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Modal Rules are Co-Implications

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**Abstract**

In [13], it was shown that modal logic for coalgebras dualises—concerning definability— equational logic for algebras. This paper establishes that, similarly, modal rules dualise implications: It is shown that a class of coalgebras is definable by modal rules iff it is closed under H (images) and Σ (disjoint unions). As a corollary the expressive power of rules of infinitary modal logic on Kripke frames is characterised.

# Introduction

The investigation of the relationship of modal logic and coalgebras is moti- vated by coalgebras being a generalisation of transition systems. A first major achievement was Moss’ paper [15] on ‘coalgebraic logic’ where it was shown how to formulate a modal logic for Ω-coalgebras depending in a canonical way on the functor Ω : **Set** *→* **Set**. Since then, modal logics as a specification language for coalgebras have been investigated in a number of papers, e.g. [17,18,12,10,9,5,16]. On the other hand, it is also interesting to apply cate- gorical and (co)algebraic tools in order to obtain new insights in modal logic. For example, it was shown in [13] that one can characterise the expressive power of infinitary modal logics on Kripke frames by dualising the proof of Birkhoff’s variety theorem (which, in turn, characterises the expressive power of equational logic on algebras). Here, we continue this line of research.

We start from the correspondence between implications

*i*

*i∈I*

*ti* = *t' → s* =

*s'*, *I* a set or class, and algebras. The classical result on implicationally defin-

able classes is due to Banaschewski and Herrlich [3] (see also Wechler [20]): A class of algebras is implicationally definable iff it is closed under subalgebras and products (and isomorphisms).

Similarly to [13], our aim here is to use the duality of algebras and coal- gebras to prove a dual of this theorem for coalgebras. As it turns out, the concept dual to implication is that of a *modal rule*. Theorem 4.1 establishes that a class of coalgebras is rule-definable iff it is closed under images of mor- phisms and disjoint unions. Theorem 5.2 applies this result to Kripke frames: A class of Kripke frames is definable by rules of infinitary modal logic iff it is closed under images of p-morphisms and disjoint unions.

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An algebraically similar but logically different approach is followed by Gumm [8]. There, also the results on equationally and implicationally de- finable classes of algebras are dualised. But the logic used for coalgebras is different: A formula *ϕ* is an element of the carrier of a cofree coalgebra *TC* and *ϕ* holds in a coalgebra *M* iff for all valuations *α* : *UM → C* the formula *ϕ* is not in the image of the induced morphism *α*# : *M → TC*. If we consider the semantics of a modal rule or an co-implication in the sense of Gumm as given by the corresponding coreflection morphism (see the proof of theorem 4.1 or chapter 2 in [14]), then both approaches are equivalent.

A previous version of this draft has been electronically available since February 1999. It was presented at the 11th International Congress of Logic, Methodology and Philosophy of Science, Cracow, 1999. The main improve- ment over this draft is that theorem 4.1 does not depend any more on the existence of cofree coalgebras in **Set**Ω. As a consequence, the application to Kripke frames in theorem 5.2 does not require a bound on the degree of branch- ing of the frames. This result is quite surprising and can not be transferred in an obvious way to the case of the covariety theorem in [13].

# Coalgebras

We introduce notation and briefly review coalgebras as models for modal logic (for more information see [13,14]). The classical paper on coalgebras is Rut- ten [19].

Coalgebras are given w.r.t. a category *C* and an endofunctor Ω : *C → C*. An Ω-coalgebra *M* = (*UM, fM* ) is then given by an object *UM ∈ C* and an arrow *fM* : *UM →* Ω(*UM* ) in *C*. Ω-coalgebras form a category *C*Ω where a *coalgebra morphism α* : (*UM, fM* ) *→* (*UN, fN* ) is an arrow *α* : *UM → UN* in *C* such that Ω*α ◦ fM* = *fN ◦ α*.

As an example consider the functor Ω : **Set** *→* **Set** given by Ω*X* = *PX* where *P* denotes powerset. 1 Then Ω-coalgebras are *Kripke frames*: given a coalgebra *M* and a world *x ∈ UM* , *fM* (*x*) is the set of successors of *x*. Coalgebra morphisms in **Set***P* are functional bisimulations, i.e. p-morphisms.

