STA521: Linear Algebra and Some Linear Model Theory

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Contents

L	Matrix Algebra
2	Linear Algebra
	2.1 Column Space and Rowspace
	2.2 Orthogonal Matrices
	2.3 Spectral Theorem and Decompositions
	2.4 Generalized Inverses
	2.5 Orthogonal Projections
3	Random Vectors
4	Multivariate Normal
	4.1 Zero Correlation and Independence
	4.2 Affine Property
	4.3 Marginals and conditionals
5	Chi-square Distribution
6	A Little Bit of Linear Model Theory
	6.1 Inference
	6.2 Gauss-Markov Theorem
7	Bayesian Linear Regression
	7.1 Marginal of β and predictive distribution, all t

1 Matrix Algebra

Basically taken from Sam Roweis' notes¹:

$$A(B+C) = AB + AC$$

$$(A+B)^{\mathsf{T}} = A^{\mathsf{T}} + B^{\mathsf{T}}$$

$$(AB)^{-1} = B^{-1}A^{-1}$$

$$(A^{-1})^{\mathsf{T}} = (A^{\mathsf{T}})^{-1}$$

$$|AB| = |A||B|$$

$$|A^{-1}| = 1/|A|$$

$$|A| = \prod_{i=1}^{n} \operatorname{evals}(A_i)$$

$$|cA_{n\times n}| = c^n |A_{n\times n}|$$

$$\operatorname{tr}(A) = \sum_{i=1}^{n} \operatorname{evals}(A_i)$$

$$\operatorname{tr}(ABC) = \operatorname{tr}(BCA) = \operatorname{tr}(CAB_i)$$

$$\operatorname{rank}(A) = \operatorname{rank}(A^{\mathsf{T}}A) = \operatorname{rank}(AA^{\mathsf{T}})$$

$$X^{\mathsf{T}}X \text{ and } XX^{\mathsf{T}} \text{ are positive-semidefinite and symmetric.}$$

2 Linear Algebra

Most of the results here can be found in Appendix B in Christensen.

2.1 Column Space and Rowspace

Let X be $n \times p$.

$$\begin{split} C(X) &= \{Xa \in \mathbb{R}^n : a \in \mathbb{R}^p\} \\ N(X) &= \{v \in \mathbb{R}^p : Xv = 0\} \\ p &= \dim(C(X)) + \dim(N(X)) \\ C(X^\intercal) &= N(X)^\perp \text{ (they are orthogonal complements)} \\ N(X^\intercal) &= C(X)^\perp \\ C(X) &= C(X^\intercal X) \end{split}$$

2.2 Orthogonal Matrices

Let Q be a $n \times n$ matrix.

- Q is orthogonal if its columns form an orthonormal basis of \mathbb{R}^n (that is, if they are orthogonal unit vectors).
- Equivalently, Q is orthogonal if $Q^T = Q^{-1}$.
- If Q is orthogonal, then $|Q|^2 = 1$.

¹Link: http://www.cs.nyu.edu/~roweis/notes/matrixid.pdf. Also of interest: http://www.cs.nyu.edu/~roweis/notes/gaussid.pdf (Gaussian identities).

2.3 Spectral Theorem and Decompositions

Spectral Theorem: If X is a symmetric matrix, it has real eigenvalues and it can be decomposed as $X = U\Lambda U^{\mathsf{T}}$, where Λ is a diagonal matrix with the eigenvalues of X and U is an orthogonal matrix with the eigenvectors of X. The rank of X equals the number of nonzero eigenvalues of X. Based on this decomposition, one can define matrix powers as $X^p = U\Lambda^p U^{\mathsf{T}}$.

SVD: Let X be a $n \times p$ matrix, then one can find U $(n \times n)$, Σ $(n \times p)$ and V $(p \times p)$ such that $X = U\Sigma V^{\mathsf{T}}$, where U and V are orthogonal matrices. The columns of U are eigenvectors of XX^{T} , and the columns of V are eigenvectors of $X^{\mathsf{T}}X$. Σ is a rectangular diagonal matrix with the square roots of the eigenvalues of $X^{\mathsf{T}}X$ or XX^{T} (they are the same).

Cholesky: Any positive definite matrix X can be factorized as $X = LL^{\dagger}$, where L is a lower triangular matrix.

QR: Any square matrix X can be decomposed as X = QR, where Q is an orthogonal matrix and R is upper triangular.

2.4 Generalized Inverses

Definition: A generalized inverse of a matrix X is any matrix X^- such that $XX^-X = X$. Generalized inverses exist for arbitrary matrices.

Results:

- Let X be a symmetric matrix. The Moore-Penrose generalized inverse is defined as follows. First, decompose $X = U\Lambda U^{\dagger}$. Then $X^- = U\Lambda^-U^{\dagger}$ where $\lambda_i^- = 1/\lambda_i$ if $\lambda_i \neq 0$ and $\lambda_i^- = 0$ if $\lambda_i = 0$. The Moore-Penrose generalized inverse is nice because it is symmetric and reflexive (i.e. $A^-AA^- = A^-$).
- If G and H are generalized inverses of $X^{\dagger}X$, then $XGX^{\dagger}X = XHX^{\dagger}X = X$ and $XGX^{\dagger} = XHX^{\dagger}$.

