

[Egyptian Informatics Journal (2011) 12, 107](http://dx.doi.org/10.1016/j.eij.2011.04.004)–[114](http://dx.doi.org/10.1016/j.eij.2011.04.004)

Cairo University

Egyptian Informatics Journal

[www.elsevier.com/locate/eij](http://www.elsevier.com/locate/eij) [www.sciencedirect.com](http://www.sciencedirect.com/science/journal/11108665)

ORIGINAL ARTICLE

Multicast routing with bandwidth and delay constraints based on genetic algorithms

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Received 7 November 2010; accepted 17 April 2011

Available online 20 July 2011

KEYWORDS

Multimedia communication; Multicast routing;

Multicast tree; Genetic algorithms; Bandwidth and delay

Abstract Many multimedia communication applications require a source to send multimedia information to multiple destinations through a communication network. To support these applica- tions, it is necessary to determine a multicast tree of minimal cost to connect the source node to the destination nodes subject to delay constraints on multimedia communication. This problem is known as multimedia multicast routing and has been proved to be NP-complete. The paper pro- poses a genetic algorithm for solving multimedia multicast routing, which find the low-cost multi- casting tree with bandwidth and delay constraints. In the proposed algorithm, the *k* shortest paths from the source node to the destination nodes are used for genotype representation. The simulation results show that the proposed algorithm is able to find a better solution, fast convergence speed and high reliability. It can meet the real-time requirement in multimedia communication networks. The scalability and the performance of the algorithm with increasing number of network nodes are also quite encouraged.

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1. Introduction

Multicast transmission of multimedia data is a crucial service

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Peer review under responsibility of Faculty of Computers and Information, Cairo University.

doi:[10.1016/j.eij.2011.04.004](http://dx.doi.org/10.1016/j.eij.2011.04.004)

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provided by the network layer; in fact, it allows the operator to spare a huge amount of network resources in many circum- stances. One of the most important applications that benefit form multicast transmissions is the video-clip streaming, where the same content is often sent simultaneously to even millions of users in the internet. Another application is the IPTV, which is going to be released by most of the ISP providers in the next few years. But many others can be cited.

An important problem when implementing multicast ser- vices is the design of the multicast trees, which influences the quality and should take into account the network utilization. First works addressing this problem dealt with a single

Nomenclature

*N*

*E U*

*e*(*i*, *j*)

P

*T B*(*e*)

*C*(*e*)

the set of nodes

the set of communication links the set of destination nodes

link from node *i* e *N* to node *j* e *N*

shortest path from source to destination node multicast tree

the bandwidth of *e*

the cost of *e*

*D*(*e*) the delay of *e*

Pop\_size the number of population Maxgen the max generation

*G*

*A*

gen

gen of a chromosome

account of populations account of generation

multicast session and focused on minimizing the transmission cost of each single tree. Many heuristic algorithms have been presented to solve the NP-complete unconstrained case [[1,2]](#_bookmark16), known as the Steiner tree problem. Other works, such as [[3–5]](#_bookmark17), have extended this problem by introducing constraints on the resulting quality of service (QoS), often evaluated in terms of end-to-end transmission delay.

Since in the real world several multicast sessions occur simultaneously, a new and more complex optimization prob- lem needed to be represented: the group multicast routing problem, which consists in the study of the best combination of trees for more sessions concurrently. Until now, only few papers have been published on this topic [[6–9]](#_bookmark13). In particular, Chen et al. [[8]](#_bookmark13) used an integer-programming approach consid- ering only sessions with the same bandwidth requirements. They defined the multicast packing problem in which the net- work tried to accommodate simultaneously all the multicast groups while avoiding bottlenecks on the links with high throughput (i.e., minimized the maximum congested link shared among multicast groups). Minimization of maximum congestion is achieved at the expense of increasing the size of some multicast trees which in turn affected the delay. This trade-off was addressed by adding a penalty term to the objec- tive function of the optimal packing formulation. The penalty term was a function of the amount of dilation from the size of the optimal tree obtained for each multicast session indepen- dently from the others, that is, in isolation. Since the mathe- matical programming formulation for the optimization problem was computationally intractable, they resorted to sub- optimal solutions with heuristics. Their heuristic method aimed to reduce the sharing of a link while ensuring that the size of multicast trees will never exceed alpha times the size of the optimum tree for a multicast group in isolation. Opti- mum multicast tree for each group (in isolation) was computed by using cutting plane inequalities and the branch-and-cut algorithm. Differently, Wang et al. [[9]](#_bookmark13), considered a multicast routing problem with multiple multicast sessions under a capacity limited constraint (there is no analysis on delay). In order to solve this problem they proposed two heuristic algo- rithms, Steiner-tree-based and cut-set-based. If the available bandwidth for the service is just enough, these algorithms may fail to find a solution even if the solution exists. Their heu- ristics make use of a simple distance based cost function.