A remark on epis and monos in **Set**Ω: Since a morphism *α* : (*UM, fM* ) *→* (*UN, fN* ) is also a function *α* : *UM → UN* , it is immediate that if *α* is epi (mono) in **Set**, *α* is also epi (mono) in **Set**Ω. The converse is also true for epis (see Rutten [19], 4.7), that is, a morphism in **Set**Ω is epi iff it is surjective. Concerning monos it holds: *α ∈* **Set**Ω is mono in **Set** iff it is strong mono in **Set**Ω (see the appendix), that is, a morphism in **Set**Ω is strong mono iff it is injective.

1 This only defines Ω on sets. On functions Ω is defined in the standard way, *P* being the covariant powerset functor: Given *f* : *X → Y* , Ω*f* = *λA ∈ PX.{f* (*a*) : *a ∈ A}*.

* 1. *Cofree Coalgebras*

We first give the definition of cofree coalgebras and then show how they are interpreted in the context of modal logic. To define the notion of a *cofree coalgebra* consider the diagram below:

*UTC*

`❅ #

*α*

*ϵC* ❅

❄ ❅

*C* ✛ *UM*

*α*

Let Ω be a functor. An Ω-coalgebra *TC* (and a mapping *ϵC* : *UTC → C*) is called *cofree over C* iff for all Ω-coalgebras *M* and all mappings *α* : *UM → C* there is a unique morphism *α*# : *M → TC* such that the diagram commutes. 2 Compared to universal algebra, the *set of colours C* corresponds to the set of variables and a *colouring α* to a valuation of variables.

As in the case of Ω = *P*, cofree coalgebras may not exist in **Set**Ω. This problem can be circumvented by extending the functor Ω on **Set** to a functor on **SET** 3 by defining Ω*K* = *{*Ω*X* : *X ⊂ K, X* a set*}* for classes *K*. It then follows from a theorem by Aczel and Mendler [2] that for every functor Ω on **Set** and all *C ∈* **Set** the cofree coalgebras *TC* exist in **SET**Ω. Thus, in the following, we will allow, without further mentioning, that cofree coalgebras exist in **SET**Ω instead of **Set**Ω.

As an example consider Ω = *P* and *C* = *PP* where *P* is a set of proposi- tional variables. Let *M* be an Ω-coalgebra, i.e. a Kripke frame. The functions *α* : *UM → C* are valuations: every world *x* in *M* is assigned the set of propo- sitional variables holding in *x*, that is, (*M, α*) is a *Kripke model*. (Note that an Ω-coalgebra *M* plus a valuation *α* : *UM → C* is a *C ×* Ω-coalgebra; and a morphism between *C ×* Ω-coalgebras *f* : (*M, α*) *→* (*N, β*) is an Ω-morphism *f* : *M → N* such that *β ◦ f* = *α*, see [13].) The diagram above then shows that any Kripke model (*M, α*) has a unique p-morphic image in the model (*TC, ϵC*). We can think of (*TC, ϵC*) as the disjoint union of all models based on Ω-frames with the additional feature that any two bisimilar worlds are identified.

* 1. *Strong-mono-Coreflective Classes of Coalgebras*

The concept of a strong-mono-coreflection is a generalisation of the concept of cofreeness and dualises the concept of a strong epireflection (see Borceux [4], I.3.6). Strong monos do appear here because they are the categorical way of describing subcoalgebras (see the appendix). Coreflective classes are used

2 Note that every morphism *α*# : *M → TC ∈* **Set**Ω is by definition of morphisms in **Set**Ω

also a mapping *α*# : *UM → UTC ∈* **Set**.

3 **SET** is the category of classes and class maps as in Aczel [1], chapter 7, and Aczel and Mendler [2].

because, on the one hand, they are precisely those classes closed under the operators H (closure under images of coalgebra morphisms) and Σ (closure under disjoint unions (coproducts, sums) of coalgebras), and because, on the other hand, the ‘coreflection morphisms’will allow us to see what the defining modal rules will be (section 4).

