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[](http://crossmark.crossref.org/dialog/?doi=10.1016/j.eij.2019.04.001&domain=pdf)Microarray spot segmentation algorithm based on integro-differential operator

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# a r t i c l e i n f o

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# a b s t r a c t

Microarray technology has increased exponentially in the past few years. Such technology encompasses various applications related to drug design, tumor detection, clinical diagnosis and treatment, and envi- ronmental health research. However, the segmentation of the spots in microarray image is still a problem due to variations of spots qualities such as spots shapes and sizes for example. Hence, we have introduced a new microarray spot segmentation algorithm based on Integro-Differential Operator (IDO). Because it includes a spot detection step, this IDO can be used to find any spot regardless of its size and shape within the microarray image. The IDO algorithm is applied on the cDNA microarray images to improve the accu- racy and the efficiency of the spots segmentation process. As the IDO is able to segment each spot based on the fact that the illumination difference between the inside and the outside of the pixels in spot edge circle is maximum. We have also tested our algorithm on the Stanford Microarray Database (SMD). The numerical results show that, the IDO is a powerful technique to improve the overall spots segmentation on the microarray image and to also give better results in spot segmentation and analysis process.

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1. Introduction

DNA segmentation refers to the process of automatically detect- ing the spots (genes) in a given microarray image. This process helps in extracting features from the discriminative texture of the cDNA, while excluding the surrounding regions. A microarray image showing genes (spots) is seen in [Fig. 1](#_bookmark3).

Spot segmentation plays a key role in the performance of the gene recognition system. This is because improper segmentation can lead to incorrect feature extraction from less discriminative regions, thereby reducing the recognition performance [[1]](#_bookmark17).

cDNA microarray image analysis pass through three major steps:

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Step one: cDNA image noise filtering

This is the process of removing noise from cDNA microarray image without affecting the genes data. A fast noise detection method without resorting to pairwise distance computations between each pixel is discussed in [[2]](#_bookmark18).

Step two: Spot addressing and localization

This is a separation process of the spots into a distinct cells [[3]](#_bookmark29), which is based on calculating the vertical and horizontal image intensity profile, as discussed in [[4–6]](#_bookmark19).

Step three: Microarray image segmentation process

The process splits the image pixels into foreground and back- ground pixels [[7]](#_bookmark19). Microarray image segmentation techniques can be categorized into four categories;

* 1. *Fixed circle segmentation*

This method assumes that all the spots have perfect circle shape and same size [[8]](#_bookmark19). Some cDNA microarrays segmentation software have been developed based on the fixed circle segmentation method, like ScanAlyze developed by Eisen in 1999 [[9]](#_bookmark19), and Gene- Pix developed by Axon Instruments Inc. in 1999 [[10]](#_bookmark19).

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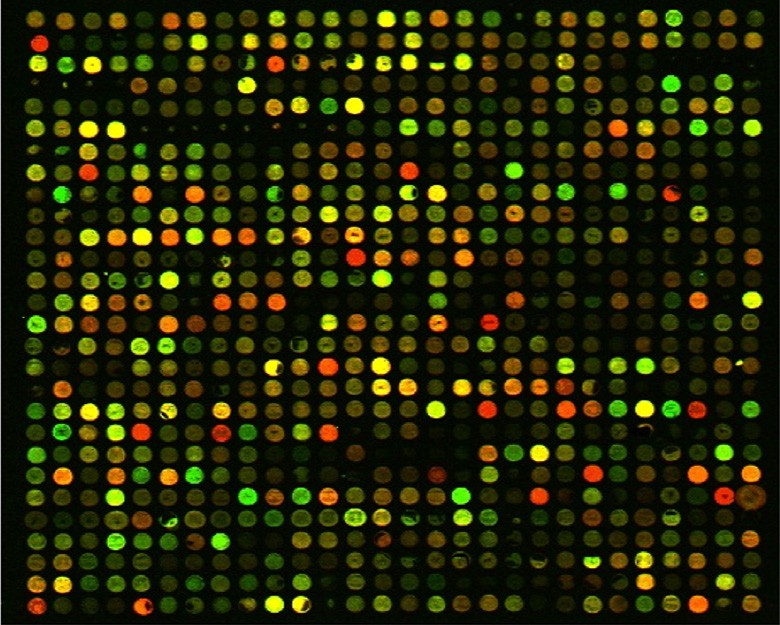


Fig. 1. cDNA microarray image.

