

作业讲解

2024年5月23日 9:47

<https://notion-next-lovat-ten.vercel.app/>

```
// 解析命令行输入，分离命令和参数
void parseInput(char* input, char* args[]) {
    int i = 0;
    args[i] = strtok(input, " \\n");
    while (args[i] != NULL) {
        i++;
        args[i] = strtok(NULL, " \\n");
    }
}
```

strtok

↳ token

SYNOPSIS

```
#include <string.h>
```

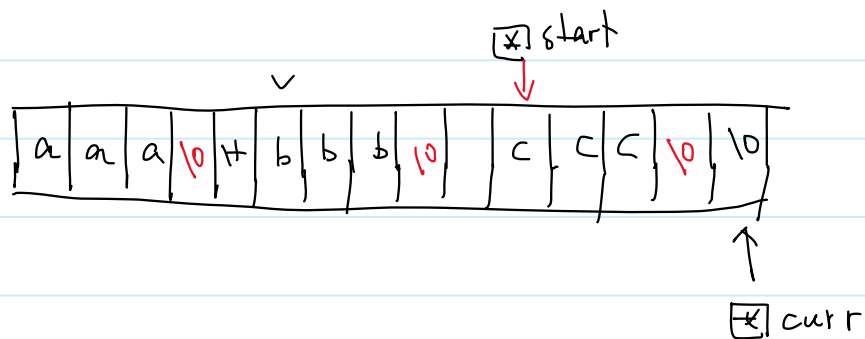
```
char *strtok(char *str, const char *delim);
```

↳ 传入传出参数

↑ 分隔符

↳ " \\n "

str



static

broken_pipe1.c

```
1 #include <func.h>
2
3 int main(int argc, char* argv[])
4 {
5     int fd = open("pipe1", O_WRONLY);
6     if (fd == -1) {
7         error(1, errno, "open pipe1");
8     }
9     printf("Established\n");
10
11     sleep(5);
12
13     write(fd, "Hello world\n", 11);
14
15     printf("END\n");
16     return 0;
17 }
```

broken_pipe2.c

```
1 #include <func.h>
2
3 int main(int argc, char* argv[])
4 {
5     int fd = open("pipe1", O_RDONLY);
6     if (fd == -1) {
7         error(1, errno, "open pipe1");
8     }
9     printf("Established\n");
10
11     close(fd);
12     return 0;
13 }
14
```

无名管道

2024年5月23日 11:44

在文件流(流)上是没名字的, 只能用于有血缘关系的进程之间通信

↓
一般是父子关系

PIPE(2)

Linux Programmer's Manual

NAME

pipe, pipe2 - create pipe

```
int pipe(int pipefd[2]);
```

↓
传参
提权作用

RETURN VALUE

On success, zero is returned. On error, -1 is returned, `errno` is set appropriately, and `pipefd` is left unchanged.

成功: 0

失败: -1, 设置 `errno`.

原理:

用户

pipefd

3 4

pipe(pipefd)

