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Axiomatizing Hybrid Products of Monotone Neighborhood Frames

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**Abstract**

The main aim of this paper is to propose a robust way to combine two monotone hybrid logics. This work can be regarded as a further extension of both topological semantics for hybrid logic (Ten Cate and Litak 2007) and bi-hybrid logic of *products of Kripke frames* (Sano 2010). First, we generalize the notion of *product of topologies* (Van Benthem, et al 2006) to the monotone neighborhood frames and introduce two kinds of *nominals*: *i* (e.g. for a moment of time) and *a* (e.g. for a spatial point), and the corresponding *satisfaction operators*: @*i* and @*a* to describe a product of monotone neighborhood frames. Second, we give five interaction axioms and establish a general completeness result called *pure completeness* of *bi*-hybrid logic of monotone neighborhood frames. By extending this, we also establish a pure completeness result of bi-hybrid logic of products of topologies.

*Keywords:* product of topologies, hybrid logic, product of neighborhood frames, monotone neighborhood frames, pure completeness.

# Introduction

When we want to formalize the inference containing two dimensional information (e.g. space and time, time and the individual domain, etc.), we encounter with the following problem: how can we deal with two kinds of information in one setting? In other words, we need to know how to combine two modal logics, provided we deal with each of two dimensional (e.g. spatial and temporal) information in terms of modal logic. *Product of modal logics* should be counted as one answer to this question. It have been studied comprehensively since [[5](#_bookmark25)] (see also [[4](#_bookmark26)]), based on the notion of *product of Kripke frames*. Both dimension of a given two-dimensional structure, however, are not always relational. They might be topological. So, it would be desirable to combine not only two relational structures (i.e. Kripke frames) but also two topological structures. Van Benthem, et al. [[18](#_bookmark41)] generalized the notion of product of Kripke frames to the notion of product of topologies (see

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also [[15](#_bookmark38)]). They proposed a way of combining two topological modal logics, based on topological semantics for modal logic studied by McKinsey and Tarski [[11](#_bookmark34)]. More- over, they showed that the fusion of two **S4**s is complete with respect to the product of two rational lines, while Kremer [[8](#_bookmark31)] showed that this fusion is incomplete with respect to the product of two real lines. Up to now, however, there is no study of the weaker notion of *product of neighborhood frames* (for neighborhood semantics of modal logic, the reader can refer to [[3](#_bookmark27)]).

Hybrid logic is an extended modal logic, which overcomes a weakness of expres- sive power of the basic modal logic over Kripke frames. For example, we can define the class of partial orders (the reflexive, antisymmeric and transitive relations) by nominals *i* and satisfaction operators @*i*, while this class is not definable by any set of ordinary modal formulas. Moreover, we can define the class of partial orders by *pure formulas*, i.e., formulas not containing any ordinary proposition letters. For example, the conjunction of @*i3i*, @*i3j ∧* @*j3i →* @*ij* and @*i3j ∧* @*j3k →* @*i3k* defines the class of partial orders. It is known that if a class F of Kripke frames is definable by a set of pure formulas, we can *always* obtain a strong completeness of the logic of F with respect to F [[1](#_bookmark24)]. Such result is called *pure completeness*. The author [[13](#_bookmark36)] extended the notion of product of modal logics to hybrid logics over Kripke semantics and established a pure completeness result for products of Kripke frames. He also showed that the product of any two pure complete logics enjoys a completeness result. In this sense, he expanded the range of combining logics without losing a completeness result.

The most significant feature of [[13](#_bookmark36)] is to propose the idea of *naming lines* by two kinds of nominals, instead of the ordinary idea of naming points in hybrid logic. This idea allows us to extend pure completeness result to two-dimensional Kripke semantics. In this paper, we keep this key feature also for two-dimensional neighborhood or topological semantics and see if it gives rise to the corresponding general completeness result. As a result, we will demonstrate that the idea of naming lines is robust for obtaining the completeness result.

To be more precise, this paper generalizes the method of [[13](#_bookmark36)] to both the product of monotone neighborhood frames and the product of topological spaces [[18](#_bookmark41)]. This study can also be regarded as a further extension of topological and monotone neighborhood semantics for hybrid logic studied by Ten Cate and Litak [[17](#_bookmark40)] and the author [[14](#_bookmark37)]. A main theorem of this paper is a pure completeness result for products of monotone neighborhood frames (Theorem [5.11](#_bookmark15)). By extending it, we will also establish a pure completeness result for products of topological spaces (Theorem [5.14](#_bookmark17)). As a corollary, we will show that any topo-product of two pure topo-complete logics enjoys a completeness result (Corollary [6.3](#_bookmark19)). For example, this corollary tells us that we can provide a complete axiomatization of the logic (in two-dimensional hybrid language) of all products of dense-in-itself *T*1-spaces, since the condition of being of *T*1 are definable by a pure formula [[6](#_bookmark28)]. Finally, as a limitative result, we also show that this pure axiomatizable logic of all products of dense-in-itself *T*1-spaces is incomplete with respect to the product of real lines (Theorem [6.7](#_bookmark23)).

# Product of Monotone Neighborhood Frames

A topological space is a pair *⟨ T, O⟩* such that a set *O ⊆ P*(*T* ) of *open sets* is closed under arbitrary unions and arbitrary finite intersections. Unlike this ordinary definition, we adopt the definition of topological spaces in terms of *local neighborhood basis* at a point, since this formulation allows us to regard the notion of topological space as a special case of the notion of monotone neighborhood frames as follows.

**Definition 2.1** We say that *⟨ T, τ ⟩* is a *neighborhood frame* if *T /*= *∅* and *τ* : *T → PP*(*T* ). A neighborhood frame *⟨ T, τ ⟩* is *monotone* if, for any *x ∈ T* ,

(supplementedness) *X ∩ Y ∈ τ* (*x*) implies *X, Y ∈ τ* (*x*).

*⟨ T, τ ⟩* is *normal* if it is monotone and it satisfies: for any *x ∈ T* , (non**-**emptiness) *τ* (*x*) */*= *∅*.

(intersection) *X, Y ∈ τ* (*x*) implies *X ∩ Y ∈ τ* (*x*).

*⟨ T, τ ⟩* is a *topological space* if it is normal and it satisfies: for any *x ∈ T* ,

(T) For all *X ∈ τ* (*x*), *x ∈ X*.

(4) For all *X ∈ τ* (*x*), *{ y ∈ T | X ∈ τ* (*y*) *}∈ τ* (*x*).

**Definition 2.2** Let T1 = *⟨ T*1*, τ*1 *⟩* and T2 = *⟨ T*2*, τ*2 *⟩* be monotone. We define the

*product* T1 *⊗* T2 = *⟨ T*1 *× T*2*, τh, τv ⟩* of T1 and T2 by:

*τh*(*x, y*) = *{ P ⊆ T*1 *× T*2 *| ∃ X ∈ τ*1(*x*)*.X ×{ y }⊆ P }*,

*τv*(*x, y*) = *{ P ⊆ T*1 *× T*2 *| ∃ Y ∈ τ*2(*y*)*. { x}× Y ⊆ P }*.

We say that *τh* is a *horizontal neighborhood structure* on *T*1 *× T*2 and *τv* is a *vertical neighborhood structure* on *T*1 *× T*2. If T1 and T2 are topological spaces, we say that T1 *⊗* T2 is the *product of topologies*.

