
```
clear all;
clc;
% inverse power method
A = [-2 1 4;
      1 1 1;
      4 1 -2];
% intial vector
x0 = [1;2;-1];
% initial eigenvalue guess
e1 = 1;

for i=1:5
    x1=(A-e1*eye(3))\x0;
    x1 = x1/norm(x1);
end
display(x1);

% second theta
% this will converge to eigen vector [0.7;0;-0.7] as e2 is close to
this
% eigenvector's eigenvalue.
e2 = -5;
for i=1:5
    x2=(A-e2*eye(3))\x0;
    x2 = x2/norm(x2);
end
display(x2);

% third theta
% this will converge to eigen vector [-0.57;-0.57;-05.7] as e3 is
close to this
% eigenvector's eigenvalue 3.
e3 = 3.1;
for i=1:5
    x3=(A-e3*eye(3))\x0;
    x3 = x3/norm(x3);
end
display(x3);

x1 =

    0.491539152311424
   -0.573462344363328
    0.655385536415232

x2 =

   -0.719870728700614
    0.239956909566871
    0.651311611681508
```

`x3 =`

`-0.567601149459773`

`-0.613904646795497`

`-0.548589117441132`

Published with MATLAB® R2020a