

History-Preserving Bisimilarity for Higher-Dimensional Automata via Open Maps

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Abstract

We show that history-preserving bisimilarity for higher-dimensional automata has a simple characterization directly in terms of higher-dimensional transitions. This implies that it is decidable for finite higher-dimensional automata. To arrive at our characterization, we apply the open-maps framework of Joyal, Nielsen and Winskel in the category of unfoldings of precubical sets.

Keywords: higher-dimensional automaton, history-preserving bisimilarity, homotopy, unfolding, concurrency

1 Introduction

The dominant notion for behavioral equivalence of processes is *bisimulation* as introduced by Park [31] and Milner [27]. It is compelling because it enjoys good algebraic properties, admits several easy characterizations using modal logics, fixed points, or game theory, and generally has low computational complexity.

Bisimulation, or rather its underlying semantic model of *transition systems*, applies to a setting in which concurrency of actions is the same as non-deterministic interleaving; using CCS notation [27], $a|b = a.b + b.a$. For some applications however, a distinction between these two is necessary, which has led to development of so-called *non-interleaving* or *truly concurrent* models such as Petri nets [32], event structures [30], asynchronous transition systems [4, 35] and others; see [40] for a survey.

One of the most popular notions of equivalence for non-interleaving systems is *history-preserving bisimilarity* (or *hp-bisimilarity* for short). It was introduced independently by Degano, De Nicola and Montanari in [6] and by Rabinovich and Trakhtenbrot [34] and then for event structures by van Glabbeek and Goltz in [39] and for Petri nets by Best *et.al.* in [5]. One reason for its popularity is that it is a

congruence under action refinement [5,39], another its good decidability properties: it has been shown to be decidable for safe Petri nets by Montanari and Pistore [29]. As a contrast, its cousin *hereditary* hp-bisimilarity is shown undecidable for 1-safe Petri nets by Jurdziński, Nielsen and Srba in [24].

Higher-dimensional automata (or *HDA*) is another non-interleaving formalism for reasoning about behavior of concurrent systems. Introduced by Pratt [33] and van Glabbeek [37] in 1991 for the purpose of a *geometric* interpretation to the theory of concurrency, it has since been shown by van Glabbeek [38] that HDA provide a generalization (up to hp-bisimilarity) to “the main models of concurrency proposed in the literature” [38], including the ones mentioned above. Hence HDA are useful as a tool for comparing and relating different models, and also as a modeling formalism by themselves.

HDA are geometric in the sense that they are very similar to the *simplicial complexes* used in algebraic topology, and research on HDA has drawn on a lot of tools and methods from geometry and algebraic topology such as homotopy [11,14], homology [15,20], and model categories [16,17], see also the survey [18].

In this paper we give a geometric interpretation to hp-bisimilarity for HDA, using the open-maps approach introduced by Joyal, Nielsen and Winskel in [23] and results from a previous paper [7] by the first author. Using this interpretation, we show that hp-bisimilarity for HDA has a characterization directly in terms of (higher-dimensional) *transitions* of the HDA, rather than in terms of runs as *e.g.* for Petri nets [13].

Our results imply *decidability* of hp-bisimilarity for finite HDA. They also put hp-bisimilarity firmly into the open-maps framework of [23] and tighten the connections between bisimilarity and weak topological *fibrations* [3,25].

Due to lack of space, we have had to omit all proofs in this paper. They can be found in the long version at [9].

2 Higher-Dimensional Automata

As a formalism for concurrent behavior, HDA have the specific feature that they can express all higher-order dependencies between events in a concurrent system. Like for transition systems, they consist of states and transitions which are labeled with events. Now if two transitions from a state, with labels a and b for example, are independent, then this is expressed by the existence of a *two-dimensional* transition with label ab . Fig. 1 shows two examples; on the left, transitions a and b are independent, on the right, they can merely be executed in any order. Hence for HDA, as indeed for any formalism employing the so-called *true concurrency* paradigm, the algebraic law $a|b = a.b + b.a$ does *not* hold; concurrency is not the same as interleaving.

The above considerations can equally be applied to sets of more than two events: if three events a, b, c are independent, then this is expressed using a three-dimensional transition labeled abc . Hence this is different from mutual pairwise independence (expressed by transitions ab, ac, bc), a distinction which cannot be

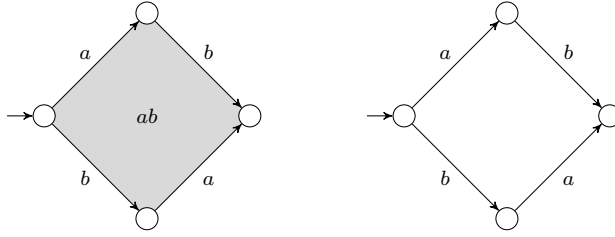


Fig. 1. HDA for the CCS expressions $a|b$ (left) and $a.b + b.a$ (right). In the left HDA, the square is filled in by a two-dimensional transition labeled ab , signifying independence of events a and b . On the right, a and b are not independent.

made in formalisms such as asynchronous transition systems [4, 35] or transition systems with independence [40] which only consider binary independence relations.