Let Ω : **Set** *→* **Set** be a functor. A **strong-mono-coreflection** for a class

*K* of Ω-coalgebras is given by coalgebras *RKM* and *strong mono*morphisms

*K* : *RKM → M* for all *M ∈* **Set**Ω such that for all *N ∈ K* every morphism

*ϵ*

*M*

*α* : *N → M* factors uniquely through *ϵK* :

*M*

*K*

*ϵ*

*M* ✛ *M RKM*

✻

`❅ *α∗*

*α* ❅

❅

*N*

*RKM* is called the *coreflection* of *M* and *ϵK*

*M*

the *coreflection morphism* of *M* .

**Proposition 2.1 (Existence of strong-mono-coreflections)** *Let* Ω *be a functor on* **Set** *and K a class of* Ω*-coalgebras. Then for all M ∈* **Set**Ω *there*

*is RKM ∈* **Set**Ω *and a strong mono ϵK*

*M*

: *RKM → M ∈* **Set**Ω *such that for*

*all N ∈ K and all α* : *N → M in* **Set**Ω *there is a unique α∗* : *N → RKM in*

**Set**Ω *such that ϵK ◦ α∗* = *α. Moreover, RKM ∈* HΣH*K.*

*M*

**Proof.** Let *M ∈* **Set**Ω. Let *A* = *{α* : *N → M | N ∈ K}* be the collection of all coalgebra morphisms *N → M* with *N ∈ K*. Now, the union of the images of all *α ∈ A* defines a subcoalgebra *RKM* of *M* with inclusion *ϵK* . 4 Clearly, for each *N ∈ K* the above factorisation property holds. Moreover, the fact that union is a quotient of a disjoint union shows that *RKM ∈* HΣH*K*. *✷*

*M*

**Definition 2.2 (Strong-mono-coreflective-classes, smc)** *Let* Ω *be a func- tor on* **Set** *and K a class of* Ω*-coalgebras. K is called strong-mono-coreflective, or* **smc** *for short, iff it is closed under isomorphisms and contains all core- flections RKM.* 5

Strong-epi-reflective classes of algebras are characterised as being exactly those classes of algebras that are closed under subalgebras and products. Du- ally, smc-classes of coalgebras are characterised by closure under homomorphic images (denoted by H) and closure under disjoint unions, i.e. coproducts (de- noted by Σ).

**Proposition 2.3** *Let* Ω *be a functor on* **Set** *and K a class of* Ω*-coalgebras.*

*K is smc iff it closed under* H *and* Σ*.*

4 Every coalgebra morphism *α ∈* **Set**Ω factors through its image Im *α*, see Rutten [19], theorem 7.1; and the union of images of coalgebra morphisms always exists, see [19], theo- rem 6.4.

5 Categorically: *K* is smc iff it is closed under isomorphisms and the inclusion functor

*K →* **Set**Ω has a right adjoint *RK* with the counit (i.e. *ϵK* ) being strong mono.

*M*

**Proof.** “only if”: Closure under H is (the dual) of [4], I.3.6.4. For closure under Σ let *Mi ∈ K* (for all *i ∈ I*) and *M* the sum of all *Mi*. Note that *RKMi* is isomorphic to *Mi*. We have to show that *RKM* is isomorphic to *M* . *ϵK*

*M*

being a strong mono, it suffices to show that *ϵK*

*M*

is epi in **Set** (and hence epi in

**Set**Ω). This follows from the observation that every *x ∈ UM* is in the image of an inclusion in*i* : *Mi → M* and every inclusion factors through *ϵK* .

*M*

“if”: Follows from *RKM ∈* HΣH*K*. *✷*

Closure under H and Σ is equivalent to closure under the operator HΣ. This is dual to the fact that, in universal algebra, SP is closure under subalgebras and products (see Gumm and Schro¨der [6] for details on closure operators on coalgebras). We can therefore phrase the proposition above as *K* smc iff *K* = HΣ(*K*).

