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Category-theoretic Structure for Independence and Conditional Independence

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**Abstract**

Relations of independence and conditional independence arise in a variety of contexts. Stochastic in- dependence and conditional independence are fundamental relations in probability theory and statistics. Analogous non-stochastic relations arise in database theory; in the setting of nominal sets (a semantic framework for modelling data with names); and in the modelling of concepts such as region disjointness for heap memory. In this paper, we identify unifying category-theoretic structure that encompasses these

different forms of independence and conditional independence. The proposed structure supports the ex- pected reasoning principles for notions of independence and conditional independence. We further identify associated notions of independent and local independent product, in which (conditional) independence is represented via a (fibred) monoidal structure, which is present in many examples.

*Keywords:* Independence, conditional independence, probability theory, database theory, nominal sets, separation logic, category theory, fibrations.

# Introduction

Relations of independence and conditional independence arise in multiple contexts. The aim of this paper is to provide axiomatic category-theoretic structure that, on the one hand, accounts for key constructions and reasoning principles associ- ated with relations of (conditional) independence in different contexts, and, on the other, includes a diversity of examples as instances of the structure. To emphasise the second point, the development is illustrated throughout by a series of running examples of notions of (conditional) independence that are of relevance to computer science. These examples concern three main flavours of independence.

* 1. *Stochastic* independence and conditional independence.

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These are fundamental relations in probability theory, widely applied in statistics. They are also key relations in the theory of Bayesian networks, where the issue of inference based on conditional independence is paramount [[12,](#_bookmark42)[10](#_bookmark40)].

* 1. *Logical* independence and conditional independence.

These are relations of (conditional) independence that arise in the context of sets (or multisets) of tuples; i.e., in the context of database tables. The principal relation of this form is *(conditional) variation independence* [[2](#_bookmark32)], which is closely related to the notion of *embedded multivalue dependency* in database theory, cf. [[25,](#_bookmark55)[28](#_bookmark58)]. See [[2](#_bookmark32)], for other examples of logical independence relations.

* 1. *Separatedness* relations.

Separatedness relations constrain the access of a number of distinct entities to an available resource, in order to ensure there is no overlap of access. Examples include: asserting that data contains disjoint names/atoms/nonces/. . . , as expressed, for example, by separatedness assertions about nominal sets [[22](#_bookmark52)]; and the partioning of a heap into disjoint regions, as expressed by the separating conjunction of separation logic [[21](#_bookmark46)].

All the above examples manifest themselves as instances of categories with *(con- ditional) independence structure*, as defined in the present paper. Such structure validates standard reasoning principles for (conditional) independence.

Our category-theoretic approach may be viewed as a generalisation of algebraic models of conditional independence, as exemplified by *graphoids* [[23](#_bookmark53)] and *sepa- roids* [[2](#_bookmark32)]. In particular, separoids (with least element) arise as a special case of our category-theory structure (in dual form), with categories restricted to preorders. For lack of space, we leave the exposition of this correspondence to a longer ver- sion of the paper. In the present version, we instead focus on the richer category- theoretic framework, whose breadth of scope is illustrated by the range of examples we consider. The category-theoretic setting naturally gives rise to a notion of *local independent product*, generalising the *conditional products* of Dawid and Studeny´ [[4](#_bookmark33)]. (Our formulation differs from the category-theoretic approach to conditional prod- ucts proposed by Flori and Fritz [[7](#_bookmark37)].) It also allows us to define a notion of *image tuple*, which plays an important role in formulating properties of independence. In categories of probability spaces, image tuples axiomatise properties of measure spaces carrying joint probability distributions.

The present paper fits in with current interest in logics of dependence and independence [[26,13](#_bookmark43)], the original *team semantics* of which is based *logical (in)dependence* as in point ([ii](#_bookmark1)) above. Athough variations of team semantics based on *stochastic independence* have been considered [[15](#_bookmark45)], no systematic semantic frame- work has been developed for general logics of dependence and independence. Our category-theoretic structure provides one possible foundation for such a develop- ment. Fleshing this out is a task for future research.

In its probabilistic incarnation, this paper also contributes to a broad ongo- ing research programme of developing category-theoretic methods for probabilistic

concepts, of which examples include [[9,](#_bookmark39)[27,](#_bookmark57)[17,](#_bookmark47)[14](#_bookmark44)]. The notion of *local independent product*, developed in the present paper, has also been applied in recent work on modelling ground references in programming languages [[18](#_bookmark48)].

# Independence structure

Let *C* be a category. A *multispan* in *C* is given by a pair

*X,* n *X fi*) *Y* ,

*i*

*i∈I*

(1)

where *X* is an object of *C* (the *domain*) and *{ fi }i∈I* is a family of morphisms indexed by a finite set *I*. Our usage of the prefix “multi” reflects the use of general finite index sets. Ordinary *spans* are simply multispans with 2-element index sets. We often write a multispan simply as *{ fi }i∈I* . (Technically, the domain *X* needs to be specified separately only when *I* is empty.)

We say that a collection of multispans *I* is:

* *stable* if, whenever *{fj}j∈J ∈I* and *h* : *I → J* is bijective, *{fh*(*i*)*}i∈I ∈ I*;
* *affine* if, whenever *{fj}j∈J ∈I* and *h* : *I → J* is injective, *{fh*(*i*)*}i∈I ∈I* .
* *relevant* if, whenever *{fj}j∈J ∈I* and *h* : *I → J* is surjective, *{fh*(*i*)*}i∈I ∈I* .

Clearly affine implies stable, as does relevant. Stability is a basic condition asserting that the family *I* treats multispans as multisets of morphisms. We henceforth ex- ploit this property by defining multispans using multiset operations, such as additive union, without directly specifying an index set.