内核

0 *
1 *
2 *
3 *
4 *

管道

读

写

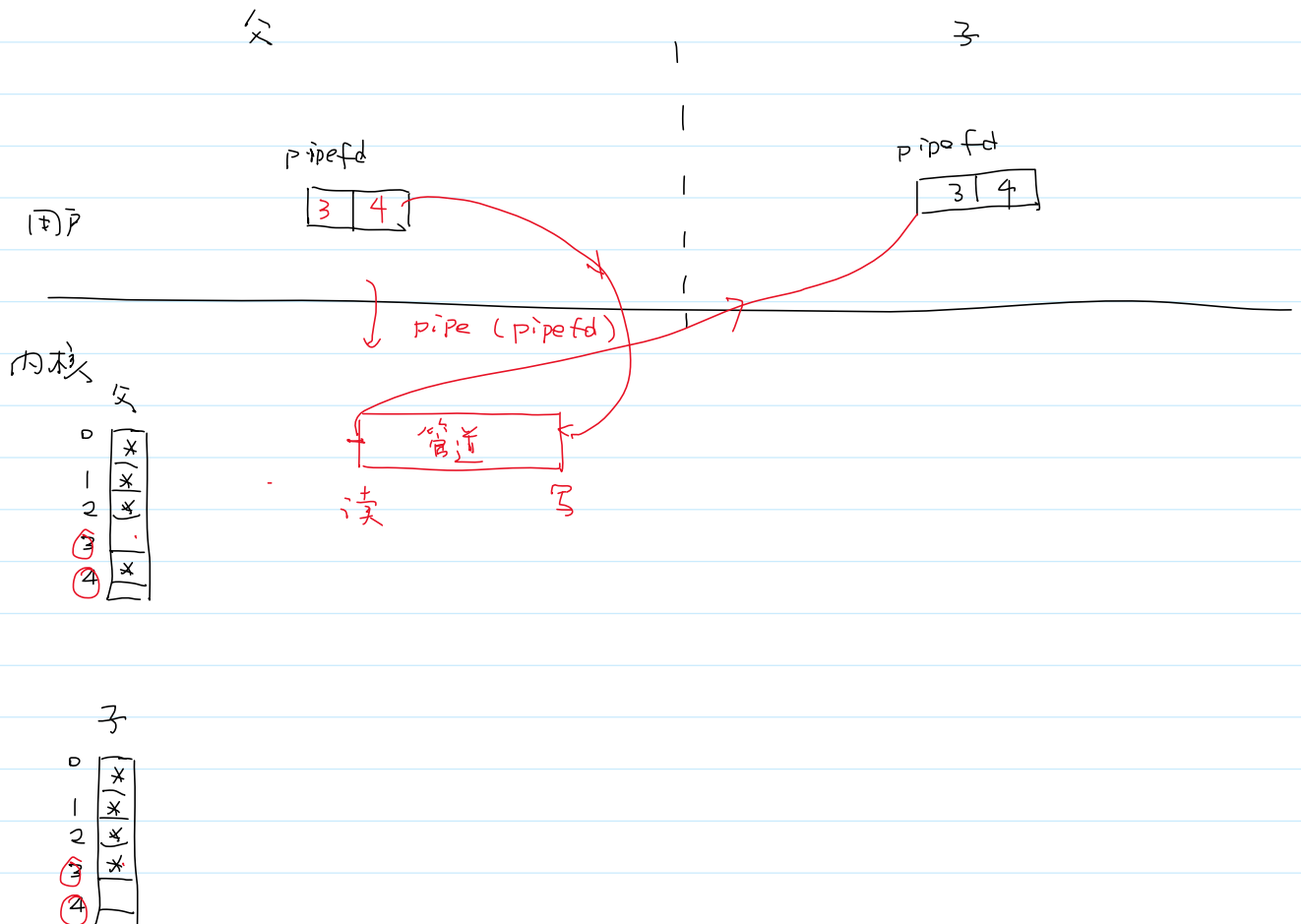
```

test_pipel.c buffers
1 #include <unistd.h>
2
3 int main(int argc, char* argv[])
4 {
5     int pipefd[2];
6     if (pipe(pipefd) == -1) {
7         error(1, errno, "pipe");
8     }
9
10    printf("pipefd[0] = %d, pipefd[1] = %d\n", pipefd[0], pipefd[1]);
11
12    char buf[1024];
13
14    write(pipefd[1], "Hello from pipe\n", 16);
15
16    read(pipefd[0], buf, 1024);
17    puts(buf);
18
19    return 0;
20 }

