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# Implementing Local Intervals in CASL

Regivan H. N. Santiago, Anamaria M. Moreira<sup>1</sup>

*Departamento de Informática e Matemática Aplicada  
Universidade Federal do Rio Grande do Norte  
Natal, Rio Grande do Norte, Brazil*

Katiane R. Lopes<sup>2</sup>

*Instituto Tocantinense Presidente Antonio Carlos  
Araguaína, Tocantins, Brazil*

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## Abstract

This paper defines the basis for the implementation in CASL (Common Algebraic Specification Language) of an interval library such that intervals behave as real numbers endowed with an error information. To achieve that, we redefine the notion of *interval local set* defined in [15] in such a way that it can be implemented in the underlying logic of CASL. With these results, it is possible to manipulate intervals in CASL, as if they were real numbers, with equational reasoning, and get an error estimation on the obtained results for free (from the width of the resulting interval). The paper describes the CASL definition of the interval library and presents a case study on a simple example requiring handling data with “tolerance” margin.

*Keywords:* Algebraic Specification Languages, Specification of Real numbers, Interval Arithmetics.

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## 1 Introduction

The rigorous specification and development of systems where (continuous) numerical data is manipulated is still an open problem, although some approaches to solve it have already been proposed. Some of them include in the formal specification language a version of the real numbers [13] and others, rational numbers [2]. Such systems work with approximations and error information, and the chosen solution is implemented through the use of libraries of data types and functions which specify this data. The advantage of these approaches lies in the algebraic laws which are the same as those for real (or rational) numbers. Therefore, it is enough to endow any algebraic specification language with these libraries and apply equational logic procedures to verify the system. However, these solutions lack the power to deal

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<sup>1</sup> Email: [regivan,anamaria@dimap.ufrn.br](mailto:regivan,anamaria@dimap.ufrn.br)

<sup>2</sup> Email: [katianelopes@hotmail.com](mailto:katianelopes@hotmail.com)

with situations where the system computes with numbers which are essentially non-representable (by rationals) — e.g. a simple system which calculates the circle area  $S = \pi \cdot r^2$ , or systems where tolerance information is required. Furthermore, in many cases, the treatment of error information is left to the implementation phase and problems arise when specifiers or designers refine such specifications, since error must be dealt with. Another approach, the one we tackle here, is to use an interval representation for real numbers. This approach has the advantage of being able to represent any real number and error information from the beginning, i.e., from the specification. However, the price is the complete loss of theorems which are valid for real number data, since (non-degenerate) intervals do not satisfy some important algebraic properties of the real numbers.

In what follows we give a solution for this problem: intervals are seen as real numbers with an error information and not just a set of real numbers. This means that a real number (e.g.  $\pi$ ) can be represented by any interval containing it (e.g.  $[3, 4]$ ). For that, there are two approaches: (1) interval arithmetic is changed to behave as nearly as possible as real arithmetic [6]; or (2) we change the notion of equality and the laws of algebra for intervals [14]. In this second approach, we define an auxiliary equality called *interval local equality* to deal with intervals to enable the verification of equational (only) properties. This work extends the ones in [14,15], as it is now directly implementable in an algebraic specification language (CASL), and rules for executing a limited local-equational reasoning with intervals have been provided.

Then, we would like to apply these results to a formal specification language, so that they can actually be used in a software development process. CASL [2] is an algebraic specification language, already well known in academia, which presents some characteristics that are essential to this work. Particularly, its strong and existential equalities, implementing respectively Scott's simple equality and equivalence [20], provide the necessary basis for a complete implementation of our approach. The library of intervals is then built upon the basic rational library of CASL and can be found in [5].

This work is then divided into the following sections: Section 2 introduces interval arithmetic and shows that it does not constitute a field like real numbers; Section 3 shows that intervals can be seen as information on real numbers and relates consistency and equality; Section 4 introduces the theory of Scott's simple equality and  $\Omega$ -sets, relating these concepts with CASL; Section 5 defines the theory of local equality and local sets; Section 6 defines a boolean interval local set which is implemented in CASL; Section 7 introduces some required axioms for the specification and prove their soundness; Section 8 shows part of the specification and puts the axioms to work; Section 9 provides a sample application and, finally, Section 10 contains some final remarks.

## 2 Interval Arithmetic

The idea of interval arithmetic was introduced by Moore [7,8] around the fifties, and we call it here **Moore arithmetic**. Some other arithmetic proposals arose along the time, but all of them work with the idea of *correctness* which is based on the following implication

$$(1) \quad x \in [a, b] \Rightarrow f(x) \in F([a, b])$$

where  $x, f(x) \in \mathbb{R}$ ,  $[a, b]$  is an interval,  $f$  is a real arithmetical function and  $F$  is an interval arithmetic representation of  $f$ <sup>3</sup>. This idea of correctness states that, if you compute with intervals, the desired result is always inside the obtained interval result. Moreover, the maximum error is the width of this result interval. In other words, if you use intervals to represent and compute real numbers the resulting error is always described in the result interval  $F([a, b])$ . From the specification viewpoint, if you describe a system with intervals instead of punctual representations (e.g. rational representations) the verification of any equational properties leads to an immediate estimate of the involved error. In what follows we briefly introduce Moore arithmetic.

### 2.1 Moore arithmetic

Moore interval arithmetic is based on the definition of intervals as given in Definition 2.1 and in interval equality as defined in Definition 2.2.

**Definition 2.1** Given  $x_1, x_2 \in \mathbb{R}$  such that  $x_1 \leq x_2$ , the set  $\{x \in \mathbb{R} : x_1 \leq x \leq x_2\}$  is called **closed interval** or here just **interval** and is denoted by  $X = [x_1, x_2]$ . Intervals of the form  $[x, x]$  are **degenerate**, where  $[x, x]$  is the interval counterpart of a real number  $x \in \mathbb{R}$ . The set of all intervals is denoted by  $\mathbb{I}(\mathbb{R})$ . If  $x_1$  and  $x_2$  are restricted to rational numbers,  $\mathbb{Q}$ , then, we define the set of all intervals with rational endpoints, and denote it by  $\mathbb{I}(\mathbb{Q})$ .

Although the theory presented here was first defined for  $\mathbb{I}(\mathbb{R})$ ,  $\mathbb{I}(\mathbb{Q})$  is particularly important for this work because it can be “implemented” in an algebraic specification language, and it inherits all the presented results.

