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Local Bigraphs and Confluence: Two Conjectures

(Extended Abstract)

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Abstract

The notion of confluence is studied on the context of bigraphs. Confluence will be important in modelling real-world systems, both natural (as in biology) and artificial (as in pervasive computing). The paper uses bigraphs in which names have multiple locality; this enables a formulation of the lambda calculus with explicit substitutions. The paper reports work in progress, seeking conditions on a bigraphical reactive system that are sufficient to ensure confluence; the conditions must deal with the way that bigraphical redexes can be intricately intertwined. The conditions should also be satisfied by the lambda calculus. After discussion of these issues, two conjectures are put forward.

*Keywords:* bigraph, locality, confluence, lambda calculus.

Bigraphs have been used to present a variety of models of concurrency within a single framework, which also provides a theory applicable to all the models. As we seek informatic understanding of extensive real-life systems that reconfigure themselves, we cannot expect that our present repertoire of abstract process calculi (including Petri nets, mobile ambients, CSP and *π*-calculus) will suffice. So, as we enlarge our repertoire of calculi —perhaps specific to a certain application (e.g. in biology or in pervasive computing)— there is a need for unifying theory.

The bigraphical model is an experiment in this direction. It is not a specific calculus, but rather a framework for defining and combining such calculi. To define a specific bigraphical reactive system (BRS) two ingredients are needed: its *signature* defines its *controls* (the kinds of nodes allowed), and its *reaction rules* define how bigraphs can reconfigure themselves.

Already the model has yielded some elements of a theory, especially of labelled transitions and behavioural congruences [[6](#_bookmark12),[4](#_bookmark9),[5](#_bookmark11),[7](#_bookmark13)], which is applicable to a variety of BRSs. The present exercise addresses a different topic. First, in *local bigraphs* [[8](#_bookmark14)] we introduce a new treatment of names that allows them to have multiple *locality* (an example follows shortly). Similar work in bigraphs is by Bundgaard and Hilde-

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brandt [[3](#_bookmark10)]. Second, we study the notion of *confluence* —i.e. independence among actions— in this setting, in the belief that it will arise frequently in applications. One need only think of modelling behaviour within a building: activity at one end of the building is largely independent of activity at the other end.

This summary omits some details, but should be accessible to those unfamiliar with bigraphs. It summarises work whose aims are as follows: to understand how activities in local bigraphs can conflict with one another, leading to non-confluence; to represent the *λ*-calculus —the classic setting for confluence studies— within local bigraphs; and thereby to learn conditions under which confluence can be assured within this wider setting. The work is in progress; the summary ends with two conjectures.

that each arrow *f* has a *support* |*f* |, a finite set; composition *g* ◦ *f* is defined only if *Mathematical framework*: We work in s-categories. They differ from categories in

|*g*|∩ |*f* | = ∅, and then |*g* ◦ *f* | = |*g*|∪ |*f* |. Two arrows *f* and *g* are *support equivalent*,

*f* *g*, if they differ only by a bijection between their supports. Support is important

for the notion of *occurrence* of one bigraph in another. For example, our Conjecture 1 rests upon analysis of when and how two redex occurrences can overlap each other.

# Local bigraphs

*I* = *X* = ⟨*X*0*,... , Xm*−1⟩ has *width m*, a finite ordinal, and assigns to each *location Local bigraphs* are arrows in an s-category whose objects are *interfaces*. An interface *i* ∈ *m* a finite set *Xi* of *names*. The *Xi* need not be disjoint; thus, for example, any *x* ∈ *X*0 ∩ *X*1 has dual locality.

If *J* = *Y* is another interface with width *n*, then a local bigraph *G* : *I* → *J* has *m*

*sites* and *n roots* (or *regions*). Each region contains an unordered tree, whose root

is the region and whose other members are either *nodes* or sites; the latter must be leaves. The interfaces dictate an assignment of names to each site and each region; the *inner* and *outer* names of *G* are those of *I* and *J* respectively. The support

|*G*| of *G* is its set of nodes; we say that *F* and *G overlap* if their supports are not

disjoint.

Figure [1](#_bookmark0) shows a local bigraph with three sites (shaded) and two roots; the trees are represented by nesting. Each node may have *ports*, the number depending on the node’s *kind* or *control* (not shown). The set of ports and inner names is partitioned into *links*; a link is either *free* (an outer name) or *bound* by a *binding port*. The example has two free links, *x*' and *z*', and one link bound by a port on the largest node. Binding ports are shown as circles, free ports as bullets.