In the last years, the genetic algorithms (GA) are gaining an increasing interest for solving complex problems in the networking field, as network design [[10]](#_bookmark13) and unicast routing [[11]](#_bookmark13). GA for multicast routing without constraints was pre- sented by Hwang et al. [[12]](#_bookmark13) and Bhattacharya et al. [[13]](#_bookmark13),

while Chen et al. [[14]](#_bookmark14) and Hamdan and El-Hawary [[15]](#_bookmark15) ad- dressed the constrained problem taking into account the QoS level provided for real-time applications in single multicast ses- sions. Randaccio and Atzori [[16]](#_bookmark18) presented an approach for group multicast routing by genetic algorithm. Chen and Sun

[[17]](#_bookmark19) proposed a new multicast routing optimization algorithm based on genetic algorithms, which find the low-cost multicast- ing tree with bandwidth and delay constraints.

In this paper, we design a multicast routing optimization algorithm with bandwidth and delay constraints based on ge- netic algorithms which can be suitable for the networks with uncertain parameters. The focus is on determining multicast routes from a source to a set of destinations with strict end- to-end delay requirements and minimum bandwidth available. The goal of this paper is to develop an algorithm to find out multicast routes with bandwidth and delay constraints by simultaneously optimizing end-to-end delay and bandwidth provided for guaranteed QoS. The scalability and the perfor- mance of the algorithm with increasing number of network nodes are also quite encouraged.

The paper is organized as follows. The problem description and formulation is given in Section 2. The genetic algorithm and its operators are presented in Section 3. Section 4 presents the proposed algorithm. Two examples are presented in Sec- tion 5, the first example with eight nodes and compare the results of our algorithm with the results of [[17]](#_bookmark19). The second example with 20 nodes. Section 6 presents the conclusion.

1. Problem description

A network is usually represented as a weighted directed graph *G* = (*N, E*), where *N* denotes the set of nodes and *E* denotes the set of communication links connecting the nodes. |*N*| and

|*E*| denote the number of nodes and links in the network, respectively [[17]](#_bookmark19). We consider the multicast routing problem with bandwidth and delay constraints from one source node to multi-destination nodes. Let *X* ¼ f*n*0; *u*1; *u*2; ... ; *um*g 2 *N*

be a set of from source to destination nodes of the multicast

tree. Where *n*0 is source node, and *U* = {*u*1, *u*2, ... , *um*} de- notes a set of destination nodes. Multicast tree *T* = (*NT*, *ET*), where *NT* C *N*, *ET* C *E*, there exists the path *PT* (*n*0, *d*) from

source node *n*0 to each destination node *d* e *U* in *T* [[17]](#_bookmark19). *e*(*i, j*) is a link from node *i* e *N* to node *j* e *N.* Three non-negative real value functions are associated with each link *e* (*e* e *E*): cost *C*(*e*), delay *D*(*e*), and available bandwidth *B*(*e*). The link cost function, *C*(*e*), may be either monetary cost or any measure of the resource utilization, which must be optimized. The link delay, *D*(*e*), is considered to be the sum of switching, queuing,

transmission, and propagation delays. The link bandwidth, *B*(*e*), is the residual bandwidth of the physical or logical link. The link delay and bandwidth functions, *D*(*e*) and *B*(*e*), define the criteria that must be constrained.

The cost of the path *PT* is defined as the sum of the cost of all links in that path and can be given by

X

*C*(*PT*) = *C*(*e*) (1)

*e*∈*PT*

The total cost of the tree *T* is defined as the sum of the cost of all links in that tree and can be given by

X

*C*(*T*) = *C*(*e*) (2)

*e*∈*ET*

The total delay of the path *P* (*n* , *d*) is simply the sum of the

and by the algorithm for finding the *k* shortest paths in Ref. [[18]](#_bookmark20), the candidate route set from source node to each destina- tion node must be proved.