* 1. *Adaptive shape segmentation*

This method assumes that the spots have a circular shape but also allows for adjusting the size of each spot [[11]](#_bookmark19). Adaptive shape segmentation methods, like watershed [[12]](#_bookmark19) and seed region grow- ing [[13]](#_bookmark19), is based on selecting start points and enlarging the detected spot area step by step until some criterion is reached. Seed region growing has been implemented in the spot software [[14]](#_bookmark19).

* 1. *Histogram segmentation*

This segmentation is used by computing a threshold value using

-Whitney test, where Mann-Whitney use a circular target mask to cover all the foreground pixels, and compute a threshold [[15]](#_bookmark19). The pixels with intensity lower than the threshold value is considered as background and the pixels with intensity value higher than the threshold value is considered as foreground [[16]](#_bookmark20).

* 1. *Clustering*

The main idea behind the clustering algorithm is to group the pixels into clusters [[17]](#_bookmark21). Clustering methods have been employed for segmenting the microarray images such as K-means [[18]](#_bookmark22) and Fuzzy C-means [[19]](#_bookmark23).

In this paper we have used IDO to separate the cDNA microarray spots from its background. Segmentation by IDO is fast, reliable and extensively employed in image processing and analysis [[21]](#_bookmark24). IDO is included in adaptive shape segmentation and it is a powerful technique where it combines the frontier approach and the region approach, IDO makes a fast detection of both edges and regions [[22]](#_bookmark25). The paper organized as follows. In the second section, the pro- posed techniques are explained in detail. Experimental results obtained after applying the proposed method on real images from the Stanford Microarray Database (SMD) [[23]](#_bookmark26) are discussed in the third section. Finally, the conclusion is analyzed in the fourth section.

1. The proposed techniques

The previous HCT spot segmentation approaches assume that the boundary of gene is a circle. However, according to our obser- vation, circle cannot model this boundary accurately. To improve the quality of segmentation, a novel IDO is proposed to detect the irregular boundary of spot. The method can successfully detect all the spot boundaries in the SMD database [[23]](#_bookmark26) and increase the recognition accuracy. This new algorithm based on applying

Integro-Differential Operator on cDNA microarray spots images for spots segmentation. The input cDNA microarray image comes across several steps before the proposed technique is performed as shown in the flowchart at [Fig. 2](#_bookmark4).

It typically involves the following steps:

500 × 500 pixels. 1. Read the cDNA microarray image and crop a spot region of

1. Spot addressing and localization based on the calculation of

vertical and horizontal image intensity profile [[6]](#_bookmark19).

1. Each spot is extracted as individual image.
2. Integro-differential operator [[20]](#_bookmark27) is applied on each spot image for spot segmentation.
3. Compare the segmentation result of Integro-Differential Operator with Hough circle transformation (HCT) method

[[11]](#_bookmark19) and measure the gene expression level.

* 1. *Dataset*

More than seven hundred of real microarray images from the Stanford Microarray Database (SMD) [[23]](#_bookmark26) are employed to illus- trate the analytic power of our proposed technique. These images

are cropped to 500 × 500 pixels spot region as shown in [Fig. 3](#_bookmark5).

* 1. *Spot addressing and extraction*

Spot addressing and extraction is one of the most challenge pro- cess in gene analysis process. This is a separation process of the spots into a distinct cells as shown in [Fig. 6](#_bookmark6) [[6]](#_bookmark19).

* + 1. *Spot addressing algorithm*

Consider an image *A* ¼ f*aij*j*i* ¼ 1; 2; .. . ; *n*j*j* ¼ 1; 2; ... ; *m*g

The horizontal and vertical intensity profile calculated as

follows:

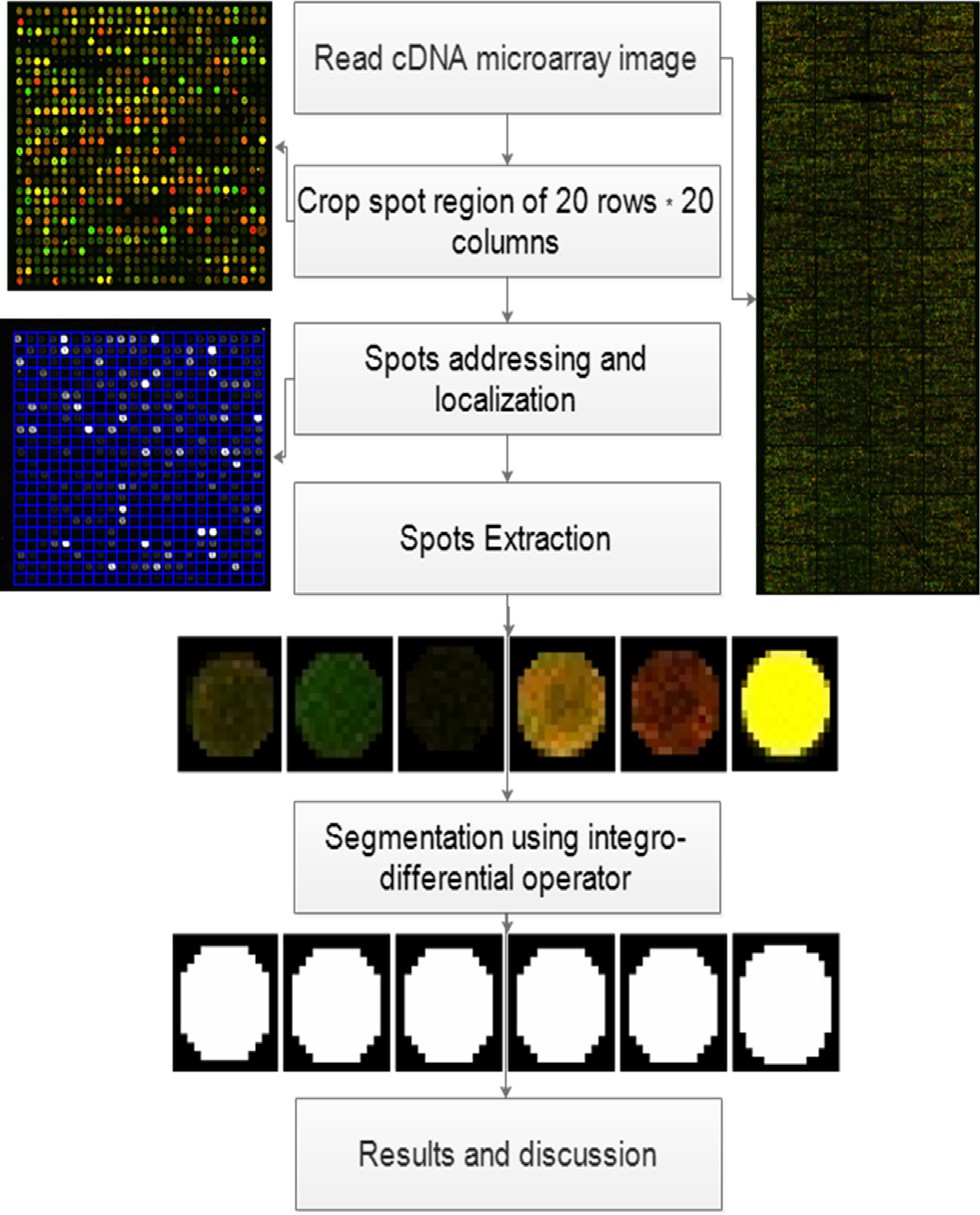


Fig. 2. The flowchart of the proposed technique.

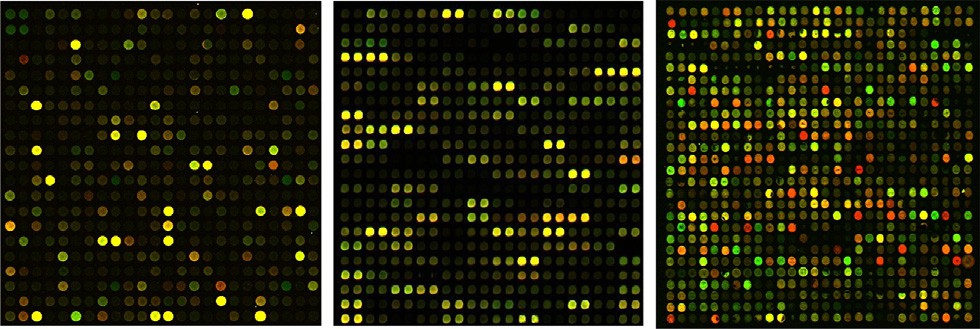


Fig. 3. Examples of the cropped cDNA microarray images.

*m*

*Hi* = *aij i* = 1; 2; ... ; *n* (1)

X

*j*=1

*n*

*Hj* = *aij j* = 1; 2; .. . ; *m* (2)

X

*i*=1

Use equation 1 and 2 to get the horizontal and the vertical grid

as shown in [Fig. 4](#_bookmark9).

