\$12.1: GEOMETRY OF R3

· So far, you've studied geometry in 2D space R2.

NOTATION:

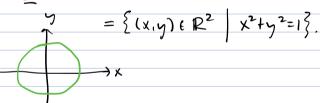
In symbols "2D space" is often denoted as a cartesian product

$$\mathbb{R}^2 = \mathbb{R} \times \mathbb{R} = \{(a,b) \mid a,b \in \mathbb{R}\}.$$

Lollection of which satisfy all objects the condition

C.g. (Example)

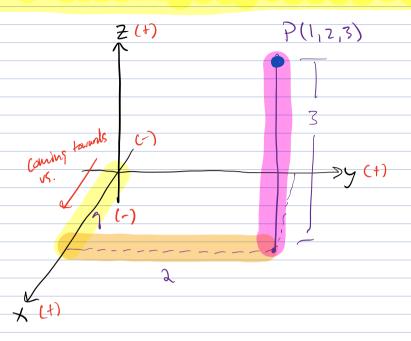
Consider the unit circle, centered at (2,10)



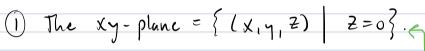
GOAL: Generalize these ideas (distances, angles, parametrizations, fins, etc...) to 3D (Really, n-dim'l Evelidean Space Rn)

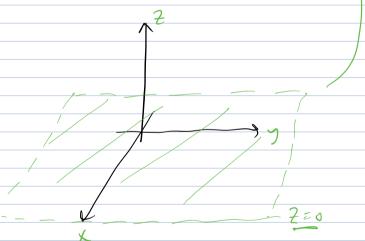
~ Then DO CALCULUS!!

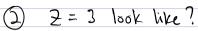
Coordinate Axes in R3 = {(x,y, 2) | x,y, 26 R}

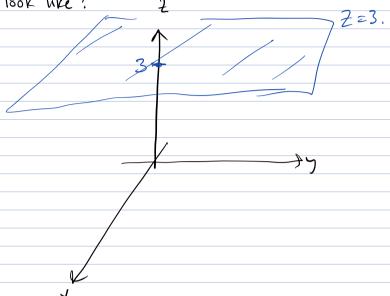


EXAMPLES: (Equations and Surfaces in R3)

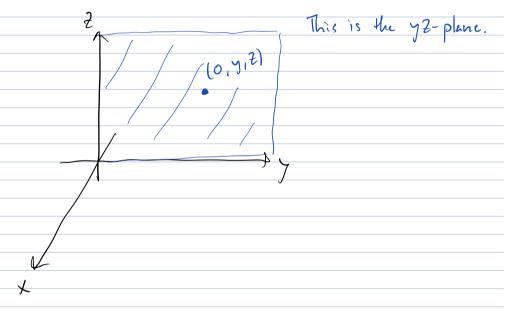


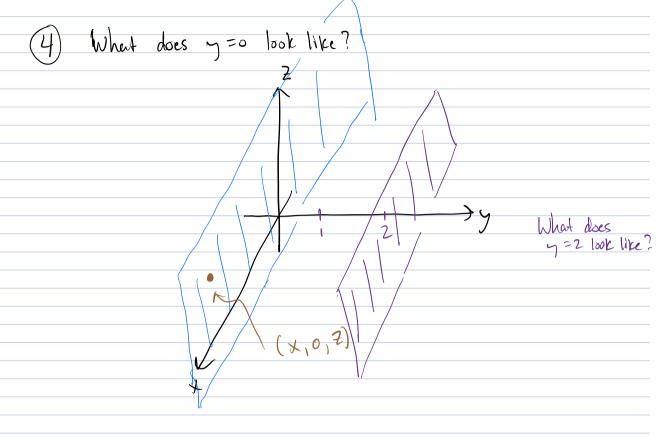


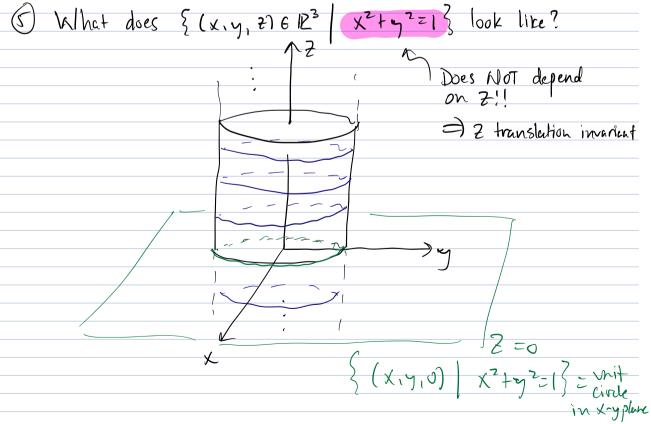


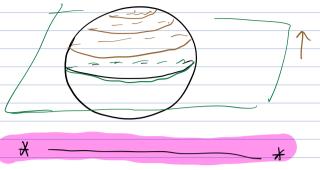


3) What does x20 look like?