The chromosome of genetic algorithms is composed of a series of integral queuing with length *m*, and the gene of the chromosome is the path in k shortest path between *n*0 and *ui*. Each chromosome in population denotes a multicast tree. Obviously, a chromosome represents a candidate solution for the multicast routing problem since it guarantees a path be- tween the source node and any of the destination nodes. Since there are so many paths between node *n*0 and *ui*, so that the encoding space of chromosomes possibly becomes larger, this decreases the convergence of solution. Now for each destina- tion node *d* e *U*, by the *k* the shortest route algorithm, [[17]](#_bookmark19)

*T* 0 the encoding space can be improved by finding out all routes

delay of all links along *PT*(*n*0, *d*):

X

*D*(*e*); *d* ∈ *U* (3)

*D*(*PT*) =

*e*∈*PT* (*n*0 ;*d*)

that satisfy bandwidth constraint from source node *n*0

to des-

The delay of multicast tree *T* is the maximum value of delay in the path from source node *n*0 to each destination node *d* e *U*.

tination node *d* e *U* and composing routes set as candidate

routes set of genetic algorithms encoding space.

X !

*D*(*T*) = max *D*(*PT*); *d* ∈ *U* (4)

*e*∈*PT* (*n*0 ;*d*)

The bandwidth of the path *PT*(*n*0, *d*) is defined as the minimum available residual bandwidth at any link along the path:

*B*(*P* ) = min(*B*(*e*); *e* ∈ *P* ) (5)

* 1. *The initial population*

The initial population is generated according to the following steps:

* *Step 1*: By assuming *U* = {*u*1, *u*2, .. . , *um*} denotes a set of destination nodes, *ui* = {*P*0, *P*1, ... , *Pk*}, (*k* is the number

of the shortest paths in *ui*) denotes a set of shortest paths

*T T* from source node to a destination node *ui*, and *Pi* =

The bandwidth of the tree *T* is defined as the minimum avail- able residual bandwidth at any link along the tree:

*B*(*T*) = min(*B*(*e*); *e* ∈ *ET*) (6)

Assume the minimum bandwidth constraint of multicast tree is *B*, and the maximum delay constraint id is *D*, given a multicast demand *R*, then, the problem of bandwidth-delay constrained multicast routing is to find a multicast tree *T*, satisfying:

1. Bandwidth constraint: *B*(*T*)= *B.*
2. Delay constraint: *D*(*T*)= *D.*

Suppose *S*(*R*) is the set and satisfies the conditions above, then, the required multicast tree *T* is:

*C*(*T*) = min(*C*(*Ts*); *Ts* ∈ *S*(*R*))

1. The proposed genetic algorithm

Genetic algorithms, as powerful and broadly applicable sto- chastic search and optimization techniques, are the most widely known types of evolutionary computation methods today. In the proposed genetic algorithm, we consider the four compo- nents: (1) an encoding method that is a genetic representation (genotype) of solutions to the program. (2) A way to create an initial population of chromosomes, (3) the objective func- tion (4) the genetic operators (crossover and mutation) that al- ter the genetic composition of offspring during reproduction.

* 1. *Encoding method*

Assuming *n*0 is source node, and *U* = {*u*1, *u*2, ... , *um*} denotes a set of destination nodes, the smallest bandwidth constraint,

{*n*0, *n*1, ... , *ui*} is a set of nodes. Then by randomly selecting *P* from each *ui, {i = 1,* ... , *m*}, we can generate the chro- mosome in the initial population as the following form:

where *g*1, g2, g3, ... , *gm* represent the ones of m shortest paths that satisfies bandwidth constraint between nod *n*0 and *ui*. (See [Fig. 1](#_bookmark2))



n0, ni, nj,………, u1 n0, ni, nj,………, u1

………………………………

n0, ni, nj,………, u1 n0, ni, nj,………, u2 n0, ni, nj,………, u2

………………………………..

n0, ni, nj,………, u2

n0, ni, nj,………, um n0, ni, nj,………, um

………………………………

n0, ni, nj,………, um

1

2

.

k

um

……………………

…

…

1

2

.

k

u2

1

2

.

k

u1

K shortest paths of satisfying bandwidth constraint between node

*n0* and the *ui*

Desti na- tion nodes.