```

#2. 惯用法

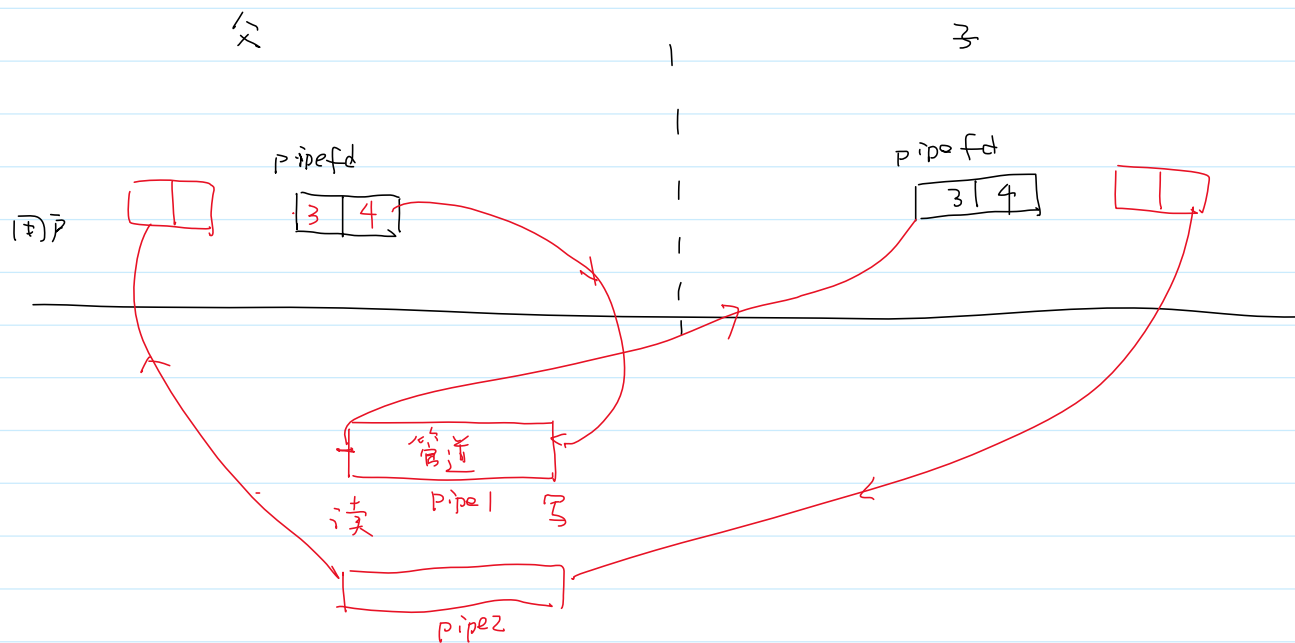
- ① 先 pipe()
- ② 后 fork()
- ③ 父进程关闭管道读端
- ④ 子进程关闭管道写端



```

test_pipe2.c buff
1 #include <func.h>
2
3 int main(int argc, char* argv[])
4 {
5     // 1. 先 pipe()
6     int pipefd[2];
7     if (pipe(pipefd) == -1) {
8         error(1, errno, "pipe");
9     }
10
11     // 2. 后 fork()
12     char buf[1024];
13
14     switch (fork()) {
15     case -1:
16         error(1, errno, "fork");
17     case 0:
18         // 3. 子进程关闭管道的另一端
19         close(pipefd[1]);
20         read(pipefd[0], buf, 1024);
21         printf("Child: %s\n", buf);
22         exit(0);
23     default:
24         // 4. 父进程关闭管道的一端
25         close(pipefd[0]);
26         sleep(2);
27         write(pipefd[1], "Hello from parent", 18);
28         exit(0);
29     }
30
31     return 0;
32 }

```

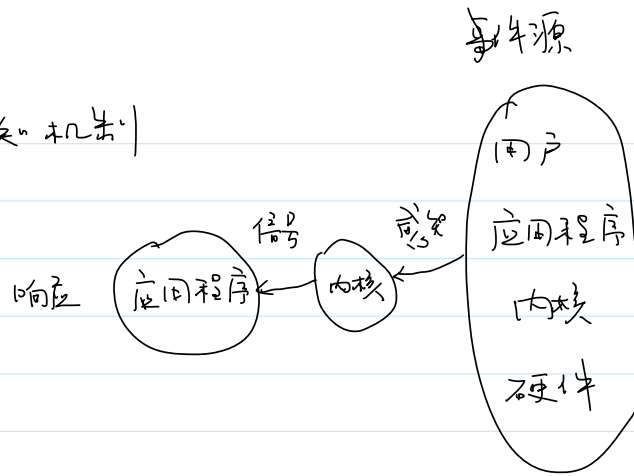


```

he@he-vm:~/cpp58/2_Linux/Linux10 (master)$ ./test_pipe3
from paren: Homework done?
from child: Done!