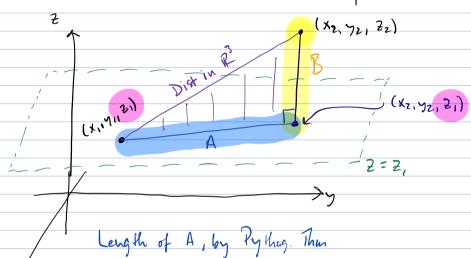






DISTANCES AND SPHERES

· In R3, How to measure the distance both two points?



 $A = \int (x_2 - x_1)^2 + (y_2 - y_1)^2$

Apply again to big A, See that

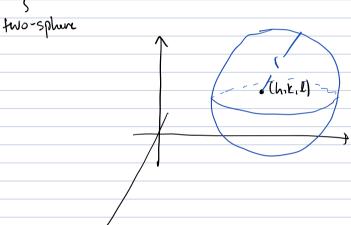
NOT a rigorous proof! We made lots of implicit assumptions,

(e.g. Said ALB, but don't really know what this means yet...)

Also, assumed Pythas. holds in 3D

- · Logiculty cleaner to take & as the DEFINITION of distance btw 2 points in 3D, and build up from there.
- · Having defined distance in \mathbb{R}^3 , can make sense of a Sphere of radius r centered at C(h,k,l)

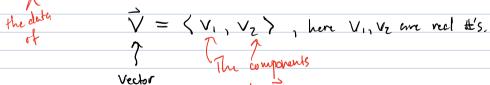
$$S^{2} = \left\{ (x, y, z) \in \mathbb{R}^{3} \mid (x-h)^{2} + (y-k)^{2} + (z-l)^{2} = r^{2} \right\}.$$



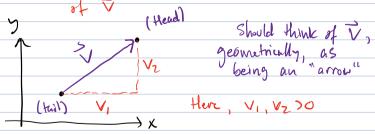
X ~_______X

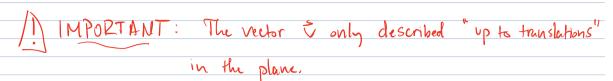
§12.2: VECTORS IN 2D AND 3D

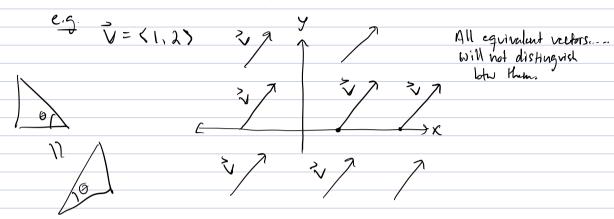
·In 2D: a Vector consists of two real #'s,



Geometric Significance:

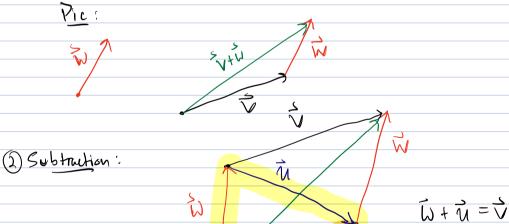






OPERATIONS W/ VECTORS

1) Addition: Sps have W= <W, Wz>. Then V+ W= <V,+W1, Vz+Wz>



3) Multiplication by a Scalar: if c is a real #, can define
$$c \stackrel{\leftarrow}{\nabla} = \langle c V_{i}, c V_{c} \rangle$$

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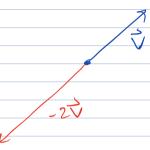
Greanetriculty:



Notice: if coo, then ci

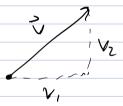
politi in some direction as is.

BUT if CCO, then "tom & around"



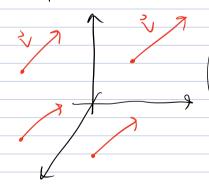
4 Length of a Vector: (Norm, magnitude)
Defined to be, $\vec{V} = \langle V_1, V_2 \rangle$

$$|\vec{V}| = \sqrt{V_1^2 + V_2^2}$$



VECTORS IN 3D:

· A 3D Vector has 3 components = < V1, V2, V3>



Lup to translations in 123