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| g1 | g2 | g3 | …. | …. | gm |

Figure 1 The chromosome representation.

* + - *Step 2*: Repeat to generate pop\_size number of chromosomes.
  1. *The objective function*

Assume the minimum bandwidth constraint of multicast tree is *B*, and the maximum delay constraint is *D*, given a multicast demand *R*, then, the problem of bandwidth-delay constrained multicast routing is to find a multicast tree *T*, that satisfies:

1. Bandwidth constraint: *B*(*T*) P *B.*
2. Delay constraint: *D*(*T*) 6 *D.*

Suppose *S*(*R*) is the set and satisfies the conditions above, then, the multicast tree *T* which we find is:

*C*(*T*) = min(*C*(*Ts*); *Ts* ∈ *S*(*R*)) (7)

That is: find a sub network *T*(*N*)= (*NT*, *ET*, *CT*) of *G* such that:

* *N* C *NT*
* There is a path from the source node to each destination node;
* The cost of *T* (*N* ) = P*e*∈*ET C*(*e*) is minimized

|  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- |
| g1 | g2 | g3 | g4 | …. | gi | gj | gm |



|  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- |
| g1 | g2 | g3 | gi | …. | …. | gk | gm |

Figure 3 Mutation operation.

The offspring generated by crossover operation is shown in [Fig. 2](#_bookmark4).

*3.4.2. Mutation operation*

The mutation operation is performed on bit-by-bit basis. In the proposed approach, the mutation operation will perform if the mutation ratio (*Pm*) is verified. The mutation ratio, *Pm* in this approach will be 0.2 and is estimated randomly. The point to be mutated is selected randomly. The offspring gener- ated by mutation is shown in [Fig. 3](#_bookmark3).

1. The proposed algorithm

The proposed GA algorithm for solving the multicast routing problem is implemented by Borland C++ Ver. 5.2 and Oper- ating system windows XP. The steps of this algorithm are as follows:

Algorithm 1

* 1. *The genetic operators*

Genetic algorithm for multicast routing Input

pop\_size, maxgen, *Pm*, *Pc*, *no*, the destination nodes *U*, *B*

Steps:

1. Generate the initial population as in Section 3.2
2. gen → 1
3. While (gen 6 maxgen) do
4. P → 1
5. While (*p* 6 pop\_size) do
6. Genetic operations
   1. Obtain chromosomes of the new population
   2. Select two chromosomes from the parent population
   3. Apply crossover according to *Pc* (*Pc* P 0.9)
   4. Mutate the new child according to *Pm* parameter (*Pm* 6 0.2)
7. Compute the delay and cost of the new child (*D*(*T*) & *C*(*T*)) according to Eqs. [(3)](#_bookmark0) and (1), respectively
8. If (*D*(*T*)= *D*) then

Save this child as a candidate solution.

1. *P* → *p* +1

End if

End

1. Compare among all solutions to obtain the tree with minimum cost
2. End
   * 1. *Crossover operation*

The crossover operation is used to breed a child from two par- ents by one cut point. The crossover operation will perform if the crossover ratio (*Pc* = 0.95) is verified. The cut point is se- lected randomly. The crossover operation is performed as follows:

* + - * *Step 1*: Select two chromosomes randomly from the current population.
      * *Step 2*: Randomly select the cut point
      * Step 3:
        1. By taking the components of the first chromosome

(from the first gene to the cut point) and fill up to the child.

* + - * 1. Also, tacking the components of the second chromo- some (from the cut point + 1 to the last gene) and fill up to the child.

Cut point

parent



g1 g2 g3 g4 … gk gl gm

|  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- |
| g1 | g2 | g3 | g4 | … | gi | gj | gm |



child

1. Experimental results

This section shows the effectiveness of the above algorithm by applying it on two examples as follows:

* 1. *First example*

parent

|  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- |
| g1 | g2 | g3 | g4 | …. | gk | gl | gm |

Figure 2 Crossover operation.

This example shows the above algorithm by using the network with eight nodes which is taken from [[17]](#_bookmark19). Each link repre- sented by a triple-group (*B*, *D*, *C*), given its value randomly as shown in [Table 1](#_bookmark5) and [Fig. 4](#_bookmark7).