**Definition 2.2** [interval equality]

Equality on intervals is based on their set nature; i.e. two intervals are considered **indiscernibles** if they are the same set. Therefore given  $A = [a_1, a_2]$  and  $B = [b_1, b_2]$

$$(2) \quad A = B \Leftrightarrow a_1 = b_1 \wedge a_2 = b_2$$

Given  $A, B \in \mathbb{I}(\mathbb{R})$ , the operations of sum, subtraction, multiplication and division are defined in Table 1, and obey the following property:

$$(3) \quad A * B = \{a * b : a \in A \wedge b \in B\}$$

<sup>3</sup> A full formalization of interval correctness and optimality can be found in [17,18,19].

Operation		Definition	OBS
$A + B$	$=$	$[a_1 + b_1, a_2 + b_2]$	$K = \{a_1 \times b_1, a_1 \times b_2, a_2 \times b_1, a_2 \times b_2\}$
$A \times B$	$=$	$[minK, maxK]$	
$-A$	$=$	$[-a_2, -a_1]$	
$\frac{1}{A}$	$=$	$[\frac{1}{a_2}, \frac{1}{a_1}]$	$0 \notin A$
$A - B$	$=$	$A + (-B)$	$0 \notin B$
$A/B$	$=$	$A \times (\frac{1}{B})$	

Table 1  
Moore arithmetic for  $A = [a_1, a_2], B = [b_1, b_2] \in \mathbb{I}(\mathbb{R})$

where  $\ast \in \{+, -, \times, /\}$  is one of the four arithmetical operations. Note that (3) trivially satisfies the correctness property described above in (1) . For division, Moore arithmetic establishes that  $0 \notin B$ . With those definitions, interval arithmetic is defined by the application of real arithmetic to the endpoints of intervals, and is trivially computational in the case of rational endpoints.

**Example 2.3**  $[3, 4] + [1, 3] = [3 + 1, 4 + 3] = [4, 7]$ ,  $-[3, 4] = [-4, -3]$ , etc.

2.2 Algebraic properties of Moore arithmetic

In Moore interval arithmetic we have that addition and multiplication are associative and commutative and have an identity element, which is  $[0, 0]$  for addition and  $[1, 1]$  for multiplication. However neither addition nor multiplication have inverse operations. Indeed,  $A + (-A) \neq [0, 0]$ , for non-degenerate intervals. Instead, they have pseudo-inverse operations where  $X - X \supseteq [0, 0]$  and  $X/X \supseteq [1, 1]$ . Finally, the distribution of multiplication over addition is replaced by sub-distributivity:  $A \times (B + C) \subseteq A \times B + A \times C$ . This weakening of algebraic properties presents serious consequences to our goal of real number representation, as shows Example 2.4.

**Example 2.4** Suppose you would like to solve the equation  $X + [3, 4] = [1, 2]$ . Applying equational logic, you would derive at most  $X + [-1, 1] = [-3, -1]$  (according to Moore Arithmetic) instead of  $X = [1, 2] - [3, 4]$  or  $X = [-3, -1]$ . In this example, subtracting  $[3, 4]$  from both sides of the equation should have given us on the left hand side  $X + [0, 0]$  which in turn would lead to  $X$ , by the fact that  $[0, 0]$  is identity for  $+$ , but we only got  $[-1, 1] \supseteq [0, 0]$ , because of the pseudo-inverse property. In this paper we show a way to overcome this problem.

3 Moore Intervals as information on real numbers

The problems shown above come from the nature of the used equality for intervals, where two intervals are considered equal if they are the same set. This section

introduces another viewpoint, which allows the definition of a weaker notion of interval equality, where *two intervals are considered equal if they may represent some common set of real numbers*. This approach deals with intervals simultaneously as an information on a real number and on the corresponding error. Within this approach, the smaller the width of an interval, the better the information of the represented real numbers, and the better the quality of the corresponding error. The inclusion monotonicity property of Moore arithmetic [9], described below, is the basis of this approach.

Inclusion monotonicity is a very important property of this arithmetic, since it states that it preserves the quality of error; e.g. if  $A \subseteq C$  and  $B \subseteq D$ , i.e. if the quality of error present in  $A$  is better than that of  $C$  and the same for  $B$  and  $D$ , then  $A + B \subseteq C + D$ , i.e., the error of  $A + B$  is better than that of  $C + D$ .

This property of Moore arithmetic gives rise to the domain approach of interval analysis [1,14]. In what follows we cite some of the definitions and propositions which establish that.

**Definition 3.1** Given  $A, B \in \mathbb{I}(\mathbb{R})$ ,  $A \sqsubseteq B$  if and only if  $B \subseteq A$ . Where  $A \sqsubseteq B$  is read “ $A$  is an information about  $B$ ”.

**Proposition 3.2** The partial order  $\langle \mathbb{I}(\mathbb{R}), \sqsubseteq \rangle$  is a directed complete partial order (dcpo) — see [14] —.

Therefore, considering degenerate intervals  $[a, a]$  as real numbers, this approach considers the set  $\mathbb{I}(\mathbb{R})$  as an information space, in the sense of Scott-Strachey [21], on real numbers. There are many interesting consequences of that. One of them is that this approach gives a foundation to usual interval algorithms in terms of domain theory. Another consequence is that it extends the viewpoint of interval from set to information, and this last viewpoint is where we start our approach.

### 3.1 Consistency and equality

One of the concepts in domain theory is that of consistency, formally:

**Definition 3.3** Given a partial order  $\langle A, \leq \rangle$  and  $x, y \in A$ ,  $x$  is **consistent** with  $y$ ,  $x \asymp y$ , if there is  $z \in A$  such that  $x \leq z$  and  $y \leq z$ .

In other words,  $x$  and  $y$  are consistent information if they inform about the same thing. In the case of intervals  $A, B \in \mathbb{I}(\mathbb{R})$ ,  $A \asymp B$  if and only if  $A \cap B \in \mathbb{I}(\mathbb{R})$ . Table 2 establishes the relation between interval equality and consistency. You should note that, although some algebraic properties of real numbers fail for intervals, they are preserved in terms of consistency. Therefore, even if classical equational logic cannot be applied to make intervals behave as real numbers with an error information, we can develop a kind of equational logic for consistency which enables us to do that. This logic and its application to CASL is what we present in this work.

Equality	Consistency
$x + (y + z) = (x + y) + z$	$x + (y + z) \asymp (x + y) + z$
$x + [0, 0] = x$	$x + [0, 0] \asymp x$
$x + y = y + x$	$x + y \asymp y + x$
$x - x \supseteq [0, 0]$	$x - x \asymp [0, 0]$
$x \times (y \times z) = (x \times y) \times z$	$x \times (y \times z) \asymp (x \times y) \times z$
$x \times [1, 1] = x$	$x \times [1, 1] \asymp x$
$x \times y = y \times x$	$x \times y \asymp y \times x$
$x/x \supseteq [1, 1]$	$x/x \asymp [1, 1]$
$x \times (y + z) \subseteq (x \times y) + (x \times z)$	$x \times (y + z) \asymp (x \times y) + (x \times z)$

Table 2  
Equality vs. Consistency —  $x, y, z \in \mathbb{I}(\mathbb{R})$

## 4 CASL and Scott equality

In this section we introduce the concept of **simple equality** and **equivalence** introduced by Dana Scott [20] and the associated models called  $\Omega$ -sets introduced by Dana Scott and Michael Fourman [4]. We also relate to with the equalities in CASL.