An unlabeled HDA is essentially a pointed precubical set as defined below. For labeled HDA, one can pass to an arrow category; this is what we shall do in Section 6. Until then, we concentrate on the unlabeled case.

A *precubical set* is a graded set $X = \{X_n\}_{n \in \mathbb{N}}$ together with mappings $\delta_k^\nu : X_n \rightarrow X_{n-1}$, $k \in \{1, \dots, n\}$, $\nu \in \{0, 1\}$, satisfying the *precubical identity*

$$\delta_k^\nu \delta_\ell^\mu = \delta_{\ell-1}^\mu \delta_k^\nu \quad (k < \ell). \quad (1)$$

The mappings δ_k^ν are called *face maps*, and elements of X_n are called *n -cubes*. As above, we shall usually omit the extra subscript (n) in the face maps. Faces $\delta_k^0 x$ of an element $x \in X$ are to be thought of as *lower faces*, $\delta_k^1 x$ as *upper faces*. The precubical identity expresses the fact that $(n-1)$ -faces of an n -cube meet in common $(n-2)$ -faces, see Fig. 2 for an example of a 2-cube and its faces.

Morphisms $f : X \rightarrow Y$ of precubical sets are graded mappings $f = \{f_n : X_n \rightarrow Y_n\}_{n \in \mathbb{N}}$ which commute with the face maps: $\delta_k^\nu \circ f_n = f_{n-1} \circ \delta_k^\nu$ for all $n \in \mathbb{N}$, $k \in \{1, \dots, n\}$, $\nu \in \{0, 1\}$. This defines a category \mathbf{pCub} of precubical sets and morphisms.

A *pointed* precubical set is a precubical set X with a specified 0-cube $i \in X_0$, and a pointed morphism is one which respects the point. This defines a category which is isomorphic to the comma category $* \downarrow \mathbf{pCub}$, where $*$ $\in \mathbf{pCub}$ is the precubical set with one 0-cube and no other n -cubes. Note that $*$ is *not* terminal in \mathbf{pCub} (instead, the terminal object is the infinite-dimensional precubical set with one cube in every dimension).

Definition 2.1 The category of *higher-dimensional automata* is the comma cate-

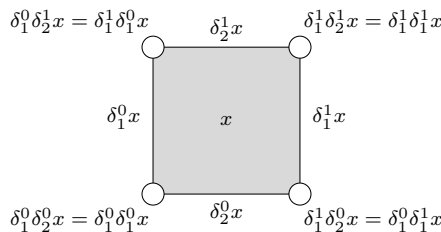


Fig. 2. A 2-cube x with its four faces $\delta_1^0 x$, $\delta_1^1 x$, $\delta_2^0 x$, $\delta_2^1 x$ and four corners.

gory $\text{HDA} = * \downarrow \text{pCub}$, with objects pointed precubical sets and morphisms commutative diagrams

$$\begin{array}{ccc} & * & \\ \swarrow & & \searrow \\ X & \xrightarrow{f} & Y \end{array}.$$

Hence a one-dimensional HDA is a transition system; indeed, the category of transition systems [40] is isomorphic to the full subcategory of HDA spanned by the one-dimensional objects. Similarly one can show [19] that the category of asynchronous transition systems is isomorphic to the full subcategory of HDA spanned by the (at most) two-dimensional objects. The category HDA as defined above was used in [7] to provide a categorical framework (in the spirit of [40]) for parallel composition of HDA. In this article we also introduced a notion of bisimilarity which we will review in the next section.

3 Path Objects, Open Maps and Bisimilarity

With the purpose of introducing bisimilarity via *open maps* in the sense of [23], we identify here a subcategory of HDA consisting of path objects and path-extending morphisms. We say that a precubical set X is a *precubical path object* if there is a (necessarily unique) sequence (x_1, \dots, x_m) of elements in X such that $x_i \neq x_j$ for $i \neq j$,

- for each $x \in X$ there is $j \in \{1, \dots, m\}$ for which $x = \delta_{k_1}^{\nu_1} \cdots \delta_{k_p}^{\nu_p} x_j$ for some indices ν_1, \dots, ν_p and a *unique* sequence $k_1 < \dots < k_p$, and
- for each $j = 1, \dots, m - 1$, there is $k \in \mathbb{N}$ for which $x_j = \delta_k^0 x_{j+1}$ or $x_{j+1} = \delta_k^1 x_j$.

Note that precubical path objects are *non-selflinked* in the sense of [11]. If X and Y are precubical path objects with representations (x_1, \dots, x_m) , (y_1, \dots, y_p) , then a morphism $f : X \rightarrow Y$ is called a *cube path extension* if $x_j = y_j$ for all $j = 1, \dots, m$ (hence $m \leq p$).

Definition 3.1 The category HDP of *higher-dimensional paths* is the subcategory of HDA which as objects has pointed precubical paths, and whose morphisms are generated by isomorphisms and pointed cube path extensions.