A stable collection of multispans *I* is said to form a *multicategory* if:

* every singleton identity *{X* id*X*) *X}* is in *I*; and
* if *{X fi*) *Y } ∈I* and *{Y gi*)*j*

*i i∈I* *i*

*Zij}j∈Ji ∈I* for all *i ∈ I* then it follows that

the composition *{X gij ◦ fi*) *Zij}i∈I, j∈Ji* is also in *I*.

The above conditions specify that multispans in *I* are maps in a *fat symmetric multicategory*, in the sense of [[19](#_bookmark49), Def. A.2.1], although we have replaced the multi- domain of *loc. cit.* with a multi-codomain. In this paper, we concern ourselves with multicategories of the above form only, with maps always given as multispans.

**Definition 2.1 (Independence structure)** *Independence structure* on a cate- gory *C* is given by an affine multicategory of multispans *I* that further satisfies:

* every singleton family *{X f*) *Y }* is in *I* .

We say that a multispan *{fi}i∈I* is *independent* if it belongs to the collection *I*. We use *⊥⊥ {fi}i∈I* and ***⊥****i∈I fi* as notation for expressing the independence of *{fi}i∈I* . We also write *f* ***⊥*** *g* to express that *⊥⊥{f, g}*.

We present a sequence of examples of categories carrying independence structure.

The same categories will be used as running examples throughout the paper.

**Example 2.1 (Finite probability distributions)** The category **FinProb** of (positive) *ﬁnite probability distributions* has as objects pairs (*X, pX* ) where *X* is a finite (necessarily nonempty) set and *pX* : *X →* (0*,* 1] satisfyies *x∈X pX* (*x*)= 1. Morphisms (*X, pX* ) to (*Y, pY* ) are (necessarily surjective) functions *f* : *X → Y* such

Σ

*Y*

*x∈f−*1(*y*)

that *p*

(*y*) = Σ

*fi*)

*p* (*x*). A family *{* (*X, p* ) (*Y ,p* ) *}*

*X*

*X*

*i*

*Yi*

*i∈I*

is *independent*

if, for every family (*yi ∈ Yi*)*i∈I* , it holds that

Σ *pX* (*x*) = *pYi* (*yi*) *.*

*i*

*x ∈* T

*i∈I*

*f−*1(*yi*)

*i∈I*

This is the usual probabilistic notion of (mutual) independence of (*fi*)*i∈I* considered as a family of random variables over sample space *X*.

**Example 2.2 (Probability spaces)** Generalising the previous, we consider the category **Prob** of *probability spaces*. A *measurable space* is given by a set *X* together with a *σ*-algebra Σ*X ⊆ P*(*X*) (where *P*(*X*) is the powerset of *X*). A *probability space* is a triple (*X,* Σ*X, PX* ), where *PX* : Σ*X →* [0*,* 1] is a probability measure on Σ*X* . A morphism from (*X,* Σ*X, PX* ) to (*Y,* Σ*Y , PY* ) is a measurable function *f* : *X → Y* (i.e., *f−*1*B ∈* Σ*X* , for every *B ∈* Σ*Y* ) that is *measure-preserving* (i.e., *PY* (*B*) =

*P* (*f−*1(*B*)), for every *B ∈* Σ ). A family *{* (*X,* Σ *,P* ) *fi*) (*Y ,* Σ

*,P* ) *}* is

*X Y X X*

*i Yi*

*Yi i∈I*

*independent* if, for all familes (*B**i ∈* Σ*Yi* )*i∈I* , it holds that

*PX*

*i∈I*

*f−*1(*Bi*) = *PY* (*Bi*) *.*

*i*

*i*

*i∈I*

This is again the usual probabilistic notion of (mutual) independence of (*fi*)*i∈I* considered as random variables.

**Example 2.3 (Surjective maps)** The category **FinSur** has, as objects, finite nonempty sets *X* and, as morphisms from *X* to *Y* , surjective functions *f* : *X → Y* . A family *{ X fi*) *Y }* is *independent* if, for all (*y ∈ Y* ) it holds that

*i i∈I i i i∈I*

*f−*1(*yi*) */*= *∅ .*

*i*

*i∈I*

This notion of independence is called *variation independence* in [[2](#_bookmark32)]. It, and its conditional generalisation (see Example [5.3](#_bookmark27)), are closely related to the notion of *embedded multivalue dependency* in database theory, cf. [[25,](#_bookmark55)[28](#_bookmark58)].

**Example 2.4 (Nominal sets)** We recall the notion of *nominal set* [[11,](#_bookmark41)[22](#_bookmark52)]. Let **Perm**(A) be the permutation group on a countably infinite set A. An element *x*, in a set *X* with **Perm**(A)-action (*π, z*) *'→ π · z* : **Perm**(A) *× X → X*, is *supported* by a subset *S ⊆* A if, for every permutation *π* that fixes every element of *S* (i.e., *π · a* = *a* for every *a ∈ S*), it holds that *π · x* = *x*. A *nominal set* is a **Perm**(A)- action (*X, ·*) in which, for every *x ∈ X*, there exists a finite *S* that supports *x*. In a nominal set, every *x ∈ X* possesses a smallest supporting set, called *the support* of *x*, notation supp*X* (*x*). The category **Nom** of nominal sets (a.k.a. the Schanuel

topos) is the full subcategory of **Perm**(A)-actions with nominal sets as objects.

*i*

*Yi*

Define *{* (*X, ·X*

) *fi*) (*Y , ·*

) *}i∈I*

to be *independent* if, for all *x ∈ X* and *i, j ∈ I*,

*i /*= *j* =*⇒* supp*Yi* (*fi*(*x*)) *∩* supp*Yj* (*fj*(*x*)) = *∅ .*

The notion of independence in nominal sets is thus given by the notion of *separat- edness* in the sense of [[22,](#_bookmark52) *§*3.4].

