1. [3 pts] If $\mathbf{a} = \langle 2, -1, 2 \rangle$ and $\mathbf{b} = \langle 1, -1, 2 \rangle$, find a non-zero vector \mathbf{c} such that $\mathbf{a} \cdot \mathbf{c} = \mathbf{b} \cdot \mathbf{c} = 0$.

Two approaches:

- 1) Compute & = a x to By geometric property of cross product, know that both & I a x to and bLaxb.
- 2) More Rudinentary solution: Let $\bar{c} = \langle c_1, c_2, c_3 \rangle$ and solve the system of equations

$$\begin{cases} \vec{a} \cdot \vec{c} = 0 \\ \vec{b} \cdot \vec{c} = 0 \end{cases} \begin{cases} \lambda c_1 - (c_2 + \lambda c_3 = 0) \\ c_1 - c_2 + \lambda c_3 = 0 \end{cases}$$

A system of two equations and 3 unknowns one possibility is $\tilde{c} = \begin{bmatrix} 0 \\ 2 \end{bmatrix}$

=14

2. [3 pts] Determine the projection vector $\operatorname{proj}_{\mathbf{a}}(\mathbf{b})$ of \mathbf{b} onto \mathbf{a} where $\mathbf{a} = \langle 1, 2, 3 \rangle$ and $\mathbf{b} = \langle 1, 2, 2 \rangle$.

Projection Vector is computed as:

proja(b) =
$$\vec{a} \cdot \vec{b} = \vec{a} \cdot \vec{b} = \vec{a} \cdot \vec{b} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix} = 1 + 4 + 6 = 11$$

Proja(b) = $\vec{a} \cdot \vec{b} = \vec{a} \cdot \vec{b} = \vec{a} \cdot \vec{a} = \vec{a}_1 + \vec{a}_2 + \vec{a}_3$

= $1 + 4 + 9$

Conclusion :

$$Proj_{\vec{a}}(\vec{b}) = \frac{11}{14} \begin{bmatrix} 1\\2\\3 \end{bmatrix}$$

3. [3 pts] If the scalar projection of **b** onto **a** is $\|\mathsf{proj}_{\mathbf{a}}(\mathbf{b})\| = 1$, determine the value of $\|\mathsf{proj}_{2\mathbf{a}}(3\mathbf{b})\|$.

Know:

Using the same formula:

the same formula:

$$|proj_{2\vec{a}}(3\vec{b})| = \frac{(2\vec{a}) \cdot (3\vec{b})}{|2\vec{a}|} = \frac{(2\vec{a}) \cdot (3\vec{b})}{|2\vec{a}|} = \frac{(2\vec{a}) \cdot (3\vec{b})}{|2\vec{a}|} = \frac{3}{||2\vec{a}||}$$

- 4. True/False. If the statement is true, give an explanation why you think so. If a statement is false, provide a counter-example.
 - (a) [3 pts] The cross product of two unit vectors is a unit vector.

FALSE Then the magnitude of cross product computed as:

| Tax 6 | = | Ta | | Tb | sin 0

= 1. | sin 0

= sin 0

| Then the magnitude of cross product computed as:

| Tax 6 | = | Ta | | Tb | sin 0

| Tax 6 | = | Ta | | Tb | sin 0

| Tax 6 | = | Ta | | Tb | sin 0

| Tax 6 | = | Ta | | Tb | sin 0

| Tax 6 | = | Ta | | Ta | | Tax 6 | = |

(b) [3 pts] If **u** is a scalar multiple of **v**, then $\mathbf{u} \times \mathbf{v} = \mathbf{0}$.

For a scalar multiple of \mathbf{v} , then $\mathbf{u} \times \mathbf{v} = \mathbf{0}$.

Ruf since $\ddot{\mathbf{u}} = c\ddot{\mathbf{v}}$, know that $\ddot{\mathbf{u}} = c\ddot{\mathbf{v}}$, know that $\ddot{\mathbf{u}} = c\ddot{\mathbf{v}}$, know that $\ddot{\mathbf{u}} = c\ddot{\mathbf{v}}$, $\ddot{\mathbf{v}} = c\ddot{\mathbf{v}}$, $\ddot{\mathbf{v}$ TRUE. Again, We Know that

(c) [3 pts] If \mathbf{u} , \mathbf{v} , and \mathbf{w} are all non-zero vectors in space and $\mathbf{u} \cdot \mathbf{v} = \mathbf{u} \cdot \mathbf{w}$, then $\mathbf{v} = \mathbf{w}$.

FALSE Consider the counter example of $\vec{u} = \vec{1}$, $\vec{\nabla} = \vec{j}$ and $\vec{w} = \vec{k}$ Then 7. 1 = 0 = 7. K But T + K!

