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AASRI Procedia 3 (2012) 468 - 473



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2012 AASRI Conference on Modelling, Identification and Control

An improved median-based Otsu image thresholding Algorithm

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Abstract

Robust and automatic thresholding of gray level images has been commonly used in the field of pattern recognition and computer vision for objects detecting, tracking and recognizing. The Otsu scheme, a widely used image thresholding technique, provides approving results for segmenting a gray level image with only one modal distribution in gray level histogram. However, it provides poor results if the histogram of a gray level is non-bimodal. For enhancing the performance of the Otsu algorithm further, in this work, an improved median-based Otsu image thresholding algorithm is presented. Finally extensive tests are performed and the experiments show that our method obtain more satisfactory results than the original Otsu thresholding algorithm.

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Keywords: Image segmentation, Image thresholding, Otsu algorithm;

1. Introduction

In the field of pattern recognition, machine learning, image processing and computer vision, gray level image segmentation is a fundamental task and a challenge for many image analysis and preprocessing process [1-2]. Many algorithms for gray level image segmenting have been introduced recently [3-10]. Among them, thresholding algorithm is a very famous technique applied in image thresholding field [2-10]. The objective of

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gray level image threshold is to divide an gray level image into K predetermined classes, C_1, \dots, C_K , based on K-1 different segmenting thresholds. Most usually, K=2 and dividing the gray level image into two parts - the foreground part, the other background part. As a pre-processing state, gray level segmenting algorithm has a very long age of study, motivated by a wide area of real applications of object detecting and image processing.

Among these algorithms, the Otsu method is a very famous and excellent scheme [4]. Otsu's algorithm is utilized the scheme for robust and automatic gray level image segmentation at certain commercial system, such as MATLAB. In image segmentation process, determining an optimal threshold t^* is usually based on the estimates of dispersion and location of intensities in C_1 and C_2 . As with various other algorithms, Otsu's algorithm uses the average sample value and the deviation to calculate the dispersion and the location. Unfortunately, for those images with the presence of very long-tailed distributions, the Otsu method usually provides poor thresholding results. The average difference (denoted by MAD) is commonly chosen as the estimate of the separation, when the point with median level is selected for the location. For addressing this problem, a median-based Otsu method is proposed in this work and obtains very satisfactory results compared with original Otsu algorithm.

2. Otsu algorithm

Suppose the intensity of a gray level image be expressed in L gray levels [1, 2, ..., L]. The number of points with gray level at i is denoted by x_i and the entire number of points can be expressed as $X = x_1 + x_2 + \cdots + x_L$. The histogram of this gray-level image is regarded as a occurrence distribution of probability

$$p(i) = \frac{x_i}{X}, \quad x_i \ge 0, \quad \sum_{i=1}^{L} x_i = 1$$
 (1)

The image pixels are divided into two parts C_0 and C_1 , i.e. foreground and background by a threshold t. Where C_0 represents pixels within levels [1, 2, ..., t], and C_1 denotes pixels within levels [t+1, ..., L]. The occurrence probabilities of this class and average can be expressed as respectively

$$\omega_0 = \omega(t) = \sum_{i=1}^t p(i). \tag{2}$$

$$\omega_{l} = 1 - \omega(t) = \sum_{i=1}^{L} p(i). \tag{3}$$

$$\mu_0 = \sum_{i=1}^t \frac{i \cdot p(i)}{\omega_0} = \frac{1}{\omega(t)} \sum_{i=1}^t i \cdot p(i) . \tag{4}$$

$$\mu_1 = \sum_{i=t+1}^{L} \frac{i \cdot p(i)}{\omega_1} = \frac{1}{1 - \omega(t)} \sum_{i=t+1}^{L} i \cdot p(i) . \tag{5}$$

Total mean can be written as

$$\mu_T = \sum_{i=1}^L i \cdot p(i) \tag{6}$$

And we can find that

$$\mu_T = \omega_0 \mu_0 + \omega_1 \mu_1 \tag{7}$$

where ω_0 and ω_1 denote probabilities of foreground part and background part. Besides, μ_0 , μ_1 and μ_T refer to the mean in gray levels of the foreground of the gray image, the background of the gray image, and the entire gray level image.

The between-class variance σ_B^2 of the two classes C_0 and C_1 is given by

$$\sigma_B^2 = \omega_0 (\mu_0 - \mu_T)^2 + \omega_1 (\mu_1 - \mu_T)^2 \tag{8}$$

The separable degree η of the class, in the discrimination analysis, is

$$\eta = \max_{1 \le i \le L} \sigma_B^2 \tag{9}$$

Finally, maximizing σ_B^2 to choose the optimal threshold t^*

$$t^* = \underset{1 \le t \le L}{\arg \max} \, \sigma_B^2 \tag{10}$$

3. Proposed algorithm

When the distribution for class C_k (k=0 or 1) is skew or heavy-tailed, it is well known that the medvalue is a very robust estimate value compared with the average gray level. We find that the med-value replace of the average may obtain a t^* that is very accurate to the presence of heavy-tailed distributions for C_k compared with these thresholds chosen by Otsu algorithm.

So, we can replace the total mean μ_T with the total median level m_T of all points in the entire gray level image. Similarly to the whole image mean value μ_T , the mean value μ_0 and μ_1 can also be replaced by median gray-level m_0 and m_1 of the foreground part C_0 and the background part C_1 respectively.