* 1. *An Example*

To illustrate the notions above and their connection to modal logic we give an example. Let Ω = B *× P*, where B is the set of Booleans. That is, every state is assigned (*b, Y* ), where *b* is a Boolean and *Y* a set. We interpret *b* as the truth value of a fixed proposition and *Y* as the set of successors. A modal language for this functor is build from the usual connectives, modal operators and propositional variables from a set *P* , plus a propositional constant denoted by *start* . A **Set**Ω-coalgebra *M* = (*UM, f* ) is a Kripke frame together with a predicate interpreting *start* . To be more precise, let *α* : *UM → PP, x ∈ UM, p ∈ P* . Then (boolean cases as usual and *π*1*, π*2 denoting the projections from the product B *×P* to its components):

|  |  |  |
| --- | --- | --- |
| *M, α, x |*= *start* | *⇔* | *π*1 *◦ f* (*x*)= *true* |
| *M, α, x |*= *p* | *⇔* | *p ∈ α*(*x*) |
| *M, α, x |*= *✷ϕ* | *⇔* | *∀y ∈ π*2 *◦ f* (*x*): *M, α, y |*= *ϕ* |

The states *x* satisfying the first clause are called states marked by *start* . Next, we want to axiomatise a subclass of these Kripke frames by modal rules. A modal rule *ϕ/ψ* (where *ϕ, ψ* are modal formulas) is interpreted via

*M |*= *ϕ/ψ ⇐⇒ ∀α* : *UM → PP* : *M, α |*= *ϕ ⇒ M, α |*= *ψ*

Modal axioms are rules with true premise. Now, consider the following rules:

(refl) *✷p → p* (trans) *✷p → ✷✷p* (start) *start → ✷p/p*

The first two are the well-known axioms defining reflexivity and transitivity on Kripke frames. The third one is the start rule from Kro¨ger [11]. In the

presence of reflexivity and transitivity it expresses that every state has to be reachable from a state marked by *start* .

Call Φ the set of the three rules above and let *K* be the class of Kripke frames defined by Φ. We show that *K* is smc. Define *RKM* as the largest subcoalgebra of *M* satisfying Φ (that is, to find *RKM* , take the largest subcoal- gebra of *M* that is reflexive and transitive and then cut off all states that are

not reachable by a state marked by *start* ). *ϵK* : *RKM → M* is the canonical

*M*

embedding and it is a strong mono since it is injective. Recalling the defini- tion of a coreflective subcategory, it remains to show that for all *N ∈* **Set**Ω satisfying Φ it holds that for all *f* : *N → M* there is a unique *g* : *N → RKM* such that *f* = *ϵK ◦ g*:

*M*

*K*

*ϵ*

*M* ✛ *M RKM*

.✻

`❅ .

*g*

❅ .

*f* ❅ .

*N*

Consider a factorisation *N →e*

Im *f →m*

*M* of *f* . Since rules are invariant under

taking images (see proposition 3.5) it follows that Im *f |*= Φ. Moreover *m* : Im *f → M* is a subcoalgebra of *M* and since *RKM* is the largest subcoalgebra

of *M* satisfying Φ, *m* factors through *ϵK*

*M*

*M*

as *m* = *ϵK*

* *g'* for some *g'*. Now,

*g* = *g' ◦ e* is the required morphism and *g* is uniquely determined since *ϵK* is

*M*

injective.

Finally, let us note that *K* is closed under images and disjoint unions (coproducts) but not under subcoalgebras. Hence *K* is an example of a co- quasivariety that is not a covariety.

# Modal Logics for Coalgebras

There are many different kinds of modal logics but most of them share the following features that are essential for a logic for coalgebras: formulas are evaluated in points (worlds, states) and they are invariant under bisimulations. Compared to the paper on covarieties [13] the definition below changed a little: Since we have no requirement that the functor Ω is bounded, a logic has to have formulas for arbitrary large sets of colours.

**Definition 3.1** *Let* Ω *be a functor. A* **modal logic for coalgebras** *L is given by the following:*

* + *a class Col of sets (the sets in Col are called sets of colours of L), where Col contains for each cardinal κ a set with cardinality ≥ κ, and for each C ∈ Col a class of formulas LC,*
  + *for all C ∈ Col, for all M ∈* **Set**Ω*, and for all valuations α* : *UM → C a*

*relation |*=*C ⊂ UM × LC. (Write M, α, x |*= *ϕ for* (*x, ϕ*) *∈ |*=*C .)*

(*M,α*)

(*M,α*)

* + *for all C ∈ Col, M, N ∈* **Set**Ω*, α* : *UM → C, β* : *UN → C, ϕ ∈ LC,*

*x ∈ UM, and all C ×* Ω*-morphisms* 6 *f* : (*M, α*) *→* (*N, β*)*, it has to hold*

*M, α, x |*= *ϕ ⇔ N, β, f* (*x*) *|*= *ϕ.*

The last condition says that formulas have to be invariant under bisimulations respecting not only the structure of the Ω-coalgebras but also the given val- uations. As usual, *M, x |*= *ϕ*, (*M |*= *ϕ*) are defined by quantifying over all valuations (and all elements) of *M* .

