

# Coopération de drones dans un système hétérogène

Compte rendu de stage n°10

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# Sommaire

## 1 Trajectoire de point à point

```
STATUS/1 @ getErrorMessage, L752: runWaypointMission
STATUS/1 @ getCMDSetMissionMSG, L987: MISSION_OBTAIN_CONTROL_REQUIRED

STATUS/1 @ printInfo, L206: Mission Manager status:

STATUS/1 @ printInfo, L207: There are 1 waypt missions and 0 hotspot missions
Initializing Waypoint Mission..
Waypoint created at (LLA): 0.000000      0.000000      0.000000
Creating Waypoints..
Waypoint created at (LLA): 0.000000      0.000000      0.000000
```

```

STATUS/1 @ getErrorCodeMessage, L752: uploadWaypoints
STATUS/1 @ getCMDSetMissionMSG, L987: WAYPOINT_MISSION_DATA_NOT_ENOUGH
Waypoint created at (LLA): 0.000001    0.000001    1.000000

STATUS/1 @ getErrorCodeMessage, L752: uploadWaypoints
STATUS/1 @ getCMDSetMissionMSG, L987: WAYPOINT_MISSION_DATA_NOT_ENOUGH
Waypoint created at (LLA): 0.000000    0.000002    2.000000

STATUS/1 @ getErrorCodeMessage, L752: uploadWaypoints
STATUS/1 @ getCMDSetMissionMSG, L987: WAYPOINT_MISSION_DATA_NOT_ENOUGH
Waypoint created at (LLA): -0.000001    0.000002    3.000000

STATUS/1 @ getErrorCodeMessage, L752: uploadWaypoints
STATUS/1 @ getCMDSetMissionMSG, L987: WAYPOINT_MISSION_DATA_NOT_ENOUGH
Waypoint created at (LLA): -0.000002    0.000001    4.000000

STATUS/1 @ getErrorCodeMessage, L752: uploadWaypoints
STATUS/1 @ getCMDSetMissionMSG, L987: WAYPOINT_MISSION_DATA_NOT_ENOUGH
Waypoint created at (LLA): -0.000001    0.000000    5.000000

STATUS/1 @ getErrorCodeMessage, L752: uploadWaypoints
STATUS/1 @ getCMDSetMissionMSG, L987: WAYPOINT_MISSION_DATA_NOT_ENOUGH
Waypoint created at (LLA): 0.000000    0.000000    0.000000

STATUS/1 @ getErrorCodeMessage, L752: uploadWaypoints
STATUS/1 @ getCMDSetMissionMSG, L987: WAYPOINT_MISSION_DATA_NOT_ENOUGH
Uploading Waypoints..

```

```
STATUS/1 @ getErrorCodeMessage, L752: runWaypointMission  
STATUS/1 @ getCMDSetMissionMSG, L987: MISSION_OBTAIN_CONTROL_REQUIRED
```