It is easy to see that *τh* and *τv* are monotone. Given two topological spaces T1 and T2, let us remark that T1 *⊗* T2 = *⟨ T*1 *× T*2*, τh, τv ⟩* does not coincide with the *product topology ⟨ T*1 *× T*2*, τ*1*,*2 *⟩* of T1 and T2, where *τ*1*,*2(*x, y*) is the *⊇*-closure of *{ X × Y | X ∈ τ*1(*x*) and *Y ∈ τ*2(*y*) *}*. However, we can regard, e.g., *τh* as the product topology of the topology determined by *τ*1 and the *discrete topology* on *T*2. By this view and the following proposition, we can state that our definition of product of topologies in terms of local neighborhood basis and Van Benthem, et al. [[18](#_bookmark41)]’s definition in terms of open sets, are the same.

**Proposition 2.3** *Let* T1 *= ⟨ T*1*, τ*1 *⟩ and* T2 *= ⟨ T*2*, τ*2 *⟩ be monotone.* (i) *If τ*1 *and τ*2 *are normal, then τh and τv are normal.* (ii) *If τ*1 *and τ*2 *are topological spaces, then τh and τv are also topological spaces.*

**Proof.** (i) is easy. Let us show (ii). It suffices to check that (T) of *τ*1 implies

(T) of *τh* and that (4) of *τ*1 implies (4) of *τh*. We only show (4), since (T) is easy to show. Assume that *τ*1 satisfies (4) and that *P ∈ τh*(*x, y*). We need to establish that *{⟨ xj, yj ⟩∈ T*1 *× T*2 *| P ∈ τh*(*xj, yj*) *} ∈ τh*(*x, y*), i.e., there exists *Z ∈*

*τ*1(*x*) such that *Z × { y } ⊆ { ⟨ xj, yj ⟩∈ T*1 *× T*2 *| P ∈ τh*(*xj, yj*) *}*. By assumption, there exists *X ∈ τ*1(*x*) such that *X ×{ y }⊆ P* . Since *τ*1 satisfies (4) and *X ∈ τ*1(*x*),

*{ xj ∈ T*1 *| X ∈ τ*1(*xj*) *}∈ τ*1(*x*). Since *X×{ y }⊆ P* , *{ xj ∈ T*1 *| X ∈ τ*1(*xj*) *}×{ y }⊆*

*{⟨ xj, yj ⟩∈ T*1 *× T*2 *| P ∈ τh*(*xj, yj*) *}*.

# Hybrid Semantics on Product on Monotone Neigh- borhood Frames

Let us introduce the syntax. First of all, it is worth noting that our syntax has two disjoint sets NOM1 and NOM2 of nominals. E.g., one can consider that an element of NOM1 represents an instant of time and an element of NOM2 represents a coordinate of space. So, our vocabulary consists of:

1. two countable but disjoint sets of nominals NOM1 = *{ i, j, k,... }* and NOM2

= *{ a, b, c, . . . }*,

1. a countable set PROP of propositional variables, where we assume that PROP

is disjoint from NOM1 *∪* NOM2,

1. Boolean connectives: *¬*, *∧*,
2. two modal operators:1 (e.g. for time) and2 (e.g. for space) (*3α* is the defined dual of *α*, where *α* = 1 or 2),
3. two kinds of satisfaction operators: @*i* (*i ∈* NOM1), @*a* (*a ∈* NOM2). Then, the set of formulas is defined inductively by:

*ϕ* ::= *i | a | p | ¬ϕ| ϕ ∧ ψ |* 1*ϕ|* 2*ϕ|* @*iϕ|* @*aϕ*.

We say that *ϕ* is *pure* if *ϕ* does not contain any propositional variables. For example, @*i*@*a3*1(*i ∧ 3*2*a*) is pure. If *ϕ* is constructed only from the vocabulary (ii), (iii) and (iv) above, we say that *ϕ* is a *two-dimensional modal formula*. Moreover, we define the following two sublanguages: *L*1 := *{ ¬, ∧,* 1 *} ∪* PROP *∪* NOM1 *∪*

*{* @*i | i ∈* NOM1 *}* and *L*2 := *{ ¬, ∧,* 2 *} ∪* PROP *∪* NOM2 *∪ {* @*a | a ∈* NOM2 *}*. We say that *ϕ* is a *Lα-formula* if it is constructed from the vocabulary of *Lα* (*α* = 1, 2).

Let us provide the semantics to our syntax. Intuitively, we define our valuation so that the denotation of *i ∈* NOM1 is a vertical line *{ x}×T*2 and the denotation of *a ∈* NOM2 is a horizontal line *T*1 *×{ y }* over *T*1 *×T*2. In this sense, we call *i, j, k, ···* *vertical nominals* and *a, b, c, ··· horizontal nominals* below in this paper. So, let us define a *valuation* as follows. Given any product T1 *⊗* T2 of monotone neighborhood frames, we say that a mapping *V* : PROP *∪* NOM1 *∪* NOM2 *→ P*(*T*1 *× T*2) is a *valuation* if (i) for any *i ∈* NOM1, *|π*1[*V* (*i*)]*|* = 1 and *π*2[*V* (*i*)] = *T*2; (ii) for any *a ∈* NOM2, *|π*2[*V* (*a*)]*|* = 1 and *π*1[*V* (*a*)] = *T*1, where *πα* : *T*1 *× T*2 *→ Tα* is the projection onto *Tα* [1](#_bookmark0) [2](#_bookmark1) . Note that the denotation of *p* is a subset of *T*1 *× T*2. Let

1 As for *V* (*i*), the condition *π*2[*V* (*i*)] = *T*2 excludes the possibility that *V* (*i*) isa *non-empty proper subset*

of *{ x }× T*2.

2 Alternatively, we can also define *V* (*i*) := *π−*1[*{ x }*] for some *x ∈ T*1 and *V* (*a*) := *π−*1[*{ y }*] for some

1 2

*y ∈ T*2.

us denote a unique element of *π*1[*V* (*i*)] by *iV* and a unique element of *π*2[*V* (*a*)] by *aV* . Then, we can derive that *V* (*i*)= *{ iV }× T*2 and *V* (*a*)= *T*1 *×{ aV }*. We call a pair *⟨* T1 *⊗* T2*,V ⟩* a *monotone neighborhood product model* (simply *product model*, when it causes no confusion).

Then, for any pair M = *⟨* T1 *⊗* T2*,V ⟩*, any *⟨ x, y ⟩ ∈ T*1 *× T*2 and any *ϕ*, the