Then calculate the columns width CW and Rows width RW by counting the number of zeros in *Hi and Hj* respectively.

Then draw the gridding map, which separate the spots into dis- tinct cells as shown in [Fig. 5](#_bookmark7).

Finally, extract each spot as a separate image as shown in [Fig. 6](#_bookmark6).

* 1. *Integro-Differential Operator*

Integro-Differential Operator (IDO) is included in adaptive shape segmentation and it is a powerful technique where it combi- nes the frontier approach and the region approach, it makes a fast detection of both edges and regions. IDO is based on the fact that the illumination difference between inside and outside of pixels in spot edge is maximum. In other words, if you calculate the dif- ference in values of pixels gray level in spot, this value is higher than any other object in the image. This fact turns to color of spot

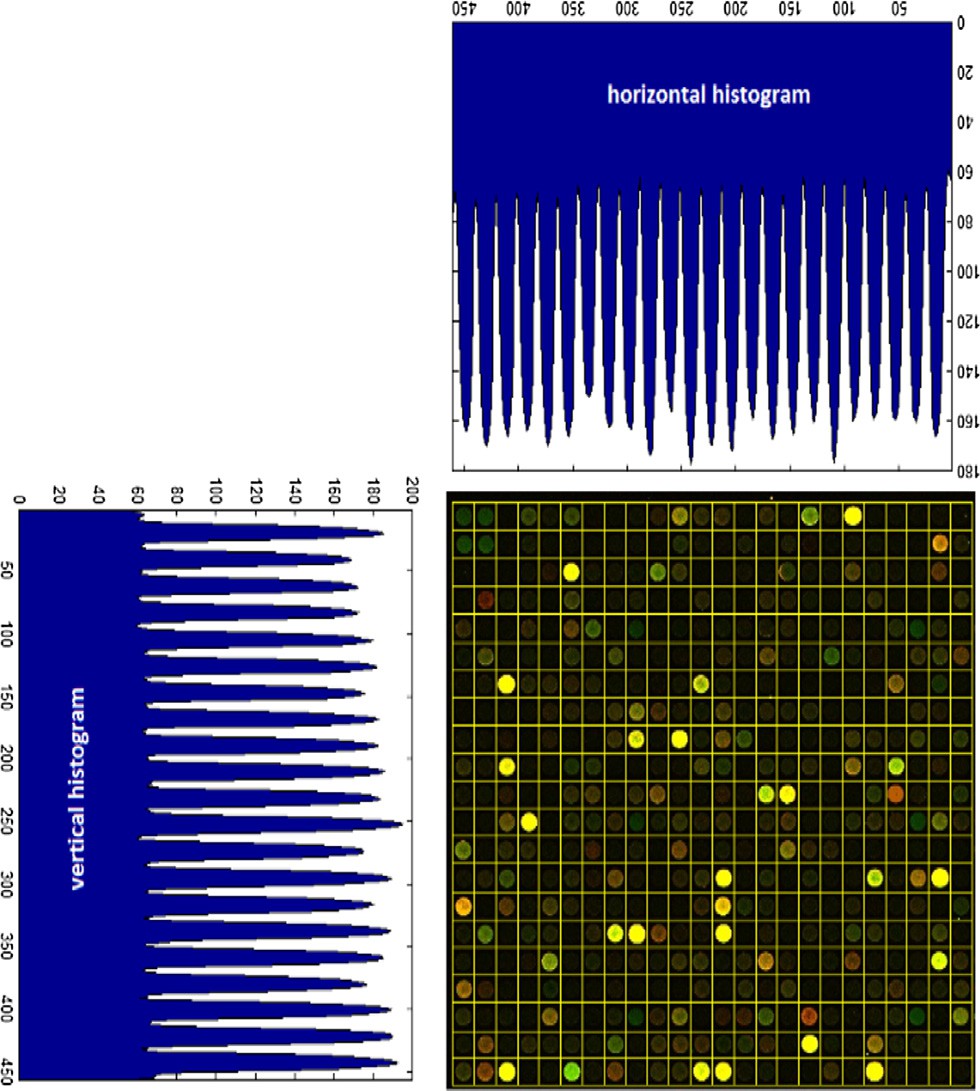
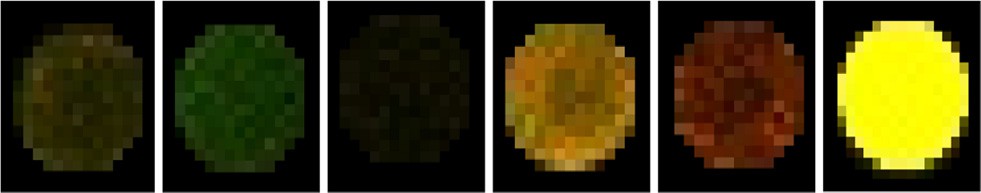
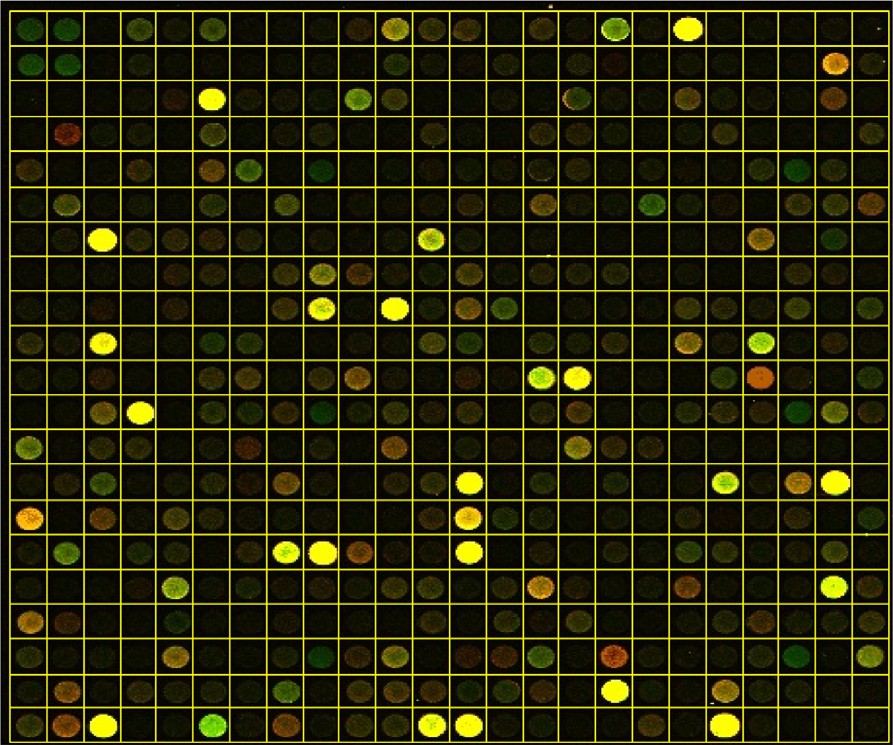