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| Table 1 The bandwidth, delay, and cost of the given network ([Fig. 4](#_bookmark7)). | | | |  | |
| Link | *B* bandwidth | *D* delay | *C* cost |
| 1–2 | 15 | 3 | 6 |
| 1–3 | 10 | 1 | 5 |
| 1–5 | 13 | 3 | 4 |
| 1–6 | 8 | 3 | 6 |
| 2–4 | 13 | 2 | 6 |
| 2–8 | 15 | 2 | 8 |
| 3–4 | 12 | 3 | 4 |
| 4–6 | 10 | 3 | 6 |
| 4–7 | 9 | 1 | 3 |
| 4–8 | 9 | 3 | 4 |  | **6** |
| 5–6 | 12 | 2 | 6 |  |  |
| 6–7 | 10 | 2 | 4 |  |  |

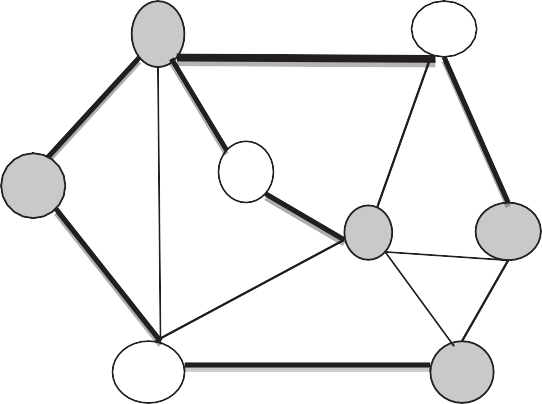
Figure 5 The multicast tree obtained by the proposed genetic algorithm.

7–8

12

2

6



**1**

**2**

**3**

**4**

**8**

**7**

**1**

**2**

**3**

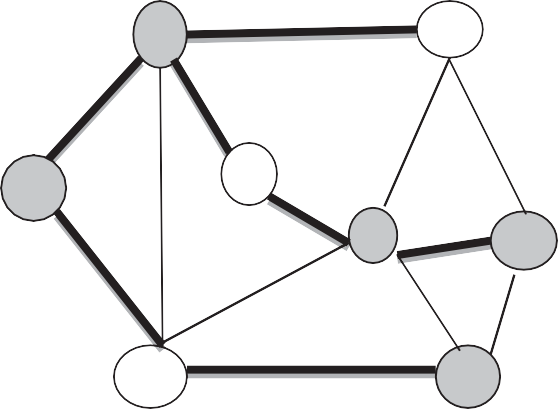
**5**

**4**

**8**

**6**

**7**



**1**

**2**

**3**

**5**

**4**

**8**

**6**

**7**

Figure 4 Network topology structure. Figure 6 The multicast tree obtained by [[17]](#_bookmark19).

|  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- |
| Table 2 The candidate path set from source node 1 to each destination node for example 1.  Destination node The shortest paths | | | | | | | |
| 4 | 1 | 2 | 8 | 7 | 6 | 4 |  |
|  | 1 | 3 | 4 |  |  |  |  |
|  | 1 | 5 | 6 | 4 |  |  |  |
|  | 1 | 2 | 4 |  |  |  |  |
|  | 1 | 5 | 6 | 7 | 8 | 2 | 4 |
| 5 | 1 | 5 |  |  |  |  |  |
|  | 1 | 2 | 4 | 6 | 5 |  |  |
|  | 1 | 2 | 8 | 7 | 6 | 5 |  |
|  | 1 | 3 | 4 | 6 | 5 |  |  |
| 7 | 1 | 3 | 4 | 2 | 8 | 7 |  |
|  | 1 | 3 | 4 | 6 | 7 |  |  |
|  | 1 | 2 | 4 | 6 | 7 |  |  |
|  | 1 | 2 | 8 | 7 |  |  |  |
|  | 1 | 5 | 6 | 7 |  |  |  |
|  | 1 | 5 | 6 | 4 | 2 | 8 | 7 |
| 8 | 1 | 5 | 6 | 4 | 2 | 8 |  |
|  | 1 | 3 | 4 | 2 | 8 |  |  |
|  | 1 | 3 | 4 | 6 | 7 | 8 |  |
|  | 1 | 5 | 6 | 7 | 8 |  |  |
|  | 1 | 2 | 8 |  |  |  |  |
|  | 1 | 2 | 4 | 6 | 7 | 8 |  |
|  |  |  |  |  |  |  |  |





Figure 7 The bandwidth values of the given network.