*satisfaction relation* H is defined inductively as follows:

|  |  |  |
| --- | --- | --- |
| M*, ⟨ x, y ⟩* H *p* | iff | *⟨ x, y ⟩∈ V* (*p*) |
| M*, ⟨ x, y ⟩* H *i* | iff | *x* = *iV* |
| M*, ⟨ x, y ⟩* H *a* | iff | *y* = *aV* |
| M*, ⟨ x, y ⟩* H *¬ϕ* | iff | M*, ⟨ x, y ⟩ /*H *ϕ* |
| M*, ⟨ x, y ⟩* H *ϕ ∧ ψ* | iff | M*, ⟨ x, y ⟩* H *ϕ* and M*, ⟨ x, y ⟩* H *ψ* |
| M*, ⟨ x, y ⟩* H1*ϕ* | iff | J*ϕ*) *∈ τh*(*x, y*) |
| M*, ⟨ x, y ⟩* H2*ϕ* | iff | J*ϕ*) *∈ τv*(*x, y*) |
| M*, ⟨ x, y ⟩* H @*iϕ* | iff | M*, ⟨ iV ,y ⟩* H *ϕ* |
| M*, ⟨ x, y ⟩* H @*aϕ* | iff | M*, ⟨ x, aV ⟩* H *ϕ*, |

where J*ϕ*) = *{⟨ x, y ⟩|* M*, ⟨ x, y ⟩* H *ϕ}*. We usually write *⟨ x, y ⟩* H *ϕ*, when the underlying model M is clear from the context. By monotonicity of *τh* and *τv*, we can simplify the satisfactions of1*ϕ* and2*ϕ* as:

|  |  |  |
| --- | --- | --- |
| M*, ⟨ x, y ⟩* H1*ϕ* | iff | *∃ X ∈ τ*1(*x*)*. ∀ xj ∈ X.* M*, ⟨ xj,y ⟩* H *ϕ*, |
| M*, ⟨ x, y ⟩* H2*ϕ* | iff | *∃ Y ∈ τ*2(*y*)*. ∀ yj ∈ Y.* M*, ⟨ xj, yj ⟩* H *ϕ*. |

Remark that the behavior of @*iϕ* is different from one-dimensional hybrid logic. In one-dimensional semantics, if *ϕ* holds at the state named by *i*, then @*iϕ* holds at *all* states. In our two-dimensional semantics, (*iV , y*) *∈* J*ϕ*) does not imply J@*iϕ*)

= *T*1 *× T*2 in general.

We need more semantic definitions. A formula *ϕ* is *valid ona product model* M (notation: M H *ϕ*) if M*, ⟨ x, y ⟩* H *ϕ* for any pair *⟨ x, y ⟩* in M. We say that *ϕ* is *valid on* T1 *⊗* T2 (notation: T1 *⊗* T2 H *ϕ*) if *⟨* T1 *⊗* T2*,V ⟩* H *ϕ* for any valuation *V* . We also say that a set Λ of formulas is *valid* on T1 *⊗* T2 (notation: T1 *⊗* T2 H Λ) if T1 *⊗* T2 H *ϕ* for any *ϕ ∈* Λ. A set Λ of formulas *deﬁnes* a class F of product of monotone neighborhood frames if, for any T1 *⊗* T2, T1 *⊗* T2 H Λ iff T1 *⊗* T2 *∈* F. A setΛ of formulas is *satisﬁable* in a class F of product of monotone neighborhood frames if there exists some T1 *⊗* T2 *∈* F and some valuation *V* on it and some pair

*⟨ x, y ⟩* from T1 *⊗* T2 such that all formulas of Λ are true at *⟨ x, y ⟩* of *⟨* T1 *⊗* T2*,V ⟩*.

**Proposition 3.1** *All the formulas in Table* [1](#_bookmark2) *are valid on any product of monotone neighborhood frames.*

Table 1

Interaction Axioms for Product of Monotone Neighborhood Frames

**Com**@ @*a*@*ip ↔* @*i*@*ap* **Com**1@21@*ap ↔* @*a* 1*p* **Com**2@12@*ip ↔* @*i* 2*p* **Red**@1 @*ia ↔ a*

**Red**@2 @*ai ↔ i*

**Proof.** We only show the validity of **Com**1@2. *⟨ x, y ⟩* H1@*ap* iff :

*∃ X ∈ τ*1(*x*)*. ∀ xj ∈ X.⟨ xj,y ⟩* H @*ap* iff *∃ X ∈ τ*1(*x*)*. ∀ xj ∈ X.⟨ xj, aV ⟩* H *p*

iff *⟨ x, aV ⟩* H1*p* iff *⟨ x, y ⟩* H @*a* 1*p*, as desired.

The one-dimensional nature of the horizontal and vertical neighborhood frames is emphasized by the following proposition (cf. [[18](#_bookmark41), Proposition 3.10]).

**Proposition 3.2** (i) *A L*1*-formula ϕ is valid on* T1 *⊗* T2 iff *ϕ is valid on* T1*.*

(ii) *A L*2*-formula ϕ is valid on* T1 *⊗* T2 iff *ϕ is valid on* T2*.*

**Proof.** We can show these two items by the similar argument for product of Kripke frames [[13](#_bookmark36), Proposition 2.2].

# Monotone Hybrid Product Logic

**Definition 4.1** A set Λ of formulas is a **Name***-logic* if Λ contains all tautologies and Λ is closed under **MP** and **Name** in Table [2](#_bookmark4). Λ is a *monotone bi-hybrid logic* if Λ is a **Name**-logic and Λ contains **K**@, **Selfdual**, **Ref** , **Intro***,* **BMon**, **Agree** in Table [2](#_bookmark4) and Λ is closed under **Mon**, **Nec**@, **Sub** in Table [2](#_bookmark4). A monotone bi-hybrid logic Λ is *normal* if it contains **N** and **R**.

One difference from the notion of bi-hybrid logic in [[13](#_bookmark36)] consists in the axiom **BMon** in Table [2](#_bookmark4). In [[13](#_bookmark36)], the author used the axiom **Back**: @*np → α*@*np*, where *n ∈* NOM*α* (*α* = 1, 2). However, we cannot use it in this context, because @*ip →* 1@*ip* defines (non-emptiness) of *τ*1 [[14](#_bookmark37)]. On the other hand, it is easy to see that @*ip ∧* 1*q →* 1(@*ip ∧ q*) is valid on all monotone neighborhood frames

*⟨ T*1*, τ*1 *⟩*. Another difference consists in whether we include the inference rule **BG**

from Table [2](#_bookmark4) in the definition. We will discuss this below.

In order to capture the interaction between two dimensions, however, we also need the five interaction axioms in Table [1](#_bookmark2).

**Definition 4.2** A monotone bi-hybrid logic Λ is a *monotone hybrid product logic* if Λ contains all formulas: **Com**@, **Com***3*1@2, **Com***3*2@1, **Red**@1 and **Red**@2 in Ta- ble [1](#_bookmark2). We denote the smallest monotone hybrid product logic by (**MName***,* **MName**).

*H*(@) *H*(@)

