第一性原理

2024年5月24日 9:28

程序

=

指令 + 数据

数据：类型，值，类，对象。

指令：运算符，语句，函数，方法，闭包，---

程序的运行方式：{ 同步 / 异步
并发 / 并行

创建线程

2024年5月24日 10:14

test_create3.c

```c
#include <func.h>

typedef struct {
    int id;
    char name[25];
    char gender;
    int chinese;
    int math;
    int english;
} Student;

void print_ids(const char* prefix) {
    printf("%s: ", prefix);
    printf("pid = %d, ppid = %d, tid = %lu\n",
           getpid(), getppid(), pthread_self());
}

void* start_routine(void* args) {
    Student* p = (Student*) args;
    // 在子线程访问主线程栈里面的数据
    printf("%d %s %c %d %d %d\n",
           p->id,
           p->name,
           p->gender,
           p->chinese,
           p->math,
           p->english);

    print_ids("new_thread");

    return NULL;
}

int main(int argc, char* argv[])
{
    // 主线程
    print_ids("main");

    Student s = {1, "xixi", 'f', 100, 100, 100}; // 主线程的栈

    pthread_t tid;
    int err = pthread_create(&tid, NULL, start_routine, &s);
    if (err) {
        error(1, err, "pthread_create");
    }

    printf("main: new_thread = %lu\n", tid);

    // 注意事项：当主线程终止时，整个进程就终止了。
    sleep(2);
    return 0;
}
```

终止线程

2024年5月24日 10:50

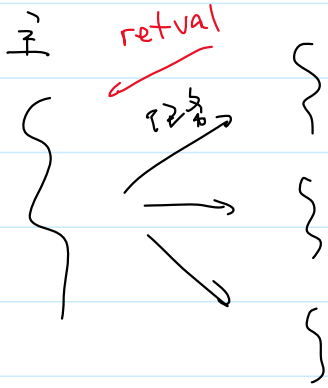
进程	线程
从 main 返回	从 start_routine 返回
exit()	pthread_exit()
收到信号	pthread_cancel()

pthread_exit()

2024年5月24日 10:55

```
PTHREAD_EXIT(3)                Linux Programmer's Manual

NAME
       pthread_exit - terminate calling thread

SYNOPSIS
       #include <pthread.h>

       void pthread_exit(void *retval);
```

void* retval，返回任意值给主线程.



pthread_join()

2024年5月24日 11:01

```
PTHREAD_JOIN(3)          Linux Programmer's Manual

NAME
       pthread_join - join with a terminated thread

SYNOPSIS
       #include <pthread.h>

       int pthread_join(pthread_t thread, void **retval);
```

等待子线程结束，并接收子线程返回值。

thread：等待哪个子线程结束

void** retval：接收子线程的返回值。

test_join1.c buffers

```c
#include <func.h>

typedef struct {
    int* arr;
    int left;
    int right;
} Section;

void* start_routine(void* args) {
    Section* sec = (Section*) args;
    int sum = 0;
    for (int i = sec->left; i <= sec->right; i++) {
        sum += sec->arr[i];
    }

    // pthread_exit((void*)sum);
    return (void*) sum;
}

int main(int argc, char* argv[])
{
    // 主线程
    int arr[100];
    for (int i = 1; i <= 100; i++) {
        arr[i - 1] = i;
```

```
    }

    pthread_t tid1, tid2;
    Section sec1 = {arr, 0, 49};
    Section sec2 = {arr, 50, 99};

    int err = pthread_create(&tid1, NULL, start_routine, &sec1);
    if (err) {
        error(1, err, "pthread_create");
    }

    err = pthread_create(&tid2, NULL, start_routine, &sec2);
    if (err) {
        error(1, err, "pthread_create");
    }

    // 主线程：等待子线程结束，并接收返回值
    int result1;
    err = pthread_join(tid1, (void**)&result1); // 无限期等待
    if (err) {
        error(1, err, "pthread_join %lu\n", tid1);
    }

    int result2;
    err = pthread_join(tid2, (void**)&result2);
    if (err) {
        error(1, err, "pthread_join %lu\n", tid2);
    }

    printf("main: sum = %d\n", result1 + result2);
    return 0;
}
```

```
he@he-vm:~/cpp58/2_Linux/Linux11 (master)$ ./test_join1
main: sum = 5050
```