CASL [2,10] is a first order algebraic specification language proposed by "The Common Framework Initiative for algebraic specification and development" (COFI), sponsored by IFIP WG1.3, aiming to establish a standard to the algebraic specification area.

The central language resulting from this effort is CASL (Common Algebraic Specification Language), from which sub-languages and extensions may be defined. The ability to correctly deal with intervals representing real numbers and error estimates can be seen as one extension to the core CASL language. However, the features already present in the core language are enough to specify the solution that we propose in this paper. So, our solution is implemented via the inclusion of a CASL library with the definitions for intervals, local equality and other related concepts. The basic features of CASL that allow us to do this are partiality and the two equalities presented in the following.

Partiality in CASL is implemented with two equalities: **strong**, denoted by  $x = y$ , and **existential**, denoted by  $x \stackrel{e}{=} y$ . Existential equality formalizes the following situation: **"both  $x$  and  $y$  are defined and they are equal"**

This kind of equality is suitable to express laws like associativity for semi-groups (i.e.  $x + (y + z) \stackrel{e}{=} (x + y) + z$ , where  $x + (y + z)$  and  $(x + y) + z$  are both terms which are always defined). The second kind of equality (strong equality) enables the terms to be undefined, and formalizes the following situation: **"if  $x$  is defined then  $y$  is defined and they are equal, and if  $y$  is defined then  $x$  is defined"**

### and they are equal”

Formally, strong equality can be expressed in terms of existential equality by the following formula:

$$(4) \quad x = y \leftrightarrow [(def(x) \rightarrow x \stackrel{e}{=} y) \wedge (def(y) \rightarrow y \stackrel{e}{=} x)]$$

In this meaning of equality, all undefined terms are equal. One example of a theory which can be expressed by this second equality of CASL is category theory. For example, the law of associativity for composition can be expressed as “ $x \circ (y \circ z) = (x \circ y) \circ z$ ”, where for non composable morphisms  $x, y$  and  $z$  we have the equality for undefined terms  $x \circ (y \circ z)$  and  $(x \circ y) \circ z$ .

So, in CASL, equality has two meanings: one which requires definition (existence of an interpretation) of both terms and other which allows them to be undefined. The theory and models of these meanings for equality were formalized in [4,20], where existential “ $\stackrel{e}{=}$ ” and strong equality “ $=$ ”, in CASL, are named, respectively, **simple equality** and **equivalence**.

The theory of simple (existential) equality is given by the following axiomatics:

#### (Axioms for simple equality)

- (1) **Ref1:**  $x \stackrel{e}{=} x \leftrightarrow def(x)$ ;
- (2) **Symmetry:**  $x \stackrel{e}{=} y \rightarrow y \stackrel{e}{=} x$ ; and
- (3) **Transitivity:**  $x \stackrel{e}{=} y \wedge y \stackrel{e}{=} z \rightarrow x \stackrel{e}{=} z$ .

The second meaning for CASL equality, called **equivalence** in Scott’s work, is formalized by axiom (4) above which is equivalent to

$$(5) \quad x = y \leftrightarrow (def(x) \vee def(y) \rightarrow x \stackrel{e}{=} y)$$

In this work, following CASL conventions, we use the notation  $=$  for strong equality and equivalence (Scott uses “ $\equiv$ ” instead) and  $\stackrel{e}{=}$  for existential and simple equality (Scott uses “ $\equiv$ ”).

### 4.1 Models

The models for simple equality and, consequently, the sets designated by CASL basic specifications are generalizations of usual sets. In what follows we present such models, called  $\Omega$ -sets. They are based on some classical algebraic notions such as partial orders, lattices and Heyting algebras [4,12,11].

Complete Heyting algebras (cHa) can be viewed as algebraic structures and are frequently used to interpret some logics like first order intuitionistic logic. They are used for valuation of predicates (relations). In what follows, simple equality, equivalence, and definability are interpreted as relations in which the codomain is a cHa. The resulting models are called  $\Omega$ -sets [4].

#### Definition 4.1 [ $\Omega$ -sets]

Given a cHa  $\Omega$ , an  $\Omega$ -set is a mathematical structure of the form

$\langle A, \llbracket \cdot \stackrel{e}{=} \cdot \rrbracket : A \times A \rightarrow \Omega \rangle$  such that <sup>4</sup> :

- (1) **Symmetry:**  $\llbracket x \stackrel{e}{=} y \rrbracket = \llbracket y \stackrel{e}{=} x \rrbracket$ ;
- (2) **Transitivity:**  $\llbracket x \stackrel{e}{=} y \rrbracket \wedge \llbracket y \stackrel{e}{=} z \rrbracket \leq \llbracket x \stackrel{e}{=} z \rrbracket$ .

On any  $\Omega$ -set we can define the relations of definability and equivalence:

- (1) **refl:**  $\llbracket def(x) \rrbracket = \llbracket x \stackrel{e}{=} x \rrbracket$ ;
- (2) **equiv:**  $\llbracket x = y \rrbracket = \llbracket def(x) \rrbracket \vee \llbracket def(y) \rrbracket \Rightarrow \llbracket x \stackrel{e}{=} y \rrbracket$  <sup>5</sup>.

Observe that  $\Omega$ -sets generalize classical sets, for which the cHa is the well known boolean algebra  $\{0, 1\}$ .

As indicated in Section 3.1, we would like to use consistency as a kind of equivalence relation which would enable us to manipulate intervals as if they were real numbers. However, consistency is not a transitive relation on intervals. For example,  $[1, 3] \asymp [2, 5]$  and  $[2, 5] \asymp [4, 6]$ , but  $[1, 3] \not\asymp [4, 6]$ . Since simple equality is transitive, it is not enough to formalize consistency. In what follows, we present the notion of *local equality* and *local sets*, introduced in [16,15] to overcome this problem. Local equality is not a primitive equality, it is an auxiliary relation (like any other relation, e.g.,  $\leq$ ), defined using simple equality.

## 5 Local equality and local sets

Assuming simple equality (or in CASL terms existential equality) as primitive, local equality is a relation which has a pre-condition on the transitive axiom. The idea is to control the application of the transitive law in such a way that it is not required for all triple of elements  $x$ ,  $y$ , and  $z$ , but only for those where consistency is transitive.