A *cube path* in a precubical set X is a morphism $P \rightarrow X$ from a precubical path object P . In elementary terms, this is a sequence (x_1, \dots, x_m) of elements of X such that for each $j = 1, \dots, m - 1$, there is $k \in \mathbb{N}$ for which $x_j = \delta_k^0 x_{j+1}$ (start of new part of a computation) or $x_{j+1} = \delta_k^1 x_j$ (end of a computation part). We show an example of a cube path in Fig. 3.

A cube path in a HDA $i : * \rightarrow X$ is *pointed* if $x_1 = i$, hence if it is a pointed morphism $P \rightarrow X$ from a higher-dimensional path P . We will say that a cube path (x_1, \dots, x_m) is *from* x_1 *to* x_m , and that a cube $x \in X$ in a HDA X is *reachable* if there is a pointed cube path to x in X .

Cube paths can be *concatenated* if the end of one is compatible with the beginning of the other: If $\rho = (x_1, \dots, x_m)$ and $\sigma = (y_1, \dots, y_p)$ are cube paths with

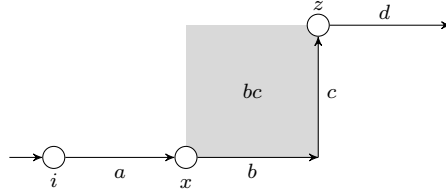


Fig. 3. Graphical representation of the two-dimensional cube path $(i, a, x, b, bc, c, z, d)$. Its computational interpretation is that a is executed first, then execution of b starts, and while b is running, c starts to execute. After this, b finishes, then c , and then execution of d is started. Note that the computation is partial, as d does not finish.

$y_1 = \delta_k^1 x_m$ or $x_m = \delta_k^0 y_1$ for some k , then their *concatenation* is the cube path $\rho * \sigma = (x_1, \dots, x_m, y_1, \dots, y_p)$. We say that ρ is a *prefix* of χ and write $\rho \sqsubseteq \chi$ if there is a cube path ρ for which $\chi = \rho * \sigma$.

Definition 3.2 A pointed morphism $f : X \rightarrow Y$ in HDA is an *open map* if it has the right lifting property with respect to HDP, i.e. if it is the case that there is a lift r in any commutative diagram as below, for morphisms $g : P \rightarrow Q \in \text{HDP}$, $p : P \rightarrow X, q : Q \rightarrow Y \in \text{HDA}$:

$$\begin{array}{ccc} P & \xrightarrow{p} & X \\ g \downarrow & \nearrow r & \downarrow f \\ Q & \xrightarrow{q} & Y \end{array}$$

HDA X, Y are *bisimilar* if there is $Z \in \text{HDA}$ and a span of open maps $X \leftarrow Z \rightarrow Y$ in HDA.

It follows straight from the definition that composites of open maps are again open. By the next lemma, morphisms are open precisely when they have a zig-zag property similar to the one of [23].

Lemma 3.3 For a morphism $f : X \rightarrow Y \in \text{HDA}$, the following are equivalent:

- (i) f is open;
- (ii) for any reachable $x_1 \in X$ and any $y_2 \in Y$ with $f(x_1) = \delta_k^0 y_2$ for some k , there is $x_2 \in X$ for which $x_1 = \delta_k^0 x_2$ and $y_2 = f(x_2)$;
- (iii) for any reachable $x_1 \in X$ and any cube path (y_1, \dots, y_m) in Y with $y_1 = f(x_1)$, there is a cube path (x_1, \dots, x_m) in X for which $y_j = f(x_j)$ for all $j = 1, \dots, m$.

Theorem 3.4 For HDA $i : * \rightarrow X, j : * \rightarrow Y$, the following are equivalent:

- (i) X and Y are bisimilar;
- (ii) there exists a precubical subset $R \subseteq X \times Y$ for which $(i, j) \in R$, and such that for all reachable $x_1 \in X, y_1 \in Y$ with $(x_1, y_1) \in R$,
 - for any $x_2 \in X$ for which $x_1 = \delta_k^0 x_2$ for some k , there exists $y_2 \in Y$ for which $y_1 = \delta_k^0 y_2$ and $(x_2, y_2) \in R$,
 - for any $y_2 \in Y$ for which $y_1 = \delta_k^0 y_2$ for some k , there exists $x_2 \in X$ for which $x_1 = \delta_k^0 x_2$ and $(x_2, y_2) \in R$;
- (iii) there exists a precubical subset $R \subseteq X \times Y$ for which $(i, j) \in R$, and such that for all reachable $x_1 \in X, y_1 \in Y$ with $(x_1, y_1) \in R$,