Figure 8 The delay matrix.



Figure 9 The cost matrix.

**1**

**10**

**17**

**13**

**20**

**8**

**16**

**4**

**14**

**11**

**6**

**7**

**19**

**12**

**9**

Figure 10 The multicast tree of 20 nodes.

Table 3 The candidate path set from source node 1 to each destination node for example 2.

Destination The shortest paths node

|  |  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- | --- |
| 9 | 1 | 13 | 16 | 4 | 7 | 9 |  | | |
|  | 1 | 17 | 8 | 4 | 2 | 16 | 13 | 7 | 9 |
|  | 1 | 13 | 16 | 2 | 4 | 7 | 9 |  |  |
|  | 1 | 17 | 8 | 6 | 4 | 7 | 9 |  |  |
|  | 1 | 13 | 7 | 9 |  |  |  |  |  |
|  | 1 | 17 | 8 | 4 | 7 | 9 |  |  |  |
|  | 1 | 17 | 8 | 4 | 16 | 13 | 7 | 9 |  |
|  | 1 | 17 | 8 | 6 | 4 | 16 | 13 | 7 | 9 |
| 11 | 1 | 17 | 8 | 6 | 4 | 16 | 11 |  |  |
|  | 1 | 17 | 8 | 4 | 2 | 16 | 11 |  |  |
|  | 1 | 13 | 7 | 4 | 16 | 11 |  |  |  |
|  | 1 | 13 | 16 | 11 |  |  |  |  |  |
|  | 1 | 17 | 8 | 4 | 16 | 11 |  |  |  |
|  | 1 | 17 | 8 | 4 | 7 | 13 | 16 | 11 |  |
|  | 1 | 13 | 7 | 4 | 2 | 16 | 11 |  |  |
|  | 1 | 17 | 8 | 6 | 4 | 2 | 16 | 11 |  |
| 12 | 1 | 17 | 8 | 6 | 12 |  |  |  |  |
|  | 1 | 13 | 7 | 4 | 6 | 12 |  |  |  |
|  | 1 | 13 | 16 | 2 | 4 | 8 | 6 | 12 |  |
|  | 1 | 17 | 8 | 4 | 6 | 12 |  |  |  |
|  | 1 | 13 | 16 | 4 | 6 | 12 |  |  |  |
|  | 1 | 13 | 7 | 4 | 8 | 6 | 12 |  |  |
|  | 1 | 13 | 16 | 4 | 8 | 6 | 12 |  |  |
|  | 1 | 13 | 16 | 2 | 4 | 6 | 12 |  |  |
| 14 | 1 | 13 | 16 | 4 | 6 | 8 | 14 |  |  |
|  | 1 | 13 | 16 | 2 | 4 | 6 | 8 | 14 |  |
|  | 1 | 13 | 16 | 4 | 8 | 14 |  |  |  |
|  | 1 | 13 | 7 | 4 | 8 | 14 |  |  |  |
|  | 1 | 13 | 7 | 4 | 6 | 8 | 14 |  |  |
|  | 1 | 17 | 8 | 14 |  |  |  |  |  |
|  | 1 | 13 | 16 | 2 | 4 | 8 | 14 |  |  |
| 16 | 1 | 17 | 8 | 4 | 2 | 16 |  |  |  |
|  | 1 | 17 | 8 | 6 | 4 | 16 |  |  |  |
|  | 1 | 17 | 8 | 4 | 16 |  |  |  |  |
|  | 1 | 17 | 8 | 6 | 4 | 7 | 13 | 16 |  |
|  | 1 | 13 | 7 | 4 | 16 |  |  |  |  |
|  | 1 | 13 | 7 | 4 | 2 | 16 |  |  |  |
|  | 1 | 17 | 8 | 6 | 4 | 2 | 16 |  |  |
|  | 1 | 17 | 8 | 4 | 7 | 13 | 16 |  |  |
|  | 1 | 13 | 16 |  |  |  |  |  |  |
| 17 | 1 | 17 |  |  |  |  |  |  |  |
|  | 1 | 13 | 16 | 4 | 6 | 8 | 17 |  |  |
|  | 1 | 13 | 16 | 4 | 8 | 17 |  |  |  |
|  | 1 | 13 | 7 | 4 | 8 | 17 |  |  |  |
|  | 1 | 13 | 16 | 2 | 4 | 8 | 17 |  |  |
|  | 1 | 13 | 7 | 4 | 6 | 8 | 17 |  |  |
| 19 | 1 | 17 | 8 | 14 | 19 |  |  |  |  |
|  | 1 | 13 | 7 | 4 | 8 | 14 | 19 |  |  |
|  | 1 | 13 | 16 | 4 | 8 | 14 | 19 |  |  |
|  | 1 | 13 | 7 | 4 | 6 | 8 | 14 | 19 |  |
|  | 1 | 13 | 16 | 2 | 4 | 6 | 8 | 14 | 19 |
| 20 | 1 | 10 | 20 |  |  |  |  |  |  |