There is a scoping discipline: if a link is bound, then its inner names and ports must lie within the node that binds it; if a link is free, with outer name *x*, then *x* must be located in every region that contains any inner name or port of the link.

The *composition* of *G* : *I* → *J* with *F* : *H* → *I*, written *G* ◦ *F* , is easy to define graphically: insert the roots of *F* in the sites of *G*, joining links at like names and

eliding the names. Observe that, via composition, nodes in different regions can become separated by arbitrarily many node boundaries —while still sharing links.



*x*′

*z*′

*z*

*x y*

*x z*

Fig. 1. A local bigraph *G* : ⟨{*xy*}*,* {*xz*}*,* {*z*}⟩ →⟨{*x*'}*,* {*x*'*z*'}⟩

*R R*'

*x*0

*z*

renew

resource

*x*0

*x*1

0

1

0 1



*x*0

*z*

resource

*x*0

0 := 1

*x*1

1 := 1

0 1

Fig. 2. A parametric reaction rule

An *agent a* : *ϵ* → *I* has no sites; *ϵ* is the trivial interface with width 0. We use lower-case letters for agents.

# Reaction rules and λ-calculus

rule has a redex *R* : *H* → *K* and a reactum *R*' : *H*' → *K*, which may have different We are interested in *parametric (reaction) rules* that reconfigure agents. Such a numbers *m* and *m*' of sites. A *parameter* for the rule is then an agent *a* : *H* ⊕ *I*, with width *m*. The interface *H* ⊕ *I* has width *m*; it combines two interfaces *H* and *I*, each with width *m*, by taking the union of names at each location. *H* represents

names of *a* to be bound by *R*; *I* represents names of *a* to be exported by extra free links through *R*.

Figure [2](#_bookmark1) shows a parametric rule where *R* and *R*' both have two sites. So it takes a parameter *a* = *a*0  *a*1 of width 2, with factors *a*0 and *a*1 each of unit width. The the parallel composition  is derivable from the tensor product in s-categories; if *a* and *b* have widths *m* and *n* and disjoint supports, then in *a * *b* –with width *m*+*n*– they are placed side-by-side, sharing free links. Sites in *R* and *R*' are numbered; an assignment *j* := *i* written in the *j*th site of *R*' means that the reaction should place here a copy of the *i*th factor of *a*. Thus the rule shown will discard *a*0 and duplicate *a*1, putting one copy at each site of *R*'. (We omit details of how each copy’s names are determined.)

We can think of the rule as the renew node fetching from the resource node (via the shared link *z*) a new copy of its resource *a*1. Since *R* has two regions, the renew and resource nodes may be arbitrarily far apart in a large bigraph containing an occurrence of the redex *R*; so the rule offers the possibility of action at a distance. Let us now define a certain *λ*-calculus, Λsub, in the usual way. It is a version

*x*

lam

*x*



app

var

lam(*x*)

app

var*x*

*x*

sub



*x*

def

sub(*x*) def*x*

Fig. 3. Ions for the ˆΛbig, with their algebraic representation

with explicit substitutions, but with coarser steps than that of Abadi et al [[1](#_bookmark7)]. The terms are

*M* ::= *x* | *λxM* | *MN* | *M* [*x*:=*N* ]

be confused with {*N/x*}*M* , the result of *replacing* all free occurrences of *x* in *M* by The final term construction should be read ‘*M* where *x* means *N* ’; it should not to *N* .

Definition 2.1 (reduction) The reduction rules in Λsub are as follows: (*λxM* )*N d M* [*x*:=*N* ]

({*x/y*}*M* ) [*x*:=*N* ] *d* ({*N/y*}*M* ) [*x*:=*N* ] where *M* has a unique

free occurrence of *y*

*M* [*x*:=*N* ] *d M* where *M* has no free occurrence of *x .*

Reductions may be applied to any subterm of a term.

Thus reductions are allowed even inside an explicit substitution. In the second rule,

{*x/y*}*M* distinguishes a particular free occurrence of *x* to be replaced by *N* . The three rules together achieve *β*-reduction. The explicit substitution [*x*:=*N* ] acts ‘at

a distance’ on each free occurrence of *x* in turn, rather than migrating a copy of itself towards each such occurrence as in [[1](#_bookmark7)].

We now turn to ˆΛbig, the BRS corresponding to Λsub. Figure [3](#_bookmark2) shows its signature both graphically and algebraically. There are five controls (kinds of node), shown as *ions* (elementary bigraphs); a var-node has no sites, an app-node has two, and the rest have one. lam- and sub-nodes bind a link; var- and def-nodes have one port. The shapes of a node is unimportant, except that the shape of the app-

node signifies that its sites are in left-to-right order. [1](#_bookmark3) Note that binding names are parenthesized.