**Axiom 5.1 (Axioms for local equality)** *Assuming a first order language where simple equality (existential equality in CASL) “ $\stackrel{e}{=}$ ” and definability “ $def$ ” are defined, and a partial binary operation symbol “ $\sqcup$ ” which satisfies the following laws:*

- (1) **Idempotency:**  $x \sqcup x = x$ ;
- (2) **Commutativity:**  $x \sqcup y = y \sqcup x$ ;
- (3) **Associativity:**  
 $x \sqcup (y \sqcup z) = (x \sqcup y) \sqcup z$ .

**Local equality,**  $\stackrel{lc}{=}$ , *is defined by the following axioms:*

- (1) **Refloc:**  $x \stackrel{lc}{=} x \leftrightarrow def(x)$  ;
- (2) **Symmetry:**  $x \stackrel{lc}{=} y \rightarrow y \stackrel{lc}{=} x$  ; and
- (3) **Local Transitivity:**  $def(x \sqcup z) \rightarrow (x \stackrel{lc}{=} y \wedge y \stackrel{lc}{=} z \rightarrow x \stackrel{lc}{=} z)$ .

<sup>4</sup> The symbol  $\llbracket \cdot \stackrel{e}{=} \cdot \rrbracket$  means a function which interprets the predicate symbol “ $\stackrel{e}{=}$ ”. The same is applied for other predicate symbols.

<sup>5</sup> Therefore we can consider an  $\Omega$ -set as a 4-tuple  $\langle A, \llbracket \cdot \stackrel{e}{=} \cdot \rrbracket, \llbracket def \rrbracket, \llbracket = \rrbracket \rangle$ .



## Relating Local and Simple equality.

Observe that if we assume the axioms of local equality and introduce the extra-axiom: “ $\forall x. \forall y. \text{def}(x \sqcup y)$ ”, the precondition of local equality is always true and the law of transitivity can be freely applicable again.

**Definition 5.2** [Local sets] A model for local equality is called **local set** and is an  $\Omega$ -set  $A$  endowed with a relation  $\llbracket \cdot \stackrel{lc}{=} \cdot \rrbracket : A \times A \rightarrow \Omega$  and a partial function  $\sqcup : A \times A \rightarrow A$ <sup>6</sup>, such that for all  $x, y, z \in A$ :

- (1)  $x \sqcup x = x$ ;
- (2)  $x \sqcup y = y \sqcup x$ ;
- (3)  $x \sqcup (y \sqcup z) = (x \sqcup y) \sqcup z$ ;
- (4)  $\llbracket x \stackrel{lc}{=} x \rrbracket = \llbracket \text{def} \rrbracket(x)$
- (5)  $\llbracket x \stackrel{lc}{=} y \rrbracket = \llbracket y \stackrel{lc}{=} x \rrbracket$
- (6)  $\llbracket \text{def} \rrbracket(x \sqcup z) \leq (\llbracket x \stackrel{lc}{=} y \rrbracket \wedge \llbracket y \stackrel{lc}{=} z \rrbracket \Rightarrow \llbracket x \stackrel{lc}{=} z \rrbracket)$

Santiago [14,16,15] defines a cHa in such a way that consistency on intervals becomes a simple equality. In those works, however, this cHa is not a boolean algebra, and, therefore, those definitions cannot be directly specified in CASL. In other words, a classical definition is required for the definability and simple equality for intervals. Here we show that we can use the classical cHa  $\{0, 1\}$  as a valuation, so that the implementation of local equality is immediately possible in CASL.

## 6 Interval boolean local set

The non-boolean local set found in [15], was extended to local algebras (local groups, local rings, etc) by Bedregal and Santiago [3]. We now build a boolean version for interval local equality based on a canonical extension of  $\Omega$ -sets to local sets in the following way:

**Proposition 6.1** *Given an  $\Omega$ -set  $A$  endowed with a partial operation  $\sqcup : A \times A \rightarrow A$  which is idempotent, commutative and associative, the function  $\llbracket \cdot \stackrel{lc}{=} \cdot \rrbracket : A \times A \rightarrow \Omega$ , defined by  $\llbracket x \stackrel{lc}{=} y \rrbracket = \llbracket \text{def} \rrbracket(x \sqcup y)$  defines a local set.*

**Proof.** The proof is easy. The first three properties of a local set are exactly the properties of idempotency, commutativity, and associativity of “ $\sqcup$ ”. The last three properties are proved as follows: (4)  $\llbracket x \stackrel{lc}{=} x \rrbracket = \llbracket \text{def} \rrbracket(x \sqcup x) = \llbracket \text{def} \rrbracket(x)$ ; (5)  $\llbracket x \stackrel{lc}{=} y \rrbracket = \llbracket \text{def} \rrbracket(x \sqcup y) = \llbracket \text{def} \rrbracket(y \sqcup x) = \llbracket y \stackrel{lc}{=} x \rrbracket$ ; (6) Since by definition  $\llbracket \text{def} \rrbracket(x \sqcup z) = \llbracket x \stackrel{lc}{=} z \rrbracket$ , then, trivially, local transitivity is satisfied.  $\square$

Particularly, for the boolean algebra  $\{0, 1\}$  we have:

<sup>6</sup> It is trivial to note that a local set is a 6-tuple  $\langle A, \llbracket \cdot \stackrel{e}{=} \cdot \rrbracket, \llbracket \text{def} \rrbracket, \llbracket \cdot = \cdot \rrbracket, \llbracket \cdot \stackrel{lc}{=} \cdot \rrbracket, \sqcup \rangle$ , since it is an extension of an  $\Omega$ -set  $\langle A, \llbracket \cdot \stackrel{e}{=} \cdot \rrbracket, \llbracket \text{def} \rrbracket, \llbracket \cdot = \cdot \rrbracket \rangle$ .

**Proposition 6.2** Let  $\Omega = \{0, 1\}$  be the canonical boolean algebra, “=” the usual equality of Definition 2.2 and the function  $def : \mathbb{I}(\mathbb{R}) \rightarrow \Omega$ , where  $def([a, b]) = 1$ , for all  $[a, b] \in \mathbb{I}(\mathbb{R})$ . Then, the structure,  $\langle \mathbb{I}(\mathbb{R}), = : \mathbb{I}(\mathbb{R}) \times \mathbb{I}(\mathbb{R}) \rightarrow \Omega \rangle$ , is an  $\Omega$ -set.

