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Borel Kernels and their Approximation, Categorically

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**Abstract**

This paper introduces a categorical framework to study the exact and approximate semantics of probabilistic programs. We construct a dagger symmetric monoidal category of Borel kernels where the dagger-structure is given by Bayesian inversion. We show functorial bridges between this category and categories of Banach lattices which formalize the move from kernel-based semantics to predicate transformer (backward) or state transformer (forward) semantics. These bridges are related by natural transformations, and we show in

particular that the Radon-Nikodym and Riesz representation theorems - two pillars of probability theory - define natural transformations.

With the mathematical infrastructure in place, we present a generic and endogenous approach to approxi- mating kernels on standard Borel spaces which exploits the involutive structure of our category of kernels. The approximation can be formulated in several equivalent ways by using the functorial bridges and natural transformations described above. Finally, we show that for sensible discretization schemes, every Borel ker- nel can be approximated by kernels on finite spaces, and that these approximations converge for a natural choice of topology.

We illustrate the theory by showing that our approximation scheme can be used in practice as an ap- proximate Bayesian inference algorithm and as an approximation scheme for programs in the probabilistic network specification language ProbNetKAT.

*Keywords:* Probabilistic programming, probabilistic semantics, Markov process, Bayesian inference, approximation

# Introduction

Finding a good category in which to study probabilistic programs is a subject of active research [[22,17,](#_bookmark52)[6,](#_bookmark41)[21](#_bookmark56)]. In this paper we present a dagger symmetric monoidal

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category of kernels whose dagger-structure is given by Bayesian inversion. The advantages of this new category are two-fold.

Firstly, the most important new construct introduced by probabilistic program- ming, *viz. Bayesian inversion*, is interpreted completely straightforwardly by the

*†*-operation which is native to our category. In particular we never leave the world of kernels and we therefore do not require any normalization construct. Consider for example the following simple Bayesian inference problem in Anglican ([[24](#_bookmark59)])

( defquery example

( let [x ( sample ( normal 0 1))]

( observe ( normal x 1) 0.5)

( > x 1)))

The semantics of this program is built easily and compositionally (by functoriality of *†*) in our category:

* The second line builds a Borel space equipped with a normally distributed prob- ability measure – an object (R*, μ*) of our category.
* The (normal x 1) instruction builds a Borel kernel – a morphism *f* : (R*, μ*) *→*

(R*, ν*) in our category.

* The observe statement builds the Bayesian inverse of the kernel – the morphism

*f†* : (R*, ν*) *→* (R*, μ*) in our *†*-category.

* Finally, the kernel *f†* is evaluated, i.e. the denotation of the program above is *f†*(0*.*5)(]1*, ∞*[). Since *f†* is only defined *μ*-a.s., we understand the formal ex- pression *f†*(0*.*5)(]1*, ∞*[) as the evaluation of *some* representative of *f†* at (0*.*5) and (]1*, ∞*[). The choice of representative is *μ*-a.s. irrelevant, which justifies the notation. Note also that Anglican cleanly separates the modelling process from the inference process. The snippet of code above belongs to the modelling level, whereas the choice of a representative of *f†* – that is to say of an inference al- gorithm – belongs to the inference level, which is specified separately. We only claim to provide a semantics at the modelling level.

Secondly, since Bayesian inference problems are in general very hard to compute (although the one given above has an analytical solution), it makes sense to seek approximate solutions, i.e. *approximate denotations* to probabilistic programs. As we will show, our category of kernels comes equipped with a generic and endogenous approximating scheme which relies on its involutive structure and on the structure of standard Borel spaces. Moreover, this approximation scheme converges for any choice of kernel for a natural choice of topology.

## Main contributions and structure of the paper.

Sections [2](#_bookmark3)-[6](#_bookmark30) align in a chain of logical dependencies culminating in our Con- vergence of Approximations Theorem (Theorem [6.3](#_bookmark32)) which relies on the framework developed in *§*[2](#_bookmark3), the link with operators developed in *§*[3](#_bookmark13)-[4](#_bookmark17) which allows us to access a natural operator topology, and the presentation of our approximation scheme in

*§*[5](#_bookmark22). More precisely, our main contributions can be summed up section by section as

follows:

* We build a category **Krn** of Borel kernels (*§*[2](#_bookmark3)) and we show how two kernels which agree almost everywhere can be identified under a categorical quotient operation. This technical construction is what allows us to define *Bayesian inversion* as an involutive functor, denoted *†*. This is a key technical improvement on [[6](#_bookmark41)] where the *†*-structure [4](#_bookmark1) was hinted at but was not functorial. We show that **Krn** is a dagger symmetric monoidal category.
* We introduce the category **BL***σ* of Banach lattices and *σ*-order continuous positive operators as well as the K¨othe dual functor (*−*)*σ* : **BL**op *→* **BL***σ* (*§*[3](#_bookmark13)). These will play a central role in studying convergence of our approximation schemes.

*σ*

* We provide the first [5](#_bookmark2) categorical understanding of the Radon-Nikodym and the Riesz representation theorems. These arise as natural transformations between functors relating kernels and Banach lattices (*§*[4](#_bookmark17)).
* We show how the *†*-structure of **Krn** can be exploited to approximate kernels by averaging (*§*[5](#_bookmark22)). Due to an important structural feature of **Krn** (Th. [2.1](#_bookmark4)) every kernel in **Krn** can be approximated by *ﬁnite* kernels.
* We describe a natural class of approximations schemes where the sequence of approximating kernels converges to the kernel to be approximated. The notion of convergence is given naturally by moving to **BL***σ* and considering convergence in the Strong Operator Topology (*§*[6](#_bookmark30)).
* We show how Bayesian inference can be performed approximately by showing that the *†*-operation commutes with taking approximations. This provides the basis for an approximate Bayesian inference algorithm which we apply to a simple Anglican program. A second application, as an approximation scheme for the denotation of ProbNetKAT programs [[13,](#_bookmark46)[20](#_bookmark55)] is given in the Appendix.

All the proofs can be found in the Appendix.

## Related work.

Quasi-Borel sets have recently been proposed as a semantic framework for higher- order probabilistic programs in [[22](#_bookmark57)]. The main differences with our approach are: (i) unlike [[22,](#_bookmark57)[21](#_bookmark56)] we never leave the realm of kernels, and in particular we never need to worry about normalization. This makes the interpretation of observe statements,

i.e. of Bayesian inversion, simpler and more natural. However, (ii) unlike the quasi- Borel sets of [[22](#_bookmark57)], our category is not Cartesian closed. We can therefore not give a semantics to all higher-order programs. This shortcoming is partly mitigated by the fact that the category of Polish spaces, on which our category ultimately rests, does have access to many function spaces, in particular all the spaces of functions whose domain is locally compact. We can thus in principle provide a semantics to higher-order programs, provided that *λ*-abstraction is restricted to locally compact

4 Suggested to us by Chris Heunen.

5 To the best of our knowledge.

spaces like the reals and the integers, although this won’t be investigated in this paper.

The approximation of probabilistic kernels has been a topic of investigation in theoretical computer science for nearly twenty years (see e.g. [[10,](#_bookmark45)[8,](#_bookmark43)[9,](#_bookmark44)[4](#_bookmark38)]), and for much longer in the mathematical literature (e.g. [[5](#_bookmark40)]). Our results build on the formalism developed in [[4](#_bookmark38)] with the following differences: (i) we can approximate kernels, their associated *stochastic operator* (backward predicate transformer), or their associated *Markov operator* (forward state transformer) with equivalent ease, and move freely across the three formalisms. (ii) Given a kernel *f* : *X* d *Y* , we can define its approximation *fj* : *Xj → Y j* along any quotients *Xj* of *X* and *Y j* of *Y* as in [[4](#_bookmark38)], but we can also ‘internalize’ the approximation as a kernel *f∗* : *X → Y* of the original type. Morally *fj* and *f∗* are the same approximation, but the second approximant, being of the same type as the original kernel, can be compared with it. In particular it becomes possible to study the convergence of ever finer approximations, which we do in Section [6](#_bookmark30). Finally, (iii) we opt to work with Banach lattices rather than the normed cones of [[18,](#_bookmark53)[4](#_bookmark38)] because it allows us to formulate the operator side of the theory very naturally, and it connects to a large body of classic mathematical results ([[2,](#_bookmark36)[25](#_bookmark60)]) which have been used in the semantics of probabilistic programs as far back as Kozen’s seminal [[16](#_bookmark51)].

# A category of Borel kernels

In [[6](#_bookmark41)] the first three authors presented a category of Borel kernels similar in spirit to the construction of this section, but with a major shortcoming. As we will shortly see, our category **Krn** of Borel kernels can be equipped with an involutive functor – a *dagger* operation *†* in the terminology of [[19](#_bookmark54)] – which captures the notion of *Bayesian inversion* and is absolutely crucial to everything that follows. In [[6](#_bookmark41)] this operation had merely been identified as a map, i.e. not even as a functor. In this section we show that Bayesian inversion defines a *†*-structure on a more sophisticated – but measure-theoretically very natural – category of kernels.