**Example 2.5 (Heaps)** Let *V* be a set. A *V-valued heap X* is a pair (Loc*X,* val*X* ) where Loc*X* is a finite set (of *locations*) and val*X* is a function from Loc*X* to *V* . A morphism *f* : *X*  ) *Y* is an injective function *f* : Loc*Y →* Loc*X* such that val*Y* = val*X ◦ f* . Such a morphism can be thought of exhibiting val*Y* as a projection of val*X* onto Loc*Y* as a region of Loc*X* renamed under *f* . We write **Heap**(*V* ) for the category of *V*-valued heaps. A multispan *{ X fi*) *Y }* is defined to be *independent* if, for all *i, j ∈ I*,

*i i∈I*

*i /*= *j* =*⇒ fi*(Loc*Yi* ) *∩ fj*(Loc*Yj* )= *∅ ,*

where *fi*(Loc*Yi* ) is the image of *fi* in Loc*X* . Thus independence of a family over a heap asserts pairwise disjointness of the regions defining the projections.

In the last two examples (nominal sets and heaps), the property of mutual independence reduces to pairwise independence. That is, ***⊥****i∈I fi* holds if and only if, for every pair *i, j ∈ I* with *i /*= *j*, we have *fi* ***⊥*** *fj* . This property does not hold for the first three examples. Nonetheless, in all examples, it turns out that there are more subtle senses in which general mutual independence is determined by binary independence. In fact, we shall see that this is true in two different ways.

# Independent products

An *I*-indexed *independent product i∈I Yi* classifies *I*-indexed independent multi- spans via a bijection between independent multispans ([1](#_bookmark2)) and morphisms

*X* (*fi*)*i∈I*) *Y .*

*i*

*i∈I*

The definition makes use of the following useful auxiliary notion, which can be defined for any stable collection *I* of multispans on a category *C*.

**Definition 3.1 (***I***-neutral)** A multispan *{Y gj*) *Z }* is said to be *I-neutral*

*j j∈J*

if, for every multispan

*{X fi*) *Y } {X f*) *Y }* (2)

*i i∈I*

for which the composition *{X fi*) *Y } {X gj ◦*)*f*

*i i∈I*

the multispan ([2](#_bookmark9)) is also in *I*.

*Zj}j∈J* is in *I*, it holds that

**Proposition 3.2** *I-neutral multispans form a multicategory.*

*I*-neutrality will play a prominent role in this paper. Accordingly, we identify useful collections of *I*-neutral multispans in our example categories. A multispan

*{ X fi*) *Y }*

*i∈I*

is said to be *jointly monic* if, for every parallel pair of maps

*g, h* : *Z*  ) *X*, if *fi ◦ g* = *fi ◦ h* for all *i ∈ I* then *g* = *h*. In four of our example categories, **FinProb**, **Prob**, **FinSur** and **Nom**, the joint monicity of

*{ X fi*) *Y }* coincides with *joint injectivity* of the underlying functions (i.e., for all *x, xj ∈ X*, if *fi*(*x*)= *fi*(*xj*) for all *i ∈ I* then *x* = *xj*). In the case of **Heap**(*V* ), joint monicity coincides with *joint surjectivity* (i.e., for all *x ∈* Loc*X* , there exist *i ∈ I* and *y ∈* Loc*Yi* such that *fi*(*y*)= *x*).

*i i∈I*

**Proposition 3.3** *In* **FinProb***,* **FinSur***,* **Nom** *and* **Heap**(*V* )*, every jointly monic* *multispan is I-neutral (where I is as in Examples* [*2.1*](#_bookmark3) *and* [*2.3*](#_bookmark5)*–*[*2.5*](#_bookmark6) *respectively).*

**Proposition 3.4** *In* **Prob***, a multispan { X fi*) *Y*

*i*

*}i∈I*

*is I-neutral (for I as in*

*Example* [*2.2*](#_bookmark4)*) if the family {f—*1*B | i ∈ I, B ∈* Σ*Y } generates the σ-algebra* Σ*X.*

*i* *i*

**Definition 3.5 (Independent product)** Let *I* be a finite set. We say that a category *C* with independence structure *I* has *I-indexed independent products* if, for every family *{Yi}i∈I* of objects, there exist an object *i∈I Yi* and a multispan

*Y*

satisfying:

*{ Yi*

*i∈I*

*πi*)

*i*

*}i∈I*

(3)

* the multispan ([3](#_bookmark12)) is both independent and *I*-neutral; and
* if *⊥⊥{X fi*) *Y }* then there exists a unique morphism

*i i∈I*

*X* (*fi*)*i∈*)*I*

*Yi*

*i∈I*

*,* (4)

in *C*, such that *πi ◦* (*fi*)*i∈I* = *fi*, for all *i ∈ I*.

We say that *C* has *independent products* if it has *I*-indexed independent products for every finite set *I*.

To illustrate the role of *I*-neutrality, we expand the above definition in the case of nullary (i.e. *∅*-indexed) independent products.

**Definition 3.6 (Independent terminal object)** An *independent terminal ob- ject*, in a category with independence structure, is a terminal object **1** that satisfies the implication: *⊥⊥{X fj*) *Yi}i∈I* implies *⊥⊥{X fi*) *Yi}i∈I {X* !) **1***}*.

**Proposition 3.7** *In a category with independence structure, nullary independent products coincide with independent terminal objects.*

**Proposition 3.8** *A category with independence structure has independent products if and only if it has independent terminal object and binary independent products.*

Proposition [3.8](#_bookmark13) provides a first reduction of mutual independence to iterated bi- nary independence. The mutual independence propery *⊥⊥{f*1*,..., fn}* is equivalent

to the conjunction of a sequence of binary independence statements. For example,

*⊥⊥{f*1*, f*2*, f*3*, f*4*}* holds if and only if all of: *f*1 ***⊥*** *f*2; and (*f*1*, f*2) ***⊥*** *f*3, where (*f*1*, f*2) is the pairing of the binary independent product; and ((*f*1*, f*2)*, f*3) ***⊥*** *f*4.