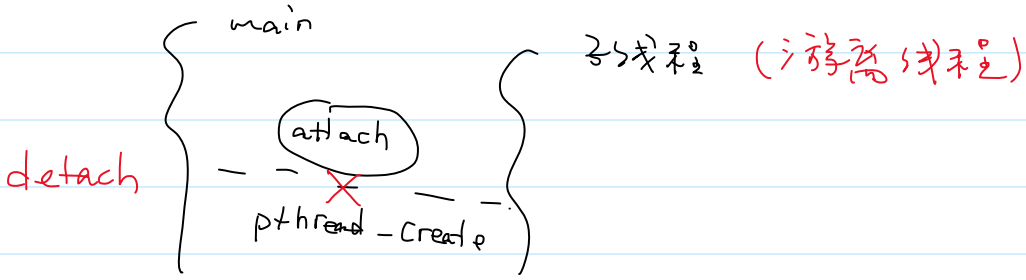
test_join2.c buffers

```
#include <func.h>

typedef struct {
    int id;
    char name[25];
    char gender;
    int chinese;
    int math;
    int english;
} Student;

void print_stu_info(Student* s) {
    printf("%d %s %c %d %d %d\n",
           s->id,
           s->name,
           s->gender,
           s->chinese,
           s->math,
           s->english);
}

void* start_routine(void* args) {
    // 注意：不能返回指向该线程栈上数据的指针
    // 因为当线程退出的时候，该线程的栈会销毁！
    // Student s = {1, "xixi", 'f', 100, 100, 100};

    Student* s = (Student*) malloc(sizeof(Student));
```

```
26
27      Student* s = (Student*) malloc(sizeof(Student));
28      s->id = 1;
29      strcpy(s->name, "xixi");
30      s->gender = 'f';
31      s->chinese = 100;
32      s->math = 100;
33      s->english = 100;
34
35      return (void*) s;
36  }
37
38  int main(int argc, char* argv[])
39  {
40      // 主线程
41      pthread_t tid1;
42
43      int err = pthread_create(&tid1, NULL, start_routine, NULL);
44      if (err) {
45          error(1, err, "pthread_create");
46      }
47
48      // 主线程：等待子线程结束，并接收返回值
49      Student* s1;
50      err = pthread_join(tid1, (void**)&s1); // 无限期等待
51      if (err) {
52          error(1, err, "pthread_join %lu\n", tid1);
53      }
54
55      print_stu_info(s1);
56
57      free(s1);
58
59      return 0;
60  }
```

pthread_detach

2024年5月24日 11:36



主线程才能接收子线程的返回值.

父进 wait 子进程

主线程 pthread_join 子线程

NAME
pthread_detach - detach a thread

SYNOPSIS
```
#include <pthread.h>

int pthread_detach(pthread_t thread);
```

thread: 要分离的子线程.

test_detach.c

```c
#include <func.h>

typedef struct {
    int id;
    char name[25];
    char gender;
    int chinese;
    int math;
    int english;
} Student;

void print_stu_info(Student* s) {
    printf("%d %s %c %d %d %d\n",
           s->id,
           s->name,
           s->gender,
           s->chinese,
           s->math,
           s->english);
}

void* start_routine(void* args) {
    // 注意：不能返回指向该线程栈上数据的指针
    // 因为当线程退出的时候，该线程的栈会销毁！
    // Student s = {1, "xixi", 'f', 100, 100, 100};

    Student* s = (Student*) malloc(sizeof(Student));
    s->id = 1;
    strcpy(s->name, "xixi");
    s->gender = 'f';
    s->chinese = 100;
    s->math = 100;
    s->english = 100;

    return (void*) s;
}

int main(int argc, char* argv[])
{
    // 主线程
    pthread_t tid1;

    int err = pthread_create(&tid1, NULL, start_routine, NULL);
    if (err) {
        error(1, err, "pthread_create");
    }

    // 主线程主动调用 pthread_detach
    err = pthread_detach(tid1);   // 使tid1处于游离状态
    if (err) {
```

```
51          error(1, err, "pthread_detach %lu", tid1);
52      }
53
54      // 主线程：等待子线程结束，并接收返回值
55      Student* s1;
56      err = pthread_join(tid1, (void**)&s1); // 无限期等待
57      if (err) {
58          error(1, err, "pthread_join %lu", tid1);
59      }
60
61      print_stu_info(s1);
62
63      free(s1);
64
65      return 0;
66  }
```

```
he@he-vm:~/cpp58/2_Linux/Linux11 (master)$ ./test_detach
./test_detach: pthread_join 131096624756288: Invalid argument
```