* 1. *Standard Borel spaces and the Giry monad*

A *standard Borel space* – or *SB space* for short – is a measurable space (*X, S*) for which there exists a Polish topology *T* on *X* whose Borel sets are the elements of *S*, i.e. such that *S* = *σ*(*T* ) (see e.g. [[15](#_bookmark47)] for an overview). Let us write **SB** for the category of standard Borel spaces and measurable maps. One key structural feature of **SB** is the following:

**Theorem 2.1** *Every* **SB** *object is a limit of a countable co-directed diagram of ﬁnite spaces.*

**Proof.** This is a consequence of the Isomorphism Theorem (Theorem 15.6 of [[15](#_bookmark47)]): two SB spaces are isomorphic iff they have the same cardinality. Uncountable SB spaces are thus all isomorphic to the Cantor space 2N which is the limit of the countable co-directed diagram (2*n*)*n∈*N with the connecting morphisms *pn*+1*,n* :

2*n*+1 *→* 2*n* truncating binary words of length *n* +1 at length *n*. Similarly all SB-spaces of cardinality *ℵ*0 are isomorphic to the one-point compactification of N, which is the limit of the countable co-directed diagram (*n*)*n∈*N with the connecting morphisms *pn*+1*,n* : *n*+1 *→ n, i '→* min(*i, n*). The case of finite SB spaces is trivial.*2*

The *Giry monad* was originally defined in two variants [[14](#_bookmark48)]:

* + - As an endofunctor G**Pol** of **Pol**, the category of *Polish spaces*, one sets G**Pol**(*X, T* ) to be the space of Borel probability measures over *X* together with the weak topology. This space is Polish [[15](#_bookmark47), Th 17.23], and the Portmanteau Theorem [[15,](#_bookmark47) Th 17.20]) gives multiple characterizations of the weak topology.
    - As an endofunctor G**Meas** of **Meas**, the category of *measurable spaces*: G**Meas**(*X, S*) is the set of probability measures on *X* together with the initial *σ*-algebra for the maps *evA* : G**Meas**(*X, S*) *→* R*,μ '→ μ*(*A*)*,A ∈ S*.

In both cases the Giry monad is defined on an arrow *f* : *X → Y* as the map *f∗* which sends a measure *μ* on *X* to the *pushforward measure f∗μ* on *Y* , defined as *G*(*f* )(*μ*)(*B*)= *f∗μ*(*B*) := *μ*(*f−*1(*B*)) for *B* a measurable subset of *Y* . We want to define the Giry monad on the category **SB** of standard Borel spaces (and measurable maps), and the two versions of the Giry monad described above offer us natural ways to do this: given an SB space (*X, σ*(*T* )) we can either compute G**Pol**(*X, T* ) and take the associated standard Borel space, or directly compute G**Meas**(*X, σ*(*T* )). Fortunately, the two methods agree.

**Theorem 2.2 ([**[**15**](#_bookmark47)**], Th 17.24)** *Let* B : **Pol** *→* **SB** *denote the functor sending a Polish space* (*X, T* ) *to its associated SB-space* (*X, σ*(*T* )) *and leaving morphisms unchanged, then*

G**Meas** *◦* B = B *◦* G**Pol***.*

We define the *Giry monad* on SB spaces to be the endofunctor G : **SB** *→* **SB** defined by either of the two equivalent constructions above. The monadic data of G is given at each SB space *X* by the unit *δX* : *X →* G*X, x '→ δx*, the Dirac *δ* measure at *x*, and the multiplication *mX* : G2*X →* G*X,* P *'→ λA.* G*X evAd*P. We refer the reader to [[14](#_bookmark48)] for proofs that *δX* and *mX* are measurable.

∫

* 1. *The construction of* **Krn**

Let us denote by **SB**G the Kleisli category associated with the Giry monad (G*, δ, m*). We denote Kleisli arrows, i.e. Markov kernels, by *X* d *Y* , and we call such an arrow *deterministic* if it can be factorized as an ordinary measurable function followed by the unit *δ*. Kleisli composition is denoted by *•*. The category *∗↓* **SB**G has arrows

*∗* d *X* as objects, where *∗* is the one point SB space (the terminal object in **SB**). An arrow from *μ* : *∗* d *X* to *ν* : *∗* d *Y* is a **SB**G arrow *f* : *X* d *Y* such that *ν* = *f • μ*, i.e. such that *ν*(*A*) = *X f* (*x*)(*A*)*dμ* for any measurable subset *A* of *Y* . This situation will be denoted in short by *f* : (*X, μ*) d (*Y, ν*), and we will call a pair (*X, μ*) a *measured SB space*.

∫

We construct a quotient of *∗↓* **SB**G, such that two *∗↓* **SB**G arrows are identified

if they disagree on a null set w.r.t. the measure on their domain. For *g, gj* : (*X, μ*) d

(*Y, ν*), we define *N* (*g, gj*)= *{x ∈ X | g*(*x*) */*= *gj*(*x*)*}*.

**Lemma 2.3** *N* (*g, gj*) *is a measurable set.*

**Proof.** By Dinkyn’s *π*-*λ* theorem, two finite measures are equal if and only if they agree on a *π*-system generating the *σ*-algebra. Any standard Borel space admits such a countable *π*-system (any countable basis for a Polish topology generating the *σ*-algebra). Let *{Bn}n∈*N be such a *π*-system. Then, for all *x ∈ X*, *g*(*x*) */*= *gj*(*x*) *⇔*

*∃n.g*(*x*)(*Bn*) */*= *gj*(*x*)(*Bn*). Hence,

*N* (*g, gj*) = *∪n{x ∈ X | g*(*x*)(*Bn*) */*= *gj*(*x*)(*Bn*)*}*

= *∪n{x ∈ X | evB* (*g*(*x*)) */*= *evB* (*gj*(*x*))*}*

*n n*

= *∪n*(*evB ◦ g − evB ◦ gj*)*—*1(R *\ {*0*}*)

*n n*

By definition of the measurable structure of G(*Y* ), *evBn*

* *g −evBn*
* *gj* is measurable,

hence *N* (*g, gj*) is also measurable. *2*

We now define a relation *∼* on Hom((*X, μ*)*,* (*Y, ν*)) by saying that for any two arrows *g, gj* : (*X, μ*) d (*Y, ν*), *g ∼ gj* if *μ*(*N* (*g, gj*)) = 0. This clearly defines an equivalence relation on Hom((*X, μ*)*,* (*Y, ν*)). In order to perform the quotient of the category *∗ ↓* **SB**G modulo *∼*, we need to check that it is compatible with composition.

**Proposition 2.4** *If g ∼ gj, then h • g • f ∼ h • gj • f.*

**Proof.** We first show that if *g ∼ gj*, then *h• g ∼ h• gj*. Clearly, for any space *V* and any deterministic function *u* : *Y → V* , *N* (*u◦g, u◦gj*) *⊆ N* (*g, gj*). By definition of the Kleisli category, *h• g* = *mZ ◦* G(*h*) *◦g* and similarly for *h• gj*. Taking *u* = *mZ ◦* G(*h*), we obtain that *μ*(*N* (*h • g, h • gj*)) *≤ μ*(*N* (*g, gj*)).

It is now enough to show that *λ*(*N* (*g • f, gj • f* )) = 0. Let us reason contraposi-

tively. We have:

*λ*(*N* (*g • f, gj • f* )) *>* 0

*⇔* ∫*w∈W* 1*N* (*g•f,g′•f* )(*w*) *dλ >* 0

*→* ∫*w∈W* Σ*n∈*N 1(*g•f* )(*w*)(*Bn*)*/*=(*g′•f* )(*w*)(*Bn*) *dλ >* 0

*→En* ∫ 1

*w∈W*

(*g•f* )(*w*)(*Bn*)*/*=(*g •f* )(*w*)(*Bn*)

*′ dλ >* 0

*→* ∫*w∈W |*(*g • f* )(*w*)(*Bn*) *−* (*gj • f* )(*w*)(*Bn*)*| dλ >* 0

*⇔* ∫*w∈W* ∫*x∈X |g*(*x*)(*Bn*) *− gj*(*x*)(*Bn*)*| df* (*w*) *dλ >* 0

*⇔* ∫*x∈X |g*(*x*)(*Bn*) *− gj*(*x*)(*Bn*)*| dμ >* 0

∫

*EX*+*⊆X*

*→*

*x∈X*+ *g*(*x*)(*Bn*) *− gj*(*x*)(*Bn*) *dμ >* 0

*→* ∫*x∈X*+ 1*g*(*—*)(*Bn*)*>g′*(*—*)(*Bn*)(*x*) *dμ >* 0

*→* ∫*x∈X*+ 1*N* (*g,g′*)(*x*) *dμ >* 0

The last line implies *μ*(*N* (*g, gj*)) *>* 0, a contradiction. *2*

**Definition 2.5** Let **Krn** be the category obtained by quotienting *∗ ↓* **SB**G hom- sets with *∼*.

The following Theorem is of great practical use and generalizes the well-known result for deterministic arrows.

**Theorem 2.6 (Change of Variables in Krn)** *Let f* : (*X, μ*) d (*Y, ν*) *be a* **Krn***-morphism. For any measurable function φ* : *Y →* R*, if φ is ν-integrable, then φ • f* (*x*)= *Y φ df* (*x*) *is μ-integrable and*

∫

*φ dν* =

∫

∫

*Y* *X*

*φ • f dμ*

**Proof.** If *φ* is *ν*-integrable, there exists a monotone sequence *{φn}* of simple functions such that *φn ↑ φ* and *Y φndν → Y φdν < ∞*. By definition each

*i*=0

*αi*1*Bi* , and by unravelling the definition we have

∫ ∫

*φn* = Σ*k*

1*Bi dν* = *ν*(*Bi*)= *f* (*x*)(*Bi*)*dμ* = 1*Bi df* (*x*)*dμ* = (1*Bi • f* )*dμ*

∫ ∫ ∫ ∫ ∫

*Y X X Y* *X*

From which it follows that

*φndν* =

∫

*Y*

∫*X* ∫*Y*

Σ*i*=0

*k*

*αi*1*Bi df* (*x*)*dμ* =

(*φn • f* )*dμ*

∫

*X*

and the result follows from the Monotone Convergence Theorem (MCT). *2*

* 1. *The symmetric monoidal structure of* **Krn**

The symmetric monoidal structure of **Krn** is defined on a pair of objects (*X, μ*)*,* (*Y, ν*) by the Cartesian product and the product of measures, i.e. (*X, μ*) *⊗* (*Y, ν*) = (*X × Y, μ ⊗ ν*). On pairs of morphisms *f* : (*X, μ*) d (*Y, ν*) and *fj* : (*Xj, μj*) d (*Y j, νj*) it is defined by (*f ⊗ fj*)(*x, xj*) := *f* (*x*) *⊗ fj*(*xj*). The un- itors, associator and braiding transformations are given by the obvious bijections.