All our example categories have independent products. By Proposition [3.8](#_bookmark13), it suffices to exhibit independent terminal object and binary independent products. The former is trivial, so we just define the latter. We do not describe the projection maps, which are obvious. In each case, the independence of the multispan ([3](#_bookmark12)) of projections is immediate, and *I*-neutrality follows from Propositions [3.3](#_bookmark10) and [3.4](#_bookmark11).

**Example 3.1 (Finite probability distributions)** In **FinProb**, the indepen- dent product *X ⊗Y* has underlying set *X ×Y* endowed with the product probability distribution *pX⊗Y* (*x, y*)= *pX* (*x*) *· pY* (*y*).

**Example 3.2 (Probability spaces)** In **Prob**, the independent product *X ⊗Y* is the product measurable space (*X × Y,* Σ*X×Y* ) with the product measure *PX ⊗ PY* .

**Example 3.3 (Surjective maps)** In **FinSur**, the independent product *X ⊗ Y* is simply the set-theoretic product *X × Y* .

**Example 3.4 (Nominal sets)** In **Nom**, the independent product *X ⊗ Y* is

*{*(*x, y*) *∈ X × Y |* supp*X* (*x*) *∩* supp*Y* (*y*)= *∅}*

with the **Perm**(A)-action inherited from the product. This is the *separated product*

defined in [[22,](#_bookmark52) *§*3.4].

**Example 3.5 (Heaps)** In **Heap**(*V* ), the independent product *X⊗Y* is defined by Loc*X⊗Y* = Loc*X* + Loc*Y* and val*X⊗Y* is the function [val*X,* val*Y* ]: Loc*X* + Loc*Y → V* defined by the universal property of the set-theoretic coproduct Loc*X* + Loc*Y* .

We end this section with a characterisation of categories with independent prod- uct structure in more familiar category-theoretic terms. Recall that *symmetric monoidal structure* on a category *C* is provided by a functor *⊗* : *C × C → C*, an object *I* (the *unit* ), together with natural isomorphisms

(*X ⊗ Y* ) *⊗ Z α*) *X ⊗* (*Y ⊗ Z*) *X ⊗ I λ*) *X X ⊗ Y σ*) *Y ⊗ X*

satisfying well-known coherence laws; see, e.g, [[20,](#_bookmark50) *§*XI.1].

A symmetric monoidal structure is said to have *projections* if the unit *I* is a terminal object [[16](#_bookmark51)]. Writing **1** for such a unit, define projection maps:

*π* = *Y ⊗ Y* id*Y*1 *⊗* !*Y*2) *Y ⊗* **1** *∼*=) *Y π* = *Y ⊗ Y* !*Y*1 *⊗* id*Y*2) **1** *⊗ Y ∼*=) *Y .*

1 1 2 1 1 2 1 2 2 2

We say the projections are *jointly monic* if *{π*1*, π*2*}* is a jointly monic span.

**Theorem 3.9** *The following are interderivable structures on a category C.*

* + *An independence structure with independent products.*
  + *A symmetric monoidal structure with jointly monic projections.*

# Tuple independence

Independent products provide a means of “pairing” maps *Y* (*f X g*) *Z* into a

single map *X* (*f,g*))

*Y ⊗ Z*, as long as *f, g* are independent. In reasoning about in-

dependence, however, it is useful to have a mechanism that allows non-independent maps to be paired. For example, it is useful to be able to assert that *h* is independent of a pair (*f, g*), in situations in which *f* is not independent of *g*.

In this section, we provide category-theoretic structure for defining “tuplings” of *I*-indexed multispans, whereby “pairings” are supplied by the case *|I|* = 2. A tupling comes with projection maps which extract its components. As in the case of independent products, these projections themselves form a multispan. In order to control the properties of tuplings, we require such projection multispans to belong to an assumed collection *J* , on which we impose suitable conditions.

*Assume that J is a given multicategory of multispans, in a category C, satisfying the additional property that every multispan in J is itself J -neutral (Deﬁnition* [*3.1*](#_bookmark8)*).*

**Definition 4.1 (***J* **-factorisation)** A *J -factorisation* of a *C* multispan

*{X fi*) *Y }* is a pair

*i i∈I*

*X p*) *P , {P qi*) *Y }*  (5)

*i*

*i∈I*

such that: the multispan *{P qi*) *Y }* is in *J* ; and *q ◦ p* = *f* , for every *i ∈ I*.

*i i∈I i* *i*

**Definition 4.2 (***J* **-image tuple)** A *J -image tuple* of a multispan *{X f*)*i*

in *C* is a pair

*Yi}i∈I*

*X ⟨fi⟩i∈I*) Img *⟨f ⟩*

*i i∈I*

*, {*Img *⟨fi⟩i∈I*

*ρi*) *Y }*

*i∈I*

*i*

that is initial among all *J* -factorisations of *{X fi*) *Yi}i∈I* ; i.e., given any *J* - factorisation ([5](#_bookmark15)), there existsa unique map Img *⟨fi⟩i∈I h*) *P* such that *h◦⟨fi⟩i∈I* = *p* and *qi ◦ h* = *ρi* for all *i ∈ I*. We say that the *J* -image tuple is *epimorphic* if the map *⟨fi⟩i∈I* is an epimorphism in *C*. (This will be used in Section [7](#_bookmark29).)

**Definition 4.3 (Image tuple structure)** *(Nonempty) image tuple structure* on a category *C* is given by a multicategory *J* of *J* -neutral multispans such that every (nonempty) multispan in *C* has a *J* -image tuple.