Formulas *ϕ ∈ LC* define subsets of the cofree coalgebra (*TC, ϵC*). It is useful to introduce the following notation:

[[*ϕ*]]*T C,єC* = *{x ∈ UTC* : *TC, ϵC,x |*= *ϕ}.*

From the invariance of the formulas under bisimulations it follows the **funda- mental property** allowing to reduce validity w.r.t. a valuation in any model to validity in the cofree models:

*M, α |*= *ϕ ⇐⇒* Im *α*# *⊂* [[*ϕ*]]*T C,єC .*

Next, we show that dualising the concept of an implication in algebra we obtain the notion of a modal rule. The reader might want to recall the semantics of implications in universal algebra. First two basic facts: Let *X* be a set of variables and *TX* be the term algebra over variables *X*. Then every valuation *α* : *X → A* has a unique lifting to an algebra morphism *αb* : *TX → A*. And every algebra morphism *αb* : *TX → A* determines a congruence relation on *TX* that we denote by ker *αb*. Next, consider an

implication *ti* = *t' → s* = *s'*. It determines two congruence relations

*i∈I* *i*

*'*

*P, Q* on the carrier of *TX*, *P* standing for the relation induced by

*i∈I ti* = *ti*

and *Q* for the relation induced by *s* = *s'*. Now, it is not difficult to see that

the implication holds in an algebra *A* iff *P ⊂* ker *αb ⇒ Q ⊂* ker *αb* for all *α* : *X → A*. This characterisation of implications is dualised by the following definition of modal rules.

**Definition 3.2 (Rules)** *Given two formulas ϕ, ψ ∈ LC we call the expres- sion ϕ/ψ a rule. The class of all rules built from formulas in LC is denoted by* Ru*C. Deﬁne |*=

*M |*= *ϕ/ψ iff ∀α* : *UM → C* : Im *α*# *⊂* [[*ϕ*]]*T C,єC ⇒* Im *α*# *⊂* [[*ψ*]]*T C,єC ,*

**Definition 3.3 (rule-definable)** *Let* Ω: **Set** *→* **Set** *be a functor and L be a modal logic for* Ω*-coalgebras. K ⊂* **Set**Ω *is rule-deﬁnable iff there are classes* Φ*C ⊂* Ru*C, C ∈ Col, such that M ∈ K ⇔ ∀C ∈ Col* : *M |*= Φ*C.*

Up to now, we have only required that formulas of modal logic are evalu- ated in points and are invariant under bisimulations. We need an additional

6 Recall that *f* : (*M, α*) *→* (*N, β*) is a *C ×* Ω-morphisms iff *f* is an Ω-morphism such that

*β ◦ f* = *α*.

property that guarantees enough expressive power.

**Definition 3.4** *A modal logic for coalgebras L is called* **expressive** *if for all C ∈ Col and every C ×* Ω*-subcoalgebra S of* (*TC, ϵC*) *there is a formula ϕ such that US* = *{x ∈ TC* : *TC, ϵC,x |*= *ϕ}.*

An important consequence of our definition of a modal logic for coalgebras is that rules are preserved under images and disjoint unions.

**Proposition 3.5** *Let L be a modal logic for* Ω*-coalgebras and let K be a rule- deﬁnable class of* Ω*-coalgebras. Then K is closed under the operators* H *and* Σ*.*

**Proof.** Let *C ∈ Col* and *ϕ, ψ ∈ LC*.

“H”: Suppose *M ∈ K* and *f* : *M → N* epi in **Set**Ω. We have to show

*M |*= *ϕ/ψ* =*⇒ N |*= *ϕ/ψ*. For a contradiction assume that *N*

*|*=*/*

*ϕ/ψ*, i.e.

there exist *β* : *UN → C* and *y ∈ UN* s.t. *N, β, y |*= *ϕ* and *N, β, y |*=*/ ψ*. Define

*α* : *UM → C* by *α* = *β ◦ f* , i.e. *f* is a *C ×* Ω-bisimulation between (*M, α*) and (*N, β*). Now, since *f* epi in **Set**Ω implies *f* epi in **Set** and since *|*= is compatible with *C ×* Ω-bisimulations, there is *x ∈ UM* such that *M, α, x |*= *ϕ*

and *M, α, x |*=*/ ψ*, which is the desired contradiction.