* 1. *The dagger structure of* **Krn**

**Krn** has an extremely powerful inversion principle:

## Theorem 2.7 (Measure Disintegration Theorem, [[15](#_bookmark47)], 17.35) *Let*

*f* : (*X, μ*) d (*Y, ν*) *be a* deterministic **Krn***-morphism, there exists a unique morphism f†* : (*Y, ν*) d (*X, μ*) *such that*

*μ*

*f • f†* = id(*Y,ν*)*.* (1)

*μ*

The kernel *f†* is called the *disintegration of μ along f* . As our notation suggests, the disintegration depends fundamentally on the measure *μ* over the domain, how- ever we will omit this subscript when there is no ambiguity. The following lemma relates disintegrations to conditional expectations.

*μ*

**Lemma 2.8 ([**[**7**](#_bookmark42)**])** *Let f* : (*X, μ*) *→* (*Y, ν*) *be a deterministic* **Krn***-morphism, let*

*σ*(*f* ) *be the σ-algebra generated by f, and let φ* : *X →* R *be measurable, then μ-a.e.*

*φ • f† • f* = E [*φ | σ*(*f* )]

We can extend the definition of (*−*)*†* to *any* **Krn**-morphism *f* : (*X, μ*) d (*Y, ν*) in a functorial way, although *f†* will not in general be a right inverse to *f* . The construction of *f†* is detailed in [[6](#_bookmark41)], but let us briefly recall how it works. The category **SB** has products which are built in the same way as in **Meas** via the product of *σ*-algebras [6](#_bookmark8) . Given any kernel *f* : (*X, μ*) d (*Y, ν*), we can canonically construct a probability measure *γf* on the product *X × Y* of SB-space by defining it on the rectangles of *X × Y* as

∫

*γf* (*A × B*)= 1*A*(*x*) *· f* (*x*)(*B*) *dμ.* (2)

*x∈X*

Equivalently, *γf* = (*δX ⊗ f* ) *•* Δ*X • μ*, where Δ*X* : *X → X × X* is the diagonal map. Letting *πX* : *X × Y → X* and *πY* : *X × Y → Y* be the canonical projections, we observe that G*πX* (*γf* ) = *μ* and G*πY* (*γf* ) = *ν*: in other words, *γf* is a coupling of

*μ* and *ν*. The disintegration of *γf* along *πY* is a kernel *π†*

*Y*

: (*Y, ν*) *→* (*X × Y, γf* ).

Finally we define:

*Y*

*f†* = *πX • π† .* (3)

6 Unlike the category **Krn**, which does *not* have products.

The following **Krn** diagram sums up the situation:

*f*

*π† s* z*,*

*πY ss* zz*,\_*

(*X, μ*), *X* (*X × Y, γ*,*f* ) *π†*

(*Y, ν*)

,*ss \_πX s Y*

*f†*

where *π†*

*X*

is explicitly given by (*δX ⊗ f* ) *•* Δ*X* . The following property characterizes

the action of (*−*)*†* on **Krn**-morphisms:

**Theorem 2.9** *For all f* : (*X, μ*) d (*Y, ν*)*, f†* : (*Y, ν*) d (*X, μ*) *is the unique* **Krn**

*morphism satisfying for all measurable sets A ⊆ X, B ⊆ Y the following equation:*

∫ ∫

1*A*(*x*) *· f* (*x*)(*B*) *dμ* = *f†*(*y*)(*A*) *·* 1*B*(*y*) *dν* (4)

*x∈X y∈Y*

**Proof.** It follows by definition of *f†* and from the disintegration theorem that

∫

*f†*(*y*)(*A*) *·* 1*B*(*y*) *dν* = *γf* (*A × B*)*,* (5)

*y∈Y*

from which Eq. [4](#_bookmark10) follows easily. It remains to prove that this uniquely characterizes *f†*. Let us reason contrapositively. Assume there exists *g* : (*Y, ν*) d (*X, μ*) verifying for all *A, B* measurable *y∈Y g*(*y*)(*A*) *·* 1*B*(*y*)= *γf* (*A × B*) as in Eq. [5](#_bookmark11) and such that *ν*(*N* (*f†, g*)) *>* 0 (assuming we take some representative of *f†*). Let *{An}n∈*N be a countable *π*-system generating the *σ*-algebra of *X*. It is enough to test equality of measures on *X* on this *π*-system. Therefore, *N* (*f†, g*) = *∪n{y | f†*(*y*)(*An*) */*= *g*(*y*)(*An*)*}*. Since *ν*(*N* (*f†, g*)) *>* 0, there must exist a *k ∈* N such that *ν*(*{y |*

∫

*f†*(*y*)(*Ak*) */*= *g*(*y*)(*Ak*)*}*) *>* 0. Therefore, *N* + = *{y | f†*(*y*)(*Ak*) *> g*(*y*)(*Ak*)*}* must

∫

also have positive measure for *ν*. But then,

*k*

*g*(*y*)(*A* ) *·* 1 (*y*) */*= *γ* (*A × N* +),

*k* + *f k*

*y∈Y Nk k*

a contradiction. *2*

In view of Eq. ([4](#_bookmark10)), we will call *f†* the *Bayesian inversion of f* , and refer to (*−*)*†* as the *Bayesian inversion operation* on **Krn**. It will be crucial throughout the rest of this paper. It is important to see that *f†* absolutely depends on the choice of *μ* and not only on *f* seen as a function. We can now improve on [[6](#_bookmark41)] and show that (*−*)*†* is indeed a *†*-operation in the strict categorical meaning of the term.

**Theorem 2.10 Krn** *is a dagger symmetric monoidal category, with* (*−*)*† given by Bayesian inversion.*

**Proof.** Let us first show that (*−*)*†* is a functor **Krn** *→* **Krn**op, i.e. that id*†* =

(*X,μ*)

id(*X,μ*) and that for any *f* : (*X, μ*) d (*Y, ν*) and *g* : (*Y, ν*) d (*Z, ρ*) we have (*g • f* )*†* = *f† ◦ g†*.

Let (*X, μ*) be an object of **Krn** and id*X,μ* the corresponding identity. By Th. [2.9](#_bookmark9), it is enough to prove, for all *A, Aj* measurable subsets of *X*, that

∫*x∈X* 1*A*(*x*) *· idX,μ*(*x*)(*Aj*) *dμ* = ∫*x∈X idX,μ*(*x*)(*A*) *·* 1*A′* (*x*) *dμ.*

We have:

1*A*(*x*) *· idX,μ*(*x*)(*Aj*) *dμ* = 1*A*(*x*) *·* 1*A′ dμ* = *μ*(*A ∩ Aj*)

∫ ∫

*x∈X x∈X*

The same calculation on the right hand side of the first equation yields trivially the same result. Hence the equality is verified.

Now, on to compatibility w.r.t. composition. In sight of Th. [2.9,](#_bookmark9) it is enough to show that for all *A ⊆ X*, *C ⊆ Z*,

∫ ∫

(*g • f* )(*x*)(*C*) *·* 1*A*(*x*) *dμ* = 1*C*(*z*) *·* (*f† • g†*)(*z*)(*A*) *dρ*

*x∈X z∈Z*

In the following, for *X* a measurable space, we denote by *SF* (*X*) the set of simple functions over *X* (finite linear combinations of indicator functions of measurable sets). We will use repeatedly the monotone convergence theorem (MCT). The left hand side of the above equation can be re-written as:

(1)

∫

∫*x∈X* ∫*y∈Y g*(*y*)(*C*) *df* (*x*) *·* 1*A*(*x*) *dμ*

=

(2) ∫

=

*x∈X*

*y∈Y* lim*n→∞ gn*(*y*) *df* (*x*)

∫

*x∈X* lim*n→∞*

*y∈Y gn*(*y*) *df* (*x*)

∫

*·* 1*A*(*x*) *dμ*

*·* 1*A*(*x*) *dμ*

where (1) is because *gn ↑ g*(*−*)(*C*)*, gn ∈ SF* (*Y* ) and (2) by monotone convergence. Note that the *n*-indexed family *x '→ y∈Y gn*(*y*) *df* (*x*) is pointwise increasing. There- fore,

∫

(*∗*) lim*n→∞* ∫*x∈X* ∫*y∈Y gn*(*y*) *df* (*x*) *·* 1*A*(*x*) *dμ*

(1) ∫ Σ*kn n n*

= lim*n→∞*

*x∈X*

*i*=1 *αi f* (*x*)(*Ci* )

*·* 1*A*(*x*) *dμ*

= lim*n→∞* Σ*kn*

*i*=1

*i*

*i*

*αn* ∫

*x∈X*

*f* (*x*)(*Cn*) *·* 1*A*(*x*) *dμ*

(2) Σ*kn n* ∫ *n †*

= lim*n→∞*

(*∗*) ∫

*i*=1 *αi*

*†*

*y∈Y* 1*Ci* (*y*) *· f*

(*y*)(*A*) *dν*

=

(3) ∫

=

*y∈Y g*(*y*)(*C*) *·* lim*n fn*(*y*) *dν*

*y∈Y g*(*y*)(*C*) *· f* (*y*)(*A*) *dν*

(*∗*) Σ*kn n* ∫ *n*

= lim*n*

*i*=1 *βi*

*y∈Y g*(*y*)(*C*) *·* 1*Di* (*y*) *dν*

(2) Σ*kn n* ∫ *† n*

= lim*n*

*i*=1 *βi*

*z∈Z* 1*C*(*z*) *· g* (*z*)(*Di* ) *dρ*

= lim*n* ∫ 1*C*(*z*) *·* ∫ Σ*kn βn*1*Dn* (*y*) *dg†*(*z*) *dρ*

(*∗*) ∫

=

*z∈Z* 1*C*(*z*) *·*

*z∈Z*

∫

*y∈Y*

*†*

*y∈Y f*

(*y*)(*C*) *dg* (*z*) *dρ*

*i*=1 *i i*

*†*

= *z∈Z* 1*C*(*z*) *·* (*f† • g†*)(*z*)(*A*) *dρ*

∫

where (*∗*) is by monotone convergence, (1) is because *gn ∈ SF* (*Y* ), (2) is by Th. [2.9](#_bookmark9) and (3) is because *fn ↑ f†*(*−*)(*A*)*, fn ∈ SF* (*Y* ). We have proved the sought identity.