**Proposition 4.4** *Let J be a multicategory of J -neutral multispans in C. Then J provides image-tuple structure on C if and only if every multispan {X fi*) *Yi}i∈I with |I|≤* 2 *has a J -image.*

All our example categories carry image tuple structure. For simplicity, we de- scribe pairings only. Nullary and unary tuples are simpler. Higher-degree tuples can be derived via Proposition [4.4](#_bookmark17).

**Example 4.1 (Finite probability distributions)** Let *J* be the collection of jointly injective multispans in **FinProb**, cf. Proposition [3.3](#_bookmark10). Given a span

*Y* (*f X g* ) *Z*, the object Img *⟨f, g⟩* is the set-theoretic image of the func- tion (*f, g*) : *X → Y × Z* with the induced (pushforward) probability distribution *p*Img *⟨f,g⟩* (*y, z*)= *x∈*(*f,g*)*−*1(*y,z*) *pX* (*x*).

Σ

**Example 4.2 (Probability spaces)** Let *J* contain all multispans

*{ X fi* ) *Y }* that are both jointly injective and jointly generating, cf. Proposition [3.4](#_bookmark11). Given a span *Y* ( *f X g* ) *Z*, define Img *⟨f, g⟩* to be the set-theoretic image (*f, g*): *X → Y × Z*, with the induced Σ-algebra

*i i∈I*

ΣImg *⟨f,g⟩* = *{B ∩* (*f, g*)(*X*) *| B ∈* Σ*Y ×Z} ,*

where Σ*Y ×Z* is the product *σ*-algebra. The measure *P*Img *⟨f,g⟩* is defined by:

*P*Img *⟨f,g⟩* (*A*)= *PX* ((*f, g*)*—*1*A*) *,* for *A ∈* ΣImg *⟨f,g⟩* .

**Example 4.3 (Surjective maps)** Let *J* be the collection of jointly injective mul- tispans in **FinSur**. Given a span *Y* (*f X g*) *Z*, the object Img *⟨f, g⟩* is the set-theoretic image of (*f, g*): *X → Y × Z*.

**Example 4.4 (Nominal sets)** Let *J* be the collection of jointly injective mul- tispans in **Nom**. Given a span *Y* (*f X g* ) *Z*, the object Img *⟨f, g⟩* is the set-theoretic image of (*f, g*): *X → Y × Z*, with **Perm**(A)-action inherited from *Z*.

**Example 4.5 (Heaps)** Let *J* be the collection of jointly surjective multispans in **Heap**(*V* ), cf. Proposition [3.3](#_bookmark10). Given a span *Y* (*f X g*) *Z*, the object Img *⟨f, g⟩* is defined by: LocImg *⟨f,g⟩* = *f* (Loc*Y* ) *∪ g*(Loc*Z*), and valImg *⟨f,g⟩* (*x*)= val*X* (*x*).

Our motivation for introducing image tuple structure is to provide a mechanism for asserting independence properties between tuples of maps. To carry this out, we need to combine independence structure and image tuple structure.

**Definition 4.5 (Tuple independence structure)** *Tuple independence struc- ture*, on a category *C*, is given by a pair (*I, J* ) where *I* is independence structure, *J* is image tuple structure, and two properties connecting these structures hold.

**(TI1)** Every multispan in *J* is *I*-neutral.

**(TI2)** If ***⊥****i∈I X fi*) *Yi* then ***⊥****i∈I* Img *⟨fi⟩i∈I ρi*) *Yi*.

In the presence of independent products, (TI2) follows from a simpler property.

**Proposition 4.6** *Let C be a category with independence structure I and image tuple structure J . Suppose also that C has independent products. Then a sufficient condition for (TI2) to hold is that J contains every multispan (*[*3*](#_bookmark12)*) of projections from an independent product.*

**Proposition 4.7** *In our example categories,* **FinProb***,* **Prob***,* **FinSur***,* **Nom** *and* **Heap**(*V* )*, the independence structure I from Examples* [*2.1*](#_bookmark3)*–*[*2.5*](#_bookmark6)*, and the image tuple structure J from Examples* [*4.1*](#_bookmark18)*–*[*4.5*](#_bookmark19)*, together provide tuple independence structure.*

We use tuple independence structure to define an independence relation between

tuples. Consider multispans *{X fi*) *Y }m* and *{X gj*) *Z }n*

. We write

*i i*=1 *i j*=1

*⟨f*1*,..., fm⟩ ⊥⊥⟨g*1*,..., gn⟩* (6)

to express binary independence between the tuples generated by the respective multispans, i.e., to express that

*⊥⊥{⟨fi⟩*1*≤i≤m , ⟨gj⟩*1*≤j≤n} .*

Although use is made of binary independence only, the next result shows how re- lations of the form ([6](#_bookmark22)) can be used to express general mutual independence, thus giving a second way of deriving mutual independence from binary independence.

**Proposition 4.8** *⊥⊥{f*1*,..., fn} if and only if, for every i with* 2 *≤ i ≤ n, we have*

*⟨f*1*,..., fi—*1*⟩ ⊥⊥⟨fi⟩.*

We next show that relations of the form ([6](#_bookmark22)) enjoy the expected reasoning princi- ples for relations of binary independence between tuples, cf. [[12](#_bookmark42)]. In the statement, we write *⟨****f*** *⟩ ⊥⊥⟨****g****⟩* for *⟨f*1*,..., fm⟩ ⊥⊥⟨g*1*,..., gn⟩*, and *⟨⟩* for the empty tuple. (All morphisms are assumed to have the same domain.)