**Proof.** Trivially, equality is symmetric and transitive. Moreover, since it is also reflexive and for all  $A \in \mathbb{I}(\mathbb{R})$ ,  $def(A) = 1$ , then  $(A = A) = 1 = def(A)$ .  $\square$

Observe that, since  $def([a, b]) = 1$ , for all  $[a, b] \in \mathbb{I}(\mathbb{R})$ , then existential “ $\stackrel{e}{=}$ ” and strong “=” equalities coincide with usual interval equality. We use the usual symbol of interval equality “=” to denote both of them.

Now, since  $\langle \mathbb{I}(\mathbb{R}), = \rangle$  is an  $\Omega$ -set, it is enough to find an appropriate “ $\sqcup$ ” in the structure to canonically build a local equality “ $\stackrel{lc}{=}$ ” for intervals. Furthermore, to serve our goal, this operation must capture consistency, in the sense that

$$(6) \quad “A \asymp B \text{ if and only if } A \stackrel{lc}{=} B”$$

The required operation is exactly interval intersection, denoted  $\cap$  (overloading), which is partial, commutative, associative, and idempotent. Therefore, the required local set is defined as:

**Definition 6.3** The **canonical interval local set** is the structure  $\langle \mathbb{I}(\mathbb{R}), =, def, \llbracket \stackrel{lc}{=} \rrbracket, \cap \rangle$ <sup>7</sup> such that  $\llbracket A \stackrel{lc}{=} B \rrbracket = \llbracket def \rrbracket(A \cap B)$ . See Proposition 6.1.

**Corollary 6.4 (Realization in CASL)** Since CASL implements strong equality, it is enough to add an interval specification with Moore arithmetics to its numbers library and define directly local equality as: “ $x \stackrel{lc}{=} y \iff def(x \text{ cap } y)$ ”. Where “ $def$ ” is primitive in CASL and “ $cap$ ” is the intersection operation of the interval library in CASL (For details see Lopes [5]).

**Corollary 6.5** All consistency properties in Table 2, can now be expressed in terms of local equality giving rise to a mathematical structure called **local field**. For if  $A \asymp B$ , then  $A \cap B \in \mathbb{I}(\mathbb{R})$  which is equivalent to  $\llbracket A \stackrel{lc}{=} B \rrbracket = 1$ . It means that this structure may be expressed in CASL language enabling the specification of systems with real numbers using intervals as if they were real numbers with an information of error.

The above properties enable us to consider consistent intervals as equals; however, they are not enough to enable us to derive local equations from local equations and carry on equational reasoning. In other words we need a kind of equational logic for local equality. For that we still need a *congruence law* and some other axioms. These laws must be introduced as axioms in the CASL Interval library. Below we show that the property of correctness — see (1) — of interval arithmetics guarantees the soundness of congruence axioms. Observe that, since CASL is a first order language, general principles like congruence cannot be stated generally, i.e. one axiom is required for each arithmetical symbol. The presentation for this

<sup>7</sup> Since existential and strong equality coincide with usual interval equality, then interval local set can be viewed as a 5-tuple. Moreover, we do not differ the syntactic “ $def$ ” from semantical “ $\llbracket def \rrbracket$ ”.

theory would be simpler if this work were to be applied to higher-order languages, such as, HASCASL [10], a higher-order extension of CASL.

## 7 Axioms for the CASL library

### 7.1 Congruence

In equational logic, congruence is a basic axiom, which states that for every operation symbol  $f$  in the specification:

$$(7) \quad x_1 = y_1 \wedge \dots \wedge x_n = y_n \rightarrow f(x_1, \dots, x_n) = f(y_1, \dots, y_n)$$

The instantiation and adaptation of this property for local equality and the four arithmetical operations gives us the axioms below.

#### Congruence axioms

- (i)  $x \stackrel{lc}{=} y \rightarrow -x \stackrel{lc}{=} -y$  (congr -k);
- (ii)  $x \stackrel{lc}{=} y \wedge (\text{def } \frac{1}{x} \wedge \text{def } \frac{1}{y}) \rightarrow \frac{1}{x} \stackrel{lc}{=} \frac{1}{y}$  (congr  $\frac{1}{k}$ );
- (iii)  $x \stackrel{lc}{=} y \wedge w \stackrel{lc}{=} z \rightarrow x + w \stackrel{lc}{=} y + z$  (congr +);
- (iv)  $x \stackrel{lc}{=} y \wedge w \stackrel{lc}{=} z \rightarrow x \times w \stackrel{lc}{=} y \times z$  (congr  $\times$ ).

**Proposition 7.1** *Congruence axioms (congr -k), (congr  $\frac{1}{k}$ ), (congr +) and (congr  $\times$ ) are sound.*

**Proof.** By definition, if  $X, Y \in \mathbb{I}(\mathbb{R})$ , then  $X \stackrel{lc}{=} Y \leftrightarrow \text{def}(X \cap Y)$ . Therefore,  $X \stackrel{lc}{=} Y$  if and only if  $X \cap Y \in \mathbb{I}(\mathbb{R})$ . Hence,

(1) If  $X \stackrel{lc}{=} Y$ , then  $X \cap Y \in \mathbb{I}(\mathbb{R})$  i.e.  $X \cap Y = [a, b] \in \mathbb{I}(\mathbb{R})$ . By definition,  $-X = \{-x \in \mathbb{R} : x \in X\}$ ,  $-Y = \{-y \in \mathbb{R} : y \in Y\}$  and  $-X \cap -Y = \{-z \in \mathbb{R} : -z \in -X \wedge -z \in -Y\} = \{-z \in \mathbb{R} : z \in X \wedge z \in Y\} = \{-z \in \mathbb{R} : z \in X \cap Y\} = \{-z \in \mathbb{R} : z \in [a, b]\} = -[a, b]$ ; i.e.  $-X \cap -Y \in \mathbb{I}(\mathbb{R})$ , and therefore  $-X \stackrel{lc}{=} -Y$ .

(2) Analogous to (congr -k).

(3) If  $X \stackrel{lc}{=} Y$  and  $W \stackrel{lc}{=} Z$ , then  $X \cap Y = [a, b] \in \mathbb{I}(\mathbb{R})$  and  $W \stackrel{lc}{=} Z = [c, d] \in \mathbb{I}(\mathbb{R})$ ,  $X + W = \{x + w \in \mathbb{R} : x \in X \wedge w \in W\}$  and  $Y + Z = \{y + z \in \mathbb{R} : y \in Y \wedge z \in Z\}$ . Since  $X \cap Y \in \mathbb{I}(\mathbb{R})$  and  $W \cap Z \in \mathbb{I}(\mathbb{R})$  then there are  $k_1 \in X \cap Y$  and  $k_2 \in W \cap Z$ . Trivially,  $k_1 \in X, k_1 \in Y, k_2 \in W$  and  $k_2 \in Z$ , and therefore  $k_1 + k_2 \in X + W$  and  $k_1 + k_2 \in Y + Z$ ; i.e.  $X + W \cap Y + Z \neq \emptyset$ . Since it is the non-empty intersection of closed intervals, then  $X + W \cap Y + Z \in \mathbb{I}(\mathbb{R})$ , which by definition means  $X + W \stackrel{lc}{=} Y + Z$ .