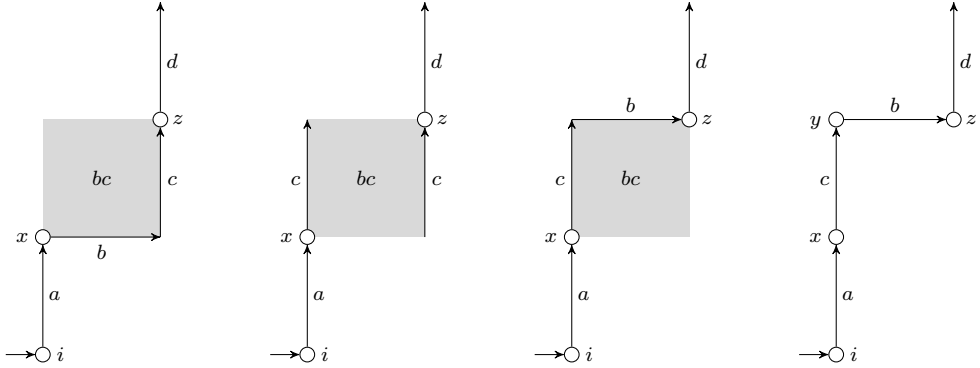


Fig. 4. Graphical representation of the cube path homotopy $(i, a, x, b, bc, c, z, d) \sim (i, a, x, c, bc, c, z, d) \sim (i, a, x, c, bc, b, z, d) \sim (i, a, x, c, y, b, z, d)$.

- for any cube path (x_1, \dots, x_m) in X , there exists a cube path (y_1, \dots, y_m) in Y with $(x_p, y_p) \in R$ for all $p = 1, \dots, m$,
- for any cube path (y_1, \dots, y_m) in Y , there exists a cube path (x_1, \dots, x_m) in X with $(x_p, y_p) \in R$ for all $p = 1, \dots, m$.

Note that the requirement that R be a precubical subset, in items (ii) and (iii) above, is equivalent to saying that whenever $(x, y) \in R$, then also $(\delta_k^\nu x, \delta_k^\nu y) \in R$ for any k and $\nu \in \{0, 1\}$.

4 Homotopies and Unfoldings

In order to reason about hp-bisimilarity, we need to introduce in which cases different cube paths are equivalent due to independence of actions. Following [38], we model this equivalence by a combinatorial version of *homotopy* which is an extension of the equivalence defining *Mazurkiewicz traces* [26].

We say that cube paths (x_1, \dots, x_m) , (y_1, \dots, y_m) are *adjacent* if $x_1 = y_1$, $x_m = y_m$, there is precisely one index $p \in \{1, \dots, m\}$ at which $x_p \neq y_p$, and

- $x_{p-1} = \delta_k^0 x_p$, $x_p = \delta_\ell^0 x_{p+1}$, $y_{p-1} = \delta_{\ell-1}^0 y_p$, and $y_p = \delta_k^0 y_{p+1}$ for some $k < \ell$, or vice versa,
- $x_p = \delta_k^1 x_{p-1}$, $x_{p+1} = \delta_\ell^1 x_p$, $y_p = \delta_{\ell-1}^1 y_{p-1}$, and $y_{p+1} = \delta_k^1 y_p$ for some $k < \ell$, or vice versa,
- $x_p = \delta_k^0 \delta_\ell^1 y_p$, $y_{p-1} = \delta_k^0 y_p$, and $y_{p+1} = \delta_\ell^1 y_p$ for some $k < \ell$, or vice versa, or
- $x_p = \delta_k^1 \delta_\ell^0 y_p$, $y_{p-1} = \delta_\ell^0 y_p$, and $y_{p+1} = \delta_k^1 y_p$ for some $k < \ell$, or vice versa.

Homotopy of cube paths is the reflexive, transitive closure of the adjacency relation. We denote homotopy of cube paths using the symbol \sim , and the homotopy class of a cube path (x_1, \dots, x_m) is denoted $[x_1, \dots, x_m]$. The intuition of adjacency is rather simple, even though the combinatorics may look complicated, see Fig. 4. Note that adjacencies come in two basic “flavors”: the first two above in which the dimensions of x_ℓ and y_ℓ are the same, and the last two in which they differ by 2.

The following lemma shows that, as expected, cube paths entirely contained in

one cube are homotopic (provided that they share endpoints).

Lemma 4.1 *Let $x \in X_n$ in a precubical set X and $(k_1, \dots, k_n), (\ell_1, \dots, \ell_n)$ sequences of indices with $k_j, \ell_j \leq j$ for all $j = 1, \dots, n$. Let $x_j = \delta_{k_j}^0 \cdots \delta_{k_n}^0 x$, $y_j = \delta_{\ell_j}^0 \cdots \delta_{\ell_n}^0 x$. Then the cube paths $(x_1, \dots, x_n, x) \sim (y_1, \dots, y_n, x)$.*

We extend concatenation and prefix to homotopy classes of cube paths by defining $[x_1, \dots, x_m] * [y_1, \dots, y_p] = [x_1, \dots, x_m, y_1, \dots, y_p]$ and saying that $\tilde{x} \sqsubseteq \tilde{z}$, for homotopy classes \tilde{x}, \tilde{z} of cube paths, if there are $(x_1, \dots, x_m) \in \tilde{x}$ and $(z_1, \dots, z_q) \in \tilde{z}$ for which $(x_1, \dots, x_m) \sqsubseteq (z_1, \dots, z_q)$. It is easy to see that concatenation is well-defined, and that $\tilde{x} \sqsubseteq \tilde{z}$ if and only if there is a homotopy class \tilde{y} for which $\tilde{z} = \tilde{x} * \tilde{y}$.