Fig. 4. Steps of gridding.

Fig. 5. The result of automatic gridding.



Fig. 6. Examples of the extracted spots as a result of the automated grading process.

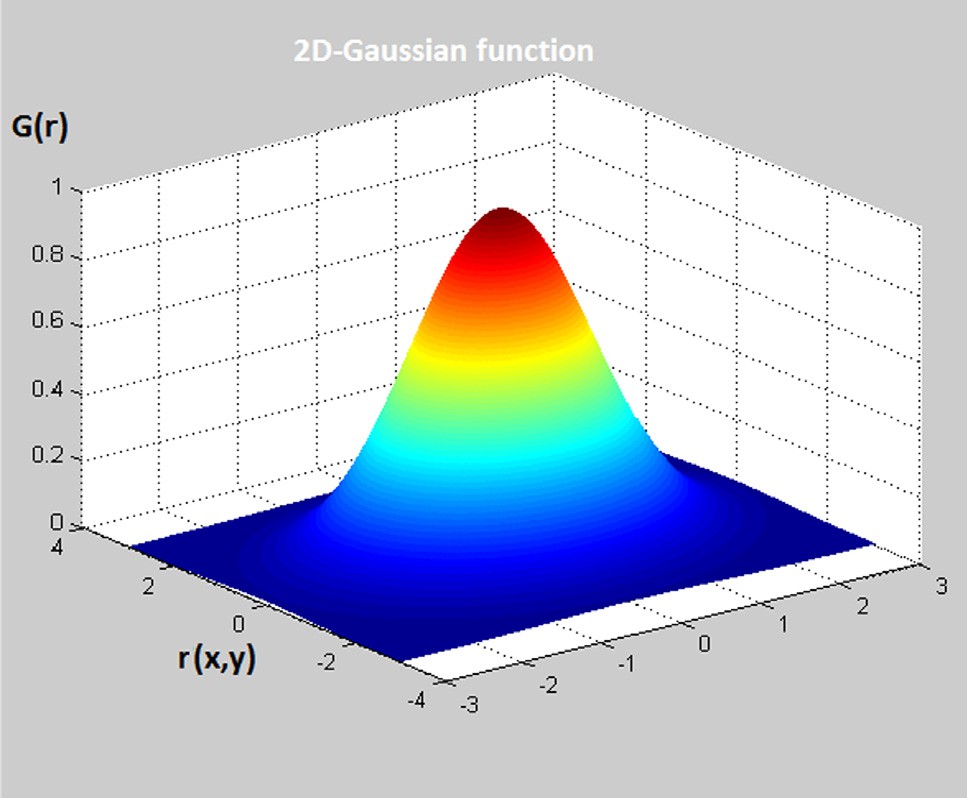


Fig. 7. 2D Gaussian smoothing function.

and color of background. [Fig. 8](#_bookmark10) present a result of segmented images using IDO.

* + 1. *IDO curve fitting algorithm*

First: Let *I*(*x*; *y*) containing a spot image like images in [Fig. 6](#_bookmark6). Then:

* + - * Search over the image domain (*x*; *y*) for the maximum in radius r of the normalized contour integral of *I*(*x*; *y*) along a circular arc ds of radius *r*, and center coordinates (*x*0; *y*0), the blurred partial derivative with respect to increasing

where the spot radius range from 7 to 11 pixel.

* + - * For locating the inner and the outer boundaries in a spot image use the following optimization:

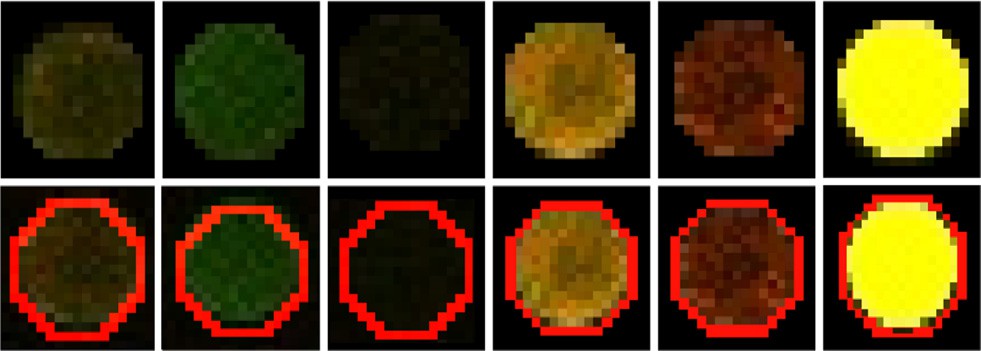


Fig. 8. Example of segmented spots using IDO.

For the edge point in the image, increment the parameters (*a*; *b*)

along the equation 10 then, get the local maxima of the results

which represent the center of the circle.

[Fig. 9](#_bookmark12) shows a random picked microarray image after applying CHT algorithm, in which each spot has a green circle around it, after that, each spot can be extracted as individual image as shown in [Fig. 10](#_bookmark11).

1. Experimental results

Image Processing Toolbox and Matlab 2012 [[24]](#_bookmark28) is used to eval-

@

max *r x y* *G r* Z

*I*(*x*; *y*)

*ds*

uate our new approach. Real twelve cDNA microarray images from

## 3

( ; *o*; *o*)

r( )\* @*r*

*r*;*x*0;*y*0

2p*r*

( ) SMD are employed to evaluate the efficiency and accuracy of the

proposed technique. This real image is cropped to the 200⁄200

where the symbol \* denotes convolution and *G*r(*r*) is Gaussian

smoothing function with sigma r = 0.5.

pixel region.

[Fig. 3](#_bookmark5) shows examples of the cropped spot regions, and then the

automated gridding algorithm [[6]](#_bookmark19) is applied to extract each spot in

1 — *r*2

*G*r(*r*)= 2pr2 *e* 2r2 (4)

* 1. *Hough circle transformation (HCT)*

Hough transform is recognized as a robust curve detection tech- nique [[11]](#_bookmark19). Hough transformation aims to find the circular patterns within an image, even noise existence, as shown in [Fig. 9](#_bookmark12).

* + 1. *HCT algorithm*

Consider a point (*xi*; *yi* ) in the image. The general equation of a circle is:

(*xi* — *a*)2 + (*yi* — *b*)2 — *r*2 = 0 (5)

where *a* and *b* are the coordinates of the center and *r* is the radius of

the circle.