Table 2

A List of Axioms and Rules

|  |
| --- |
| Axioms for Monotone Hybrid Product Logic |
| All the interaction axioms in Table 1. |
| **K**@ @*n*(*p → q*) *→* (@*np →* @[*n*](#_bookmark2)*q*), where *n* = *i* or *a*. |
| **Selfdual** *¬*@*np ↔* @*n¬p*, where *n* = *i* or *a*. |
| **Ref** @*nn*, where *n* = *i* or *a*. |
| **Intro** *n ∧ p →* @*np*, where *n* = *i* or *a*. |
| **BMon** @*np ∧ αq → α*(@*np ∧ q*), where *n ∈* NOM*α* (*α* = 1, 2). |
| **Agree** @*n*@*mp →* @*mp*, where *⟨ n, m⟩* = *⟨ i, j ⟩* or *⟨ a, b ⟩*. |
| Rules for Monotone Hybrid Product Logic |
| **MP** From *ϕ → ψ* and *ϕ*, we may infer *ψ* |
| **Mon** From *ϕ → ψ*, we may infer *ϕ → ψ*, where *∈ {* 1*,* 2 *}*. |
| **Nec**@ From *ϕ*, we may infer @*nϕ*, where *n ∈* NOM1 *∪* NOM2. |
| **Sub** From *ϕ*, we may infer *σ*(*ϕ*), where *σ* denotes a substitution that |
| uniformly replaces proposition letters by formulas and |
| nominals from NOM*α* by nominals from NOM*α* (*α* = 1, 2). |
| **Name** From *n → ϕ*, we may infer *ϕ*, |
| where *n ∈* NOM1 *∪* NOM2 does not occur in *ϕ*. |
| Additional Axioms |
| **R** ( *p ∧ q*) *→* (*p ∧ q*) where *∈ {* 1*,* 2 *}*. |
| **N**  *T* where *∈ {* 1*,* 2 *}*. |
| **T**  *p → p* where *∈ {* 1*,* 2 *}*. |
| **4**  *p → p* where *∈ {* 1*,* 2 *}*. |
| **Sep**0 @*n3αm ∨* @*m3αn →* @*nm* where *n, m ∈* NOM*α* (*α* = 1*,* 2). |
| **Sep**1 *3αn → n* where *n ∈* NOM*α* (*α* = 1*,* 2). |
| **Di** *¬ αn* where *n ∈* NOM*α* (*α* = 1*,* 2). |
| **com***→* 12*p →* 21*p* |
| **com***→* 21*p →* 12*p* |
| **chr** *3*12*p →* 2*3*1*p* |
| Additional Rules |
| **BG** From @*n3αm →* @*mϕ*, we may infer @*n αϕ*,  where *n, m ∈* NOM*α* and *m /*= *n* does not appear in *ϕ* (*α* = 1*,* 2). |

We also say that a monotone hybrid product logic Λ is *normal* if Λ contains **N** and

**R**. Λ is a *topological hybrid product logic* if Λ is a normal hybrid product logic and it contains **T** and **4** in Table [2](#_bookmark4). We denote the smallest topological hybrid product logic by (**S4Name***,* **S4Name**).

*H*(@) *H*(@)

Let us go back to the inference rule **BG**.

T

**Definition 4.3** A monotone *⟨ T, τ ⟩* is *augmented* if *τ* (*x*) *∈ τ* (*x*) for any *x ∈ T* , i.e., *τ* (*x*) has a smallest element. A topological space *⟨ T, τ ⟩* is *Alexandrov* if *⟨ T, τ ⟩* is augmented.

For one-dimensional hybrid logic, Ten Cate and Litak [[17](#_bookmark40)] showed that **BG**-rule characterizes the class of all Alexandrov spaces, and they also generalized it to a characterization of the class of all augmented monotone neighborhood frames by **BG**. We will discuss now how to extend their results in the context of the present paper (for a similar kind of characterization by **BG** in a different context, see [[12](#_bookmark35)]). Given two valuations *V* and *V j* and a horizontal or vertical nominal *m*, we say that *V j* is an *m-variant* of *V* if *V* and *V j* agree on all elements from the domain except possibly for *m*. Let us say that T1 *⊗* T2 *admits* **BG** for *α* if any valuation

*V* on T1 *⊗* T2 falsifying the consequent @*n αϕ* can be changed to some valuation *V j* such that it falsifies the antecedent @*n3αm →* @*mϕ* and *V j* is an *m*-variant of *V* .

**Proposition 4.4** *If a monotone* T1 *is augmented, then* T1 *⊗* T2 *admits* **BG** *for* 1

*for any monotone* T2*.*

**Proof.** Assume that a monotone T1 is augmented and that *V* on T1 *⊗* T2 falsifies @*i* 1*ϕ*. Then, we can find some *⟨ x, y ⟩* such that *x* = *iV* and *⟨ x, y ⟩ /*H1*ϕ*. By augmentation of *τ*1, it follows that we can choose *xj ∈ τ*1(*x*) such that *⟨ xj,y ⟩ ∈/* J*ϕ*)*V* . Let us consider some *j*-variant *V j* of *V* such that *V j*(*j*) := *{ xj }× T*2 (recall that *j* is fresh in @*i* 1*ϕ*). Then, it is easy to see that @*i3*1*j →* @*jϕ* is false at

T

*⟨ x, y ⟩* under *V j*.

**Proposition 4.5** *If a monotone* T1 *is not augmented,* T1 *⊗* T1 *fails to admit* **BG**

*for* 1*.*

**Proof.** The proof is similar to [[17](#_bookmark40), Theorem 3.4]. It suffices to care about the vertical dimension. Assume that a monotone T1 is not augmented. Thus, *τ*1(*x*) has no smallest element for some *x ∈ T*1. Fix such *x*. Then, it follows that

*{ xj ∈ X | ∃ Xj ∈ τ*1(*x*)*. xj ∈/ Xj } /*= *∅* for any *X ∈ τ*1(*x*). By the axiom of choice, we can find a sequence (*g*(*X*))*X∈τ*1(*x*) such that (0) *g*(*X*) *∈ X*, (1) *∀ X ∈ τ*1(*x*)*.X ∩*

*{ g*(*X*) *| X ∈ τ*1(*x*) *} /*= *∅*, and (2) *∀ X ∈ τ*1(*x*)*. ∃ Xj ∈ τ*1(*x*)*. g*(*X*) *∈/ Xj*. Define *V* (*i*)

= *{ x}× T*1 and *V* (*p*) = (*T*1 *\{ g*(*X*) *| X ∈ τ*1(*x*) *}*) *× T*1. By (1), we can establish

*⟨ x, x⟩ ∈/* J@*i* 1*p*)*V* . Consider any *j*-variant *V j* of *V* . We show that @*i3*1*j →* @*jp* is true at all points *⟨ x*1*, x*2 *⟩* from *T*1 *× T*1 under *V j*. By definition of (*g*(*X*))*X∈τ* (*x*) and (2), it is easy to see that *⟨ x*1*, x*2 *⟩ ∈/* J@*jp*)*V ′* implies *⟨ x*1*, x*2 *⟩ ∈/* J@*i3*1*j*)*V ′* .

**Corollary 4.6** *Let* T1 *be monotone. Then, the following are equivalent:*

1. T1 *is augmented.*
2. T1 *⊗* T2 *admits* **BG** *for* 1 *for any monotone* T2*.*
3. T1 *⊗* T1 *admits* **BG** *for* 1*.*

**Proof.** By Propositions [4.4](#_bookmark5) and [4.5](#_bookmark6).

If we restrict our attention to the product of topologies, Van Benthem, et al [[18](#_bookmark41)] showed equivalence of several characterizations of Alexandrovness in terms of **com***→*, **com***→* and **chr** from Table [2](#_bookmark4). So, we can combine these characterizations with ours and obtain the following.

**Corollary 4.7** *Let* T1 *be a topological space. Then, the following are equivalent:*

1. T1 *is Alexandrov.*
2. T1 *⊗* T2 *admits* **BG** *for* 1 *for any topological space* T2*.*
3. T1 *⊗* T1 *admits* **BG** *for* 1*.*
4. T1 *⊗* T1 H **com***→ ∧* **com***→.*
5. T1 *⊗* T2 H **com***→ for any topological space* T2*.*
6. T2 *⊗* T1 H **com***→ for any topological space* T2*.*
7. T1 *⊗* T1 H **chr***.*

**Proof.** By Corollary [4.6](#_bookmark7) and [[18](#_bookmark41), Corollary 4.19 and Corollary 4.22].

**Remark 4.8** A natural question to ask is whether we can generalize the above characterization taken from [[18](#_bookmark41)] to *monotone neighborhood frames*. This is not the case. The proof for (i) *⇒* ((v) & (vi)) and (i) *⇒* (vii) in Corollary [4.7](#_bookmark8) can go through even for monotone neighborhood frames (cf. [[18](#_bookmark41), Propositions 4.15 and 4.20]). Their proof of (iv) *⇒* (i), however, requires (non-emptiness) and (intersec- tion) of *⟨ T, τ ⟩* (cf. [[18](#_bookmark41), Propositions 4.18]). Moreover, the following tells us that the above generalization is impossible.