Finally let us show that (*−*)*†* is involutive, i.e. that for any *f* : (*X, μ*) d (*Y, ν*), (*f†*)*†* = *f* . This follows easily by two applications of Th. [2.9](#_bookmark9)): we have

∫*x∈X* 1*A*(*x*) *·* (*f†*)*†*(*x*)(*B*) *dμ* = ∫*y∈Y f†*(*y*)(*A*) *·* 1*B*(*y*) *dν*

= ∫*x∈X* 1*A*(*x*) *· f* (*x*)(*B*) *dμ*;

and since adjoints are unique, *f* = (*f†*)*†*.

The fact that (*f ⊗g*)*†* = *f† ⊗g†* follows immediately from the definitions and the property of disintegrations given by Th. [2.9](#_bookmark9). The fact that the associator, unitors and braiding transformations are unitary follows immediately from the fact that they are deterministic isomorphisms and Th. [2.7](#_bookmark6). *2*

# Banach lattices

It is well-known that kernels can alternatively be seen as predicate – i.e. real- valued function –transformers, or as state – i.e. probability measure – transformers. The latter perspective was adopted by Kozen in [[16](#_bookmark51)] to describe the denotational semantics of probabilistic programs (without conditioning). We shall see in this section and the next, that the predicate and state transformer perspectives are dual to one another in the category of *Banach lattices*, a framework incidentally also used in [[16](#_bookmark51)]. For an introduction to the theory of Banach lattices we refer the reader to

e.g. [[2,](#_bookmark36)[25](#_bookmark60)].

An *ordered real vector space V* is a real vector space together with a partial order *≤* which is compatible with the linear structure in the sense that for all *u, v, w ∈ V, λ ∈* R+

*u ≤ v ⇒ u* + *w≤v* + *w* and *u ≤ v ⇒ λu ≤ λv*

An ordered vector space (*V, ≤*) is called a *Riesz space* if the poset structure forms a lattice. A vector *v* in a Riesz space (*V, ≤*) is called *positive* if 0 *≤ v*, and its *absolute value |v|* is defined as *|v|* = *v ∨* (*−v*). A Riesz space (*V, ≤*) is *σ-order complete* if every non-empty countable subset of *V* which is order bounded has a supremum.

A *normed Riesz space* is a Riesz space (*V, ≤*) equipped with a *lattice norm*, i.e. a map *·* : *V →* R such that:

*|v|≤ |w|* implies  *v * *≤ w * *.* (6)

A normed Riesz space is called a *Banach lattice* if it is (norm-) complete, i.e. if every Cauchy sequence (for the norm *·*) has a limit in *V* .

**Example 3.1** For each measured space (*X, μ*) – and in particular **Krn**-objects – and each 1 *≤ p ≤ ∞*, the space L*p*(*X, μ*) is a Riesz space with the pointwise order. When it is equipped with the usual L*p*-norm, it is a Banach lattice. This fact is often referred to as the *Riesz-Fischer theorem* (see [[2](#_bookmark36), Th 13.5]). We will say that

*p, q ∈* N *∪ {∞}* are *H¨older conjugate* if either of the following conditions hold: (i) 1 *< p, q < ∞* and 1 + 1 = 1, or (ii) *p* = 1 and *q* = *∞*, or (iii) *p* = *∞* and *q* = 1.

*p q*

**Theorem 3.2 (Lemma 16.1 and Theorem 16.2 of [**[**25**](#_bookmark60)**])** *Every Banach lattice is σ-order complete.*

There are two very natural modes of ‘convergence’ in a Banach lattice: *order convergence* and *norm convergence*. The latter is well-known, the former less so. An order bounded sequence *{vn}n∈*N in a *σ*-complete Riesz space (e.g. a Banach lattice) *converges in order to v* if either of the following equivalent conditions holds:

*v* = lim inf *vn* :=

*n*

*n*

*vm, v* = lim sup *vn* :=

*n≤m*

*n*

*n*

*vm.*

*n≤m*

For a monotone increasing sequence *vn*, this definition simplifies to *v* = *n vn*, which is often written *vn ↑ v*.

In a general *σ*-complete Riesz space, order and norm convergence are disjoint concepts, i.e. neither implies the other (see [[25](#_bookmark60), Ex. 15.2] for two counter-examples). However if a sequence converges both in order and in norm then the limits are the same (see [[25](#_bookmark60), Th. 15.4]). Moreover, for *monotone* sequences norm convergence implies order convergence:

**Proposition 3.3 ([**[**25**](#_bookmark60)**] Theorem 15.3)** *If {vn}n∈*N *is an increasing sequence in a normed Riesz space and if vn converges to v in norm (notation vn → v*)*, then vn ↑ v.*

In a Banach lattice we have the following stronger property.

**Proposition 3.4 (Lemma 16.1 and Theorem 16.2 of [**[**25**](#_bookmark60)**])** *If {vn}n∈*N *is a* *sequence of positive vectors in a Banach lattice such that* sup*n * *vn * *converges, then*

*n vn exists and * *n vn * = *n * *vn * *.*

It can also happen that order convergence implies norm convergence. A lattice norm on a Riesz space is called *σ-order continuous* if *vn ↓* 0 (*vn* is a decreasing sequence whose infimum is 0) implies *vn * *↓* 0.

**Example 3.5** For 1 *≤ p < ∞*, the L*p*-norm is *σ-order continuous*, and thus order convergence and norm convergence coincide. However, for *p* = *∞* this is not the case as the following simple example shows. Consider the sequence of essentially bounded functions *vn* = 1[*n,*+*∞*[: it is decreasing for the order on L*∞*(R*, λ*) with the constant function 0 as its infimum, i.e. *vn ↓* 0. However *vn * =1 for all *n*.

Many types of morphisms between Banach lattices are considered in the liter- ature but most are at least *linear* and *positive*, that is to say they send positive vectors to positive vectors. From now on, we will assume that all morphisms are positive (linear) operators. Other than that, we will only mention two additional properties, corresponding to the two modes of convergence which we have examined. The first notion is very well-known: a linear operator *T* : *V → W* between normed

vector spaces is called *norm-bounded* if there exists *C ∈* R such that *Tv * *≤ C v *

for every *v ∈ V* . The following result is familiar:

**Theorem 3.6** *An operator T* : *V → W between normed vector spaces is norm- bounded iff it is continuous.*

Thus norm-bounded operators preserve norm-convergence. The corresponding order-convergence concept is defined as follows: an operator *T* : *V → W* between *σ*-order complete Riesz spaces is said to be *σ-order continuous* if whenever *vn ↑ v*, *Tv* = *T vn*. It follows that we can consider two types of dual spaces on a Banach lattice *V* : on the one hand we can consider the *norm-dual* :

*V ∗* = *{f* : *V →* R *| f* is norm-continuous*}* and the *σ-order-dual* :

*V σ* = *{f* : *V →* R *| f* is *σ*-order continuous*}*

The latter is sometimes known as the *K¨othe dual* of *V* (see [[11,](#_bookmark49)[25](#_bookmark60)]). The two types of duals coincide for a large class of Banach spaces of interest to us.

**Theorem 3.7** *If a Banach lattice V admits a strictly positive linear functional and has a σ-order-continuous norm, then V ∗* = *V σ.*

**Example 3.8** The result above can directly be applied to our running example: given a measured space (*X, μ*) and an integer 1 *≤ p < ∞*, the Lebesgue integral provides a strictly positive functional on L*p*(*X, μ*), and we already know from Ex- ample [3.5](#_bookmark14) that L*p*(*X, μ*) has a *σ*-order-continuous norm. It follows that

L*p*(*X, μ*)*∗* = L*p*(*X, μ*)*σ*

Moreover, it is well-known that if (*p, q*) are H¨older conjugate and 1 *< p, q < ∞*, then L*p*(*X, μ*)*∗* = L*q*(*X, μ*), and thus L*p*(*X, μ*)*σ* = L*q*(*X, μ*). It is also known that L1(*X, μ*)*∗* = L*∞*(*X, μ*), and thus L1(*X, μ*)*σ* = L*∞*(*X, μ*).

However Theorem [3.7](#_bookmark15) does *not* hold for L*∞*(*X, μ*) since the L*∞*-norm is not *σ*- order continuous, as was shown in Example [3.5.](#_bookmark14) It is well-known that L*∞*(*X, μ*)*∗ /*= L1(*X, μ*), and in fact L*∞*(*X, μ*)*∗* can be concretely described as the Banach lattice ba(*X, μ*) of *charges* (i.e. finitely additive finite signed measures) which are absolutely continuous w.r.t, *μ* on *X* (see [[12](#_bookmark50), IV.8.16]). However, as is shown in e.g. [[25,](#_bookmark60)[4]](#_bookmark38)

L*∞*(*X, μ*)*σ* = L1(*X, μ*) (7)

As Examples [3.5](#_bookmark14) and [3.8](#_bookmark16) show, the (*−*)*σ* operation brings a lot of symmetry to the relationship between L*p*-spaces since L*p*(*X, μ*)*σ* = L*q*(*X, μ*) for *any* H¨older conjugate pair 1 *≤ p ≤ ∞*. For this reason we will consider the category **BL***σ* whose objects are Banach lattices and whose morphisms are *σ*-order continuous positive operators. Note that the K¨othe dual of a Banach lattice is a Banach lattice, and it easily follows that (*−*)*σ* in fact defines a contravariant functor **BL**op *→* **BL***σ* which

*σ*

acts on morphisms by pre-composition. As we will now see, **BL***σ* is the category in which predicate and state transformers are most naturally defined.