Using homotopy classes of cube paths, we can now define the *unfolding* of a HDA. Unfoldings of HDA are similar to unfoldings of transition systems [40] or Petri nets [22, 30], but also to *universal covering spaces* in algebraic topology. The intention is that the unfolding of a HDA captures all its computations, up to homotopy.

We say that a HDA X is a *higher-dimensional tree* if it holds that for any $x \in X$, there is precisely one homotopy class of pointed cube paths to x . The full subcategory of HDA spanned by the higher-dimensional trees is denoted HDT. Note that any higher-dimensional path is a higher-dimensional tree; indeed there is an inclusion $\text{HDP} \hookrightarrow \text{HDT}$.

Definition 4.2 The *unfolding* of a HDA $i : * \rightarrow X$ consists of a HDA $\tilde{i} : * \rightarrow \tilde{X}$ and a pointed *projection* morphism $\pi_X : \tilde{X} \rightarrow X$, which are defined as follows:

- $\tilde{X}_n = \{[x_1, \dots, x_m] \mid (x_1, \dots, x_m) \text{ pointed cube path in } X, x_m \in X_n\}$; $\tilde{i} = [i]$
- $\tilde{\delta}_k^0[x_1, \dots, x_m] = \{\sigma = (y_1, \dots, y_p) \mid y_p = \delta_k^0 x_m, \sigma * x_m \sim (x_1, \dots, x_m)\}$
- $\tilde{\delta}_k^1[x_1, \dots, x_m] = [x_1, \dots, x_m, \delta_k^1 x_m]$
- $\pi_X[x_1, \dots, x_m] = x_m$

Proposition 4.3 *The unfolding (\tilde{X}, π_X) of a HDA X is well-defined, and \tilde{X} is a higher-dimensional tree. If X itself is a higher-dimensional tree, then the projection $\pi_X : \tilde{X} \rightarrow X$ is an isomorphism.*

Lemma 4.4 *If X is a higher-dimensional automaton and $(\tilde{x}_1, \dots, \tilde{x}_m)$ is a pointed cube path in \tilde{X} , then $(\pi_X \tilde{x}_1, \dots, \pi_X \tilde{x}_j) \in \tilde{x}_j$ for all $j = 1, \dots, m$.*

Lemma 4.5 *For any HDA X there is a unique lift r in any commutative diagram as below, for morphisms $g : P \rightarrow Q \in \text{HDP}$, $p : P \rightarrow \tilde{X}$, $q : Q \rightarrow X \in \text{HDA}$:*

$$\begin{array}{ccc} P & \xrightarrow{p} & \tilde{X} \\ g \downarrow & \nearrow r & \downarrow \pi_X \\ Q & \xrightarrow{q} & X \end{array}$$

Corollary 4.6 *Projections are open, and any HDA is bisimilar to its unfolding. \square*

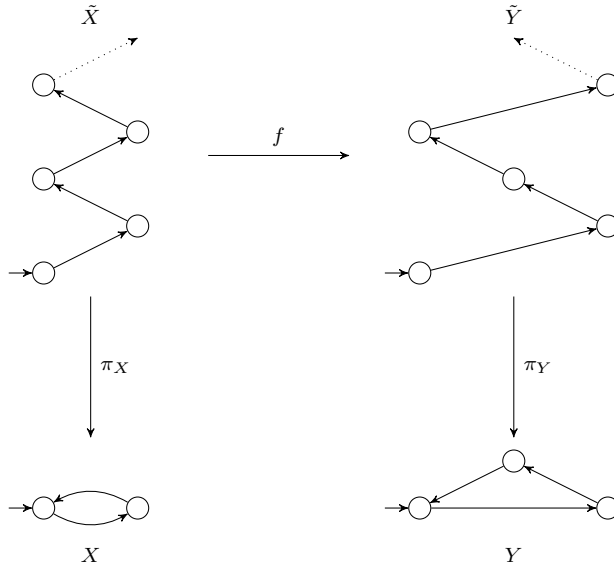


Fig. 5. Two simple one-dimensional HDA as objects of \mathbf{HDA} and \mathbf{HDA}_h . In \mathbf{HDA} there is no morphism $X \rightarrow Y$, in \mathbf{HDA}_h there is precisely one morphism $f : X \rightarrow Y$.

5 History-Preserving Bisimilarity

In this section we recall history-preserving bisimilarity for HDA from [38] and show the main result of this paper: that hp-bisimilarity and the bisimilarity of Def. 3.2 are the same. To do this, we first need to introduce *morphisms of homotopy classes of paths* and *homotopy bisimilarity*.

Definition 5.1 The category of *higher-dimensional automata up to homotopy* \mathbf{HDA}_h has as objects HDA and as morphisms pointed precubical morphisms $f : \tilde{X} \rightarrow \tilde{Y}$ of unfoldings.

Hence any morphism $X \rightarrow Y$ in \mathbf{HDA} gives, by the unfolding functor, rise to a morphism $X \rightarrow Y$ in \mathbf{HDA}_h . The simple example in Fig. 5 shows that the converse is not the case. By restriction to higher-dimensional trees, we get a full subcategory $\mathbf{HDT}_h \hookrightarrow \mathbf{HDA}_h$.