**Proposition 4.9** *There is a non-augmented monotone* T *= ⟨ T, τ ⟩ such that* T *⊗*

T *|*= **com***→ ∧* **com***→.*

**Proof.** Fix some non-empty *T* . Define *τ* : *T → PP*(*T* ) by *τ* (*x*)= *∅* for any *x ∈ T* .

Then, (*T, τ* ) is not augmented, since T *τ* (*x*) = *T ∈/ τ* (*x*). Fix any *⟨ x, y ⟩ ∈ T × T*

and any valuation *V* . Since both *τ* (*x*) and *τ* (*y*) are empty, we trivially have *⟨ x, y ⟩ ∈/*

J12*p*)*V* and *⟨ x, y ⟩ ∈/* J21*p*)*V* , as desired.

# Pure Completeness for Product of Monotone Frames

**Definition 5.1** Let Λ be a **Name**-logic. *ϕ* is *deducible* in Λ from Γ if there is a finite subset Γ*j* of Γ such that Γ*j → ϕ ∈* Λ, where Γ*j* is the conjunction of all finite elements of Γ*j* (if Γ*j* = *∅*, we define Γ*j* := *T* ). Γ is Λ*-consistent* if *⊥* is not deducible from Γ in Λ.

**Lemma 5.2** *The following derivation rules are admissible in all monotone bi- hybrid logic:*

1. *If ▶* @*j*(*ϕ → ψ*) *and j is fresh in ϕ → ψ, then ▶* @*i*(1*ϕ →* 1*ψ*)*.*
2. *If ▶ α →* @*j*(*ϕ → ψ*) *and j is fresh in α and ϕ → ψ, then ▶ α →* (@*i* 1*ϕ →*

@*i* 1*ψ*)*.*

1. *If ▶* @*b*(*ϕ → ψ*) *and b is fresh in ϕ → ψ, then ▶* @*a*(2*ϕ →* 2*ψ*)*.*
2. *If ▶ α →* @*b*(*ϕ → ψ*) *and b is fresh in α and ϕ → ψ, then ▶ α →* (@*a* 2*ϕ →*

@*a* 2*ψ*)*.*

**Proof.** It suffices to show (i) and (ii). Let us show (i). Assume that *▶* @*j*(*ϕ → ψ*) and that *j* is fresh in *ϕ → ψ*. First of all, remark that we can always use distributivity of @ over Boolean connectives from our axioms for @. Then, we can derive from **Intro** that @*j*(*ϕ → ψ*) *→* (*j →* (*ϕ → ψ*)). By this and our assumption, we obtain *▶ j →* (*ϕ → ψ*). We deduce from **Name** and the freshness assumption of *j* that *▶ ϕ → ψ*. It follows from **Mon** that *▶* 1*ϕ →* 1*ψ*. By **Nec**@, we obtain @*i*(1*ϕ →* 1*ψ*), as required. Next, we show (ii). Assume that *j* is fresh in *α* and *ϕ → ψ* and that *▶ α →* @*j*(*ϕ → ψ*), i.e., *▶* (*α ∧* @*jϕ*) *→* @*jψ*. Let us choose *k* such that *k* does not occur in *α →* (@*i* 1*ϕ →* @*i* 1*ψ*) and *k /*= *j*. By **Nec**@, *▶* @*k*((*α ∧* @*jϕ*) *→* @*jψ*). We obtain *▶* @*j*((@*kα ∧ ϕ*) *→ ψ*) by **Agree** and distributivity of @ over Boolean connectives. It follows from (i) that

*▶* @*i*(1(@*kα ∧ ϕ*) *→* 1*ψ*), since *j* does not occur in (@*kα ∧ ϕ*) *→ ψ*. By **BMon**,

*▶* @*i*((@*kα ∧* 1*ϕ*) *→* 1*ψ*). It follows from the similar argument by **Agree** to the above that *▶* @*k*((*α ∧* @*i ϕ*) *→* @*i ψ*), i.e., *▶* @*k*(*α →* (@*i* 1*ϕ →* @*i* 1*ψ*)). By **Name**, we conclude *▶ α →* (@*i* 1*ϕ →* @*i* 1*ψ*).

**Definition 5.3** Let Δ be any set of formulas.

* + Δ is *labelled* if *i ∧ a ∈* Δ for some *⟨ i, a ⟩*.
  + Δ is *monotonically* 1*-saturated* if, for every *¬*(@*i* 1*ϕ →* @*i* 1@*aψ*) *∈* Δ, there is a vertical nominal *j* which does not appear in *ϕ* and *ψ* such that *¬*@*j*(*ϕ →* @*aψ*) *∈* Δ.
  + Δ is *monotonically* 2*-saturated* if, for every *¬*(@*a* 2*ϕ →* @*a* 2@*iψ*) *∈* Δ, there is a horizontal nominal *b* which does not appear in *ϕ* and *ψ* such that *¬*@*b*(*ϕ →* @*iψ*) *∈* Δ.

The following is immediate from Definition [5.3](#_bookmark10).

**Lemma 5.4** *Let* Λ *be a monotone hybrid product logic. Suppose that* Δ *is mono- tonically α-saturated* Λ*-MCS* (*α = 1, 2*)*.*

* + 1. *If* @*j*(*ϕ →* @*aψ*) *∈* Δ *for all vertical nominals j, then* @*j* 1*ϕ →* @*j* 1@*aψ ∈* Δ

*for all vertical nominals j.*

* + 1. *If* @*b*(*ϕ →* @*iψ*) *∈* Δ *for all horizontal nominals b, then* @*b* 2*ϕ →* @*b* 2@*iψ ∈*

Δ *for all horizontal nominals b.*

**Lemma 5.5 (Lindenbaum Lemma)** *Let* Λ *be a monotone hybrid product logic.*

*Every* Λ*-consistent set of formulas can be extended to a labelled, monotonically* 1*- saturated and monotonically* 2*-saturated* Λ*-MCS, by adding both countably many new horizontal nominals and countably many new vertical nominals to the language.*

**Proof.** Suppose that Σ is Λ-consistent (henceforth ‘consistent’). Let (*in*)*n∈ω* and (*an*)*n∈ω* be two disjoint sets of countable fresh nominals. Let also (*ϕn*)*n∈ω* be an enumeration of all formulas in this expanded syntax. We are going to construct a sequence of consistent extensions (Σ*n*)*n∈ω* of Σ by induction on *n*.

**(Basis)** Define Σ0 := Σ*∪{ i*0 *∧ a*0 *}*. By two kinds of **Name**-rule, we easily establish that Σ0 is consistent.

**(Inductive Step)** Suppose that Σ*n* is consistent. Let us define Σ*n*+1 as follows: If Σ*n ∪{ ϕn }* is inconsistent, Σ*n*+1 := Σ*n*. Otherwise, Σ*n*+1 is defined by:

⎧⎪⎨Σ*n ∪{ ϕn, ¬*@*j*(*ϕ →* @*aψ*) *}* if *ϕn ≡ ¬*(@*i* 1*ϕ →* @*i* 1@*aψ*)

Σ*n*+1 :=

Σ*n ∪{ ϕn, ¬*@*b*(*ϕ →* @*iψ*) *}* if *ϕn ≡ ¬*(@*a* 2*ϕ →* @*a* 2@*iψ*)

⎪⎩Σ*n ∪{ ϕn }* o.w.

where *b ∈ { an }n∈ω* and *j ∈ { in }n∈ω* are *ﬁrst unused* vertical and horizontal nominals in Σ*n ∪{ ϕn }*, respectively.