```

事件通知机制



select, I/O 事件通知机制.

#1. 事件源.

硬件.

访问非法内存

SIGSEGV

(段错误)

segment violation

执行非法的指令

SIGILL

illegal

除0

SIGFPE

(算术异常)

float point exception

内核:

读端关闭; 写管道

SIGPIPE

应用程序:

abort()

SIGABRT

子进程终止

SIGCHLD

用户

Ctrl + C

SIGINT

Ctrl + \

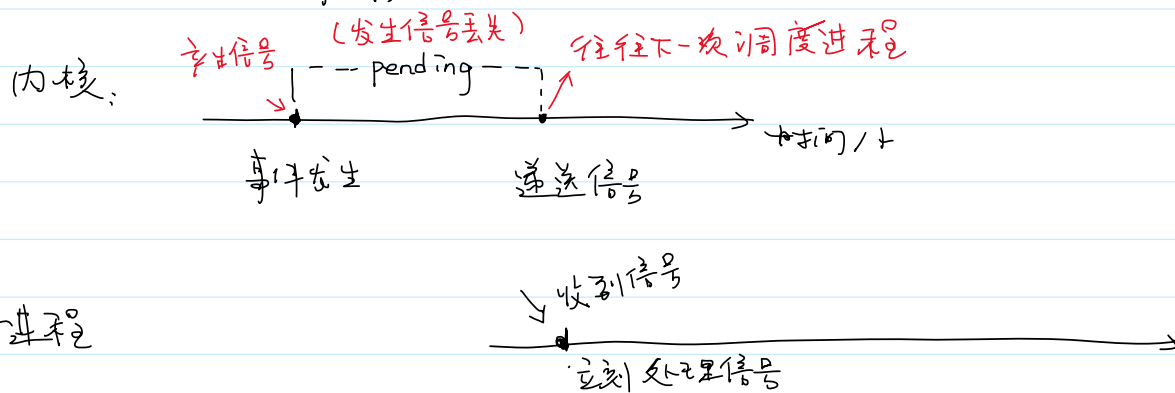
SIGQUIT

Ctrl + Z

SIGTSTP

kill 命令

#2. 内核会感知事件, 并给进程发送相应的信号.



#3. \$ man 7 signal

Signal dispositions (默认处理方式)

- Term
- Ign 忽略
- Core 终止进程, 并产生 core 文件
- Stop
- Cont

Standard signals

Signal	Standard	Action	Comment
<u>SIGABRT</u>	P1990	Core	Abort signal from abort (3)
<u>SIGALRM</u>	P1990	Term	Timer signal from alarm (2)
<u>SIGBUS</u>	P2001	Core	Bus error (bad memory access)
<u>SIGCHLD</u>	P1990	Ign	Child stopped or terminated
<u>SIGCLD</u>	-	Ign	A synonym for SIGCHLD
<u>SIGCONT</u>	P1990	Cont	Continue if stopped
<u>SIGEMT</u>	-	Term	Emulator trap
<u>SIGFPE</u>	P1990	Core	Floating-point exception
<u>SIGHUP</u>	P1990	Term	Hangup detected on controlling terminal or death of controlling process
<u>SIGILL</u>	P1990	Core	Illegal Instruction
<u>SIGINFO</u>	-	-	A synonym for SIGPWR
<u>SIGINT</u>	P1990	Term	Interrupt from keyboard
<u>SIGIO</u>	-	Term	I/O now possible (4.2BSD)
<u>SIGIOT</u>	-	Core	IOT trap. A synonym for SIGABRT
<u>SIGKILL</u>	P1990	Term	Kill signal
<u>SIGLOST</u>	-	Term	File lock lost (unused)
<u>SIGPIPE</u>	P1990	Term	Broken pipe: write to pipe with no readers; see pipe (7)
<u>SIGPOLL</u>	P2001	Term	Pollable event (Sys V); synonym for SIGIO
<u>SIGPROF</u>	P2001	Term	Profiling timer expired
<u>SIGPWR</u>	-	Term	Power failure (System V)
<u>SIGQUIT</u>	P1990	Core	Quit from keyboard
<u>SIGSEGV</u>	P1990	Core	Invalid memory reference
<u>SIGSTKFLT</u>	-	Term	Stack fault on coprocessor (unused)
<u>SIGSTOP</u>	P1990	Stop	Stop process
<u>SIGTSTP</u>	P1990	Stop	Stop typed at terminal
<u>STGSYSV</u>	P2001	Core	Bad system call (SVr4).