# From Borel kernels to Banach lattices

The aim of this section is two-fold. First, we establish functorial bridges between Borel kernels (i.e. **Krn**) and operators on Banach lattices (i.e. **BL***σ*). This will allow us to describe the convergence of a sequence of approximating kernels in terms of operator topology in *§*[6](#_bookmark30). Second, we show that the functors between **Krn** and **BL***σ* also provide an interesting structural insight into some of the most important results in classical probability theory, in particular we show that the Radon-Nikodym and Riesz representation theorems can be described as natural transformations.

**The functors** S*p* **and** T*p***.**

For 1 *≤ p ≤ ∞*, the operation which associates to a **Krn**-object (*X, μ*) the space L*p*(*X, μ*) can be thought of as either a contravariant or a covariant functor. We define the functors S*p* : **Krn** *→* **BL**op*,* 1 *≤ p ≤ ∞* as expected on objects, and on **Krn**-morphisms *f* : *X* d *Y* via the well-known ‘predicate transformer’ perspective:

*σ*

∫

S*p*(*f* ): L*p*(*Y, ν*) *→* L*p*(*X, μ*)*,φ '→ λx. φ df* (*x*)= *φ • f*

*Y*

This defines a functor (see [[6](#_bookmark41)]). We define the covariant functors T*p* : **Krn** *→*

**BL***σ,* 1 *≤ p ≤∞* as T*p* = S*p ◦* (*−*)*†*.

## The functor *M ·*.

An *ideal* of a Riesz space *V* is a sub-vector space *U ⊆ V* with the property that if *|u|≤ |v|* and *v ∈ U* then *u ∈ U* . An ideal *U* is called a *band* when for every subset *D ⊆ U* if *D* exists in *V* , then it also belongs to *U* . Every band in a Banach lattice is itself a Banach lattice. Of particular importance is the band *Bv* generated by a singleton *{v}*, which can be described explicitly as

*Bv* = *{w ∈ V |* (*|w|∧ n |v|*) *↑ |w|}*

**Example 4.1** Let *X* be an SB-space and ca(*X*) denote the set of measures of bounded variation on *X*. It can be shown ([[2](#_bookmark36), Th 10.56]) that ca(*X*) is a Banach lattice. The linear structure on ca(*X*) is as expected, the Riesz space structure is given by

(*μ ∨ ν*)(*A*)= sup*{μ*(*B*)+ *ν*(*A \ B*) *| B* measurable *,B ⊆ A}*

and the dual definition for the meet operation. The norm is given by the total variation i.e.

*μ* = sup

Σ*n*

*i*

*|μ*(*Ai*)*|* *{A*1*,..., An}* a meas. partition of *X*

Given *μ ∈* ca(*X*), the band *Bμ* generated by *μ* is just the set of measures of bounded variation which are absolutely continuous w.r.t. *μ*. In particular *Bμ* is a Banach lattice.

We can now define the functor *M ·* : **Krn** *→* **BL***σ* by:

*M ·*(*X, μ*) := *Bμ*

*M ·f* : *M ·*(*X, μ*) *→ M ·*(*Y, ν*)*,ρ '→ f • ρ*

We will usually write *M ·*(*X, μ*) as *M μ*(*X*).

**Proposition 4.2** *Let f* : (*X, μ*) d (*Y, ν*) *be a* **Krn** *arrow. Let ρ be a ﬁnite measure on X such that ρ μ. Then f • ρ ν, and thus M · deﬁnes a functor.*

**Proof.** Let *B ⊆ Y* be a measurable set. By definition, we have (*f • ρ*)(*B*) =

∫

*X evB ◦ f dρ* where we recall that *evB* : G(*X*) *→* R+ is the evaluation morphism.

Let *{f B}n∈*N be an increasing chain of simple functions converging pointwise to

*n*

*evB ◦ f* such that for each *n*, *f B* = Σ*kn αn*1*An* with *αn ≥* 0. By the MCT,

*n i*=1 *i i* *i*

∫ *kn*

(*f • ρ*)(*B*) = lim

*f B dρ* = lim

*αnρ*(*An*)*.*

Σ

*n*

*n*

*n*

*i*

*i*

*X*

*i*=1

Similarly,

*ν*(*B*)= (*f • μ*)(*B*)= lim ∫

Σ

*kn*

*f B dμ* = lim

*αnμ*(*An*)*.*

*n X n*

*n i* *i i*=1

Notice that since the integral is linear and the sequence *{f B}n* is increasing, the

*n*

sequences *{*∫*X f B dρ}n* and *{*∫*X f B dμ}n* are also increasing. Assume *ν*(*B*) = 0.

*n*

*n*

∫

Then for all *n*, *X f B dμ* = 0. We deduce that for all *n*, for all 1 *≤ i ≤ kn*, either

*n*

*αn* =0 or *μ*(*An*) = 0. Using that *ρ μ*, we deduce that for all 1 *≤ i ≤ kn*, either

*i i* ∫

*i*

*i*

*n*

*αn* = 0 or *ρ*(*An*) = 0, from which we conclude that for all *n*,

*f B*

*dρ* = 0 and

*X*

finally, (*f • ρ*)(*B*) = 0. Hence, *f • ρ ν*. *2*

## Radon-Nikodym is natural.

We now present a first pair of natural transformations which will establish a natural isomorphism between the functors T1 and *M ·*. First, we define the *Radon- Nikodym transformation* rn : *M · →* T1 at each **Krn**-object (*X, μ*) by the map

rn(*X,μ*)

: *M μ*(*X*) *→* L1(*X, μ*)*,* rn

(*X,μ*)

*dρ*

(*ρ*)=

*dμ*

where *dρ/dμ* is of course the Radon-Nikodym derivative of *ρ* w.r.t. *μ*. The fact that this transformation defines a positive operator between Banach lattices is simply a restatement of the usual Radon-Nikodym theorem [[12](#_bookmark50), III.10.7.], combined with the well-known linearity property of the Radon-Nikodym derivative. To see that it is also *σ*-order-continuous, consider a monotone sequence *μn ↑ μ* converging in order

to *μ* in *M ν*(*X*). This means that for any measurable set *A* of *X*, lim*n→∞ μn*(*A*)= *μ*(*A*). Since (*dμn/dν*)*n∈*N is bounded in L1-norm the function *g* = *n dμn/dν* exists and is simply the pointwise limit *g*(*x*) = lim*n→∞ dμn/dν*(*x*). It now follows from the monotone convergence theorem (MCT) that

∫ *gdν* =∫

*n→∞*

*A*

lim

*A*

*dμn dν* = lim ∫

*dμn dν* = lim *μ*

(*A*) = *μ*(*A*)

*n*

in other words, *g* = *dμ/dν* and rn is well-defined. That rn is also natural has – to our knowledge – never been published.

*dν*

*n→∞*

*A*

*dν*

*n→∞*

**Theorem 4.3** *The Radon-Nikodym transformation is natural.*

**Proof.** We start by proving the following Lemma

**Lemma 4.4** *For any f* : (*X, μ*) d (*Y, ν*)*, φ ∈* L1(*Y, ν*)*, and BX ⊆ X measurable*

∫ ∫ *φdf* (*x*) *dμ* = ∫ *φ*(*y*)*f†*(*y*)(*BX* ) *dν*

*BX Y Y*

**Proof.** We start by showing the equation on characteristic functions. If *BY* is measurable in *Y* , we have

∫*BX*

∫*Y*

1*BY df* (*x*) *dμ* = *f* (*x*)(*BY* ) *dμ*

∫

*BX*

∫

= 1*BY*

*Y*

(*y*)*f†*(*y*)(*BX* ) *dν* Eq. ([4](#_bookmark10))

Since *φ* is measurable and integrable, there exists a sequence *φn ↑ φ* of simple functions such that lim*n Y φn dν < ∞*, and the results follows by the linearity of integration and the MCT. *2*

∫

We can now prove the naturality of rn. Let *f* : (*X, μ*) d (*Y, ν*) bea **Krn**-morphism; we have on the one hand

rn(*Y,μ*) *◦ M ·*(*f* )(*ρ*)(*y*)= rn(*Y,ν*)(

∫

*X*

∫

*f* (*x*)(*−*) *dρ*)(*y*)

and on the other

T1(*f†*) *◦* rn(*X,μ*)

= *d X f* (*x*)(*−*)*dρ* (*y*) (*∗*)

*dν*

(*ρ*)(*y*)= T (*f†*) *dρ* (*y*)

∫

*p dμ*

*dρ*

*†*

= *df* (*y*) (*∗∗*)

*X dμ*

To show the equality of these two maps in L1(*Y, ν*) it is enough to show that they are equal *ν*-a.e. To see this, we show that (*∗∗*) satisfies the condition to be the

Radon-Nikodym derivative (*∗*). Let *BY* be a measurable subset of *Y* . We have from the well-known property of Radon-Nikodym derivatives:

∫*BY*

*d X f* (*x*)(*−*) *dρdν* =

*dν x∈X*

∫ ∫

*f* (*x*)(*BY*

) *dρ*

Moreover, we have

∫*BY*

*dρ*

∫

*df*

*X dμ*

(1)

(*y*) *dν* =

*†*

(2)

=

*x∈X*

*x∈X*

∫

∫

*dρ*

*dμ* (*x*)*f* (*x*)(*BY* ) *dμ*

*f* (*x*)(*B*) *dρ*

where (1) is by Lemma [4.4](#_bookmark18) and (2) is a well-known property of Radon-Nikodym derivatives. *2*

Secondly, we define the *Measure Representation transformation* mr : T1 *→ M ·*

at each **Krn**-object (*X, μ*) by the map mr(*X,μ*) : T1(*X, μ*) *→ M* (*X, μ*) defined as

∫

mr(*X,μ*)(*f* )(*BX* )= *fdμ*

*BX*

This is a very well-known construction in measure theory, and the fact that mr(*X,μ*) is a *σ*-order continuous operator between Banach lattices is immediate from the linearity of integrals and the MCT.