The between-class variance σ_B^2 of the two parts C_0 and C_1 can be rewritten as

$$\sigma_B^2 = \omega_0 (m_0 - m_T)^2 + \omega_1 (m_1 - m_T)^2 \tag{11}$$

And the googness threshold t^* is chosen by maximizing σ_R^2

$$t^* = \underset{1 \le t \le L}{\arg \max} \, \sigma_B^2 \tag{12}$$

4. Experiments

In the experiments, the original Otsu method and our proposed Otsu method are implemented in Visual C++ 2008 and ran on an AMD Athlon 7750 Dual-Core 2.7GHz processor with a 2G RAM and a Windows XP platform. There are four testing images, i.e. coin image, defective tile image, stain1 image and stain2 image, and they are dispalyed in Fig.1. And Table 1 gives size of four testing images, thresholds obtained from the original Otsu method and the proposed Otsu method. Fig.2-Fig.5 display thresholding results of above four testing images. From the thresholding results we can find that our proposed Otsu method obtain the optimal threshold and satisfactory results, while the original Otsu method obtain very poor thresholding results compared with the proposed Otsu algorithm.

Table 1. Image size and thresholds from original and proposed Otsu methods

Image Name	Image Size	Thresholds	
		Original Otsu method	Proposed Otsu method
Coin	490×400	108	58
Defective Tile	423×390	172	184
Stain1	150×80	204	151
Stain2	850×170	154	119

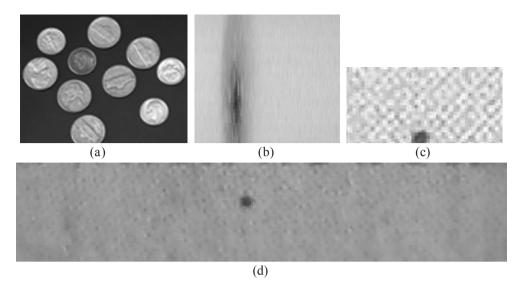


Fig.1. Testing images (a) Coin image; (b) Defective tile image; (c) Stain1 image; (d) Stain2 image.

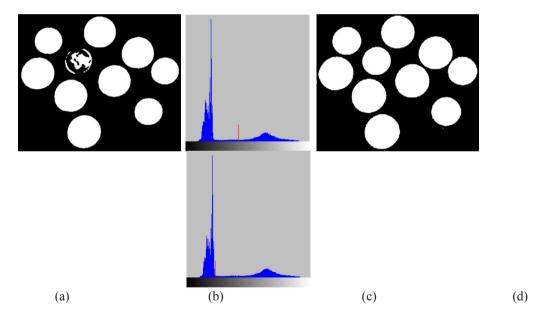


Fig. 2. Thresholding result of coin image (a) Result of original Otsu algorithm; (b) Threshold of original Otsu method; (c) Result of proposed Otsu method; (d) Threshold of proposed Otsu method.

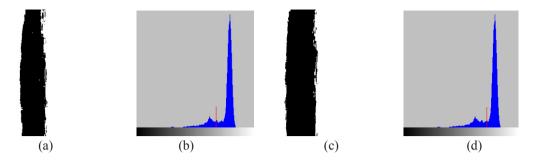


Fig.3. Thresholding result of defective tile image (a) Result of original Otsu method; (b) Threshold of original Otsu method; (c) Result of proposed Otsu method; (d) Threshold of proposed Otsu method.

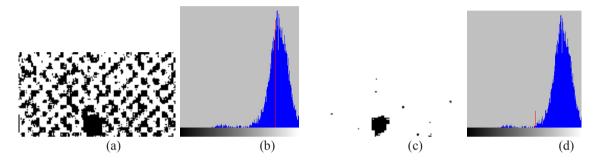


Fig.4. Thresholding result of stain1 image (a) Result of original Otsu method; (b) Threshold of original Otsu method; (c) Result of proposed Otsu method; (d) Threshold of proposed Otsu method.

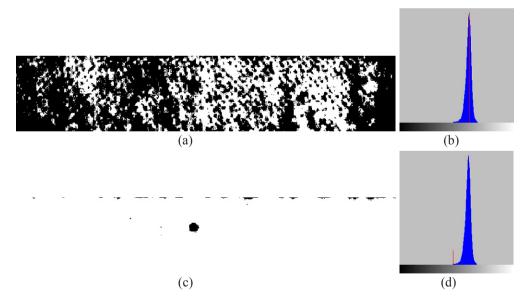


Fig. 5. Thresholding result of stain 2 image (a) Result of original Otsu method; (b) Threshold of original Otsu method; (c) Result of proposed Otsu method; (d) Threshold of proposed Otsu method.

5. Conclusion

In this paper, a median-based Otsu algorithm for thresholding images is proposed. The original Otsu scheme obtains improving results for segmenting an gray level image with a bimodal distributed histogram. Unfortunately, it provides very poor thresholding results if the histogram is only one modal in the histogram. It is clear that, when the distribution of histogram of an image is skew distributed, or when there are noises in the gray level image, the median is a very effective selection of location compared to the total mean. In this motivation, we replace the means of the foreground, the background and the entire gray level image in the original Otsu method with the medians of the foreground, the background and the whole image in the proposed Otsu method. Compared with the original Otsu algorithm, our proposed Otsu method obtains accurate threshold and satisfactory thresholding results.

Acknowledgements

This research was supported by the Opening Project of Key Laboratory Ministry of Education (NO. 450060445325), the Opening Project of Key Laboratory of Sea Battlefield Countermine Simulation Technology of Ministry of Education of Jilin University (NO. 450060481223), and Graduate Innovation Fund of Jilin University (NO. 20121104).

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