不同的信号代表发生了不同的事件.

			synonym for SIGIO
	SIGPROF	P2001	Term Profiling timer expired
	SIGPWR	-	Term Power failure (System V)
Ctrl + \	SIGQUIT	P1990	Core Quit from keyboard
	SIGSEGV	P1990	Core Invalid memory reference
	SIGSTKFLT	-	Term Stack fault on coprocessor (unused)
	SIGSTOP	P1990	Stop Stop process
Ctrl + Z	SIGTSTP	P1990	Stop Stop typed at terminal
	SIGSYS	P2001	Core Bad system call (SVr4); see also seccomp(2)
	SIGTERM	P1990	Term Termination signal
	SIGTRAP	P2001	Core Trace/breakpoint trap
	SIGTTIN	P1990	Stop Terminal input for background process
	SIGTTOU	P1990	Stop Terminal output for background process
	SIGUNUSED	-	Core Synonymous with SIGSYS
	SIGURG	P2001	Ign Urgent condition on socket (4.2BSD)
	SIGUSR1	P1990	Term User-defined signal 1
	SIGUSR2	P1990	Term User-defined signal 2
	SIGVTALRM	P2001	Term Virtual alarm clock (4.2BSD)
	SIGXCPU	P2001	Core CPU time limit exceeded (4.2BSD); see setrlimit(2)
	SIGXFSZ	P2001	Core File size limit exceeded (4.2BSD); see setrlimit(2)
	SIGWINCH	-	Ign Window resize signal (4.3BSD, Sun)

The signals **SIGKILL** and **SIGSTOP** cannot be caught, blocked, or ignored.

↑
用户自定义信号处理函数

信号的执行流程

2024年5月23日 15:53

SIGNAL(2)

Linux Prog

NAME

signal - ANSI C signal handling ↔ 注册信号处理函数

SYNOPSIS

`#include <signal.h>` 别名

`typedef void (*sighandler_t)(int);` typedef 类型 别名;

`sighandler_t signal(int signum, sighandler_t handler);`
函数指针

`SIG_IGN` 忽略

`SIG_DFL` 默认行为

RETURN VALUE

`signal()` returns the previous value of the signal handler, or `SIG_ERR` on error.

In the event of an error, `errno` is set to indicate the cause.

成功: 先前的信号处理函数

失败: `SIG_ERR`, 设置 `errno`.

test_signal.c

```
1 #include <func.h>
2
3 void handler(int signo) {
4     switch (signo) {
5         case SIGINT:
6             printf("Caught SIGINT\n");
7             break;
8         case SIGTSTP:
9             printf("Caught SIGTSTP\n");
10            break;
11        default:
12            printf("Unknown %d\n", signo);
13    }
14 }
15
16 int main(int argc, char* argv[])
17 {
18     // 注册信号处理函数 (捕获信号)
19     sighandler_t oldhandler = signal(SIGINT, handler);
20     if (oldhandler == SIG_ERR) {
21         error(1, errno, "signal %d", SIGINT);
22     }
23
24     oldhandler = signal(SIGTSTP, handler);
25     if (oldhandler == SIG_ERR) {
26         error(1, errno, "signal %d", SIGTSTP);
27     }
28
29     for(;;) {
30     }
31     return 0;
32 }
```