**Theorem 4.5** *The Measure Representation transformation is natural.*

**Proof.** We start with the following elementary lemma.

**Lemma 4.6** *If ψ, φ ∈* L1(*X, μ*) *then*

∫ ∫

*ψφ dμ* = *ψ d*(mr(*M,μ*)*φ*)

*X* *X*

**Proof.** The proof of naturality now follows easily: it is enough to show the equality in the case where *ψ* = 1*BX* for a measurable subset *BX* of *X*, and the result then extends to all measurable functions by linearity of integrals and the MCT. We have

1*BX φ dμ* =

∫ ∫

*BX*

*X*

*φdμ* := mr(*M,μ*)(*φ*)(*BX* )

= 1*BX d*(mr(*M,μ*)(*φ*))

∫

*X*

*2*

To show naturality we now let *f* : (*X, μ*) d (*Y, ν*) bea **Krn**-morphism, *φ ∈* L1(*X, μ*)

and *BY* measurable in *Y*

mr(*Y,ν*)T1(*f†*)(*φ*)(*BX* )

= mr(*Y,ν*)(*φ • f†*)(*BY* )

∫

= *φ • f† dν*

*BY*

∫

∫

= *φdf †*(*y*) *dν*

*BY X*

∫

= *f* (*x*)(*BY* )*φ*(*x*) *dμ* Lemma [4.4](#_bookmark18)

*X*

∫

= *f* (*x*)(*BY* ) *d*( d(mr(*X,μ*)(*φ*)) Lemma [4.6](#_bookmark19)

*X*

= *M ·f ◦* mr(*X,μ*)(*φ*)(*BY* )

*2*

## Riesz representations are natural.

We now present a second pair of natural transformations which will establish a natural isomorphism between (*−*)*σ ◦* S*∞* and *M ·*. First, we define the *Riesz Representation* transformation rr : (*−*)*σ ◦* S*∞ → M ·* at each **Krn**-object (*X, μ*) by the map rr(*X,μ*) : (*−*)*σ ◦* S*∞*(*X, μ*) *→ M ·*(*X, μ*) defined as

rr(*X,μ*)(*F* )(*BX* )= *F* (1*BX* )

This construction is key to a whole collection of results in functional analysis commonly known as Riesz Representation Theorems (see [[2](#_bookmark36)] Chapter 14 for an overview). One can readily check that the Riesz Representation transformation is well-defined: rr(*X,μ*)(*F* )(*∅*) = *F* (0) = 0 and the *σ*-additivity of rr(*X,μ*)(*F* ) fol- lows from the *σ*-order-continuity of *F* . To see that rr(*X,μ*)(*F* ) *μ*, assume that *μ*(*BX* ) = 0, then clearly 1*BX* = 0 *μ*-a.e., i.e. 1*BX* = 0 in L*∞*(*X, μ*), and thus *F* (1*BX* )= 0.

**Theorem 4.7** *The Riesz Representation transformation is natural.*

**Proof.** Again, we start with a simple but helpful Lemma.

**Lemma 4.8** *Let F ∈* (S*∞*(*X, μ*)*σ and φ ∈* S*∞*(*X, μ*)*, then*

*F* (*φ*)= ∫*X φ d*(rr(*X,μ*)(*F* ))

**Proof.** Starting with characteristic functions, let *φ* = 1*B* for some measurable subset *B* of *X*. We then have

*F* (1*B*) := rr(*X,μ*)(*F* )(*B*)= ∫*X* 1*B d*(rr(*X,μ*)(*F* ))

We can then extend the result to simple functions by linearity and to all functions in L*∞*(*X, μ*) by the MCT. *2*

To show naturality we now let *f* : (*X, μ*) d (*Y, ν*) be a **Krn**-morphism, *F ∈*

(S*∞*(*X, μ*))*σ* and *BY* measurable in *Y* . We have

*M ·f ◦* rr(*X,μ*)(*F* )(*BY* )= *f* (*x*)(*BY* ) *d*(rr(*X,μ*)(*F* ))

∫

*X*

= *F* (*f* (*·*)(*BY* )) Lemma [4.8](#_bookmark20)

∫

= *F* (

*X*

1*BY df* (*·*))

= *F* (1*BY • f* )

= rr(*Y,ν*)(*F* (*−• f* ))(*BY* )

= rr(*Y,ν*) *◦* (T1*f* )*σ*(*F* )(*BY* )

*2*

Finally, we define the *Functional Representation transformation* fr at each **Krn**- object (*X, μ*) by the map fr(*X,μ*) : *M ·*(*X, μ*) *→* (*−*)*σ ◦* S*∞*(*X, μ*) by

∫

fr(*X,μ*)(*μ*)(*φ*)= *φdμ*

*X*

This construction is also completely standard in measure theory, although it has never to our knowledge been seen as a natural transformation.

**Theorem 4.9** *The Functional Representation transformation is well-deﬁned, i.e.*

fr(*X,μ*) *is a σ-order continuous positive operator, and is natural.*

**Proof.** We start by showing that fr is well defined. The linearity of fr(*X,μ*) is easily checked on simple functions and extended by the CMT. Positivity is also immediate. For the *σ*-order continuity, let *μm ↑ μ*, *φ ∈* L*∞*(*X, μ*), and *φn ↑ φ* be a monotone approximation of *φ* by simple functions. We need to show that

lim

*m→∞* ∫

*X*

*φ dμm* =

*X*

∫

∫

*φ dμ*

For note first that the doubly indexed series *X φndμm* is monotonically increasing in *m*, since the *μm* are monotonically increasing. Note also that the differences

∫ ∫

*dmn* := *φn dμm*+1 *− φn dμm*

*X* *X*

are monotonically increasing in *n*. Indeed we have

∫*X*

∫

*φn*+1 *dμm*+1 *−*

∫

*X*

*φn*+1 *dμm* *−* ∫

*φndμm*+1 *−*

∫

*X*

*φn dμm*

= (*φn*+1 *− φn*) *dμm*+1 *−*

*X*

∫

*X* *X*

(*φn*+1 *− φn*) *dμm >* 0

since the sequences *φn* and *μm* are monotonically increasing. Since *dmn* is monoton- ically increasing in *n* we can apply the CMT to *dmn* seen as a function of *m* w.r.t. the counting measure, i.e.

*∞*

lim

Σ

*n→∞*

*m*

*∞*

*dmn* =

Σ

*m*

lim

*n→∞*

*dmn*

which is to say, by taking partial sums

Σ ∫

*m*

*dkn* = lim

lim

*φn dμm*

*n→∞ m→∞*

lim

lim

*k*=1

*n→∞ m→∞ X m*

= lim

*m→∞*

*k*Σ=1

lim

*n→∞*

*dkn*

= lim lim ∫

*φn dμm*

*m→∞ n→∞ X*

which concludes the proof that fr is well-defined.

We now prove naturality. Let *f* : (*X, μ*) d (*Y, ν*) be a **Krn**-morphism, *ρ ∈ M μ*(*X*) and *φ ∈* S*∞*(*Y, ν*) we then have

fr(*Y,ν*) *◦ M ·f* (*ρ*)(*φ*)= ∫

∫

*Y*

=

*Y*

*φ d*(*M ·f* (*ρ*)(*φ*))

(*φ • f* ) *dρ* Theorem [2*.*6](#_bookmark5)

= S*∞*(*f* ) ∫ (*−*) *dρ* (*φ*)

*Y*

= S*∞*(*f* ) *◦* fr(*X,μ*)(*ρ*)(*φ*)

*2*

## Natural Isomorphisms

We have now defined the following four natural transformations:

T mr z*M ·*  fr z(S)*σ*

1 ¸*c*rn ¸*c*rr *∞*

In fact, both pairs form natural isomorphisms which can be restricted to arbitrary H¨older conjugate pairs (*p, q*).

**Theorem 4.10** rn *and* mr *are inverse of one another, in particular there exists a*

natural *isomorphism between M μ*(*X*) *and* L1(*X, μ*)*.*

**Proof.** The fact that rn(*X,μ*) and mr(*X,μ*) are inverse of each other is just a restate- ment of the two well-known equalities for Radon-Nikodym derivatives:

*d — φ dμ* = *φ* and *dρ dμ BX dμ*

∫ ∫

*dμ* = *ρ*(*BX* )

*2*

**Theorem 4.11** rr *and* fr *are inverse of each other, in particular there exists a*

natural *isomorphism between M μ*(*X*) *and* (L*∞*(*X, μ*))*σ.*

**Proof.** Let (*X, μ*) be a **Krn**-object, let *F ∈* (L*∞*(*X, μ*))*σ* and let *φ ∈* L*∞*(*X, μ*). We have

∫

fr(*X,μ*) *◦* rr(*X,μ*)(*F* )(*φ*)= *φ d*(rr(*X,μ*)(*F* )) = *F* (*φ*)

*X*

where the last equality follows from Lemma [4.8](#_bookmark20). Similarly, we have

∫

rr(*X,μ*) *◦* fr(*X,μ*)(*ρ*)(*BX* )= fr(*X,μ*)(*ρ*)(1*BX* ) = 1*BX dρ* = *ρ*(*BX* )

*X*

*2*

We can now conclude that the isomorphism proved in Theorem 6 of [[6](#_bookmark41)] is in fact natural.

**Corollary 4.12** *There exists a* natural *isomorphism between* T1 := S1 *◦* (*−*)*† and*

(*−*)*σ ◦* S*∞.*

We can in fact restrict this result to *any* H¨older conjugate pair (*p, q*):

**Theorem 4.13** *For* 1 *≤ p ≤∞ with H¨older conjugate q, the natural transformation*

rn *◦* rr *restricts to a natural transformation* (*−*)*σ ◦* S*q →* T*p.*

**Proof.** The case *p* = 1 has been treated already, for the case of 1 *< p < ∞*, see for example the proof of Theorem 4.4.1 of [[3](#_bookmark39)]. Finally for the case of *p* = *∞*, see Proposition 3.3 of [[4](#_bookmark38)]. *2*

The correspondence between the various categories and functors discussed in this section are summarized by

(*—*)*σ*

*M*

(8)

**BL**op ¸*c* fr ¸*c* mr **Krn**op

**B** **L**,*,σ*,*,¸*

*·*

S1

*σ* ,*¸*

rr zrn z *,*

S*∞* (*—*)*†*

**Krn**

# Approximations

In this section we develop a scheme for approximating kernels which follows nat- urally from the *†*-structure of **Krn**. Consider *f* : (*X, μ*) d (*Y, ν*) and a pair of

deterministic maps *p* : (*X, μ*) *→* (*Xj, p∗μ*) and *q* : (*Y, ν*) *→* (*Y j, q∗ν*) (typically these maps coarsen the spaces *X* and *Y* ).