The parametric equations for a circle in polar coordinates are:

*xi* = *a* + *r* cos h (6)

*yi* = *b* + *r* sin h (7)

Where h is the gradient angle.

Solving for the parameters of the circle we obtain the equations:

*a* = *xi* — *r* cos h (8)

*b* = *yi* — *r* sin h (9)

We can eliminate the radius from the pair of equations above to

yield

*b* = *a* tan h — *xi* tan h + *yi* (10)

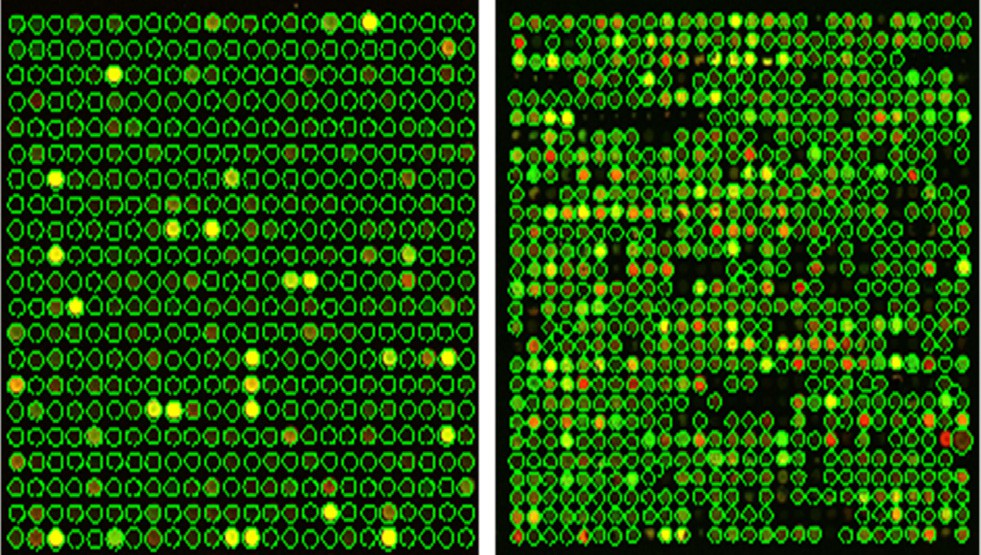


Fig. 9. The result of applying CHT on the cDNA microarray image.

the cropped image as individual image, as in [Fig. 6](#_bookmark6). This algorithm is based on calculating the horizontal and vertical intensity profile using Eqs [(1) and (2)](#_bookmark5) respectively to get the rows and columns width and draw the grid map as shown in [Fig. 5](#_bookmark7). After that IDO algorithm is applied in order to get a circle around the spot in the spot image, as in [Fig. 8](#_bookmark10). The pixels inside the circle are clustered as a signal and the ones outside the circle as background as in

11 pixel to get the radius r and the spot center point (*x*0; *y*0), then [Fig. 11](#_bookmark13). In IDO algorithm we use the spot radius range from 7 to apply the Eq. [(3)](#_bookmark10) for locating the inner and the outer boundaries

scale sigma r = 0.5 as a smoothing function. Finally compare the and use 2D Gaussian function, presented in Eq. [(4)](#_bookmark10) and [Fig. 7](#_bookmark8) with segmentation result of the proposed technique with other tech-

niques like GenePix® [[10]](#_bookmark19) and HCT [[11]](#_bookmark19) using quality index value Q-index and gene expression level GL.

1. The quality index (Q-index)

The Quality index (Q-index) [[25]](#_bookmark30) is used to evaluate the quality of the segmentation results of the proposed method (IDO) and HCT via the results of GenePix® as presented in the [Figs. 12A–12C](#_bookmark14).

Let *o* = {*oi*|*i* = 1; 2; 3; ... ; *N*} and *t* = {*ti*|*i* = 1; 2; 3; ... ; *N*} be the

original and the test image, respectively.

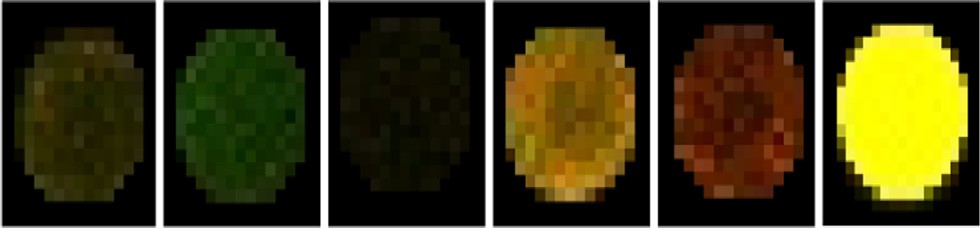


Fig. 10. Example of the extracted spots.