用户

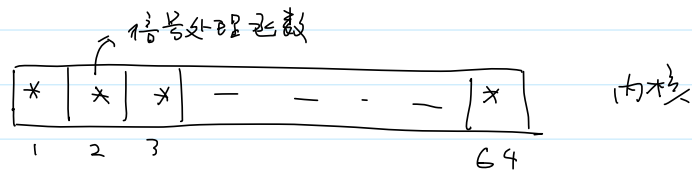
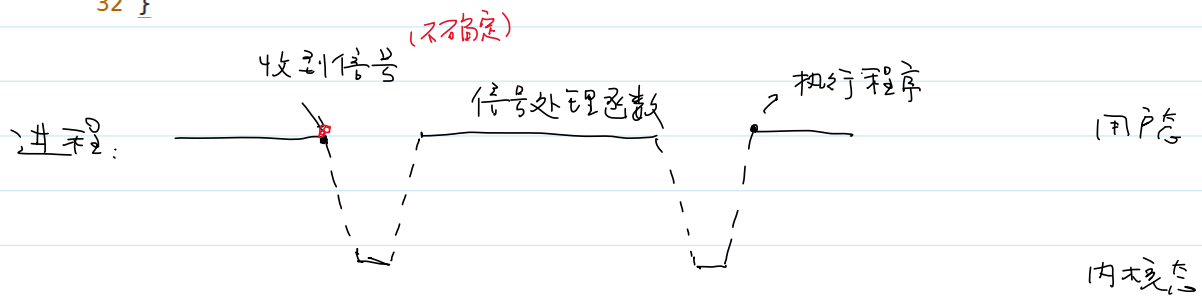
信号: 异步的

(不确定)

```

31 return 0;
32 }

```



信号的特点:

① 不稳定

② 异步的 (什么时候收到信号是不确定, 收到信号后, 会立刻马上执行信号处理函数)

③ 不同系统关于信号=语义也不一样。

注册信号处理函数

2024年5月23日 16:24

SIGNAL(2)

Linux Prog

NAME

signal - ANSI C signal handling ↔ 注册信号处理函数

SYNOPSIS

I #include <signal.h> 别名

typedef void (*sig handler_t)(int);

typedef 类型 别名;

sig handler_t signal(int signum, sig handler_t handler);

函数指针

SIG_IGN 忽略

SIG_DFL 默认行为

RETURN VALUE

I signal() returns the previous value of the signal handler, or SIG_ERR on error.

In the event of an error, errno is set to indicate the cause.

成功: 先前的信号处理函数

失败: SIG_ERR, 设置 errno.

The signals **SIGKILL** and **SIGSTOP** cannot be caught, blocked, or ignored.

```
test_signal2.c
1 #include <unistd.h>
2
3 int main(int argc, char* argv[])
4 {
5     printf("pid = %d\n", getpid());
6
7     // 忽略 SIGINT 信号
8     sig handler_t oldhandler = signal(SIGINT, SIG_IGN);
9     if (oldhandler == SIG_ERR) {
10         error(1, errno, "signal SIGINT");
11     }
12
13     sleep(10);
14
15     printf("Wake up\n");
16
17     signal(SIGINT, SIG_DFL);
18
19     for(;;) {
20
21     }
22     return 0;
23 }
```

```
1 #include <func.h>
2
3 void handler(int signo) {
4     switch (signo) {
5     case SIGKILL:
6         printf("Caught SIGKILL\n");
7         break;
8     case SIGSTOP:
9         printf("Caught SIGSTOP\n");
10        break;
11    }
12 }
13
14 int main(int argc, char* argv[])
15 {
16     printf("pid = %d\n", getpid());
17
18     sighandler_t oldhandler = signal(SIGKILL, handler);
19     if (oldhandler == SIG_ERR) {
20         error(0, errno, "signal SIGKILL");
21     }
22
23     oldhandler = signal(SIGSTOP, handler);
24     if (oldhandler == SIG_ERR) {
25         error(0, errno, "signal SIGSTOP");
26     }
27 }
28
29 for(;;) {
30 }
31
32
33 return 0;
34 }
```

发送信号

2024年5月23日 16:25

① kill 命令

KILL(1)

User Commands

NAME

I

kill - send a signal to a process

kill -SIGkill pid...

he@he-vm:~\$ kill -9 7438

KILL(2)

Linux Programmer's Manual

NAME

kill - send signal to a process

权限,

SYNOPSIS

```
#include <sys/types.h>
#include <signal.h>
```

```
int kill(pid_t pid, int sig);
```

pid,

和 wait pid 的 pid 含义不一样

> 0: 给指定的进程发送信号.