(4) Analogous to (congr  $\times$ ). □

More generally, we have:

**Theorem 7.2** *If  $F : \mathbb{I}(\mathbb{R}) \rightarrow \mathbb{I}(\mathbb{R})$  is a correct interval function which represents a real function  $f : \mathbb{R} \rightarrow \mathbb{R}$ , i.e.,  $F$  has property (1), then it satisfies congruence for local equality.*

**Proof.** Suppose  $[a, b] \stackrel{lc}{=} [c, d]$ , then  $[a, b] \cap [c, d] \in \mathbb{I}(\mathbb{R})$ . Since  $F$  is correct — see (1) — then for all  $x \in [a, b] \cap [c, d]$ ,  $f(x) \in F([a, b])$  and  $f(x) \in F([c, d])$ , then  $F([a, b]) \cap F([c, d]) \in \mathbb{I}(\mathbb{R})$ , and hence  $F([a, b]) \stackrel{lc}{=} F([c, d])$ .  $\square$

## 7.2 $\sqsubseteq$ -introduction and monotonicity

The next axiom is responsible for the introduction of the definition of intersection in the deductions. This axiom is very important, because without it it is not possible to derive local equality.

$$(\text{sup-intro}) \quad X \sqsubseteq U \wedge Y \sqsubseteq V \wedge U = V \rightarrow \text{def}(X \sqsubseteq Y) \wedge X \sqsubseteq V \wedge Y \sqsubseteq U$$

This axiom defines the condition for the intersection existence and also generates the information  $X \sqsubseteq V$  and  $Y \sqsubseteq U$  in the deduction; this is done for the case where  $U$  and  $V$  are different terms but with the same meaning, enabling us to use this fact when needed in deductions. This axiom is called  **$\sqsubseteq$ -introduction** and its ASCII abbreviation is “(sup-intro)”.

**Proposition 7.3** *Axiom  $\sqsubseteq$ -introduction is sound.*

**Proof.** Given  $X, U, Y, V \in \mathbb{I}(\mathbb{R})$ , suppose  $X \sqsubseteq U, Y \sqsubseteq V$  and  $U = V$  then  $X \cap Y \supseteq U$ . Therefore,  $X \cap Y \neq \emptyset$  and hence  $X \cap Y \in \mathbb{I}(\mathbb{R})$  and  $\llbracket \text{def} \rrbracket(X \cap Y) = 1$ . Since  $U = V$ , Then  $X \sqsubseteq V$  and  $Y \sqsubseteq U$ .  $\square$

The next axioms express the monotonicity of Moore arithmetics. Observe that “ $\sqsubseteq$ ” is the opposite order of inclusion order “ $\subseteq$ ”. Therefore, inclusion monotonicity of Moore arithmetic and the definition of “ $\sqsubseteq$ ” (section 3) are enough to prove their soundness.

## Monotonicity of arithmetics

$$(M +) \quad X \sqsubseteq Y \wedge W \sqsubseteq Z \rightarrow X + W \sqsubseteq Y + Z.$$

$$(M \times) \quad X \sqsubseteq Y \wedge W \sqsubseteq Z \rightarrow X \times W \sqsubseteq Y \times Z.$$

$$(M -) \quad X \sqsubseteq Y \rightarrow -X \sqsubseteq -Y.$$

$$(M \text{ invm}) \quad X \sqsubseteq Y \rightarrow \frac{1}{X} \sqsubseteq \frac{1}{Y}; \text{ if } 0 \notin X \text{ or } 0 \notin Y.$$

## 8 Applying the axioms

The interval library for CASL is implemented in Lopes [5]. The library extends “Basic/Numbers vs. 0.7” library, which contains a specification of rational numbers. From this specification of rationals the Cartesian product called *RatPair* is built. An element of *RatPair* has the form  $[x..y]$ . The set of Moore intervals called *IntervalRat* is a subset of *RatPair*, where for all  $[x..y] \in \text{RatPair}$ ,  $x \leq y$ . The specification was developed and checked (syntax and statics semantics) with CATS (CASL Tool Set) <sup>8</sup>.