Lemma 5.2 The natural projection isomorphisms $\pi_X : \tilde{X} \rightarrow X$ for $X \in \mathbf{HDT}$ extend to an isomorphism of categories $\mathbf{HDT}_h \cong \mathbf{HDT}$.

Restricting the above isomorphism to the subcategory HDP of \mathbf{HDT} allows us to identify a subcategory \mathbf{HDP}_h of \mathbf{HDT}_h isomorphic to HDP.

Definition 5.3 A pointed morphism $f : X \rightarrow Y$ in \mathbf{HDA}_h is *open* if it has the right lifting property with respect to \mathbf{HDP}_h , i.e. if it is the case that there is a lift r in any commutative diagram as below, for all morphism $g : P \rightarrow Q \in \mathbf{HDP}_h$,

$p : P \rightarrow X, q : Q \rightarrow Y \in \text{HDA}_h$:

$$\begin{array}{ccc} P & \xrightarrow{p} & X \\ g \downarrow & \swarrow r & \downarrow f \\ Q & \xrightarrow{q} & Y \end{array}$$

$\text{HDA } X, Y$ are *homotopy bisimilar* if there is $Z \in \text{HDA}_h$ and a span of open maps $X \leftarrow Z \rightarrow Y$ in HDA_h .

The connections between open maps in HDA_h and open maps in HDA are as follows.

Lemma 5.4 *A morphism $f : X \rightarrow Y$ in HDA_h is open if and only if $f : \tilde{X} \rightarrow \tilde{Y}$ is open as a morphism of HDA . If $g : X \rightarrow Y$ is open in HDA , then so is $\tilde{g} : \tilde{X} \rightarrow \tilde{Y}$.*

We also need a lemma on prefixes in unfoldings.

Lemma 5.5 *Let X be a HDA and $\tilde{x}, \tilde{z} \in \tilde{X}$. Then there is a cube path from \tilde{x} to \tilde{z} in \tilde{X} if and only if $\tilde{x} \sqsubseteq \tilde{z}$.*

Proposition 5.6 *For $\text{HDA } i : * \rightarrow X, j : * \rightarrow Y$, the following are equivalent:*

- (i) X and Y are homotopy bisimilar;
- (ii) there exists a precubical subset $R \subseteq \tilde{X} \times \tilde{Y}$ with $(\tilde{i}, \tilde{j}) \in R$, and such that for all $(\tilde{x}_1, \tilde{y}_1) \in R$,
 - for any $\tilde{x}_2 \in \tilde{X}$ for which $\tilde{x}_1 = \delta_k^0 \tilde{x}_2$ for some k , there exists $\tilde{y}_2 \in \tilde{Y}$ for which $\tilde{y}_1 = \delta_k^0 \tilde{y}_2$ and $(\tilde{x}_2, \tilde{y}_2) \in R$,
 - for any $\tilde{y}_2 \in \tilde{Y}$ for which $\tilde{y}_1 = \delta_k^0 \tilde{y}_2$ for some k , there exists $\tilde{x}_2 \in \tilde{X}$ for which $\tilde{x}_1 = \delta_k^0 \tilde{x}_2$ and $(\tilde{x}_2, \tilde{y}_2) \in R$;
- (iii) there exists a precubical subset $R \subseteq \tilde{X} \times \tilde{Y}$ with $(\tilde{i}, \tilde{j}) \in R$, and such that for all $(\tilde{x}_1, \tilde{y}_1) \in R$,
 - for any cube path $(\tilde{x}_1, \dots, \tilde{x}_n)$ in \tilde{X} , there exists a cube path $(\tilde{y}_1, \dots, \tilde{y}_n)$ in \tilde{Y} with $(\tilde{x}_p, \tilde{y}_p) \in R$ for all $p = 1, \dots, n$,
 - for any cube path $(\tilde{y}_1, \dots, \tilde{y}_n)$ in \tilde{Y} , there exists a cube path $(\tilde{x}_1, \dots, \tilde{x}_n)$ in \tilde{X} with $(\tilde{x}_p, \tilde{y}_p) \in R$ for all $p = 1, \dots, n$;
- (iv) there exists a precubical subset $R \subseteq \tilde{X} \times \tilde{Y}$ with $(\tilde{i}, \tilde{j}) \in R$, and such that for all $(\tilde{x}_1, \tilde{y}_1) \in R$,
 - for any $\tilde{x}_2 \sqsupseteq \tilde{x}_1$ in \tilde{X} , there exists $\tilde{y}_2 \sqsupseteq \tilde{y}_1$ in \tilde{Y} for which $(\tilde{x}_2, \tilde{y}_2) \in R$,
 - for any $\tilde{y}_2 \sqsupseteq \tilde{y}_1$ in \tilde{Y} , there exists $\tilde{x}_2 \sqsupseteq \tilde{x}_1$ in \tilde{X} for which $(\tilde{x}_2, \tilde{y}_2) \in R$.