= 0: 给同进程组的所有进程发送信号.

-1: 给所有能够发送信号的进程发送信号 (除了自己)

< -1: 给指定进程组的进程发送信号.

RETURN VALUE

On success (at least one signal was sent), zero is returned. On error, -1 is returned, and `errno` is set appropriately.

成功: 0

失败: -1, 设置 `errno`.

```

test_kill.c buffers
1 #include <func.h>
2
3 int main(int argc, char* argv[])
4 {
5     // ./test_kill signo pid...
6     if (argc < 3) {
7         error(1, 0, "Usage: %s signo pid...", argv[0]);
8     }
9
10    int signo;
11    sscanf(argv[1], "%d", &signo);
12
13    for (int i = 2; i < argc; i++) {
14        pid_t pid;
15        sscanf(argv[i], "%d", &pid);
16
17        if (kill(pid, signo) == -1) {
18            error(0, errno, "kill(%d, %d)", pid, signo);
19        }
20    }
21    return 0;
22 }
23

```

RAISE(3) Linux Programmer's Manual

NAME

`raise` - send a signal to the caller

SYNOPSIS

```
#include <signal.h>
```

```
int raise(int sig);
```

↑ 等待

```
kill(getpid(), sig);
```

```
int err = raise(signo);
```

```
if (err) {
```

```
    ...
}
```

RETURN VALUE

`raise()` returns 0 on success, and nonzero for failure.

成功: 0

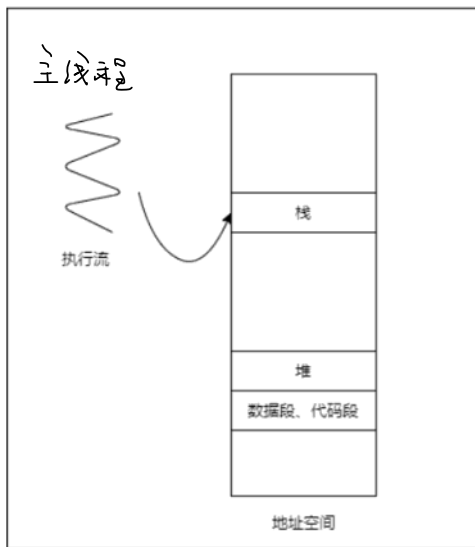
失败: 非 0

线程

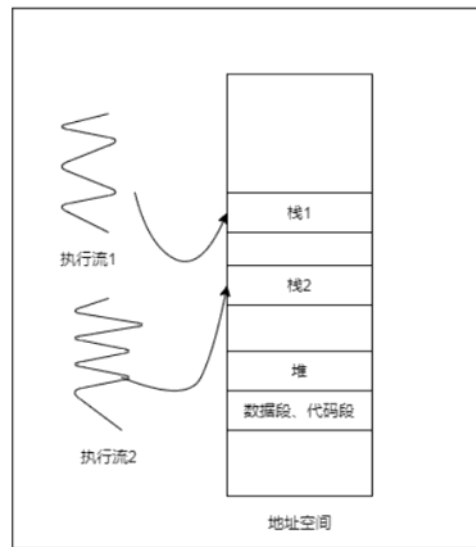
2024年5月23日 17:25

#1. What, 什么是线程.

} 一条执行流程



进程



线程

主线程, 8M

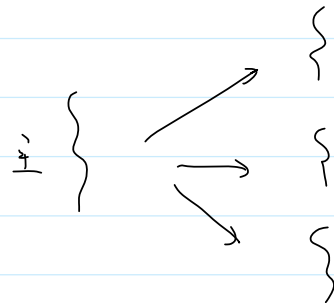
其它线程, 2M

引入线程.

进程是资源分配的最小单位.

线程是调度的最小单位.

线程共享进程的所有资源.



为什么要引入线程?