pthread_cancel (了解)

2024年5月24日 14:28

NAME

pthread_cancel - send a cancellation request to a thread

发送取消请求

SYNOPSIS

```
#include <pthread.h>

int pthread_cancel(pthread_t thread);
```

test_cancel.c

```
1  #include <func.h>
2
3  void* start_routine(void* args) {
4      for(;;) {
5
6      }
7  }
8
9  int main(int argc, char* argv[])
10 {
11     pthread_t tid;
12
13     int err;
14     err = pthread_create(&tid, NULL, start_routine, NULL);
15     if (err) {
16         error(1, err, "pthread_create");
17     }
18
19     sleep(1);
20
21     err = pthread_cancel(tid);
22     if (err) {
23         error(1, err, "pthread_cancel %lu", tid);
24     }
25
26     // 等待子线程结束
27     err = pthread_join(tid, NULL);
28     if (err) {
29         error(1, err, "pthread_join %lu", tid);
30     }
31     return 0;
32 }
```

R

→阻塞 S

```
he@he-vm:~$ ps -elLf | grep "./test_cancel"
0 S he         16170   13125   16170  0    2  80   0 -  2775 futex_ 14:36 pts/1    00:00:00 ./test_cancel
1 R he         16170   13125   16171 99    2  80   0 -  2775 -      14:36 pts/1    00:02:48 ./test_cancel
```

会立即响应，以及可能响应，取决于线程属性

The **pthread_cancel**() function sends a cancellation request to the thread thread. Whether and when the target thread reacts to the cancellation request depends on two attributes that are under the control of that thread: its cancelability state and type.

取消状态　取消类型

NAME

pthread_setcancelstate, pthread_setcanceltype - set cancelability state and type

SYNOPSIS

```
#include <pthread.h>

int pthread_setcancelstate(int state, int *oldstate);
int pthread_setcanceltype(int type, int *oldtype);
```

线程属性

CANCEL_STATE：是否响应

PTHREAD_CANCEL_ENABLE （能够，默认值）

PTHREAD_CANCEL_DISABLE （不能够）

CANCEL_TYPE： 何时响应，

PTHREAD_CANCEL_DEFERRED （延迟响应，延迟到取消点才响应） 默认值

PTHREAD_CANCEL_ASYNCHRONOUS （在任何时刻都可以响应）

取消点：（可能会陷入长时间阻塞）

```
accept()
aio_suspend()
clock_nanosleep()
close()
connect()
creat()
fcntl() F_SETLKW
fdatasync()
fsync()
getmsg()
getpmsg()
lockf() F_LOCK
mq_receive()
mq_send()
mq_timedreceive()
mq_timedsend()
msgrcv()
msgsnd()
msync()
nanosleep()
open()
openat() [Added in POSIX.1-2008]
pause()
poll()
pread()
pselect()
pthread_cond_timedwait()
pthread_cond_wait()
pthread_join()
pthread_testcancel()
putmsg()
putpmsg()
pwrite()
read()
readv()
recv()
recvfrom()
recvmsg()
select()
sem_timedwait()
sem_wait()
send()
sendmsg()
sendto()
sigpause() [POSIX.1-2001 only (moves to "may" list in POSIX.1-2008)]
sigsuspend()
sigtimedwait()
sigwait()
sigwaitinfo()
sleep()
system()
tcdrain()
usleep() [POSIX.1-2001 only (function removed in POSIX.1-2008)]
wait()
waitid()
waitpid()
write()
writev()
```