“Σ”: Similar to the above. Let (*Mi*)*i∈I* be a family of models in *K* and

*M* = Σ*i∈IMi*. Suppose *M*

*|*=*/*

*ϕ/ψ*. That is, there exist *α* : *UM → C* and

*x ∈ UM* such that *M, α, x |*= *ϕ* and *M, α, x |*=*/ ψ*. Since sums in **Set**Ω are

constructed as sums in **Set** 7 there is a *j ∈ I* such that *x ∈ Mj*. Now, using that the inclusion in*j* of *Mj* into *M* is a bisimulation shows *Mj, ij,x |*= *ϕ* and

*Mj, ij,x |*=*/ ψ*. *✷*

# Rule-Definable Classes of Coalgebras

We have already seen that rule-definable classes are closed under H and Σ. To show the converse, one uses that every class *K* closed under H and Σ is strong- mono-coreflective (smc) and then shows that *K* is ‘defined’by its coreflection morphisms.

**Theorem 4.1 (Characterisation of rule-definable classes)**

*Let* Ω : **Set** *→* **Set** *be a functor and L an expressive modal logic for* Ω*- coalgebras. Then a class K is deﬁnable by rules of L iff K is closed under* H *and* Σ*.*

**Proof.** “only if” is proposition 3.5. For “if” note that *K* is smc by propo- sition 2.3. The defining rules are now determined by the coreflection mor-

phisms *ϵK* : *RKM → M* . Define Φ*C* for *C ∈ Col* as follows. For *M ∈* **Set**Ω,

*M*

*|UM| ≤ |C|*, choose an injective mapping *i* : *UM → C*. By expressive-

ness there are formulas *ϕC , ψC ∈ LC* such that **[***ϕC* ]]*T C,єC* = Im *i*# and

*M M M*

[[*ψC* ]]*T C,єC* = Im(*i*# *◦ ϵK* ). Let Φ*C* = *{ϕC /ψC*

: *M ∈* **Set**Ω*, |UM| ≤ |C|}*.

*M M M M*

7 Categorically: *U* : **Set**Ω *→* **Set** creates all colimits, see [19], theorem 4.5.

We have to show *N ∈ K ⇔ ∀C ∈ Col* : *N |*= Φ*C*.

“ *⇒* ”: Let *ϕC /ψC ∈* Φ*C* and suppose *N, β |*= *ϕC* , i.e. Im *β*# *⊂* [[*ϕC* ]]*T C,єC* .

1. *M M M*

By definition of *ϕC* there is *i* : *UM → C* with **[***ϕC* ]]*T C,єC* = Im *i*#. Hence, *β*#

*M*

*M*

factors through *i*# as *β*# = *i*# *◦ f* for some *f* : *N → M* . Since *N ∈ K* and *K*

is smc, *f* factors through *ϵK* as *f* = *ϵK ◦ g* for some *g* : *N → RKM* . It follows

*M*

*M*

Im *β*# = Im(*i*# *◦ ϵK ◦ g*) *⊂* Im(*i*# *◦ ϵK* )= [[*ψC* ]]*T C,єC* , i.e. *N, β |*= *ψC* .