To export free names from their occupants, the ions with sites are generalised

to

lam(*x*) ⊕ id*Z* app ⊕ (id*Y* | id*Z*)

sub(*x*) ⊕ id*Z* def*x* ⊕ id*Z .*

The app-ion exports names *Y* from its first site, *Z* from its second.

formally, but illustrate their meaning by examples. A *prime* composition *F* | *G* is Two new operators appear here. In this abstract we do not define operators like *F * *G* (and derivable from it), but it merges the outer regions of *F* and *G* into

one. The operator ⊕ is called *extension*. The extension *I* ⊕ *I*' of interfaces (with same width) was defined earlier. Given *G* : *I* → *J* and *ω* : *I*' → *J*' (a wiring, i.e. a node-free bigraph) one can form *G* ⊕ *ω* : *I* ⊕ *I*' → *J* ⊕ *J*' provided the interface extended by adding the linkage of *ω*. Thus id*Y* | id*Z*, with inner width 2 and outer extensions are defined; it has the same tree structure as *G*, but the linkage of *G* is *Y* and *Z* as outer names. The operators ◦ *, * *,* | and ⊕, though partial, have a rich width 1, is a suitable extension for app; it exports the union of the inner name-sets

algebraic theory.

The free names in a bigraph built from the above ions correspond exactly to the free variables in a *λ*-term. Thus *λx x*(*xy*) will translate into the bigraph

(lam(*x*) ⊕ id*y*) ◦ (app ⊕ (id*x* | id*xy*)) ◦ (var*x * ((app ⊕ (id*x* | id*y*)) ◦ (var*x * var*y*))) *.* (Here a set such as {*xy*} has been written without curly brackets.) Of course, this notation is not recommended for developing *λ*-calculus theory! – but it has

the advantage that the free names exported with each term constructor are made explicit.

We now translate Λsub into ˆΛbig. The translation function **[***M* ]]*X* is indexed by the set *X*, which must include all the free variables of *M* . Thus each term *M* has many bigraph images. This technique was used to model the asynchronous *π*-calculus [[4](#_bookmark9)].

Definition 2.2 (*λ*-terms into bigraphs)

[[*x*]]*X**x*

d=ef var ⊕ *X*

[[*λxM* ]]*X*

*x*

d=ef (lam ⊕ id ) ◦ [[*M* ]]

[[*MN* ]]*X*

(*x*) *X X* *x*

(*x*) *X X* *x x X* *X*

d=ef (app ⊕ (id | id )) ◦ ([[*M* ]] [[*N* ]] )

[[*M* [*x*:=*N* ]]]*X*

*X X X* *X*

d=ef (sub ⊕ id ) ◦ ([[*M* ]] | ((def ⊕ id ) ◦ [[*N* ]] )) *.*

We shall not discuss this translation fully. But it is worth noting that alpha-

convertible *λ*-terms have equal images; this is because bound names are elided by

1 Multiple-site Controls are definable from single-site ones, site, with the help of a sorting discipline.

A



app

lam

0

*x*

1



*x*

0:=0

1:=1

sub

def

C

*x*

0:=0

1 :=0

def



*x*

0

var

def

D



0

1

sub

def

0:=0

*R R*'

|  |  |  |
| --- | --- | --- |
| A | app◦ (lam(*x*)  id) | sub(*x*) ◦ (id*x* | def*x*) |
| C | var*x*  def*x* | id  def*x* |
| D | sub(*x*) ◦ (id | def*x*) | id |

Fig. 4. Parametric reaction rules for ˆΛbig

composition. We are now ready to present the reaction rules for the BRS ˆΛbig.

Definition 2.3 (dynamics) ˆΛbig has three reaction rules: A (apply), C (copy) and D (discard). They are shown both graphically and algebraically in Figure [4](#_bookmark4).

Note that rule C has width 2. Thus, in C, an occurrence of the ‘variable’ *x* may be distant from the defining equation that will replace it with a ‘term’. This rule exploits the multiple locality of names in local bigraphs; it is similar to the rule of Figure [2](#_bookmark1).