检查是否有响应请求，如果有，就立刻响应。

线程清理函数

2024年5月24日 15:07

进程终止

从main返回 (√)

exit() (√)

响应信号 (×)

线程终止

从start_routine返回 (×)

pthread_exit() (√)

响应pthread_cancel请求 (√)

atexit()注册进程退出函数

pthread_cleanup_push()

pthread_cleanup_pop()

栈

执行顺序 与注册顺序相反

NAME

pthread_cleanup_push, pthread_cleanup_pop - push and pop thread cancellation clean-up handlers

SYNOPSIS

```
#include <pthread.h>

void pthread_cleanup_push(void (*routine)(void *),
                          void *arg);
void pthread_cleanup_pop(int execute);
```

execute.

0: 不执行

非0: 执行

```c
void* start_routine(void* args) {
    // 注册线程清理函数
    pthread_cleanup_push(cleanup, "first");
    pthread_cleanup_push(cleanup, "second");
    pthread_cleanup_push(cleanup, "third");

    pthread_cleanup_pop(1);
    pthread_cleanup_pop(0);

    sleep(5);

    printf("thread1: I'm going to die...\n");
    pthread_exit(NULL);     // 子线程退出
    // 后面的代码肯定不会被执行

    pthread_cleanup_pop(0);
}
```

→ cleanup: third

(不会执行)

```
he@he-vm:~/cpp58/2_Linux/Linux11 (master)$ ./test_cleanup
cleanup: third
thread1: I'm going to die...
cleanup: first
```

注意事项：① 从 start_routine 返回，不会执行线程清理函数。

② pthread_cleanup_push 和 pthread_cleanup_pop 必须成对出现

解释：宏函数

2024年5月24日 16:01

pthread_cleanup_push() 和 pthread_cleanup_pop 必须成对出现

```
demo.c                                                    buffers
  1 #include <func.h>
  2
  3 #define FOO() {                 \
  4     printf("I love xixi\n");    \
  5     printf("I love xixi\n");    \
  6     printf("I love xixi\n");    \
  7 }
  8
  9 int main(int argc, char* argv[])
 10 {
 11     int flag = 1;
 12     if (flag)
 13         FOO();
 14     else
 15         printf("I love liuyifei\n");
 16
 17     return 0;
 18 }
```

if (flag) ?
- - .
{ ;
else

```
9092 int main(int argc, char* argv[])
9093 {
9094     int flag = 1;
9095     if (flag)
9096         { printf("I love xixi\n"); printf("I love xixi\n"); printf("I love xixi\n"); };
9097     else
9098         printf("I love liuyifei\n");
9099
9100     return 0;
9101 }
```

```
he@he-vm:~/cpp58/2_Linux/Linux11 (master)$ make
gcc demo.c -o demo -Wall -g -lpthread
demo.c: In function ‘main’:
demo.c:14:5: error: ‘else’ without a previous ‘if’
   14 |     else
      |     ^~~~
```

```
demo.c
  1 #include <func.h>
  2
  3 #define FOO()                   \
  4 do {                            \
  5     printf("I love xixi\n");    \
  6     printf("I love xixi\n");    \
  7     printf("I love xixi\n");    \
  8 } while(0)
  9
 10 int main(int argc, char* argv[])
 11 {
 12     int flag = 1;
 13     if (flag)
 14         FOO();
 15     else
 16         printf("I love liuyifei\n");
 17
 18     return 0;
 19 }
```

```c
int main(int argc, char* argv[])
{
    int flag = 1;
    if (flag)
        do { printf("I love xixi\n"); printf("I love xixi\n"); printf("I love xixi\n"); } while(0);
    else
        printf("I love liuyifei\n");

    return 0;
}
```

```c
#  define pthread_cleanup_push(routine, arg) \
  do {                                       \
    __pthread_cleanup_class __clframe (routine, arg)

/* Remove a cleanup handler installed by the matching pthread_cleanup_push.
   If EXECUTE is non-zero, the handler function is called. */
#  define pthread_cleanup_pop(execute) \
    __clframe.__setdoit (execute);                \
  } while (0)
```