**Claim 5.6** Σ*n*+1 *is consistent.*

**Proof of Claim.** It suffices to check the case where Σ*n ∪{ ϕn }* is consistent and *ϕn ≡ ¬*(@*i* 1*ϕ →* @*i* 1@*aψ*). Recall that *j* is fresh in Σ*n ∪{ ϕn }*. Assume for the purpose of *reductio* that Σ*n*+1 is inconsistent. Then there exist *γ*1*,..., γn ∈* Σ*n* such that *▶ ϕn ∧ ¬*@*j*(*ϕ →* @*aψ*) *→ ¬ l γl*. Let us put *η*:= *l γl*. It follows from propositional logic that *▶ ϕn ∧ η →* @*j*(*ϕ →* @*aψ*). By Lemma [5.2](#_bookmark9) (ii) and the choice of *j*, we obtain *▶ ϕn ∧ η →* (@*i* 1*ϕ →* @*i* 1@*aψ*), which is equivalent to

*▶ ¬*(*ϕn ∧ η*) by *ϕn ≡ ¬*(@*i* 1*ϕ →* @*i* 1@*aψ*). This tells us the inconsistency of Σ*n ∪{ ϕn }*. A contradiction. *E*

Finally, we put Σ*ω*:= *n∈ω* Σ*n*. Then, by construction we can easily establish that Σ*ω* is a labelled, monotonically1- and2-saturated MCS.

Let us now define the notion of a *Henkin-style product model*.

**Definition 5.7** Let Λ be a monotone hybrid product logic. Given any Λ-MCS Δ, we define a *Henkin-style product model* MΔ = *⟨* T1 *⊗* T2*, V*Δ *⟩* where T*α* := *⟨ Tα, τα ⟩* (*α* = 1, 2), as follows:

* For any vertical nominal *i* and any horizontal nominal *a*, let us define: [*i*] :=

*{ j |* @*ij ∈* Δ *}*, *|a|* := *{ b |* @*ab ∈* Δ *}*.

* Define *T*1 := *{* [*i*] *| i* : vertical nominal *}* and *T*2 := *{ |a|| a* : horizontal nominal *}*.
* We also define *τ*1 : *T*1 *→ PP*(*T*1) and *τ*1 : *T*2 *→ PP*(*T*2) as follows:

*X ∈ τ*1([*i*]) iff *∃ θ.* (@*i* 1*θ ∈* Δ and *∀ k.* (@*kθ ∈* Δ implies [*k*] *∈ X*))*, Y ∈ τ*2(*|a|*) iff *∃ θ.* (@*a* 2*θ ∈* Δ and *∀ c.* (@*cθ ∈* Δ implies *|c|∈ Y* ))*.*

* Define the mapping *V*Δ by: *V*Δ(*l*) = *{⟨* [*j*]*, |b|⟩|* @*j*@*bl ∈* Δ *}* for any *l ∈* PROP *∪*

NOM1 *∪* NOM2.

It is clear that *τ*1 and *τ*2 are monotone: Let us check that *τ*1 is monotone. Assume that *X ∈ τ*1([*i*]) and *X ⊆ Y* . By definition, there exists some *θ* such that @*i* 1*θ ∈* Δ and *∀ k.* (@*kθ ∈* Δ implies [*k*] *∈ X*)). Since *X ⊆ Y* , we have

*∀ k.* (@*kθ ∈* Δ implies [*k*] *∈ Y* )). Then, we can conclude that *Y ∈ τ*1([*i*]).

**Lemma 5.8 (Truth Lemma)** *Let* Λ *be a monotone hybrid product logic. For all monotonically* 1*- and* 2*-saturated* Λ*-MCSs* Δ*, all pairs ⟨ i, a ⟩ and all formulas ϕ,* MΔ*, ⟨* [*i*]*, |a|⟩* H *ϕ* iff @*i*@*aϕ ∈* Δ*.*

**Proof.** First, we check that *V*Δ is really a valuation. In order to show that, it suffices to show that *V*Δ(*i*) := *{* [*j*] *|* @*ij ∈* Δ *}× T*2 and that *{* [*j*] *|* @*ij ∈* Δ *}* is a singleton. We can establish the first clause, since *V*Δ(*i*) = *{⟨* [*j*]*, |b|⟩|* @*j*@*bi ∈* Γ *}* and *▶* @*j*@*bi ↔* @*ji* (by **Nec**@ and **Red**@2) and *▶* @*ji ↔* @*ij*. As for the second clause, it suffices to note that we have *▶* @*ii* and *▶* @*ij ∧* @*jk →* @*ik*.

Second, we prove our main statement by induction on *ϕ*. We only demonstrate it for the following case: *ϕ* is of the form2*ψ*. The proofs for the cases: (a) *ϕ* is of the form *j* and (b) *ϕ* is of the form @*jϕ*, are the same as in the proof of [[13](#_bookmark36), Lemma 3.11].

We can demonstrate the case where *ϕ* is of the form2*ψ* as follows:

MΔ*, ⟨* [*i*]*, |a|⟩* H2*ψ*

iff *∃ Y ∈ τ*2(*|a|*)*. ∀ y ∈ Y. ⟨* [*i*]*,y ⟩* H *ψ*

iff *∃ θ.* (@*a* 2*θ ∈* Δ and *∀ c.* (@*cθ ∈* Δ implies *|c|∈ Y* ) and *∀ y ∈ Y. ⟨* [*i*]*,y ⟩* H *ψ*) iff *∃ θ.* (@*a* 2*θ ∈* Δ and *∀ c.* (@*cθ ∈* Δ implies *⟨* [*i*]*, |c|⟩ ∈* J*ψ*)))

iff *∃ θ.* (@*a* 2*θ ∈* Δ and *∀ c.* (@*cθ ∈* Δ implies @*i*@*cψ ∈* Δ)) iff @*i*@*a* 2*ψ ∈* Δ

As for the right-to-left direction of the last equivalence, take @*iψ* as *θ*. Then, by **Com**@ and **Com**2@1, we can establish the desired statement. As for the left-to- right direction, let us fix our witness *θ*. By Lemma [5.4](#_bookmark11) (monotone2-saturation), we obtain @*a* 2@*iψ ∈* Δ. By **Com**@ and **Com**2@1, we establish @*i*@*a* 2*ψ ∈* Δ, as required.

**Definition 5.9** M = *⟨* T1 *⊗* T2*,V ⟩* is *named* if, for any *⟨ x, y ⟩* in M, there exists

*⟨ i, a ⟩* such that *x* = *iV* and *y* = *aV* .

Then, we can easily establish the following (cf. [[1](#_bookmark24), Lemma 7.22]).

**Lemma 5.10** *Given any named product model* M *= ⟨* T1 *⊗* T2*,V ⟩ and any pure formula ϕ, if* M H *σ*(*ϕ*) *for all uniform substitutions σ, then* T1 *⊗* T2 H *ϕ.*

This lemma tells us that the notion of uniform substitution (**Sub** in Table [2](#_bookmark4)) fits well with a named model also in monotone hybrid product logic.