(*X, μ*,)*¸*

*c*

*f* z

*p,q* (z*Y , ν*,) *¸* (9)

*c*

*f*

*† †*

*p*

*q*

*p*

*q*

*μ ν*

*cj*ι*z*

z*cj*ι*z*

(*X , p∗μ*)

*fp,q*

(*Y , q∗ν*)

The *†*-structure of **Krn** allows us to define the new kernels

*fp,q* := *q† • q • f • p† • p* : *X* d *Y* (10)

*ν μ*

*fp,q* := *q • f • p†*

*μ*

: *Xj* d *Y j* (11)

The supscript notation is meant to indicate that the approximation lives ‘upstairs’ in Diagram ([9](#_bookmark23)) and conversely for the subscripts. Intuitively, *fp,q* and *fp,q* take the average of *f* over the fibres given by *p, q* according to *μ* and *ν* (see *§*[7](#_bookmark35) for concrete calculations). The advantage of ([11](#_bookmark25)) is that we can approximate a kernel on a huge space by a kernel on a, say, finite one. The advantage of ([10](#_bookmark24)) is that although it is more complicated, it is morally equivalent and has the same type as *f* , which means that we can compare it to *f* .

A very simple consequence of our definition is that Bayesian inversion commutes with approximations. We shall use this in *§*[7](#_bookmark35) to perform *approximate Bayesian inference*.

**Theorem 5.1** *Let f* : (*X, μ*) d (*Y, ν*)*, let p* : *X → Xj and q* : *Y → Y jn be a pair* *of deterministic maps, then*

(*f†*)*q,p* = (*fp,q*)*† and* (*f†*)*q,p* = (*fp,q*)*†*

In practice we will often consider endo-kernels *f* : *X* d *X* with a single coars- ening map *p* : *X → Xj* to a *ﬁnite space*. In this case ([10](#_bookmark24)) simplifies greatly.

**Proposition 5.2** *Under the situation described above*

*fp* := *p† • p • f • p† • p* = *f • p† • p* (12)

*ν μ μ*

In the case covered by Proposition [5.2](#_bookmark27), the interpretation of *fp* is very natural: for each *x ∈ X* the measure *f* (*x*) is approximated by its average over the fibre to which *x* belongs, conditioned on being in the fibre. For fibres with strictly positive *μ*-probability, this is simply

*fp*(*x*)(*A*)= *y∈p−*1(*p*(*x*)) *f* (*y*)(*A*) *dμ*

∫

*μ*(*p—*1(*p*(*x*))

However ([12](#_bookmark28)) also covers the case of *μ*-null fibres. Note also that in the case where *fp* = *f* , the map *p* corresponds to what is known as a strong functional bisimulation for *f* .

## Approximating is non-expansive.

It is well-known that conditional expectations are non-expansive and we know from Lemma [2.8](#_bookmark7) that pre-composing by *p† • p* as in ([12](#_bookmark28)) amounts to conditioning. The following lemma is an easy consequence.

*μ*

**Lemma 5.3** *Let f* : (*X, μ*) d (*Y, ν*) *and q* : *X → Xj be a deterministic quotient, then for all* 1 *≤ p ≤∞ and φ ∈* L*p*(*Y, ν*)

 S*pfq*(*φ*)  *≤ *S*pf* (*φ*) 

*p p*

## Compositionality of approximations.

In the case where we wish to approximate a composite kernel *g • f* , it might be convenient, for modularity reasons, to approximate *f* and *g* separately. This does not entail any loss of information provided the quotient maps are hemi- bisimulations, in the following sense. Let *p* : *X → Xj,q* : *Y → Y j,r* : *Z → Zj* be deterministic quotients and let *f* : (*X, μ*) d (*Y, ν*)*,g* : (*Y, ν*) d (*Z, ρ*) be com- posable kernels. We say that *q* is a left hemi-bisimulation for *f* if *f* = *q† • q • f* , and conversely that it is a right hemi-bisimulation for *g* if *g* = *g • q† • q* holds. In either case, one can verify using Theorems [2.7](#_bookmark6) and [5.1](#_bookmark26) that approximation commutes with composition, i.e. that (*g • f* )*p,r* = *gq,r • fp,q*.

## Discretization schemes.

We will use ([11](#_bookmark25)) and ([12](#_bookmark28)) to build sequences of arbitrarily good approximations of kernels. For this we introduce the following terminology.

**Definition 5.4** We define a *discretization scheme for an SB-space X* to be a count- able co-directed diagram (ccd) of finite spaces for which *X* is a cone (not necessarily a limit).

If (*Xi*)*i∈I* is a discretization scheme of *X* and *pi* : *X → Xi* are the maps making *X* a cone, then it follows from the definition that if *i < j*, *σ*(*pi*) *⊆ σ*(*pj*) where *σ*(*pi*) is the *σ*-algebra generated by *pi*. For each *i ∈ I* the finite quotient *pi* defines a *measurable partition* of *X* whose disjoint components *p—*1(*{k}*)*,k ∈ Xi* we will call *cells*. By Theorem [2.1](#_bookmark4) every SB-space has a discretization scheme for which it is not just a cone but a limit. In practice we will work with discretization schemes linearly ordered by N. In this case the sequence (*X, σ*(*pn*))*n∈*N defines what probabilists call a *ﬁltration* and we will denote the approximation *fpn* given by ([12](#_bookmark28)) simply by *fn*.

*i*

# Convergence

We now turn to the question of convergence of approximations. There appears to be little literature on the subject of the convergence of approximations of Markov

kernels. One rare reference is [[5](#_bookmark40)]. Via the functor S*p* defined above in Sections [3](#_bookmark13) and [4](#_bookmark17) we can seek a topology in terms of the *operators associated to a sequence of kernels*. Indeed, following [[5](#_bookmark40)], we will prove convergence results for the *Strong Operator Topology* (SOT).

**Definition 6.1** We will say that a sequence of kernels *fn* : *X* d *Y converges to f* : *X* d *Y in strong operator topology*, and write *fn−→*s*f* , if S1*fn* converges to S1*f* in the strong operator topology, i.e. if

lim

*n→∞*

 S1*fn*(*φ*) *−* S1*f* (*φ*)  1 =0

## Proving convergence.

The following key lemma is a consequence of L´evy’s upward convergence Theo- rem ([[23](#_bookmark58), Th. 14.2]) .

**Lemma 6.2** *Let f* : (*X, μ*) d (*Y, ν*) *be a* **Krn***-morphism and let pn* : *X → Xn,n ∈*

N *be a discretization scheme such that for BX the Borel σ-algebra of X we have*

*BX* = *σ* ( *n σ*(*pn*))*, and let A ⊆ Y be measurable, then for fn* := *f • p • pn*

*†*

*n*

lim

*n→∞*

*fn*(*x*)(*A*)= *f* (*x*)(*A*)

*for μ-almost every x ∈ X. Moreover,*

lim

*n→∞*

 S1*fn*(1*A*) *−* S1*f* (1*A*)  1 =0

**Proof.** The map *f* (*−*)(*A*): *X →* R defines a random variable, and the discretiza- tion scheme defines a filtration *σ*(*pn*) *⊆ σ*(*pn*+1) whose union is *BX* . Following Lemma [2*.*8](#_bookmark7) and Proposition [5.2](#_bookmark27) we have

*fn*(*x*)(*A*) := *f* (*x*)(*A*) *• p† • pn* = E [*f* (*x*)(*A*) *| σ*(*pn*)]

*n*

We thus have a sequence *fn*(*−*)(*A*) of random variables *X →* R which is adapted to the filtration *σ*(*pn*)*,n ∈* N by construction. We can now compute for any *m < n*

E [*fn*(*x*)(*A*) *| σ*(*pm*)]

=*f* (*x*)(*A*) *• p† • pn • p† • pm*

*n m*

(1) *† †*

= *f* (*x*)(*A*) *• pn • pn •* (*pnm • pn*) *• pm*

(2)

*† † †*

= *f* (*x*)(*A*) *• pn • pn • pn • pnm • pm*

(3) *† m*

= *f* (*x*)(*A*) *• pm • pm* = *f*

(*x*)(*A*)

where (1) is by definition ([5.4](#_bookmark29)), (2) is by Thm ([2.10](#_bookmark12)) and (3) is by Theorem ([2.7](#_bookmark6)). We have thus shown that *fn*(*−*)(*A*) is a martingale for the filtration generated by the discretization scheme, and the result now follows from L´evy’s upward convergence Theorem ([[23](#_bookmark58), Th. 14.2]) since *f* (*x*)(*A*)= E [*f* (*x*)(*A*) *| σ* ( *n σ*(*pn*))]. *2*

**Theorem 6.3 (Convergence of Approximations Theorem)** *Under the con- ditions of Lemma* [*6.2*](#_bookmark31)*, for μ-almost every x ∈ X*

lim

*n→∞*

*fn*(*x*)(*A*)= *f* (*x*)(*A*)

*for all Borel subsets A. Moreover,*

lim

*n→∞*

 S1*fn*(*φ*) *−* S1*f* (*φ*)  1 =0

*for any φ ∈* L1(*X, ν*)*. In other words fn−→*s*f.*

**Proof.** Let (*Bn*)*n∈*N be a countable basis for the Borel *σ*-algebra of *X*, which we assume w.l.o.g. is closed under finite unions and intersections. It follows from Lemma [6.2](#_bookmark31) that for each *Bn*, lim*k fk*(*x*)(*Bn*)= *f* (*x*)(*Bn*) for all *x ∈ X \ Nn* where *μ*(*Nn*) = 0. It follows that for every *x ∈ X \ i Ni*

lim *fk*(*x*)(*Bn*)= *f* (*x*)(*Bn*)