## Proposition 4.9

1. *⟨****f*** *⟩ ⊥⊥⟨****g****⟩ implies ⟨π****f*** *⟩ ⊥⊥⟨πj****g****⟩, where π and πj are permutations of the vectors*

***f*** *and* ***g*** *respectively.*

1. *⟨****f*** *⟩ ⊥⊥⟨ ⟩.*
2. *⟨****f*** *⟩ ⊥⊥⟨****g****⟩ implies ⟨****g****⟩ ⊥⊥⟨****f*** *⟩.*
3. *⟨****f*** *⟩ ⊥⊥⟨****g****,* ***h****⟩ implies ⟨****f*** *⟩ ⊥⊥⟨****g****⟩.*
4. *⟨****f*** *⟩ ⊥⊥⟨****g****,* ***h****⟩ and ⟨****h****⟩ ⊥⊥⟨****g****⟩ implies ⟨****f*** *,* ***h****⟩ ⊥⊥⟨****g****⟩.*

# Local independence structure

This section begins the second part of the paper, in which we address the notion of *conditional independence*. The main idea is to coherently impose independent structure on slice categories *C/U* . Informally, one thinks of an object *u* : *X →U* of *C/U* as presenting a *U* -indexed family *{u—*1(*z*)*}z∈U* , and of a morphism *X f*) *Y* from *u* to *v* : *Y →U* as presenting a family of maps

*{f* T*u−*1(*z*): *u—*1(*z*) ) *v—*1(*z*)*}z∈U*

between fibres. Under this intuition, independence of a multispan *{ X fi*) *Yi }i∈I* , between objects *u* : *X → U* and *{vi* : *Yi → U}i∈I* of *C/U* , can be thought of as expressing, for every *z ∈ U* , the mutual independence of *{fi* T*u−*1(*z*)*}i∈I* . This amounts to a statement of independence of maps conditional on *z ∈ U* .

The main definition of this section requires independence structure on every slice

*C/U* together with an axiom that relates the structure across different slices.

**Definition 5.1 (Independent square)** Suppose *IU* is independence structure on a slice category *C/U* . A commuting square in *C*

*X f* ) *Y*

*g* (7)

v v

*Z*  ) *U*

is said to be an *independent square* if *{f, g}∈ IU* . We also write *f* ***⊥****U g* for this.

**Definition 5.2 (Local independence structure)** *Local independence structure* on a category *C* is given by independence structure *IU* , on every slice category *C/U* , such that independent squares compose; i.e., given a commuting diagram in *C*

*X f* ) *Y g* ) *Z*

*u* (*A*) *v*

(*B*) *w*

(8)

v *r* v *s* v

)

)

*U V W*

in which (A) and (B) are independent squares, then so is the outside rectangle (AB).

All our example categories carry local independence structure, generalising the previously identified independence structure. For each category *C*, we define when a multispan *{ X fi*) *Y }* , between objects *u* : *X →U* and *{v* : *Y →U}* in the slice category *C/U* , is in *IU* .

*i i∈I i i i∈I*

**Example 5.1 (Finite prob. distributions)** A multispan *{ X f*)*i*

*Yi }i∈I* , in the

slice category **FinProb***/U* , is defined to be in *IU* if, for every *z ∈ U* and family (*yi ∈ v—*1(*z*))*i∈I* , it holds that

*i*

Σ *pX* (*x*) = *pYi* (*yi*) *.*

*−*1 *pU* (*z*)

*f* (*y* )

*pU* (*z*)

*x ∈* T

*i∈I*

*i*

*i*

*i∈I*

This equality asserts that *{fi}i∈I* , qua random variables, are mutually conditionally independent, conditioned on *u* qua random variable.

**Example 5.2 (Probability spaces)** A multispan *{ X fi*) *Yi }i∈I* , in the slice category **Prob***/U* , is defined to be in *IU* if *{fi}i∈I* , qua random variables, are mutually conditionally independent, conditioned on *u* qua random variable. Recall that, for general probability spaces, conditional independence is defined in terms of conditional probability in its formulation as a special case of conditional expectation.

This defines *{fi}i∈I* to be in *IU* if: for every family *{Bi ∈* Σ*Yi }i∈I* ,

**P**( *f—*1*Bi | u*)= **P**(*f—*1*Bi | u*) almost surely (w.r.t. *PX* T*u−*1(Σ

*i*

*U*

))).

*i∈I i∈I*

**Example 5.3 (Surjective maps)** A multispan *{ X fi*) *Y*

*i*

*}i∈I*

, in **FinSur***/U* ,

is defined to be in *IU* if, for every *z ∈ U* and family *{yi ∈ v—*1(*z*)*}i∈I* , we have:

*i*

*f—*1(*yi*) */*= *∅ .*

*i*

*i∈I*

**Example 5.4 (Nominal sets)** In **Nom**, a multispan *{ X fi*) *Y }* , in the slice category **FinSur***/U* , is defined to be in *IU* if, for every *x ∈ X* and *i, j ∈ I* we have

*i i∈I*

*i /*= *j* =*⇒* supp*Yi* (*fi*(*x*)) *∩* supp*Yj* (*fj*(*x*)) = supp*U* (*u*(*x*)) *.*

(It is equivalent to replace the above equality with an inclusion *⊆*, because every morphism *X u*) *U* in **Nom** satisfies supp (*u*(*x*)) *⊆* supp (*x*).)

*U* *X*

**Example 5.5 (Heaps)** In **Heap**(*V* ), a multispan *{ X fi*) *Y }* , in the slice category **Heap**(*V* )*/U* , is defined to be in *IU* if, for all *i, j ∈ I*,

*i i∈I*

*i /*= *j* =*⇒ fi*(Loc*Yi* ) *∩ fj*(Loc*Yj* )= *u*(Loc*U* ) *.*

Thus independence of a family over a heap asserts pairwise disjointness of regions outside of a shared region specified by the conditioning morphism.

