

# Part II Electrodynamics and Optics

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# Preface

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## CHAPTER 1

# Electromagnetic Waves

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### 1.1 Revision of Part IB

Electrostatic and magnetostatic experiments lead to the concepts of the electric field  $\mathbf{E}$  and the magnetic induction (or magnetic flux density)  $\mathbf{B}$  in vacuum. Experimentally the Lorentz force on a point charge  $q$  moving with velocity  $\mathbf{v}$

$$\mathbf{F} = q(\mathbf{E} + \mathbf{v} \times \mathbf{B}), \quad (1.1)$$

where  $\mathbf{E}$  is the “force per unit charge,” and  $\mathbf{B}$  is the “force per unit current.” More generally, the charge is distributed, with  $\rho_T(\mathbf{r})$  and  $\mathbf{J}_T(\mathbf{r})$  the total charge and current density distributions. We additionally have the continuity equation:

$$\iint_S \mathbf{J}_T \cdot d\mathbf{S} = - \iiint_V \frac{\partial \rho_T}{\partial t} dV \quad (1.2)$$

In statics and in vacuum summarise experimental observations:

$$\text{Gauss (ES):} \quad \iint_S \mathbf{E} \cdot d\mathbf{S} = \iiint_V \frac{\rho_T}{\epsilon_0} dV, \quad (1.3)$$

$$\text{Gauss (MS):} \quad \iint_S \mathbf{B} \cdot d\mathbf{S} = 0, \quad (1.4)$$

$$\oint_C \mathbf{E} \cdot d\mathbf{l} = 0, \quad (1.5)$$

$$\text{Ampère} \quad \oint_C \mathbf{B} \cdot d\mathbf{l} = \iint_S \mu_0 \mathbf{J}_T \cdot d\mathbf{S}. \quad (1.6)$$

The surface  $S$  bounds the volume  $V$  and contour  $C$  bounds the surface  $S$ .

Differential form (using Gauss’s and Stokes’s theorems):

$$\nabla \cdot \mathbf{E} = \frac{\rho_T}{\epsilon_0}, \quad (1.7)$$

$$\nabla \cdot \mathbf{B} = 0, \quad (1.8)$$

$$\nabla \times \mathbf{E} = 0, \quad (1.9)$$

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{J}_T, \quad (1.10)$$

$\rho_T(\mathbf{r})$  and  $\mathbf{J}_T(\mathbf{r})$  are sources for  $\mathbf{E}$  and  $\mathbf{B}$  respectively.

Eqs. (1.5) and (1.9) imply that in electrostatics  $\mathbf{E}$  is a conservative field, and can be written in terms of a scalar potential:

$$\mathbf{E} = -\nabla \phi(\mathbf{r}). \quad (1.11)$$

Eqs. (1.6) and (1.10) imply that in magnetostatics  $\mathbf{B}$  is a conservative field in regions where  $\mathbf{J}_T = 0$ , and can be written in terms of a magnetic scalar potential:

$$\mathbf{B} = -\mu_0 \nabla \phi_m(\mathbf{r}) \quad (1.12)$$

### 1.1.1 Maxwell's Equations

This leads to Maxwell's Equations for EM fields in vacuum:

$$\nabla \cdot \mathbf{E} = \frac{\rho_T}{\epsilon_0}, \quad (1.13)$$

$$\nabla \cdot \mathbf{B} = 0, \quad (1.14)$$

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}, \quad (1.15)$$

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{J}_T + \mu_0 \epsilon_0 \frac{\partial \mathbf{E}}{\partial t}. \quad (1.16)$$

The equations for  $\mathbf{E}$  and  $\mathbf{B}$  are now interlinked by the time-dependent inductive and displacement current terms - Electromagnetism.

Eqs. (1.7) and (1.11) give Poisson's Equation:

$$\nabla^2 \phi = -\frac{\rho_T}{\epsilon_0} \quad (1.17)$$

Similarly Eqs. (1.12) and (1.8) give

$$\nabla^2 \phi_m = 0, \quad (1.18)$$

for regions where  $\mathbf{J}_T = 0$ .

The equations for  $\mathbf{E}$  and  $\mathbf{B}$  are independent, electrostatics and magnetostatics are separate theories. Faraday's experimental results on electromagnetic induction, and Maxwell's insights allow electricity and magnetism to be unified. The unified theory of Electromagnetism is fully relativistic as we will see.