2024年5月23日 17:35

- ① 进程之间切换, (CPU的高速缓存, TLB失效), 开销大
同进程线程之间切换, 开销小.
- ② 进程之间通信, 需要打破隔离屏障,
线程之间通信, 开销很小.
- ③ 进程创建和销毁比较耗时.
线程的创建和销毁要轻量很多.
- ⋮

线程的基本操作

2024年5月23日 17:43

① 获取线程的基本信息、

② 创建线程、

③ 终止线程

④ 等待线程

⑤ 线程清理
、

获取线程的标识

2024年5月23日 17:44

PTHREAD_SELF(3) Linux Programmer's Manual

NAME

pthread_self - obtain ID of the calling thread

SYNOPSIS

```
#include <pthread.h>

pthread_t pthread_self(void);
```

Compile and link with -pthread.

-lpthread

RETURN VALUE

This function always succeeds, returning the calling thread's ID.

```
Makefile
1 Srcs := $(wildcard *.c)
2 Outs := $(patsubst %.c, %, $(Srcs))
3
4 CC := gcc
5 CFLAGS = -Wall -g -lpthread
6
7 ALL: $(Outs)
8
9 %: %.c
10     $(CC) $< -o $@ $(CFLAGS)
11
12 .PHONY: clean rebuild ALL
13
14 clean:
15     $(RM) $(Outs)
16 rebuild: clean ALL
```

```
l648:typedef unsigned long int pthread_t;
```

```
test_pthread_self.c
1 #include <func.h>
2
3 int main(int argc, char* argv[])
4 {
5     pthread_t tid = pthread_self();
6
7     printf("tid = %lu\n", tid);
8     return 0;
9 }
```

```
he@he-vm:~/cpp58/2_Linux/Linux10/pthread (master)$ ./test_pthread_self  
tid = 136581611161408
```

创建线程

2024年5月23日 17:53

PTHREAD_CREATE(3)

Linux Programmer'

NAME

pthread_create - create a new thread

SYNOPSIS

```
#include <pthread.h>
int pthread_create(pthread_t *thread, const pthread_attr_t *attr,
void *(*start_routine) (void *), void *arg);
```

Compile and link with -pthread.

返回值.

任意参数

pthread 库设计原则:

返回值是 int, 表示调用成功或失败.

成功: 0

失败: 错误码, 不会设置 errno.

thread: 返回时, 存放创建线程 ID.

attr: 线程属性, 一般填 NULL, 表示采用默认属性.

start_routine: 线程的入口函数.

arg: 线程的入口函数的参数.

```
test_pthread_create.c
1 #include <func.h>
2
3 void print_ids(const char* prefix) {
4     printf("%s: ", prefix);
5     printf("pid = %d, ppid = %d", getpid(), getppid());
6     printf("tid = %lu\n", pthread_self());
7 }
8
9 void* start_routine(void* args) {
10     print_ids("new_thread");
11     return NULL;
12 }
13
14
15 int main(int argc, char* argv[])
16 {
17     // 主线程 I
18     print_ids("main");
19
20     pthread_t tid;
21     int err = pthread_create(&tid, NULL, start_routine, NULL);
22     if (err) {
23         error(1, err, "pthread_create");
24     }
25
26     printf("main: new thread = %lu\n", tid);
```

子线程的执行流程

主线程的执行流程

```
23     pthread_create(&tid, NULL, pthread_create, NULL);  
24 }  
25  
26 printf("main: new_thread = %lu\n", tid);  
27  
28 // 注意事项: 当主线程终止时, 整个进程就终止了。  
29 sleep(2);  
30 return 0;  
31 }
```

```
he@he-vm:~/cpp58/2_Linux/Linux10/pthread (master)$ ./test_pthread_create  
main: pid = 8908, ppid = 7770, tid = 130354905302848  
main: new_thread = 130354901939776  
new_thread: pid = 8908, ppid = 7770, tid = 130354901939776
```

预告

2024年5月23日

21:27

线程的基本操作,

pthread_create

pthread_exit

pthread_join

pthread_detach

pthread_cancel

pthread_cleanup_push

pthread_cleanup_pop

线程的同步:

互斥: 互斥锁,
死锁

等待条件成立. 信号量.