**Theorem 5.11** *Let* Γ *be a set of pure formulas and* Λ *the smallest monotone hybrid product logic containing* Γ*. Then,* Λ *is sound and strongly complete for the class of all products of monotone neighborhood frames deﬁned by* Γ*.*

**Proof.** Soundness is straightforward. In order to establish the strong completeness, assume that Δ is Λ-consistent. By Lemma [5.5](#_bookmark12), there exists a labelled, monotonically

1- and2-saturated MCS Δ+ such that Δ *⊆* Δ+. Construct the Henkin-style product model MΔ+ = *⟨* T1 *⊗* T2*, V*Δ+ *⟩*. Since Δ+ is labelled, *i ∧ a ∈* Δ+ for some pair *⟨ i, a ⟩*. By **Intro** and *i ∧ a ∈* Δ+, @*i*@*aϕ ∈* Δ+ holds for any *ϕ ∈* Δ+. So, we derive from Lemma [5.8](#_bookmark13) that Δ is satisfiable in MΔ+ . Finally, we show that T1 *⊗* T2 belongs to the class F of product frames defined by Γ. For any *γ ∈* Γ, we have MΔ+ H *σ*(*γ*) for all uniform substitutions *σ*. So, T1 *⊗* T2 H Γ by Lemma [5.10](#_bookmark14).

**Corollary 5.12** (**MName***,* **MName**) *is sound and strongly complete for the class of*

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*all product of monotone neighborhood frames.*

**Theorem 5.13** *Let* Γ *be a set of pure formulas. The smallest normal hybrid product logic* Λ *containing* Γ *is sound and strongly complete for the class of all product of normal neighborhood frames deﬁned by* Γ*.*

**Proof.** Soundness is straightforward. As for strong completeness, it suffices to show that T*α* (*α* = 1, 2) satisfies (non-emptiness) and (intersection) in the Henkin-style product model MΔ+ = *⟨* T1 *⊗* T2*, V*Δ+ *⟩* (recall the proof of Theorem [5.11](#_bookmark15)). We can easily establish (non-emptiness), because the axiom **N** is pure and **N**:1*T* and

2*T* define (non-emptiness) of *τ*1 and *τ*2, respectively. Let us establish that *τ*1 and *τ*2 satisfy (intersection) by the axiom **R**. Consider *X, Xj ∈ τ*1([*i*]). We demonstrate *X ∩ Xj ∈ τ*1([*i*]). Thus,

*∃ θX.* (@*i* 1*θX ∈* Δ and *∀ k.* (@*kθX ∈* Δ implies [*k*] *∈ X*))*,*

*∃ θX′ .* (@*i* 1*θX′ ∈* Δ and *∀ k.* (@*kθX′ ∈* Δ implies [*k*] *∈ Xj*))*.*

Then, we have @*i* 1*θX ∧* @*i* 1*θX′ ∈* Δ. By **R** for1, @*i* 1(*θX ∧ θX′* ) *∈* Δ. It is easy to see that *∀ k.* (@*k*(*θX ∧ θX′* ) *∈* Δ implies [*k*] *∈ X ∩ Xj*)).

**Theorem 5.14** *Let* Γ *be a set of pure formulas. The smallest topological hybrid product logic* Λ *containing* Γ *is sound and strongly complete for the class of all product of topological spaces deﬁned by* Γ*.*

**Proof.** We only show the strong completeness. It suffices to show that T*α* (*α* = 1, 2) satisfies the conditions: (T) and (4) in the Henkin-style product model MΔ+ =

*⟨* T1 *⊗* T2*, V*Δ+ *⟩* (recall the proof of Theorem [5.11](#_bookmark15) and Theorem [5.13](#_bookmark16)). First, let us establish (T) of *τ*1. Assume *X ∈ τ*1([*i*]). We show that [*i*] *∈ X*. This means that:

@*i* 1*θX ∈* Δ and *∀ k.* (@*kθX ∈* Δ implies [*k*] *∈ X*)*.*

for some *θX* . By **T**-axiom, we have @*iθX ∈* Δ. Then, we obtain [*i*] *∈ X*, as required. Second, let us establish (4) of *τ*1. Assume *X ∈ τ*1([*i*]). We show *{* [*j*] *| X ∈ τ*1([*j*]) *}∈*

*τ*1([*i*]). Similarly to the argument for (T), we can find *θX* such that @*i* 1*θX ∈* Δ and *∀ k.* (@*kθX ∈* Δ implies [*k*] *∈ X*). By **4**-axiom, we have @*i* 11*θX ∈* Δ. For the witness of *{* [*j*] *| X ∈ τ*1([*j*]) *} ∈ τ*1([*i*]), let us consider1*θX* . Then, it suffices to check that: *∀ k.* (@*k* 1*θX ∈* Δ implies *X ∈ τ*1([*k*])). Consider any *k* with @*k* 1*θX ∈* Δ. Our witness for *X ∈ τ*1([*k*]) should be *θX* . Then, it suffices to check that:

*∀ k .* @*k′ θX ∈* Δ implies [*k* ] *∈ X.*

*j j*

However, this is trivial.

**Corollary 5.15** (**S4Name***,* **S4Name**) *is sound and strongly complete for the class of*

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*all product of topological spaces.*

# An Application of Topological Pure Completeness

**Definition 6.1** Let T = *⟨ T, τ ⟩* be a topological space.

1. T is a *T*0*-space* if, for any *x, y ∈ T* , *x /*= *y* implies that there exists *X ⊆ T* such that (*y ∈/ X* and *X ∈ τ* (*x*)) or (*x ∈/ X* and *X ∈ τ* (*y*)).
2. T is a *T*1*-space* if for any *x, y ∈ T* , *x /*= *y* implies that there exist *X ∈ τ* (*x*) and

*Y ∈ τ* (*y*) such that *y ∈/ X* and *x ∈/ Y* .

1. T is *dense-in-itself* if *{ x} ∈/ τ* (*x*) for any *x ∈ T* .

**Fact 6.2 (Gabelaia [**[**6**](#_bookmark28)**] (cf. [**[**16**](#_bookmark39)**]))** *With respect the class of all topological spaces, we have:*

1. **Sep**0 *for* 1 *in Table* [*2*](#_bookmark4) *deﬁnes the class of all T*0*-spaces.*
2. **Sep**1 *for* 1 *in Table* [*2*](#_bookmark4) *deﬁnes the class of all T*1*-spaces.*
3. **Di** *for* 1 *in Table* [*2*](#_bookmark4) *deﬁnes the class of all dense-in-itself spaces.*

Remark that all the formulas in Fact [6.2](#_bookmark18) are *pure*.

Let us consider the one-dimensional hybrid language *Lα*. We say that a set Λ of *Lα*-formulas is a (*one-dimensional*) *topological hybrid logic* if it contains all axioms *of Lα* in monotone bi-hybrid logic as well as **N**, **R**, **T** and **4** and is closed under **MP**, **Mon**, **Nec**@, the uniform substitution **Sub**, **Name** for *Lα* (remark that we do not require the closure under **BG**). A topological hybrid logic Λ of *Lα*-formulas is *topologically complete* if there exists a class F of topological spaces such that Λ is the logic of F, i.e., Λ = *{ ϕ* of *Lα | ϕ* is valid on F *}*. We also say that Λ is *pure* *topo-complete* if there exists a class F of topological spaces such that Λ is the logic of F and F is definable by some set of pure formulas in *Lα*. Let Λ*α* be a topologically complete logic in *Lα* (*α* = 1, 2). The *topo-product logic* Λ1 *×t* Λ2 is defined as the set of all valid formulas (of two-dimensional hybrid language) on any product T1 *⊗* T2 such that Λ*α* is valid on T*α* (*α* = 1, 2). We define (Λ1*,* Λ2) as the smallest topological hybrid product logic containing both Λ1 and Λ2.