*M M M M*

“ *⇐* ”: Let *N ∈* **Set**Ω. Choose *C ∈ Col*, *|C| ≥ |UN|*, and *i* : *UN → C*

such that Im *i*# = [[*ϕC* ]]*T C,єC* . We show Im *i*# = Im(*i*# *◦ ϵK*) (which implies,

*N N*

since *i*# and *ϵK* injective, *N RKN* and hence *N ∈ K*). “*⊃*” is obvious and

*N*

Im *i*# *⊂* [[*ψC* ]]*T C,єC* = Im(*i*# *◦ ϵK*) holds due to *N, i |*= *ϕC /ψC* . *✷*

1. *N N N*

**Remark 4.2** *In the case of* Ω = *P the cofree coalgebras TC do not exist in* **Set**Ω *but in* **SET**Ω*. This has no effect on the proof since for all α*# : *M → TC, M ∈* **Set**Ω*, also* Im *α*# *∈* **Set**Ω*. Note that this reasoning cannot be transferred to the proof of the covariety theorem in [13] since there one needs to consider coreflections RKTC (called FKC in [13]) of the cofree coalgebras which usually are only in* **Set**Ω *if TC ∈* **Set**Ω *(which is not the case for* Ω= *P and C /*= *{}).*

# Rule Definable Classes of Kripke Frames

The generality of theorem 4.1 allows for many applications. For example it is possible to give a version of this theorem for coalgebraic logic (Moss [15]). For covarieties instead of smc-classes this has been carried out in [13]. Coalgebraic logic has the advantage that it gives a definition of a modal logic for coalgebras for all functors Ω (preserving weak pullbacks). But here we only want to give one example of a (concrete) modal logic. We choose Ω = *P* and show that our theorem becomes a statement about rule-definable classes of Kripke frames.

We denote with *ML* the infinitary modal logic built from a proper class of propositional variables **Prop**, the constant *⊥*, the operators *¬, ✷* and conjunc- tions over any set of formulas. and *✸* are defined as abbreviations. When *P ⊂* **Prop** and *P* a set we write *ML*(*P* ) for the class of formulas taking only variables from *P* .

In order to apply theorem 4.1 we need the following lemma:

**Lemma 5.1** *The collection of all ML*(*P* ) *where P ranges over subsets of* **Prop** *is an expressive modal logic for coalgebras w.r.t. the functor P. Fur- thermore, the classes* Ru*PP (see deﬁnition 3.2) are the classes of rules of ML*(*P* )*.*

**Proof.** Instantiating *Col* of definition 3.1 by *{PP* : *P ⊂* **Prop***,P* a set*}* and

*C*

*|*=

(*M,α*)

by the usual satisfaction relation of modal logic, it is immediate that

the conditions of definition 3.1 are met. Expressiveness can be shown as

in [13]. Next, let *ϕ/ψ ∈* Ru*PP* and *M* be a Kripke frame. Then, according to the definition of a rule in modal logic, *M |*= *ϕ/ψ* iff *∀α* : *UM → PP* : *M, α |*= *ϕ ⇒ M, α |*= *ψ*, matching definition 3.2. *✷*

**Theorem 5.2** *Let K be a class of Kripke frames. Then K is rule-deﬁnable iff K is closed under p-morphic images and disjoint unions.*

**Proof.** Recall that *Col* = *{PP* : *P ⊂* **Prop***,P* a set*}*. “if”: By lemma 5.1 and theorem 4.1.

“only if”: *K* is rule-definable, that is, there is a class Φ *⊂ {ϕ/ψ* : *ϕ, ψ ∈ ML}* such that *K* = *{M ∈* **Set**Ω : *M |*= Φ *}*. Let *KPP* = *{M ∈* **Set**Ω :

*M |*= Φ *∩* Ru*PP }*. We can then write *K* = *{KPP* : *PP ∈ Col}* and, by

proposition 3.5, *K* = *{*HΣ*KPP* : *PP ∈ Col}*. Now, it follows from a general

fact on closure operators that *K ⊃* HΣ *{KPP* : *PP ∈ Col}* and, therefore,

*K ⊃* HΣ*K*. *✷*

Some readers might feel that the ‘detour’ via coalgebras is unneccessary and a proof of the theorem from first principles could be shorter. Let us therefore emphasise that our proof is in fact easy and short: once we estab- lished that a class *K* closed under p-morphic images and disjoint unions is

determined by the coreflection morphisms *ϵK*

*M*

(see proposition 2.3), it remains

only to check that the coreflection morphisms (or more generally, generated subframes, ie., strong-monos) are indeed definable by rules (see lemma 5.1 and the proof of theorem 4.1).

