_{t=0}(F \circ \gamma)$$

$T_p M$ is defined by all tangent vectors to all curves passing p .

Remark 6. The two definitions are equivalent in the sense of isomorphism. Moreover, the second definition holds a linear structure naturally. To figure out its dimension, given a parameterization (U_α, f_α) at p , the **coordinate curves** are curves

$$\gamma_i(t) = f_\alpha(f_\alpha^{-1}(p) + (0, \dots, t, \dots, 0))$$

γ_i play the same role as The tangent vector of γ_i can be denoted as $\frac{\partial}{\partial x^i}$ under the second definition and (1). $T_p M$ has a basis $\{\frac{\partial}{\partial x^i}\}_{i=1}^n$, so it's n -dimensional.

Definition 4 (Differential). Let M, N be differentiable manifolds