必须成对出现

线程的同步

2024年5月24日 14:21

unsync.c buffers

```c
#include <func.h>

void* start_routine(void* args) {
    long* value = (long*) args;
    for(long i = 0; i < 100000000; i++) {
        (*value)++;
    }
}

int main(int argc, char* argv[])
{
    long* value = (long*)calloc(1, sizeof(long)); // *value = 0

    pthread_t tid1, tid2;
    pthread_create(&tid1, NULL, start_routine, value);
    pthread_create(&tid2, NULL, start_routine, value);

    // 主线程等待两个子线程结束
    pthread_join(tid1, NULL);
    pthread_join(tid2, NULL);

    printf("value = %ld\n", *value);
    return 0;
}
```

对共享数据的操作

value → 共享数据

```
he@he-vm:~/cpp58/2_Linux/Linux11 (master)$ ./unsync
value = 109940427
he@he-vm:~/cpp58/2_Linux/Linux11 (master)$ ./unsync
value = 109631762
he@he-vm:~/cpp58/2_Linux/Linux11 (master)$ ./unsync
value = 107046228
```

思考：① 为什么结果不正确？ ++ 操作不是原子性

② 为什么结果每一次都不一样？ 调度是不确定的

原子性：cpu 指令是原子的

instruction 1 → 切换

instruction 2 → 切换

instruction 3 → 切换

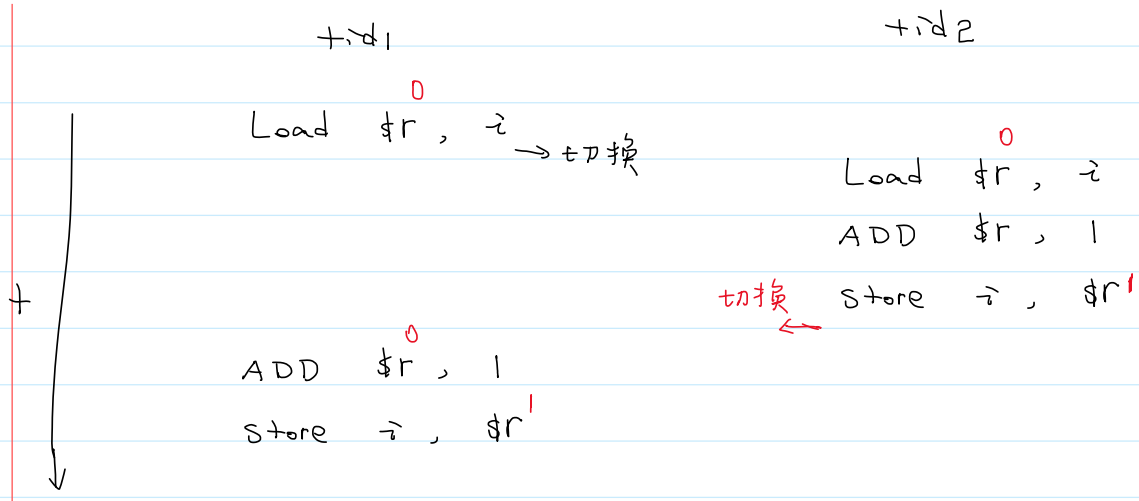
i++：

Load $r, i

ADD $r, 1

Store i, $r

i = 1



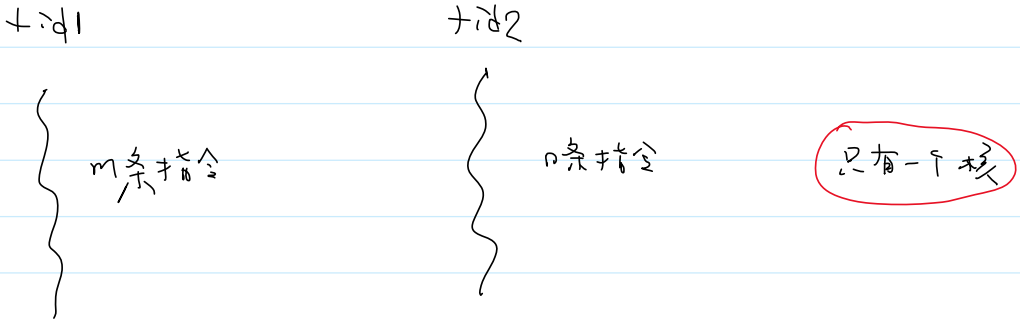
补2. 术语

程序并发执行时.