#### 1.1.1.1 Media

In the presence of a medium

$$\begin{Bmatrix} \mathbf{E} \\ \mathbf{B} \end{Bmatrix} \rightarrow \begin{Bmatrix} \text{electric} \\ \text{magnetic} \end{Bmatrix} \text{dipole moments per unit volume} \begin{Bmatrix} \mathbf{P} \\ \mathbf{M} \end{Bmatrix}. \quad (1.19)$$

The electric polarization  $\mathbf{P}$ :

$$\mathbf{P} \rightarrow \begin{cases} \text{volume charge density} & \rho_P = -\nabla \cdot \mathbf{P} \\ \text{surface charge density} & \sigma_P = \mathbf{P} \cdot \hat{\mathbf{n}} \end{cases}, \quad (1.20)$$

where  $\hat{\mathbf{n}}$  is the surface normal unit vector.

If  $\mathbf{P}$  varies with time, so does  $\rho_P$ , and there is an associated volume current density  $\mathbf{J}_P$  given by the continuity equation for the polarization charge:

$$\nabla \cdot \mathbf{J}_P = -\dot{\rho}_P = \nabla \cdot \dot{\mathbf{P}} \implies \mathbf{J}_P = \dot{\mathbf{P}}. \quad (1.21)$$



The magnetization  $\mathbf{M}$ :

$$\mathbf{P} \rightarrow \begin{cases} \text{volume charge density} & \mathbf{J}_M = \nabla \times \mathbf{M} \\ \text{surface charge density} & \mathbf{j}_M = \mathbf{M} \times \hat{\mathbf{n}} \end{cases}. \quad (1.22)$$

Eqs. (1.13-1.16) involve the total charge and current volume distributions.

$$\rho_T = \rho + \rho_P = \rho - \nabla \cdot \mathbf{P} \quad (1.23)$$

$$\mathbf{J}_T = \mathbf{J} + \mathbf{P} + \mathbf{J}_M = \mathbf{J} + \dot{\mathbf{P}} + \nabla \times \mathbf{M}, \quad (1.24)$$

where  $\rho$  and  $\mathbf{J}$  refer to the “real”, free charges and currents present.

Substituting for  $\rho_T$  and  $\mathbf{J}_T$  in Eqs. (1.13-1.16):

$$\nabla \cdot \mathbf{E} = \frac{\rho - \nabla \cdot \mathbf{P}}{\epsilon_0}, \quad (1.25)$$

$$\nabla \cdot \mathbf{B} = 0, \quad (1.26)$$

$$\nabla \times \mathbf{E} = -\dot{\mathbf{B}}, \quad (1.27)$$

$$\nabla \times \mathbf{B} = \mu_0 \left( \mathbf{J} + \dot{\mathbf{P}} + \nabla \times \mathbf{M} \right) + \mu_0 \epsilon_0 \dot{\mathbf{E}}. \quad (1.28)$$

Define the auxiliary fields,  $\mathbf{D}$  the electric displacement and  $\mathbf{H}$  the magnetic intensity:

$$\mathbf{D} = \epsilon_0 \mathbf{E} + \mathbf{P}, \quad (1.29)$$

$$\mathbf{H} = \frac{\mathbf{B}}{\mu_0} - \mathbf{M}. \quad (1.30)$$

Eqs. (1.25-1.28) then become the standard form for Maxwell's Equations:

$$\nabla \cdot \mathbf{D} = \rho, \quad (1.31)$$

$$\nabla \cdot \mathbf{B} = 0, \quad (1.32)$$

$$\nabla \times \mathbf{E} = -\dot{\mathbf{B}}, \quad (1.33)$$

$$\nabla \times \mathbf{H} = \mathbf{J} + \dot{\mathbf{D}}. \quad (1.34)$$

$\rho$  and  $\mathbf{J}$  are free charge and current densities, the response of the medium is included via the auxiliary fields  $\mathbf{D}$  and  $\mathbf{H}$ . In integral form:

$$\text{Gauss (ES):} \quad \iint_S \mathbf{D} \cdot d\mathbf{S} = \iiint_V \rho dV, \quad (1.35)$$

$$\text{Gauss (MS):} \quad \iint_S \mathbf{B} \cdot d\mathbf{S} = 0, \quad (1.36)$$

$$\text{Faraday, Lenz:} \quad \oint_C \mathbf{E} \cdot d\mathbf{l} = -\frac{\partial}{\partial t} \iint_S \mathbf{B} \cdot d\mathbf{S}, \quad (1.37)$$

$$\text{Ampère:} \quad \oint_C \mathbf{H} \cdot d\mathbf{l} = \iint_S \left( \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t} \right) \cdot d\mathbf{S}. \quad (1.38)$$