Assuming the source node is node 1 and the destination nodes are {4, 5, 7, 8} as shown in [Fig. 4](#_bookmark7). By using the algo- rithm, [[18]](#_bookmark20) for finding the *k* shortest paths with smallest band- width constraint *B* = 10, we can find the candidate route set from source node 1 to each destination node as illustrated in [Table 2](#_bookmark9).

The parameters setting in the proposed algorithm are pop\_size = 20, *Pm* = 0.2, *Pc* = 0.9, maxgen = 600. The bandwidth *B* = 10, and the delay *D* = 7.

Thus, the desired multicast tree of the above network is shown in [Fig. 5](#_bookmark6) with cost 44.

The multicast tree obtained by [[17]](#_bookmark19) is shown in [Fig. 6](#_bookmark8).

By comparing the multicast tree obtained by the proposed genetic algorithm, given in [Fig. 5](#_bookmark6) and the other one which ob- tained by using genetic algorithm [[17]](#_bookmark19), given in [Fig. 6](#_bookmark8), we noted the following:

1. The bandwidth *B* of the path 1 → 3 → 4 → 8 in the tree obtained by [[17]](#_bookmark19) equal to 9 according to Eq. [(5)](#_bookmark1) which is

not 10 as it is imposed.

1. The path 1 → 2 is not true, because the node 2 does not rep- resent the destination node.

Hence, the multicast tree obtained by [[17]](#_bookmark19) is not correct, based on the parameters imposed.

* 1. *Second example*

This example shows the above algorithm by using the network with 20 nodes taken from [[18]](#_bookmark20). Each link represented by a tri- ple-group (*B*, *D*, *C*), given its value randomly and are shown in the following matrices ([Figs. 7–9](#_bookmark10)). The source node *n*0 is node 1, destination node set *U* = {9, 11, 12, 14, 16, 17, 19, 20}, the smallest bandwidth constraint *B* = 12. And by the algorithm for finding the *k* shortest paths in Ref. [[18]](#_bookmark20), we can find the candidate route set from source node 1 to each destination node, as shown in [Table 3](#_bookmark11).

The parameters setting in the algorithm: pop\_size = 20,

*Pm* = 0.2, *Pc* = 0.9, maxgen = 600. The source node *n*0 is

the node no. 1 and the destination nodes are *U* = {9, 11, 12, 14, 16, 17, 19, 20}, and *D* = 11, we find the multicast tree as shown in [Fig. 10](#_bookmark12) with cost = 122.

1. Conclusions and future work

This paper proposes a genetic algorithm for solving multime- dia multicast routing based on bandwidth and delay con- straints. The proposed algorithm uses the *k*th shortest paths algorithm, [[18]](#_bookmark20) to construct route set. The encoding space can be improved by finding out all routes that satisfy band- width constraint from source node to destination node and composing routes set as candidate routes set of genetic algo- rithms encoding space. The algorithm guaranteed and speeded searching ability of the optimal solution and the global conver- gence of solution by heuristic crossover and mutation opera- tion can be achieved.

By comparing the results of the above algorithm with the algorithm in [[17]](#_bookmark19), the multicast tree found by [[17]](#_bookmark19) is not right. Experimental results of second example showed the pro- posed algorithm has effect on the multicast routing of large

computer networks.

This algorithm can be applied to multi-constraint’s QoS multicast routing problem; only the chromosome who will changed and the delay constraint can be improved so as to make the algorithm widely applied.

Appendix A. Appendix

[Table 3](#_bookmark11).

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