(d) [3 pts] The vector equation

Α

-> Det | 1 | 2 | 2 | 0 | 1 | 8 | has a solution in \mathbb{R}^3 . FALSE Want to find
a solution to the

system of equations $\begin{vmatrix}
y-z\\-(x-z)\\x-y
\end{vmatrix} = \begin{bmatrix}0\\1\\6\end{bmatrix} = \begin{vmatrix}y-z\\1\\6\end{bmatrix} = \begin{vmatrix}y-z\\2\\x-y
\end{vmatrix}$

- 5. Consider the points P(3,1,1), Q(4,1,2), and R(4,4,1) in \mathbb{R}^3 .
 - (a) [3 pts] Find an equation for the plane containing the points P, Q, and R.

Comple
$$\overrightarrow{PQ} = {}^{"}Q - P^{"} = \begin{bmatrix} 4 \\ 1 \\ 2 \end{bmatrix} - \begin{bmatrix} 3 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$
and
$$\overrightarrow{QR} = \begin{bmatrix} 4 \\ 4 \end{bmatrix} - \begin{bmatrix} 4 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 3 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \\ 3 \\ -1 \end{bmatrix} - \overrightarrow{U} \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} + \overrightarrow{K} \begin{bmatrix} 0 \\ 0 \\ 3 \end{bmatrix}$$

$$= \begin{bmatrix} -3 \\ 1 \end{bmatrix} \cdot \cdot -3(x-3) + (y-1) + 3(z-1) = 0$$
15 equation of plane

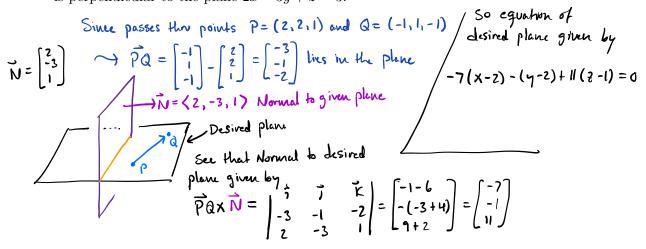
(b) [2 pts] Find the area of the triangle with vertices P, Q, and R.

Area of
$$\Delta = \frac{1}{2} \| \vec{Pa} \times \vec{PR} \|$$

$$= \frac{1}{2} \sqrt{(-3)^2 + 1^2 + 3^2} = \frac{1}{2} \sqrt{9 + 1 + 9}$$

$$= \sqrt{19}/2$$

6. [4 pts] Find an equation of the plane which passes through the points (2,2,1) and (-1,1,-1) and is perpendicular to the plane 2x - 3y + z = 3.



7. [4 pts] Find a set of parametric equations for the line of intersection of the planes:

So line of inhersection is parallel to PXS

$$\begin{array}{c|cccc}
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 & 1 & 1$$

To find a point on line of intersection, solve $\frac{20/3}{3}$ System of equations ... one solution is $\vec{V}_0 = \frac{39/3}{3}$

8. [4 pts] Find an equation of the plane containing both the point P(1, -1, 5) and the line L parametrized by:

$$\mathbf{r}(t) = \begin{cases} x(t) = 1 + 2t \\ y(t) = -1 + 3t \\ z(t) = 4 + t \end{cases}$$

 $\mathbf{r}(t) = \begin{cases} x(t) = 1 + 2t \\ y(t) = -1 + 3t \\ z(t) = 4 + t \end{cases}$ Since P contains the line parametrized by $\vec{r}(t) = \vec{r}(t) \rightarrow \vec{r}(t)$ contains the direction vector $\vec{v} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$ Vector $\vec{\nabla} = \begin{bmatrix} 2 \\ 3 \\ 1 \end{bmatrix}$

Also, plane P contains the vector $\vec{w} = \vec{r}(0) - \begin{bmatrix} -1 \\ 5 \end{bmatrix} = \begin{bmatrix} 1 \\ 4 \end{bmatrix} - \begin{bmatrix} 1 \\ 5 \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \end{bmatrix}$ \longrightarrow \vec{N} for place \vec{P} given by $\vec{N} = \vec{\nabla} \times \vec{W} = \vec{D} + \vec{J} = \vec{J} \times \vec{J} = \begin{bmatrix} -3 \\ 2 \end{bmatrix}$

9. Suppose that a plane P passes through the points (4,2,1) and (-3,5,7), and suppose that P is parallel to the z-axis. Find an equation for the plane P.

Since plane P is parallel to Z-axis, it contains the vector $\ddot{K} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$

Also, Peontains the vector $\vec{\nabla} = \begin{bmatrix} 47 \\ 2 \end{bmatrix} - \begin{bmatrix} -3 \\ 57 \end{bmatrix} = \begin{bmatrix} 7 \\ -3 \\ -6 \end{bmatrix}$

So Normal direction to plan given by

$$\vec{N} = \vec{\nabla} \times \vec{k} = \begin{bmatrix} \vec{1} & \vec{j} & \vec{k} \\ 7 & -3 & -6 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} -3 \\ -7 \\ 0 \end{bmatrix}$$

So equation of plane given by