We now assert that reaction in ˆΛbig exactly matches reduction in Λsub:

Proposition 2.4 (reaction matches reduction) [[*M* ]]*X d g if and only if*

*M d M* ' *for some M* ' *such that* [[*M* ']]*X* *g .*

In fact, for each reduction by a rule for Λsub there is a matching reaction by the corresponding rule for ˆΛbig, and conversely. In a recent draft O’Conchuir [[9](#_bookmark15)] has proved (strong) confluence directly for Λsub, so this translates immediately into a confluence proof for ˆΛbig. Our purpose here is different; we use the bigraphical

*g*0

'

*g g g*

*g*1

*g*0

'

\*

\*

\*

\*

*g g*

*g*1

*g*0

'

\*

\*

*g*

*g*1

one−step strong weak

Fig. 5. Three notions of confluence

representation to illustrate the confluence properties that we seek for bigraphs in general.

# Confluence in bigraphs

Recall that for any given reduction or reaction relation ‘ *d* ’ there are three familiar notions of *confluence*, shown in Figure [5](#_bookmark5). They all say that if *g* can react to become either *g*0 or *g*1, then these two reacta can in turn react to reach a common result.

Clearly *one-step* ⇒ *strong* ⇒ *weak*, and it is well-known that these implications are strict in general. The most positive result for a BRS would be that strong confluence

holds outright. This is indeed true (the Church-Rosser theorem) for the classical *λ*- calculus, and (by O’Conchuir) for Λsub also. However, in bigraphs we cannot expect this in general. Instead, we shall look for conditions that ensure non-interference between two competing reactions *g d g*0 and *g d g*1; such conditions may depend on the reaction rules that underlie the two translations, and on the extent to which the two redices overlap (if at all) in *g*. Moreover, it is in general easier to establish weak confluence in such cases.

If we succeed in showing that weak confluence always holds for a certain class of agents under certain reaction rules, and if this class is itself preserved by reaction, then we may look to well-known methods from the theory of the *λ*-calculus that allow us to deduce strong from weak confluence. One such method is based upon *de-*

*velopments* [[2](#_bookmark8)]. A development is a reduction sequence *M d M*1 *d M*2 *d* ··· in

which the only redices reduced are the residuals of an arbitrary set of redices present

initially in *M* . The method is based upon the theorem that if all developments are of finite length, then weak confluence implies strong confluence.

Before going further, we note that BRSs can be wilder than the *λ*-calculus! One property, used again and again in case analyses for the *λ*-calculus, is that when a term contains two redices then they are either disjoint or else nested (one inside the other). This fails for ground redices in BRSs; worse, it even fails for the parametric redices underlying them. Indeed, Figure [6](#_bookmark6) shows two possible parametric redices which are intimately entwined, each partly inside the other.

*R x* redexes *y S g*



*x*

*y*

A

B′

B

A′

A A′ B′ B

Fig. 6. An agent *g* containing two intertwined redices *R* and *S*

We do not know whether this property —redices nested or disjoint— is essential for weak confluence, or for finiteness of developments, in a BRS. However, recent investigation has explored a classification of ways in which two competing redices can

overlap. If a parametric redex *R* supports a reaction *g d g*0, then *r* = (*R* ⊕ *ω*) ◦ *a*

reaction *g d g*1, then *s* = (*S* ⊕ *ζ*) ◦ *b* occurs in *g*. The *ground* redices *r* and *s* can occurs in *g*, for some parameter *a* and wiring *ω*. Similarly, if redex *S* supports a overlap in different ways; for example *s* may not overlap with *R*, but may partly

overlap with *a*. The investigation identifies four principal cases for such overlap, and claims that under certain further conditions the weak confluence diagram can be completed by *g*0 *d* ∗*g*' and *g*0 *d* ∗*g*'. As this work is not complete we confine ourselves at present to two indeterminate conjectures about reactions in BRSs:

Conjecture 1 (weak confluence in ˆΛbig) *Weak confluence holds for certain sets of agents in certain BRSs, including the set of all images of* Λsub*-terms in* ˆΛbig*.*

Conjecture 2 (finite developments in ˆΛbig) *Developments are ﬁnite for certain sets of agents in certain BRSs.*

Together, these two results will lead to strong confluence for the agents mentioned. Conjecture 1 is reasonably firm, since (as indicated) much of the analysis has been done. Conjecture 2 is left vague at present. It is possible that, in ˆΛbig, developments are finite only under some constraint. O’Conchuir’s detailed study [[9](#_bookmark15)]

may help to identify such a constraint.

# Conclusion

The aim of this work is not to find yet another proof of the Church–Rosser theorem for a variant of the *λ*-calculus, but rather to learn from such proof techniques in order to analyse confluence for a wider class of agents and reaction rules than that for which it has hitherto been studied. This will lead to a better understanding not only of practically useful BRSs, but also of confluence itself.

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