Again, the requirement that R be a precubical subset is equivalent to saying that whenever $(\tilde{x}, \tilde{y}) \in R$, then also $(\delta_k^\nu \tilde{x}, \delta_k^\nu \tilde{y}) \in R$ for any k and $\nu \in \{0, 1\}$. The next result is what will allow us to relate hp-bisimilarity and bisimilarity.

Theorem 5.7 *HDA X, Y are homotopy bisimilar if and only if they are bisimilar.*

The following is an unlabeled version of hp-bisimilarity for HDA as defined in [38]:

Definition 5.8 HDA $i : * \rightarrow X$, $j : * \rightarrow Y$ are *history-preserving bisimilar* if there exists a relation R between pointed cube paths in X and pointed cube paths in Y for which $((i), (j)) \in R$, and such that for all $(\rho, \sigma) \in R$,

- for all $\rho' \sim \rho$, there exists $\sigma' \sim \sigma$ with $(\rho', \sigma') \in R$,
- for all $\sigma' \sim \sigma$, there exists $\rho' \sim \rho$ with $(\rho', \sigma') \in R$,
- for all $\rho' \sqsupseteq \rho$, there exists $\sigma' \sqsupseteq \sigma$ with $(\rho', \sigma') \in R$,
- for all $\sigma' \sqsupseteq \sigma$, there exists $\rho' \sqsupseteq \rho$ with $(\rho', \sigma') \in R$.

We are ready to show the main result of this paper, which together with Theorem 5.7 gives our characterization for hp-bisimilarity.

Theorem 5.9 HDA X , Y are homotopy bisimilar if and only if they are history-preserving bisimilar.

Corollary 5.10 History-preserving bisimilarity is decidable for finite HDA.

6 Labels

We finish this paper by showing how to introduce labels into the above framework of bisimilarity and homotopy bisimilarity. Also in the labeled case, we are able to show that the three notions of bisimilarity, homotopy bisimilarity and history-preserving bisimilarity agree.

For labeling HDA, we need a subcategory of \mathbf{pCub} isomorphic to the category of sets and functions. Given a finite or countably infinite set $S = \{a_1, a_2, \dots\}$, we construct a precubical set $!S = \{!S_n\}$ by letting

$$!S_n = \{(a_{i_1}, \dots, a_{i_n}) \mid i_k \leq i_{k+1} \text{ for all } k = 1, \dots, n-1\}$$

with face maps defined by $\delta_k^\nu(a_{i_1}, \dots, a_{i_n}) = (a_{i_1}, \dots, a_{i_{k-1}}, a_{i_{k+1}}, \dots, a_{i_n})$.

Definition 6.1 The category of *higher-dimensional tori* HDO is the full subcategory of \mathbf{pCub} generated by the objects $!S$.

As any object in HDO has precisely one 0-cube, the pointed category $* \downarrow \mathbf{HDO}$ is isomorphic to HDO. It is not difficult to see that HDO is indeed isomorphic to the category of finite or countably infinite sets and functions, cf. [21].

Definition 6.2 The category of *labeled higher-dimensional automata* is the pointed arrow category $\mathbf{LHDA} = * \downarrow \mathbf{pCub} \rightarrow \mathbf{HDO}$, with objects $* \rightarrow X \rightarrow !S$ labeled pointed precubical sets and morphisms commutative diagrams

$$\begin{array}{ccc} & * & \\ \swarrow & & \searrow \\ X & \xrightarrow{f} & Y \\ \downarrow & & \downarrow \\ !S & \xrightarrow{\sigma} & !T \end{array}$$

Definition 6.3 A morphism $(f, \text{id}) : (* \rightarrow X \rightarrow !S) \rightarrow (* \rightarrow Y \rightarrow !S)$ in LHDA is *open* if its component f is open in HDA. Labeled HDA $* \rightarrow X \rightarrow !S$, $* \rightarrow Y \rightarrow !S$ are *bisimilar* if there is $* \rightarrow Z \rightarrow !S \in \text{LHDA}$ and a span of open maps $X \leftarrow Z \rightarrow Y$ in LHDA.

Next we establish a correspondence between split traces [38] and cube paths in higher-dimensional tori. For us, a *split trace* over a finite or countably infinite set S is a pointed cube path in $!S$. Hence *e.g.* a split trace $a^+b^+a^-b^+b^-$ (in the notation of [38]) corresponds to the cube path (i, a, ab, b, bb, b) . Both indicate the start of an a event, followed by the start of a b event, the end of an a event, the start of a b event, and the end of a b event. Note that contrary to ST-traces [38], the split trace contains no information as to which of the two b events has terminated at the b^- .

By definition, a torus $!S$ on a finite or countably infinite set $S = \{a_1, a_2, \dots\}$ contains all n -cubes $(a_{i_1}, \dots, a_{i_n})$. Hence we have the following lemma:

Lemma 6.4 Let $(x_1, \dots, x_m), (y_1, \dots, y_m)$ be pointed cube paths in $!S$ with $x_m = y_m$. Then $(x_1, \dots, x_m) \sim (y_1, \dots, y_m)$. \square

Homotopy classes of split traces are thus determined by their endpoint and length:

Corollary 6.5 The unfolding of a higher-dimensional torus $i : * \rightarrow !S \in \text{HDO}$ is isomorphic to the pointed precubical set $j : * \rightarrow Y$ given as follows:

- $Y_n = \{(x, m) \mid x \in !S_n, m \geq n, m \equiv n \pmod{2}\}$, $j = (i, 0)$
- $\delta_k^0(x, m) = (\delta_k^0 x, m - 1)$, $\delta_k^1(x, m) = (\delta_k^1 x, m + 1)$ \square

The definitions of open maps and bisimilarity in HDA_h can now easily be extended to the labeled case. Again, we only need label-preserving morphisms.