<sup>8</sup> See <http://www.informatik.uni-bremen.de/cofi/Tools/CATS.html>

Below we show parts of this specification (omitting, e.g., the definition of some operations, names of axioms):

```

library Interval version 0.7 from Basic/Numbers version 0.7 ge
spec RatPair = Rat
then %def

generated type RatPair ::= [_____] (proj1:Rat;proj2:Rat)

ops proj1_: RatPair -> Rat;
    proj2_: RatPair -> Rat;

vars a,b,c,d: Rat
. [a..b]=[c..d] <=> a=c /\ b=d %(Interval_Equality)%

then %def ...

then %def
sort IntervalRat = { a : RatPair . proj1(a) <= proj2(a) }
then %def

ops
[1..1],[0..0] : IntervalRat;
__+__ : IntervalRat * IntervalRat -> IntervalRat,
    comm,assoc,unit [0..0];
inva__ : IntervalRat -> IntervalRat;
__--__ : IntervalRat * IntervalRat -> IntervalRat;
__*__ : IntervalRat * IntervalRat -> IntervalRat,
    comm,assoc,unit [1..1];
invm__ : IntervalRat ->? IntervalRat;
__/_ : IntervalRat * IntervalRat -> IntervalRat;
m__ : IntervalRat -> Rat; %(midpoint)%
dist : IntervalRat * IntervalRat -> Rat; %(Distance)%
width__ : IntervalRat -> Rat; %(width)%
abs: IntervalRat -> Rat; %(absolute value)%
__cap__ : IntervalRat * IntervalRat ->? IntervalRat;
    %(Intersection)%

then
preds __include__:IntervalRat*IntervalRat;
    degen__:IntervalRat; %($$ is degenerate)%
    __lc__:IntervalRat*IntervalRat; %(Local equality)%
    __inf__:IntervalRat*IntervalRat; %(Inform. Order)%

vars x, y, w, z:IntervalRat
% Some definitions
. def x % Every interval is defined
. x include y <=> (proj1(x) >= proj1(y) /\
    proj2(x) <= proj2(y))
. degen(x) <=> proj1(x) = proj2(x)
. (x inf y) <=> (proj1(x) <= proj1(y)
    /\ proj2(y) <= proj2(x))
%Local equality axioms
. (x lc x) <=> def x %(reflloc%)

Rat . (x lc y) => (y lc x)
. def (x cap z) => ((x lc y) /\ (y lc z) => (x lc z))
%Local equality introduction
. (x lc y) <=> def (x cap y) %(IntroLc01%)
. (x = y) => (x lc y) %(IntroLc02%)
% Congruence
. (x lc y) => (inva(x) lc inva(y))
. ((x lc y) /\ (def (invm(x)) /\ def (invm(y))))
    => (invm(x) lc invm(y))
. ((x lc y) /\ (w lc z)) => ((x + w) lc (y + z))
. ((x lc y) /\ (w lc z)) => ((x * w) lc (y * z))

% defSup
. ((x inf w) /\ (y inf z) /\ (w = z))
    => def(x cap y) /\ (x inf z) /\ (y inf w)
%Monotonicity
. ((x inf y) /\ (w inf z)) => (x + w) inf (y + z)
. ((x inf y) /\ (w inf z)) => (x * w) inf (y * z)
. (x inf y) => (inva(x) inf inva(y))
. (x inf y) => (invm(x) inf invm(y))

then %implies

vars x, y, z, w:IntervalRat

%(Subdistributivity)
. x * (y + z) = (x * y) + (x * z) if degen(x)
. x * (y + z) include (x * y) + (x * z)
% local field axioms
. (x + (y + z)) lc ((x + y) + z)
. (x * (y * z)) lc ((x * y) * z)
. (x + y) lc (y + x)
. (x * y) lc (y * x)
. (x + inva(x)) lc w /\ w = [0..0]
. (x * invm(x)) lc w /\ w = [1..1]
. (x + w) lc x /\ w = [0..0]
. (x * w) lc x /\ w = [1..1]
. (x * (y + z)) lc ((x * y) + (x * z))
% Algebraic properties of intervals
. (x + (y + z)) = ((x + y) + z) %(Ass+)%
. (x * (y * z)) = ((x * y) * z) %(Comm+)%
. (x + y) = (y + x)
. (x * y) = (y * x)
. (x + w) = x /\ w = [0..0] %(id+)%
. (x * w) = x /\ w = [1..1]
. (x + inva(x)) = w /\ (w = [0..0] if degen(x)) %(inv+)%
. (x * invm(x)) = w /\ (w = [1..1] if degen(x))
. (x * (y + z)) = ((x * y) + (x * z))
    if degen(x) /\ degen(y) /\ degen(z)

end

```

Observe that in “% *Local equality introduction*” we introduced the axiom “ $x = y \Rightarrow x \stackrel{lc}{=} y$ ” which is trivially sound.

In what follows we show the resolution of the equation  $\pi + x = \sqrt{2}$ , making the annotation of information error in [3,4], [1,2] and  $X$ . “pi” and “sqrt{2}” are any degenerate intervals which respectively approximate  $\pi$  and  $\sqrt{2}$ . This resolution shows that the application of local equality on intervals enable us to algebraically manipulate them as we do with real numbers.

In some points of the following deduction, we use the usual replacement of equals by equals, since local equality is a binary predicate as any other. We abbreviate usual replacement of equals by equals by (eq) (which is primitive in CASL). We denote by (cong) the congruence for strong equality (which is also primitive in CASL). We omit, as possible, the instantiation of axioms and modus ponens is abbreviated by “MP”. Every occurrence of (refl) comes from the definability of every interval. The axioms below were introduced in the text or were introduced in

the specification (and come from interval theory). We use “ $-x$ ” instead of  $inva(x)$ .  
(8)

1. $\pi + x = \sqrt{2}$	- Hypothesis	20. $(-\pi + \pi) + x = -\pi + \sqrt{2}$	(eq: Ass+, 19)
2. $X \inf x$	- Hypothesis	21. $(\pi + (-\pi)) + x = -\pi + \sqrt{2}$	(eq: Comm+, 20)
3. $[3,4] \inf \pi$	- Hypothesis	22. $0 + x = -\pi + \sqrt{2}$	(eq: inv+, 21)
4. $[1,2] \inf \sqrt{2}$	- Hypothesis	23. $x + 0 = -\pi + \sqrt{2}$	(eq: com+, 22)
5. $[3,4] + X \text{ lc } [1,2]$	- Hypothesis	24. $x = -\pi + \sqrt{2}$	(eq: id+, 23)
6. $[3,4] + X \inf \pi + x$	(MP: M+,2,3)	25. $-[3,4] \inf -\pi \wedge [1,2] \inf \sqrt{2}$	(Intro $\wedge$ : 7,4)
7. $- [3,4] \inf -\pi$	(MP: M-,3)	26. $-[3,4]+[1,2] \inf -\pi + \sqrt{2}$	(MP: 25, M+)
8. $\pi = \pi$	- Refl	27. $X \inf x \wedge -[3,4]+[1,2] \inf -\pi + \sqrt{2}$	(Intro $\wedge$ : 2,26)
9. $\pi = \pi \Rightarrow -\pi = -\pi$	- Congr. Rat	28. $X \inf x \wedge -[3,4]+[1,2] \inf -\pi + \sqrt{2} \wedge$	$x = -\pi + \sqrt{2}$ (Intro $\wedge$ : 27,24)
10. $-\pi = -\pi$	(MP: 8,9)	29. $\text{def}(X \text{ cap } -[3,4] + [1,2]) \wedge X \inf -\pi + \sqrt{2} \wedge$	$-[3,4] + [1,2] \inf x$ (MP: sup-intro, 28)
11. $-[3,4] = -[3,4]$	- Refl	30. $\text{def}(X \text{ cap } -[3,4] + [1,2])$	(Elim $\wedge$ : 29)
12. $-[3,4] \text{ lc } -[3,4]$	(MP: 11, IntroLc02)	31. $X \text{ lc } -[3,4] + [1,2]$	(MP: 30, reflloc)
13. $-[3,4] \text{ lc } -[3,4] \wedge [3,4] + X \text{ lc } [1,2]$	(Intro $\wedge$ : 12, 5)	32. $X \text{ lc } [-4+1, -3+2]$	- Applying + and -
14. $-[3,4] + ([3,4] + X) \text{ lc } -[3,4] + [1,2]$	(MP: 13, congr+)	33. $X \text{ lc } [-3, -1]$	- integer library
15. $(-[3,4] + [3,4]) + X \text{ lc } -[3,4] + [1,2]$	(eq: 14, Ass+)		
16. $X + (-[3,4] + [3,4]) \text{ lc } -[3,4] + [1,2]$	(eq: 15, Comm+)		
17. $X + ([3,4] + (-[3,4])) \text{ lc } -[3,4] + [1,2]$	(eq: 16, Comm+)		
18. $-[3,4] + ([3,4] + X) \inf -\pi + (\pi + x)$	(MP: 7,6,M+)		
19. $-\pi + (\pi + x) = -\pi + \sqrt{2}$	(cong: 10,1)		