# Conclusion

This paper showed that the duality between quotients in algebra and subcoal- gebras in coalgebra does not only allow for a dual of Birkhoff’s variety theorem but also for a dual of the result characterising implicationally definable classes of algebras. Moreover, it was shown that the modal concept corresponding to an implication is not that of a formula *ϕ → ψ* but that of a rule *ϕ/ψ*.

To study finitary specification languages for coalgebras containing (the expressiveness of) modal rules and appropriate deduction calculi is left for future research.

Let us mention that the duality of algebras and coalgebras has been used here as a heuristics. The proof of theorem 4.1 is not the formal (categorical) dual of a corresponding proof for algebras since it depends on the category of sets (and coalgebras over **Set** are dual to algebras over **Set***op*). As shown in

[14] it is possible to give an account of the duality of modal and equational logic which makes the duality precise in a categorical sense.

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# A Strong Monomorphisms

We establish that the strong monos in a category of coalgebras **Set**Ω are precisely the injective morphisms, ie. the subcoalgebras. First recall the definition of a strong mono (see eg. Borceux [4], I.4.3).

**Definition A.1 (Strong mono)** *A mono f* : *M → N is called strong iff for all epis g* : *X → Y and all u* : *X → M, v* : *Y → N such that f ◦ u* = *v ◦ g there is a (necessarily unique) w* : *Y → M such that w ◦ g* = *u and f ◦ w* = *v:*

*X g* ✲ *Y w....*

✠

*u* ❄ *...* *v*

❄

*M*  ✲ *N f*

From a technical point of view, this factorisation property is crucial to the results of this paper (it is used implicitely in almost all of the proofs). An immediate consequence is the following useful proposition.

**Proposition A.2 (Extremal monos)** *A strong mono m is extremal, that is, if*

*m factors as m* = *f ◦ e with e epi, then e is iso.*

In the category **Set** monos, extremal monos, and strong monos are all simply injective mappings. In the category of Ω-coalgebras monos need not be injective (see Gumm and Schr¨oder [7]). The following proposition shows that strong monos are precisely the injective morphisms in **Set**Ω.

**Proposition A.3**

1. *If f ∈* **Set**Ω *is mono as a mapping in* **Set** *then f is strong mono in* **Set**Ω*.*
2. *Every morphism f ∈* **Set**Ω *factors uniquely as an epi followed by a strong mono. Moreover, this factorisation is obtained as the epi/mono factorisation of f in* **Set***.*
3. *Strong monos in* **Set**Ω *are monos in* **Set***.* **Proof.**
   1. Let *f, g, u, v ∈* **Set**Ω as in the diagram above and *f* mono in **Set**, *g* epi in **Set**Ω. Since *g* epi in **Set** (Rutten [19], 4.7) the required *w* exists as a mapping in **Set**. It remains to show that *w* is a morphism in **Set**Ω, i.e. Ω*w ◦fY* = *fM ◦w* where *fY , fM* are the structure maps of the coalgebras *Y, M* , respectively. Drawing the appropriate diagram, this follows from *g, u* morphisms in **Set**Ω, *g* epi in **Set** and *w ◦ g* = *u* in **Set**.
   2. Let *h* : *X → Y ∈* **Set**Ω and *UX →e*

Im *h →m*

*UY* the factorisation of *h* in

**Set** through its image Im *h*. We have to show that Im *h* can be equipped in a unique way with a coalgebra structure such that *e, m* become morphisms in **Set**Ω. This follows from the “diagonal fill in”:

*UX e* ) Im *h*

Ω*e ◦ fX*

*f*Im *h* /

v s/

/

*fY ◦ m*

v

Ω Im *h*

) Ω*UY*

Ω*m*

The diagonal fill in exists because either Im *h /*= *{}* and Ω*m* mono 8 and *e* epi or Im *h* = *{}* and the empty map makes the diagram commute.

That *m* is strong in **Set**Ω follows from (1). Uniqueness of the factorisation in

**Set**Ω may be found in [4], I.4.4.5.

* 1. By (2), a strong mono *h* : *X → Y* in **Set**Ω factors as epi/strong-mono *h* = *e◦m*. Since *h* is also extremal and *e* is epi, it follows *e* iso. *m* is strong, so is *h*.

*✷*

8 Im *h /*= *{}* and *m* mono implies *m* split mono, hence Ω*m* mono.