# Local independent products

This section defines a local version of the independent products of Section [3](#_bookmark7). The definition needs to ensure the existence of independent products with respect to the local independence structure on every slice category, and also that this structure coheres in an appropriate way across slice categories.

**Definition 6.1 (Independent product square)** Given independence structure *IU* on a slice category *C/U* ,a commuting square ([7](#_bookmark23)) in *C* is said to be an *independent product square* if *{X f*) *Y, X g*) *Z}* is the span of projections from a binary independent product in *C/U* .

**Definition 6.2 (Local independent products)** A category *C* with local inde- pendence structure is said to have *local independent products* if the independence structure on each slice category *C/U* has independent products, and if every com- muting diagram ([8](#_bookmark24)) satisfies: if (B) is an independent product square and the outer rectangle (AB) is an independent square then (A) is also an independent square.

Given *X u*) *U* and *Y v*) *U* in *C* we use the following notation for the binary

independent product *u ⊗U v* of *u* and *v* as (tacitly understood) objects of *C/U* .

*X ⊗ Y π*2 ) *Y*

*U*

*π*1 *v*

v v

(9)

*X*  ) *U*

*u*

Note that *X ⊗U Y* is characterised as the apex of a universal independent square completing *u* and *v*.

We now exhibit binary local independent products in each of our example cate- gories (although restricting to a subcategory in the case of **Prob**). In each case we consider maps *X u*) *U* and *Y v*) *U* and define the object *X ⊗ Y* as above.

*U*

**Example 6.1 (Finite probability distributions)** In **FinProb**, the local inde- pendent product *X ⊗U Y* has the set-theoretic pullback *X ×U Y* as underlying set, endowed with the *relative product* probability distribution:

*pX⊗U Y*

(*x, y*)= *pX* (*x*) *· pY* (*y*) *.*

*pU* (*u*(*x*))

**Example 6.2 (Polish probability spaces)** Local independent products of prob- ability spaces amount to *relative products* in the sense of [[8,](#_bookmark38) *§*458L], which do not exist for arbitrary probability spaces. We therefore restrict **Prob** to a subcategory of well-behaved probability spaces. A *Polish probability space* is given by a Polish space *X* (i.e., a topological space whose topology arises from a complete separable metric) together with a probability measure *PX* on the *σ*-algebra Σ*X* of Borel sets. The category **PolProb** is the full subcategory of **Prob** on Polish probability spaces. The local independence structure of Example [5.2](#_bookmark26) restricts to **PolProb**. We now outline the construction of local independent products, which is somewhat involved. The object *X ⊗U Y* is given by the set-theoretic pullback *X ×U Y* , endowed with a topology as a Polish space that makes it a pullback in the category of Borel- measurable functions between analytic spaces. The Borel measure on Borel subsets of *X ×U Y* is defined by:

*PX⊗U Y* (*C*) = ∫*z∈U* (*Pu−*1(*z*) *⊗ Pv−*1(*z*))(*C*) d*PU ,*

where (*z, A*) *'→ Pu−*1(*z*)(*A*) : *U ×* Σ*X →* [0*,* 1] is a *regular conditional probability* for the function *u* : *X → U* , similarly (*z, B*) *'→ Pv−*1(*z*)(*B*) is a regular conditional probability for *v*, and *⊗* computes the product measure.

The above construction is known in ergodic theory, see, e.g., [[6](#_bookmark36), Def. 6.15]; Similar constructions have been used in computer science in the theory of Markov processes [[5,](#_bookmark35)[3](#_bookmark34)]. I have not found the universal property, as a universal independent square, in the literature.

**Example 6.3 (Nominal sets)** In **Nom**, *X ⊗U Y* is the set

*{*(*x, y*) *∈ X ×U Y |* supp*X* (*x*) *∩* supp*Y* (*y*)= supp*U* (*u*(*x*))*}* with the **Perm**(A)-action inherited from the pullback.

**Example 6.4 (Heaps)** In **Heap**(*V* ), Loc*X⊗U Y* is defined to be the set-theoretic

pushout Loc*X* +*U* Loc*Y* , and val*X⊗Y* is the function [val*X,* val*Y* ]: Loc*X* +*U* Loc*Y → V*

defined by the universal property of the pushout.

We end this section, by observing that local independent products give rise to fibred symmetric monoidal structure. For any *C* with local independent structure, define *C*ind to be the subcategory of the arrow category *C→*, containing every object of *C→*, whose morphisms are independent squares.

**Theorem 6.3** *If C has local independent products then:*

* 1. *The codomain functor* cod : *C*ind *→C is a ﬁbration.*
  2. *A morphism in C*ind *is cartesian iff it is an independent product square.*
  3. *The ﬁbre category over U is isomorphic to C/U.*
  4. *For every morphism U r*) *V in C, the reindexing functor r∗* : *C/V → C/U*

*maps multispans in IV to multispans in IU .*

* 1. *Every reindexing functor r∗* : *C/V → C/U is strong monoidal with respect to independent product in slice categories.*

# Conditional independence

In this section, we extend the tuple independence structure of Section [4](#_bookmark14) to a local version in slice categories. We call the resulting structure *conditional independence structure* since it supports reasoning principles about conditional independence.

Suppose *J* is a multicategory of *J* -neutral multispans in *C*. Define a collection

*J /U* of multispans in the slice category *C/U* by:

* A multispan *{ X fi*) *Yi }i∈I* , between objects *X u*) *U* and *{Yi vi*) *U}i∈I* in

*C/U* , is defined to be in *J /U* if the *C*-multispan *{fi}i∈I* is in *J* .