*k→∞*

for all basic Borel sets *Bn*, and *μ*( *i Ni*) = 0. Now we use the *π − λ*-lemma with (*Bn*)*n∈*N as our *π*-system. We define

*L* := *{C | fn*(*x*)(*C*) *→ f* (*x*)(*C*) for all *x ∈ X \ ∪iNi}*

and show that it is a *λ*-system. Clearly each *Bn ∈ L*. Suppose *C ∈ L*, it is then immediate that *Cc ∈ L*. Now consider a sequence *Ci ∈ L* with *Ci ⊆ Ci*+1, and let

*C∞* := *∪∞*

*i*=1

*Ci*. We want to show that

lim *fn*(*x*)(*C∞*)= lim lim *fn*(*x*)(*Cm*) *n n m*

(*∗*) *n*

= lim lim *f* (*x*)(*Cm*)

*m n*

= lim *f* (*x*)(*Cm*)

*m*

= *f* (*x*)(*C∞*)

where (*∗*) is the only step we need to justify. To show the iterated limits can be switched, note first that since

*|fn*(*x*)(*Cm*) *− f* (*x*)(*C∞*)*|* = *|fn*(*x*)(*Cm*) *− f* (*x*)(*Cm*)+ *f* (*x*)(*Cm*) *− f* (*x*)(*C∞*)*|*

*≤ |fn*(*x*)(*Cm*) *− f* (*x*)(*Cm*)*|* + *|f* (*x*)(*Cm*) *− f* (*x*)(*C∞*)*|*

since the two terms converge separately, for any *ϵ >* 0 we can find *N >* 0 s. th. for all *m, n ≥ N* , *|fn*(*x*)(*Cm*) *− f* (*x*)(*C∞*)*| < є/*2 + *є/*2 = *ϵ*. Thus lim(*m,n*)*→∞ fn*(*x*)(*Cm*)= *f* (*x*)(*C∞*).

Now note also that for all *m*0 *∈* N the sequence *fn*(*x*)(*Cm*0 ) converges to *f* (*x*)(*Cm*0 ) (by definition of *L*), and it is not hard to see that *f* (*x*)(*Cm*) converges to *f* (*x*)(*C∞*). Conversely for all *n*0 *∈* N, the sequence *fn*0 (*x*)(*Cm*) converges to

*fn*0 (*C∞*) (by virtue of *fn*0 (*x*) being a measure). For *є/*2 *>* 0 we can find *N >* 0 such that for all *m, n > N* , *|fn*(*x*)(*Cm*) *− f* (*x*)(*C∞*)*| < є/*2. We can also find *M >* 0 such that for all *m > M* , *|fn*(*x*)(*Cm*) *− fn*(*x*)(*C∞*)*| < є/*2. By taking the maximum of *N* and *M* it is clear that for all *m, n* above this maximum

*|fn*(*x*)(*C∞*) *− f* (*x*)(*C∞*)*|*

*≤ |fn*(*x*)(*C∞*) *− fn*(*x*)(*Cm*)*|* + *|fn*(*x*)(*Cm*) *− f* (*x*)(*C∞*)*| < ϵ*

We have thus shown that

lim lim

*fn*(*x*)(*Cm*) = lim *fn*(*x*)(*Cm*)

*m→∞ n→∞*

(*m,n*)*→∞*

= *f* (*x*)(*C∞*) = lim

lim

*fn*(*x*)(*Cm*)*.*

*n→∞ m→∞*

Thus *L* is a *λ*-system, and it follows from the *π − λ*-lemma that *σ*((*Bn*)*n∈*N) *⊆ L*

which concludes the proof of pointwise almost everywhere convergence.

For the proof of L1-convergence we start by showing that

lim

*n→∞*

 S*pfn*(1*A*) *−* S*p*(1*A*) 

= 0 (13)

for any Borel subset *A*. For this we use exactly the same reasoning as above. The only difference is that we need to check that

1

lim

*n→∞* ∫

*X*

*|fn*(*x*)(*C∞*) *− f* (*x*)(*C∞*)*| dμ* =0

For this we use the fact that we have just shown *fn*(*x*)(*C∞*) *→ f* (*x*)(*C∞*) pointwise almost everywhere, and that *|fn*(*x*)(*C∞*) *− f* (*x*)(*C∞*)*| ≤* 1 with 1 *μ*-integrable. It follows by dominated convergence that

lim *|fn*(*x*)(*C∞*) *− f* (*x*)(*C∞*)*| dμ*

*n→∞* ∫

*X*

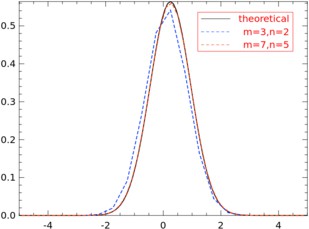
= ∫ lim *|fn*(*x*)(*C∞*) *− f* (*x*)(*C∞*)*| dμ* =0

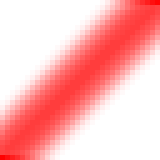
*X n→∞*

which concludes the proof of ([13](#_bookmark33)). To extend the result to simple functions and then to arbitrary functions *φ ∈* L1(*X, ν*) is routine. *2*

Note that operators of the shape S*pfn* obtained from a discretization scheme are *ﬁnite rank operators*. Thus, we, in fact, also obtained a theorem to approximate stochastic operators by *stochastic operators of ﬁnite rank* for the SOT topology. In general, we cannot hope for convergence in the stronger norm topology since the identity operator – which is stochastic – is a limit of operators of finite rank in the norm topology iff the space is finite dimensional.

Note also that the various relationships established in Section [4](#_bookmark17) allow us to move from an approximation of a kernel to an approximation of the corresponding Markov operator. Since a discretization scheme making *fn−→*s*f* will also make





inf

2.93

0.86

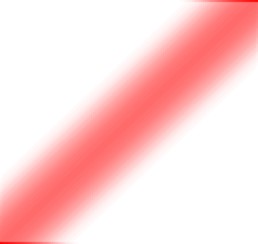
-1.21

-3.28

-inf

-inf -3.28 -1.21 0.86 2.93

inf



inf

3.58

1.16

-1.26

-3.68

-inf

-inf -3.68 -1.26 1.16 3.58

inf

Fig. 1. Log-likelihood of *f* 5*,*3 Fig. 2. Log-likelihood of *f* 6*,*10 Fig. 3. Approximate posteriors

(*f†*)*n−→*s*f†*, it follows from Theorem [4.10](#_bookmark21) that we get a finite rank approximation of the Markov operator *M ·*(*f* ).

# Application: Approximate Bayesian Inference

Consider again the inference problem from the introduction. There one needed to invert *f* (*x*) = *N* (*x,* 1) with prior *μ* = *N* (0*,* 1). We can use Theorem [5.1](#_bookmark26) to see how our approximate Bayesian inverse compares to the exact solution which in this simple case is known to be *f†*(0*.*5) = *N* (1*/*4*,* 1*/*2). To do this, we use a doubly indexed discretization scheme:

*μ*

*qmn* : R *→* 2 *× m × n* +2

defining a window of width 2*m* centred at 0 divided in 2*mn* equal intervals; with the remaining intervals (*−∞, −m*] and (*m, ∞*) each sent to a point (hence the +2 above).

Since all classes induced by *qmn* have positive *μ*-mass, approximants can be computed simply as:

∫

*fm,n*([*k*])([*l*]) = *μ*[*k*]*—*1 *N* (*x,* 1)([*l*]) *dμ*

*x∈*[*k*]

where [*k*], [*l*] range over classes of *qmn*. The corresponding stochastic matrices are shown in Fig. [1](#_bookmark34) and [2](#_bookmark34) for *m, n* = 5*,* 3 and 6*,* 10 respectively.

Since these approximants are finite, their Bayesian inverse can be computed directly by Bayes theorem (i.e. taking the adjoint of the stochastic matrices):

*fm,n†*

([*l*])([*k*]) =

*μ*[*k*] *· fm,n*([*k*])([*l*])

*ν*[*l*]

(14)

with *ν* = *f∗*(*μ*). Commutation of inversion and approximation guarantees that the

*fm,n†* converge to *f†*.

Indeed, Fig. [3](#_bookmark34) shows the the Lebesgue density of *fm,n†*(0*.*5) for *m, n* = 3*,* 2 (in dashed blue) and 7*,* 5 (dashed red). The latter approximant is already hardly distinguishable from the exact solution (solid black).

It must be emphasized that this example is meant only as an illustration and does not constitute a universal solution to the irreducibly hard (not even computable

in general [[1](#_bookmark37)]) problem of performing Bayesian inversion. Also, not all quotients are equally convenient: what makes the approach computationally tractable is that the fibres are easily described and the measure conveniently evaluated on such fibres.

# Conclusion

We have presented a framework for the exact *and* approximate semantics of first- order probabilistic programming. The semantics can be read off either in terms of kernels between measured spaces, or in terms of operators between L*p* spaces. Either forms come with related involutive structures: Bayesian inversion for (mea- sured) kernels between Standard Borel spaces, and K¨othe duality for positive linear and *σ*-continuous operators between Banach lattices. Functorial relations between both forms can themselves be related by way of natural isomorphisms. Our main result is the convergence of general systems of finite approximants in terms of the strong operator topology (the SOT theorem). Thus, in principle, one can com- pute arbitrarily good approximations of the semantics of a probabilistic program of interest for any given (measurable) query. Future work may allow one to derive stronger notions of convergences given additional Lipschitz control on kernels, or to develop approximation schemes that are adapted to the measured kernel of in- terest. More ambitiously perhaps, one could investigate whether MCMC sampling schemes commonly used to perform approximate Bayesian inference in the context of probabilistic programming could be seen as randomized approximations of the type considered in this paper.

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