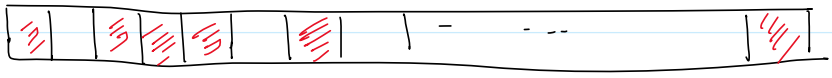
竞态条件: (race condition)

1. 多个执行流程
2. 共享资源
3. 程序的结果(状态)取决于执行流程调度的情况

↓ 为什么并发问题比较困难



调度: C_{m+n}^{m} 种情况



异步和同步.

异步: 任何调度情况都可能发现 (速度快)

(两个执行流程又称任何主流)

（此时执行流程又产生了新的变化）

同步。让一些调度不可能出现。（同步会有一些开销）

互斥锁
条件变量

并发。一种现象：在一个时间段中，执行流程可以交替执行

进程1　　进程2　　一个CPU，一核

t1
t1
t2
t2
t3
t3

并行。一种技术。同一时刻，可以执行多个执行流程。（并行是并发一种）

进程1　　进程2

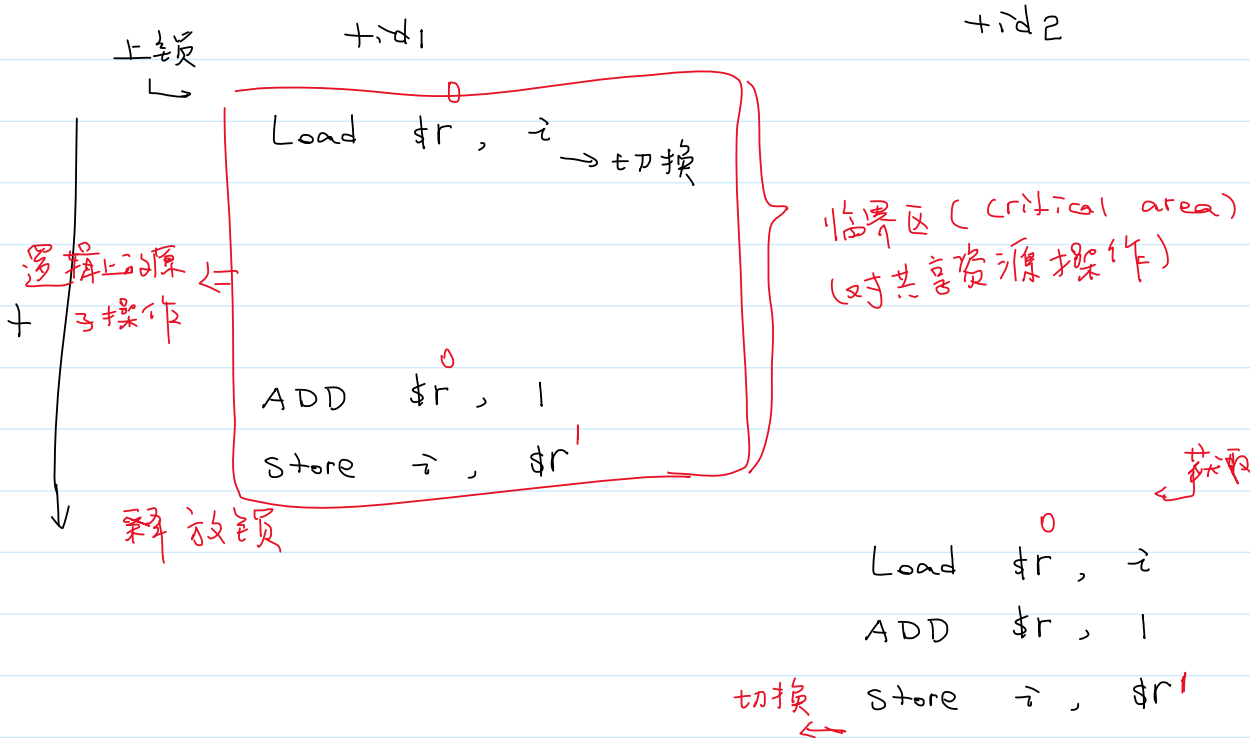
t1　　t1
t2　　t2
t3　　t3

同步

2024年5月24日 17:22

① 互斥地访问资源。 ② 等待某个条件成立。

i++; ⇐ 操作共享资源



互斥锁

2024年5月24日 16:38

SYNOPSIS

```
#include <pthread.h>

int pthread_mutex_init(pthread_mutex_t *restrict mutex,
    const pthread_mutexattr_t *restrict attr);
pthread_mutex_t mutex = PTHREAD_MUTEX_INITIALIZER;
```

动态 → 初始化

静态 → 默认属性

SYNOPSIS

```
#include <pthread.h>

int pthread_mutex_lock(pthread_mutex_t *mutex);
int pthread_mutex_trylock(pthread_mutex_t *mutex);
int pthread_mutex_unlock(pthread_mutex_t *mutex);
```

无限期阻塞

不会阻塞

完事后放锁

SYNOPSIS

```
#include <pthread.h>

int pthread_mutex_destroy(pthread_mutex_t *mutex);
```

销毁

sync.c

```c
#include <func.h>

pthread_mutex_t mutex = PTHREAD_MUTEX_INITIALIZER; // 静态初始化：默认属性
// 状态：未初始化，初始化，上锁，没上锁，销毁..

void* start_routine(void* args) {
    long* value = (long*) args;
    for(long i = 0; i < 100000000; i++) {
        pthread_mutex_lock(&mutex);
        (*value)++;   // 临界区：对共享资源的操作
        pthread_mutex_unlock(&mutex);
    }

    return NULL;
}

int main(int argc, char* argv[])
{
    long* value = (long*)calloc(1, sizeof(long)); // *value = 0