Definition 6.6 The category of *labeled higher-dimensional automata up to homotopy* LHDA_h has as objects labeled HDA $* \rightarrow X \rightarrow !S$ and as morphisms pairs of precubical morphisms $(f, \sigma) : (* \rightarrow \tilde{X} \rightarrow !\tilde{S}) \rightarrow (* \rightarrow \tilde{Y} \rightarrow !\tilde{T})$ of unfoldings.

Definition 6.7 A morphism $(f, \text{id}) : (* \rightarrow X \rightarrow !S) \rightarrow (* \rightarrow Y \rightarrow !S)$ in LHDA_h is *open* if its component f is open in HDA_h . Labeled HDA $* \rightarrow X \rightarrow !S$, $* \rightarrow Y \rightarrow !S$ are *homotopy bisimilar* if there is $* \rightarrow Z \rightarrow !S \in \text{LHDA}_h$ and a span of open maps $X \leftarrow Z \rightarrow Y$ in LHDA_h .

The proof of the next theorem is exactly the same as the one for Theorem 5.7.

Theorem 6.8 Labeled HDA X, Y are homotopy bisimilar if and only if they are bisimilar. \square

Also for the labeled version, we can now show that homotopy bisimilarity agrees with history-preserving bisimilarity. We first recall the definition from [38], where we extend the labeling morphisms to cube paths by $\lambda(x_1, \dots, x_m) = (\lambda x_1, \dots, \lambda x_m)$:

Definition 6.9 Labeled HDA $* \xrightarrow{i} X \xrightarrow{\lambda} !S$, $* \xrightarrow{j} Y \xrightarrow{\mu} !S$ are *history-preserving bisimilar* if there exists a relation R between pointed cube paths in X and pointed

cube paths in Y for which $((i), (j)) \in R$, and such that for all $(\rho, \sigma) \in R$,

- $\lambda(\rho) = \mu(\sigma)$,
- for all $\rho' \sim \rho$, there exists $\sigma' \sim \sigma$ with $(\rho', \sigma') \in R$,
- for all $\sigma' \sim \sigma$, there exists $\rho' \sim \rho$ with $(\rho', \sigma') \in R$,
- for all $\rho' \sqsupseteq \rho$, there exists $\sigma' \sqsupseteq \sigma$ with $(\rho', \sigma') \in R$,
- for all $\sigma' \sqsupseteq \sigma$, there exists $\rho' \sqsupseteq \rho$ with $(\rho', \sigma') \in R$.

Theorem 6.10 *Labeled HDA X, Y are homotopy bisimilar if and only if they are history-preserving bisimilar.*

7 Conclusion

We have shown that hp-bisimilarity for HDA can be characterized by spans of open maps in the category of pointed precubical sets, or equivalently by a zig-zag relation between cubes in all dimensions. Aside from implying decidability of hp-bisimilarity for HDA, and together with the results of [38], this confirms that HDA is a natural formalism for concurrency: not only does it generalize the main models for concurrency which people have been working with, but it also is remarkably simple and natural.

One major question which remains is whether also *hereditary* hp-bisimilarity can fit into our framework. Because of its back-tracking nature, it seems that simple unfoldings of HDA are not the right tools to use; one should rather consider some form of back-unfoldings of forward-unfoldings. Given the undecidability result of [24], it seems doubtful, however, that any characterization as simple as the one we have for hp-bisimilarity can be obtained.

Another important question is how HDA relate to other models for concurrency which are not present in the spectrum presented in [38]. One major such formalism is the one of *history-dependent automata* which have been introduced by Montanari and Pistore in [28, 29] and have recently attracted attention in model learning [1, 2]. We conjecture that up to hp-bisimilarity, HDA are equivalent to history-dependent automata.

With regard to the geometric interpretation of HDA as directed topological spaces, there are two open questions related to the work laid out in the paper: In [7] we show that morphisms in HDA are open if and only if their geometric realizations lift pointed directed paths. This shows that there are some connections to weak factorization systems [3] here which should be explored; see [25] for a related approach.

In [8] we relate homotopy of cube paths to directed homotopy of directed paths in the geometric realization. Based on this, one should be able to prove that the geometric realization of the unfolding of a higher-dimensional automaton is the same as the universal directed covering [12] of its geometric realization and hence that morphisms in HDA_h are open if and only if their geometric realizations lift dihomotopy classes of pointed dipaths.

The precise relation of our HDA unfolding to the one for Petri nets [22, 30] and other models for concurrency should also be worked out. A starting point for this research could be the work on symmetric event structures and their relation to presheaf categories in [36].

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