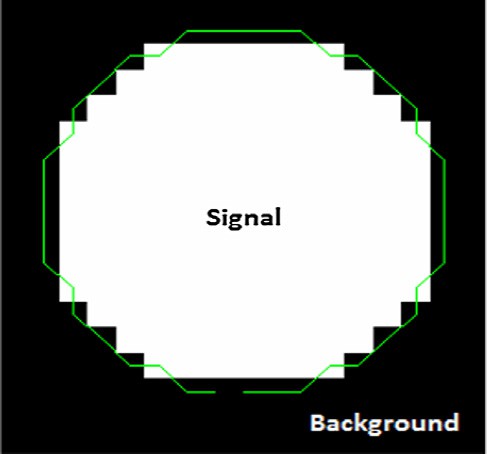


Fig. 11. Clustered spot image.

Fig. 12A. Q-index using IDO via GenePix®.

Table 1

The numerical results of Q-index for IDO and HCT via GenePix®.



|  |  |  |  |
| --- | --- | --- | --- |
|  | Min(Q-index) | Max(Q-index) | Mean(Q-index) |
| IDO | 0.0049 | 1 | 0.6292 |
| HCT | 2.9055e—04 | 0.9545 | 0.5616 |

Fig. 13A. Gene expression level using IDO.



Fig. 12B. Q-index using HCT via GenePix®.



Fig. 13B. Gene expression level using HCT.



Fig. 12C. Q-index using IDO and HCT via GenePix®.



*Q* — *index* = 4r*ot O*¯*T*¯

(r2 + r2)(*O*¯ 2 + *T*¯2 )

## (11)

*o t*

where

*N*

= 1 X *i* ( )

*O*¯ *O* 12

*N i*=1

Fig. 13C. Gene expression level using GenePix®.

*N*

= 1 X *i* ( )

*T*¯ *T* 13

*N i*=1

r2 = 1 X(*O* — *Oi*)2 (14)

*N*

Table 2

Numerical results of GL for IDO, HCT and GenePix®.

Min(GL) Max(GL) Mean(GL)

IDO —1.1476 0.9531 0.0141

*o N* — 1

*i*=1

*N*

HCT —1.1676 0.9531 0.0122

GenePix® —1.1421 0.9531 0.0145

r2 = 1 X(*T* — *Ti*)2 (15)

*t N* — 1

*i*=1

*N*

Also the visual results presented in the [Figs. 12A–12C](#_bookmark14) show that the IDO has the best result comparing with the HCT method.

r*ot* = 1 X(*O* — *Oi*)(*T* — *Ti*) (16)

*N* — 1 *i*=1

From the numerical results of Q-index for IDO and HCT via Gen-

ePix® in [Table 1](#_bookmark15), we found the Q-index of IDO variant from 0.0049 to 1 with a mean value of 0.6292. This is better than the values of the Q-index of HCT which variant from 2.9055e to 04 to 0.9545 with a mean value of 0.5616.

* 1. *Gene expression level Gl*

Gene expression level *Gl* is measured for each spot (gene) as in [Figs. 13A–13C](#_bookmark15) [[25]](#_bookmark30).

## *Gl* = log Red layer intensity (17)

*Green* layer intensity



Fig. 13D. Gene expression level using IDO, HCT and GenePix®.

The numerical results of gene expression level in [Table 2](#_bookmark16) and visual results in [Figs. 13A–13](#_bookmark15)D show that the IDO and GenePix® have a convergent result.

1. Conclusion

This paper presents an enhanced spot segmentation approach using Integro- Differential Operator, which includes a spot detec- tion step. IDO used to find spots regardless to its size and shape within the microarray image. It’s able to segment each spot based on the fact that the illumination difference between inside and outside of pixels in spot edge circle is maximum. The IDO algo- rithm is applied on the cDNA microarray images to improve the accuracy and the efficiency of the spots segmentation process. We have tested our new algorithm on the Stanford Microarray

Database (SMD). This new method was compared to other meth- ods like HCT and GenePix®. The numerical and visual results show that, the proposed technique is an effective in spot addressing, localization and segmentation.

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