**Corollary 6.3** *Let* Λ*α be a pure topo-complete logic of Lα* (*α =* 1*,* 2)*. Then:*

(Λ1*,* Λ2)= Λ1 *×t* Λ2*.*

**Proof.** By Theorem [5.14](#_bookmark17) and Proposition [3.2](#_bookmark3).

Let denote the smallest topological hybrid product logic containing **Sep**1 and **Di**

by (**S4T**1**DiName***,* **S4T**1**DiName**). Then, this corollary and Fact [6.2](#_bookmark18) assure us that

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(**S4T**1**DiName***,* **S4T**1**DiName**) is strongly complete with respect to all products of

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two dense-in-itself *T*1-spaces.

Since R with the Euclidean topology (i.e., the real line) satisfies *T*1 and density- in-itself, it is tempting to think that (**S4T**1**DiName***,* **S4T**1**DiName**) is (weakly) com-

*H*(@) *H*(@)

plete with respect to R *⊗* R, in the sense that *ϕ ∈* (**S4T**1**DiName***,* **S4T**1**DiName**)

*H*(@) *H*(@)

iff R *⊗* R H *ϕ*, for any *ϕ*. In what follows in this section, we show that this is not

the case. Let us recall that a *two-dimensional modal formula* is a formula does not contain any hybrid vocabulary. We define the set **S4** *⊕* **S4** (usually called *fusion*) of two-dimensional modal formulas as the smallest normal bimodal logic containing **S4**-axioms for both1 and2. Below, let Q be the rational line.

**Fact 6.4 (Van Benthem, et al [**[**18**](#_bookmark41)**])** *Then,* **S4** *⊕* **S4** *is complete with respect to*

Q *⊗* Q*, i.e., ϕ ∈* **S4** *⊕* **S4** iff Q *⊗* Q H *ϕ for any two dimensional modal formula ϕ.*

**Lemma 6.5** (**S4T**1**DiName***,* **S4T**1**DiName**) *is conservative over* **S4** *⊕* **S4***, i.e., for*

*H*(@) *H*(@)

*any two dimensional modal formula ϕ, ϕ ∈* (**S4T**1**DiName***,* **S4T**1**DiName**) *implies*

*ϕ ∈* **S4** *⊕* **S4***.*

*H*(@)

*H*(@)

**Proof.** We show the contrapositive implication. Suppose that *ϕ ∈/* **S4** *⊗* **S4**. We deduce from Fact [6.4](#_bookmark20) that Q *⊗* Q */*H *ϕ*. Remark that the rational line Q satisfies *T*1 and density-in-itself. Then, it is easy to see that (**S4T**1**DiName***,* **S4T**1**DiName**) is

sound with respect to Q *⊗* Q, i.e.,

*H*(@)

*H*(@)

*ψ ∈* (**S4T**1**DiName***,* **S4T**1**DiName**) implies Q *⊗* Q H *ψ*

*H*(@) *H*(@)

for any (two dimensional hybrid) formula *ψ*. Therefore, it follows from Q *⊗* Q */*H *ϕ*

that *ϕ ∈/* (**S4T**1**DiName***,* **S4T**1**DiName**).

*H*(@) *H*(@)

**Fact 6.6 (Kremer [**[**8**](#_bookmark31)**]) S4** *⊕* **S4** *is incomplete with respect to* R *⊗* R*, i.e., there exists some two dimensional modal formula ϕ such that ϕ /∈* **S4***⊕***S4** *and* R*⊗*R H *ϕ.*

**Theorem 6.7** (**S4T**1**DiName***,* **S4T**1**DiName**) *is incomplete with respect to* R *⊗* R*,*

*H*(@) *H*(@)

*i.e., there exists some formula ϕ such that ϕ /∈* (**S4T**1**DiName***,* **S4T**1**DiName**) *and*

R *⊗* R H *ϕ.*

*H*(@)

*H*(@)

**Proof.** By Fact [6.6](#_bookmark22) and Lemma [6.5](#_bookmark21).

# Further Directions and Open Problems

* 1. *Local Deﬁnability*

In the same sprit as did in [[17](#_bookmark40)], we can also include the *downarrow binders* in our syntax. The downarrow binder *↓ i* (or *↓ a*) binds a nominal *i* (or *a*) to the first (or,

second, respectively) argument of the current state. Given any *⟨ T*1 *× T*2*, τh, τv,V ⟩*, we can define

*⟨ T*1 *× T*2*, τh, τv,V ⟩, ⟨ x, y ⟩* H*↓ i. ϕ* iff *⟨ T*1 *× T*2*, τh, τv,V* [*i '→ x*] *⟩, ⟨ x, y ⟩* H *ϕ,*

where *V* [*i '→ x*] is the *i*-variant of *V* such that it sends *i* to *{ x}× T*2. We can also give the similar clause to *↓ a. ϕ*. A technique of *local deﬁnability* allows us to capture this semantics by the axiom **DA**1: @*j*(*↓ i. ϕ ↔ ϕ*[*i/j*]), where *ϕ*[*i/j*] is the result of replacing all free instances of *i* by *j* in *ϕ*. We can also consider the corresponding axiom **DA**2 for *↓ a. ϕ*. By the similar argument to [[2](#_bookmark29), Theorem 5], we can immediately transfer Theorems [5.11](#_bookmark15), [5.13](#_bookmark16), and [5.14](#_bookmark17) to the syntax extended with the downarrow binders *↓ i* and/or *↓ a*.

* 1. *Dependant Product of Monotone Neighborhood Frames*

In [[13](#_bookmark36)], the author considered the dependence of the horizontal dimension to the vertical dimension by the notion of *dependent product of Kripke frames* and revealed that we still retain pure completeness result. It would be interesting to see if we can obtain the corresponding result for the notion of *dependant product of monotone neighborhood frames*.

* 1. *Hybrid Product Logic over Product of Euclidean spaces*

Theorem [6.7](#_bookmark23) established the incompleteness of (**S4T**1**DiName***,* **S4T**1**DiName**) with

*H*(@) *H*(@)

respect to R*⊗*R. In this stage, the author does not know if we can obtain a complete

axiomatization of the logic of R *⊗* R in our two-dimensional hybrid syntax. If the syntax for one-dimensional hybrid logic is expanded with the *global modality* E*ϕ* (read: ‘*ϕ* holds at some states’), the logic of the real line R in this syntax is not *ﬁnite* axiomatizable [[9](#_bookmark32)] (via Gargov-Goranko translation [[7](#_bookmark30)], see also [[10](#_bookmark33)]). However, Kudinov [[9](#_bookmark32)] also showed that the logic of R*n* (*n ≥* 2 is fixed) in the above syntax with the global modality is axiomatizable. Therefore, it would be interesting to study whether the hybrid product logic of R*n ⊗* R*n* (*n ≥* 2 is fixed) is axiomatizable or not.

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