**Proposition 7.1** *If J is a multicategory of J -neutral multispans in C then J /U*

*is a multicategory of J /U-neutral multispans in C/U.*

**Proposition 7.2** *If J provides nonempty epimorphic image tuple structure on C*

*then J /U provides nonempty epimorphic image tuple structure on C/U .*

**Definition 7.3 (Conditional-independence structure)** A pair (*{IU }U∈|C|, J* ) provides *conditional-independence structure* on a category *C* if: *{IU }U∈|C|* provides local independent structure, *J* provides nonempty epimorphic image-tuple struc- ture, property (CI) below holds, and the two local versions below of (TI1) and (TI2) from Definition [4.5](#_bookmark20) hold in every slice category *C/U* .

**(CI)** In every commuting diagram ([8](#_bookmark24)): if *g◦f* ***⊥****W u* and *{g, v}∈J* then *f* ***⊥****V u*.

**(LTI1)** Every multispan in *J /U* is *IU* -neutral.

**(LTI2)** If *{X fi*) *Y }*

*i*

*i∈I*

*∈ IU*

is nonempty then the multispan of image-tuple

projections *{*Img *⟨f ⟩ ρi*) *Y }* is also in *I* .

*i i∈I i i∈I U*

The above can be also be given an alternative formulation that emphasises that it implies the existence of tuple independence structure on every slice category. How- ever, the chosen formulation is the one that is more convenient to work with, and to verify in examples. For example, one of its advantages is that it admits the following simplification in the presence of local independent products, cf. Proposition [4.6](#_bookmark21).

**Proposition 7.4** *Suppose C has local independent structure {IU }U∈|C| and nonempty epimorphic image-tuple structure J such that (CI) holds. Suppose fur- ther that C has terminal object and local independent products. Then (LTI1) holds if and only if (TI1) holds. Also, a sufficient condition for (LTI2) to hold is that J contains every span {π*1*, π*2*} of projections from a binary local independent product.*

*X* (*π*1 *X ⊗ Y π*2) *Y*

*U*

**Proposition 7.5** *For our main example categories,* **FinProb***,* **Prob***,* **FinSur***,* **Nom** *and* **Heap**(*V* )*, the local independence structure {IU }U∈|C| deﬁned in Exam- ples* [*5.1*](#_bookmark25)*–*[*5.5*](#_bookmark28) *and the image tuple structure J deﬁned in Examples* [*4.1*](#_bookmark18)*–*[*4.5*](#_bookmark19) *together provide conditional independence structure.*

Analogously to Section [4](#_bookmark14), we show that conditional independence structure val- idates standard reasoning principles for conditional independence. Henceforth, we assume that (*{IU }U∈|C|, J* ) is conditional independence structure on a category *C*.

Given *{X fi*) *Y }n*

, *{X gj*) *Z }m*

and *{X ek*) *W }l*

, we write

*i i*=1

*j j*=1

*k k*=1

*⟨f*1*,..., fn⟩ ⊥⊥⟨g*1*,..., gm⟩| ⟨e*1*,..., el⟩* (10) to express that the commuting diagram below is an independent square.

*X ⟨****e****,* ***f*** *⟩* ) Img *⟨****e****,* ***f*** *⟩*

*⟨****e****,* ***g****⟩*

v

*∼*= *◦⟨ρ*1*,..., ρl⟩*

v

Img *⟨****e****,* ***g****⟩*

*∼*= *◦⟨ρ*1*,..., ρl⟩*

) Img *⟨****e****⟩*

Here, we write, e.g., Img *⟨****e****,* ***f*** *⟩* for the image tuple Img *⟨e*1*,..., el, f*1*,..., fn⟩* and *ρ*1*,..., ρl* are the corresponding projections, see Definition [4.2](#_bookmark16). The codomain Img *⟨ρ*1*,... .ρl⟩* of each tuple*⟨ρ*1*,..., ρl⟩* can be shown to be isomorphic to Img *⟨****e****⟩*, thus providing the two unnamed isomorphisms in the diagram.

The independent square above can be understood as expressing binary con- ditional independence between the tuples *⟨****f*** *⟩* and *⟨****g****⟩*, with *⟨****e****⟩* acting as the conditioning tuple, as suggested by the notation ([10](#_bookmark30)). The result below states

that the relation ([10](#_bookmark30)) indeed enjoys the expected laws of conditional independence, cf. [[1,](#_bookmark31)[24,](#_bookmark54)[12,](#_bookmark42)[2](#_bookmark32)].

## Theorem 7.6

1. *⟨****f*** *⟩ ⊥⊥⟨****g*** *⟩ | ⟨****e*** *⟩ implies ⟨π*(***f*** )*⟩ ⊥⊥⟨πj*(***g*** )*⟩ | ⟨πjj*(***e*** )*⟩, where π, πj and πjj are permutations of the vectors.*
2. *⟨****f*** *⟩ ⊥⊥⟨****e*** *⟩| ⟨****e*** *⟩.*
3. *⟨****f*** *⟩ ⊥⊥⟨****g*** *⟩| ⟨****e*** *⟩ implies ⟨****g*** *⟩ ⊥⊥⟨****f*** *⟩| ⟨****e*** *⟩.*
4. *⟨****f*** *⟩ ⊥⊥⟨****g****,* ***h*** *⟩| ⟨****e*** *⟩ implies ⟨****f*** *⟩ ⊥⊥⟨****g*** *⟩| ⟨****e*** *⟩.*
5. *⟨****f*** *⟩ ⊥⊥⟨****g*** *⟩| ⟨****e****,* ***h*** *⟩ and ⟨****f*** *⟩ ⊥⊥⟨****h*** *⟩| ⟨****e*** *⟩ implies ⟨****f*** *⟩ ⊥⊥⟨****h****,* ***g*** *⟩| ⟨****e*** *⟩*
6. *⟨****f*** *⟩ ⊥⊥⟨****h****,* ***g*** *⟩| ⟨****e*** *⟩ implies ⟨****f*** *⟩ ⊥⊥⟨****g*** *⟩| ⟨****e****,* ***h*** *⟩.*

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