    pthread_t tid1, tid2;
    pthread_create(&tid1, NULL, start_routine, value);
    pthread_create(&tid2, NULL, start_routine, value);

    // 主线程等待两个子线程结束
    pthread_join(tid1, NULL);
    pthread_join(tid2, NULL);
```

```
26      pthread_join(tid1, NULL);
27      pthread_join(tid2, NULL);
28
29      // 销毁互斥锁
30      pthread_mutex_destroy(&mutex);
31
32      printf("value = %ld\n", *value);
33      return 0;
34  }
```

```
he@he-vm:~/cpp58/2_Linux/Linux11 (master)$ ./sync
value = 200000000
```

银行例子

2024年5月24日 17:44

bank.c

```c
#include <func.h>

typedef struct {
    int id;
    int balance;
    pthread_mutex_t mutex; // 细粒度锁
} Account;

Account acct1 = {1, 100, PTHREAD_MUTEX_INITIALIZER};
// pthread_mutex_t mutex = PTHREAD_MUTEX_INITIALIZER; // 全局锁，粒度太大

int withdraw(Account* acct, int money) {
    pthread_mutex_lock(&acct->mutex);
    if (acct->balance < money) {
        return 0;
    }

    sleep(1);   // 让某种调度出现的概率最大化

    acct->balance -= money;
    pthread_mutex_unlock(&acct->mutex);

    printf("%lu: withdraw %d\n", pthread_self(), money);
    return money;
}

void* start_routine(void* args) {
    withdraw(&acct1, 100);
    return NULL;
}

int main(int argc, char* argv[])
{
    pthread_t tid1, tid2;
    pthread_create(&tid1, NULL, start_routine, NULL);
    pthread_create(&tid2, NULL, start_routine, NULL);

    pthread_join(tid1, NULL);
    pthread_join(tid2, NULL);

    // pthread_mutex_destroy(&mutex);
    // 打印账号的余额
    printf("balance: %d\n", acct1.balance);
    return 0;
}
```