## 9 A simple application

Some systems developed in engineerings require the treatment of data and tolerance, i.e. those systems require the ability to deal with non-exact quantities with known precision, and must be able to produce outputs which are numbers with known precision. In what follows we present a simple system of this kind. It calculates the value of a resistance  $R_p$  of two resistors  $R_1$  and  $R_2$  which are connected in parallel. The well known formula for that is

$$(9) \quad R_p = \frac{1}{\frac{1}{R_1} + \frac{1}{R_2}}$$

The values of resistance for those resistors are usually known with a guaranteed tolerance given by the manufacturer. For example, a resistor of 6.80 ohms with 10% of tolerance, guarantees that the resistance's value of the resistor varies between  $6.80 \pm 0.68$ , i.e. it lies between  $6.80 - 0.68 = 6.12$  and  $6.80 + 0.68 = 7.48$  Ohms — or in other words the value of resistance belongs to the interval  $[6.12, 7.48]$ .

Therefore, when we have a resistance of 6.80 Ohms with 10% of tolerance conected with an other, in parallel, with 4.7 Ohms and 5% of tolerance, the combination of resistance must vary between 2.58 Ohms and 2.97 Ohms. Since for resistors  $R_1 = 6.80 \pm 0.68$  and  $R_2 = 4.70 \pm 0.23$ , the result calculated by the engineer belongs to interval  $[2.58, 2.97]$ , for which the midpoint with the respective tolerance is equal to  $2.77 \pm 0.20$ .

We mean that this kind of systems take into account data which are intervals, and the corresponding algorithm which will implement *the interval version* of (9) must implement operations that deal with intervals. Equation (9), designed for real numbers, can be extended to Moore arithmetic (namely to the following interval

expression  $R_p = [1, 1]/([1, 1]/R_1 + [1, 1]/R_2)$  producing the results above, when applied to those inputs. This system can be easily specified using our library in the following way:

```
spec Resistor_Parallel = Interval
then
  ops par_res: IntervalRat * IntervalRat -> IntervalRat
  vars R1,R2: IntervalRat
  . par_res(R1,R2)=[1..1]/([1..1]/R1 + [1..1]/R2)
end
```

Note that it is easy to convert the real expression (9) to the following:

$$(10) \quad R_p = \frac{R_1 \times R_2}{R_1 + R_2}.$$

and define an alternative interval specification for that, namely:

```
spec Resistor_Parallel = Interval
then
  ops par_res: IntervalRat * IntervalRat -> IntervalRat
  vars R1,R2: IntervalRat
  . par_res(R1,R2)=(R1*R2)/(R1 + R2)
end
```

However, when we give the same inputs discussed above for  $R_1$  and  $R_2$ , the interval expression  $R_p$  (described in the last specification) is equal to  $[2.20, 3.48]$ , for which the midpoint with the respective tolerance is given by  $2.84 \pm 0.64$ ; i.e. a different result. Therefore, although (9) and (10) describe the same real function, their interval extensions are not the same — they are different interval functions, which means that one expression cannot be equationally derived from the other. However the outputs have the following property:  $[2.58, 2.97] \cap [2.20, 3.48] \neq \emptyset$  — moreover  $[2.20, 3.48] \supseteq [2.58, 2.97]$ ; i.e. the outputs are consistent information about the real value  $R_p$ . More generally, it is possible to prove that for all interval  $A$  and  $B$ , both interval extensions produce consistent outputs. Hence although we cannot derive one interval extension from another using equational logic of CASL, it is possible to derive it using the relation of local equality, since it simulates the field behavior of real numbers on intervals as exemplified in the derivation (8).

## 10 Final Remarks

This work contributes to the use of formal specifications in the development of software that deals with numerical data with error or tolerance information. This is done through the definition of a library for intervals in the algebraic specification language CASL and the adaptation of some basic concepts as equality and congruence, needed for equational reasoning, in such a way that intervals with rational endpoints can represent real numbers and associated error estimates. This provides

in the specification level facilities for some already available programming languages for interval computations, like Pascal-XSC and C-XSC.

The results in this paper extend those in [14,15] as follows:

- (i) they are now directly implementable in an algebraic specification language (CASL) with the definition and use of a boolean version of local sets, and
- (ii) rules for executing a limited local-equational reasoning with intervals have been provided. Of course, these results may also be applied to other algebraic specification languages, provided partiality and both kinds of Scott equality, as explained in Section 4, are available in the language.

Note that the approach here did not require an extension or any redefinition of the CASL core, all the mathematical development was done for that, and the result was the introduction of local equality as a simple relation symbol of a CASL theory.

There are still some limits to this solution. The first one comes from the first order logic underlying CASL, leading to the need for multiple axioms for the more general properties (e.g., congruence) needed (one axiom for each functional symbol of a specification). This can be solved by the use of a higher order language or a higher order extension of CASL. It may also be solved through the use of generic modules, but both solutions are still future work.

Another problem lies in the implementation of a version of replacement of equals by equals for local equality. Something like:

$$(11) \quad s \stackrel{lc}{=} t \wedge P(s) \rightarrow P(t).$$

However, taking  $s = [3, 5], t = [4, 6]$  and  $P(s) : "s < [6, 6]"$ <sup>9</sup>. Since " $[3, 5] \stackrel{lc}{=} [4, 6]$ " and " $P([3, 5])$ " hold, then we would derive  $P([4, 6]) : "[4, 6] < [6, 6]"$  which does not hold. Therefore, (11) is not a valid principle. It happens because we are working with information about objects instead of objects themselves, and therefore properties of an information  $s$  are not necessarily properties of  $t$ . Observe that the approach presented here deals with non-finitely representable objects (irrational numbers) and can be extended to other domains. Therefore, a replacement law for locally equal objects is a required subject of investigation if we want to increase the automation of the verification process (derivation of local equations), e.g., by rewriting systems.

Finally, we still do not know if there is a way to standardize the conversion of specifications which describe interval functions to another which describe a local equivalent expression which always return the optimal outputs. For example, we still do not have a way to convert the second specification above into the first. However, the answer seems to be in the deep study of the algebraic properties of pseudo-inverses and sub-distributivity (fourth, eighth and ninth properties of Table 2). This is also a subject of future work.

---

<sup>9</sup>  $[a, b] < [c, d]$  if and only if  $b < c$  (Moore [9] p. 10)



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