### 1.1.1.2 Constitutive Relations

For linear, isotropic media:

$$\mathbf{P} = \epsilon_0 \chi \mathbf{E} \quad \text{and} \quad \mathbf{M} = \chi_m \mathbf{H}, \quad (1.39)$$

where  $\chi$  is the dielectric susceptibility and  $\chi_m$  is the magnetic susceptibility. Defining:

$$\text{the relative permittivity (or dielectric “constant”)} \epsilon = 1 + \chi \quad (1.40)$$

$$\text{the relative magnetic permeability } \mu = 1 + \chi_m \quad (1.41)$$

gives the constitutive relations:

$$\boxed{\mathbf{D} = \epsilon\epsilon_0\mathbf{E} \quad \text{and} \quad \mathbf{B} = \mu\mu_0\mathbf{H}.} \quad (1.42)$$

$\epsilon$  and  $\mu$  encapsulate the responses (polarization and magnetisation) of the medium to the EM fields.

## 1.2 Electromagnetic Energy

The energy  $U$  of the EM fields in a volume  $\mathcal{V}$  bounded by the surface  $\mathcal{S}$  is:

$$\iiint_{\mathcal{V}} \left( \frac{1}{2} \mathbf{E} \cdot \mathbf{D} + \frac{1}{2} \mathbf{B} \cdot \mathbf{H} \right) dV \quad (1.43)$$

and from the MEs it can be shown that:

$$\frac{dU}{dt} = - \iint_{\mathcal{S}} \mathbf{E} \times \mathbf{H} \cdot d\mathbf{S} - \iiint_{\mathcal{V}} \mathbf{J} \cdot \mathbf{E} dV, \quad (1.44)$$

the sum of a power flux and a dissipative term. So the energy density at a point is

$$\boxed{u = \frac{1}{2} \mathbf{E} \cdot \mathbf{D} + \frac{1}{2} \mathbf{B} \cdot \mathbf{H},} \quad (1.45)$$

and the energy flux is given by the Poynting Vector

$$\boxed{\mathbf{N} = \mathbf{E} \times \mathbf{H}.} \quad (1.46)$$

## 1.3 The Vector Potential

Note from Eq. (1.37) that when there is a time-dependent magnetic induction  $\mathbf{B}$ ,  $\mathbf{E}$  is no longer in general a conservative field and  $\mathbf{E} \neq -\nabla\phi$ . Now  $\nabla \cdot (\nabla \times \mathbf{F}) = 0$  for any vector field  $\mathbf{F}$ , so Eq. (1.32) implies that there is a vector field  $\mathbf{A}$  – the magnetic vector potential – of which the curl is  $\mathbf{B}$ ,

$$\boxed{\mathbf{B} = \nabla \times \mathbf{A}.} \quad (1.47)$$

From Eq. (1.37):

$$\nabla \times \mathbf{E} = -\dot{\mathbf{B}} = -\nabla \times \dot{\mathbf{A}} \quad (1.48)$$

and integrating:

$$\mathbf{E} = -\dot{\mathbf{A}} - \nabla\phi. \quad (1.49)$$

## 1.4 Boundary Conditions

From the integral forms of Maxwell's Eqs. (1.35-1.38) it is easy to derive conditions for the continuity of components of the EM fields at interfaces between two media

- $\mathbf{D}_\perp$  is conserved in the absence of any free charges at the interface,
- $\mathbf{B}_\perp$  is conserved,
- $\mathbf{E}_\parallel$  is conserved,
- $\mathbf{H}_\parallel$  is conserved in the absence of any free current at the interface.

## 1.5 Electromagnetic Waves

For any vector field  $\mathbf{F}$ ,  $\nabla \times (\nabla \times \mathbf{F}) = \nabla(\nabla \cdot \mathbf{F}) - \nabla^2 \mathbf{F}$ . In regions with  $\rho = 0$ ,  $\mathbf{J} = \mathbf{J}$ , taking the curl of Eq. (1.33) and substituting  $\nabla \times \mathbf{H}$  from Eq. (1.34):

$$\nabla \times (\nabla \times \mathbf{E}) = -\nabla \times \dot{\mathbf{B}} \quad (1.50)$$



## CHAPTER 2

# Optics

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## CHAPTER 3

# Electrodynamics

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## CHAPTER 4

# Dipole Radiation

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## CHAPTER 5

# Antennas

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## CHAPTER 6

# Light Scattering

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## CHAPTER 7

# Special Relativity

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## CHAPTER 8

# Radiation and Relativistic Electrodynamics

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## APPENDIX A

# Code

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