2.5 Orthogonal Projections

Definition: P is a perpendicular projection operator (ppo) onto C(X) if and only if

- $v \in C(X)$ implies Pv = v.
- $v \perp C(X)$ implies Pv = 0.

Properties:

- $P = X(X^{\mathsf{T}}X)^{-}X^{\mathsf{T}}$ is the ppo onto C(X). If $X^{\mathsf{T}}X$ is invertible, $P = X(X^{\mathsf{T}}X)^{-1}X^{\mathsf{T}}$.
- P is a ppo onto C(P) if and only if PP = P (idempotent) and $P^{\dagger} = P$ (symmetry).
- Ppos are unique.
- If P is ppo onto C(X), then C(X) = C(P).
- If P is ppo onto C(X), (I-P) is ppo onto $C(X)^{\perp}$.
- Let P_1 and P_2 be ppos onto $C(P_1)$, $C(P_2)$, then $P_1 + P_2$ is the ppo onto $C(P_1, P_2)$ if and only if $C(P_1) \perp C(P_2)$.

- If $\{o_1, o_2, \dots, o_r\}$ is an orthonormal basis of C(X) and we construct O such that its columns are $\{o_1, o_2, \dots, o_r\}$, then OO^{T} is the ppo onto C(X).
- If P is ppo its eigenvalues are either 0 or 1, and $tr(P) = \sum evals(P) = r(P)$.

3 Random Vectors

Definition: Let Y be a random vector such that $E(Y) = \mu$. The covariance matrix of Y is

$$Cov(Y) = E[(Y - \mu)(Y - \mu)^{\mathsf{T}}].$$

The elements of the diagonal are variances, the off-diagonal elements are covariances.

Properties

Let Y be a random vector with $E(Y) = \mu$ and $Cov(Y) = \Sigma$, and let A and b be a matrix and a vector with constants, respectively:

- $\bullet \ E(AY+b) = A\mu + b.$
- $Cov(AY + b) = A\Sigma A^{\mathsf{T}}$.
- Expectation of a quadratic form: Assume A is symmetric, then $E(Y^{\dagger}AY) = \operatorname{tr}(A\Sigma) + \mu^{\dagger}A\mu$.

4 Multivariate Normal

These are notes I took after watching the videos on the Multivariate Normal that Jeff Miller uploaded to his YouTube².

Definition: $Y = (Y_1, ... Y_n)^{\mathsf{T}}$ follows a Multivariate Normal (MVN) with mean μ and covariance Σ if any linear combination of the components is $v^{\mathsf{T}}Y \sim \text{Normal}(v^{\mathsf{T}}\mu, v^{\mathsf{T}}\Sigma v)$, for $v \in \mathbb{R}^n$. If $|\Sigma| = \det(\Sigma) \neq 0$, Y has the following pdf:

$$f(Y) = \frac{1}{\sqrt{|2\pi\Sigma|}} \exp\left\{-\frac{1}{2}\left[(Y-\mu)^{\mathsf{T}}\Sigma^{-1}(Y-\mu)\right]\right\}.$$

Remark: Recall that if $c \in \mathbb{R}$ and A is an $n \times n$ matrix, then $|cA| = c^n |A|$.

4.1 Zero Correlation and Independence

Let $Y \sim \text{MVN}(\mu, \Sigma)$. For an arbitrary partition

$$\left[\begin{array}{c} Y_1 \\ Y_2 \end{array}\right] \sim \text{MVN}\left(\left[\begin{array}{c} \mu_1 \\ \mu_2 \end{array}\right], \left[\begin{array}{cc} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{array}\right]\right),$$

then $Cov(Y_1, Y_2) = \Sigma_{12} = 0$ if and only if Y_1 and Y_2 are independent. That is, uncorrelation implies independence.

²YouTube channel: https://www.youtube.com/user/mathematicalmonk.

Corollary: $Y \sim \text{MVN}(\mu, \sigma^2 I)$ and $AB^{\dagger} = 0$, then AY and BY are independent.

Caution! X_1 and X_2 normally distributed does not imply $(X_1, X_2) \sim \text{MVN}$. For example, let $X_1 \sim \text{N}(0, 1)$ and

$$X_2 = \begin{cases} X_1 & \text{if } |X_1| \le 1\\ -X_1 & \text{if } |X_1| > 1. \end{cases}$$

 X_1 and X_2 are Normal, but (X_1, X_2) is not Multivariate Normal. Also, if two Normal random variables are uncorrelated, it doesn't mean they're independent (unless they are jointly MVN!).

4.2 Affine Property

Any affine transformation of a MVN is MVN. If $X \sim \text{MVN}(\mu, \Sigma)$, then $AX + b \sim \text{MVN}(A\mu + b, A\Sigma A^{\mathsf{T}})$, for any matrix of constants A and vector b of conformable sizes.

Some operations:

- Constructing: If $X_1, X_2, ..., X_n \sim N(0,1)$ are independent, then $(X_1, X_2, ..., X_n) = X \sim \text{MVN}(0, I)$. We have $AX + \mu \sim \text{MVN}(\mu, \Sigma)$, where $\Sigma = AA^{\mathsf{T}}$. Using the spectral theorem, one can find A such that $AA^{\mathsf{T}} = \Sigma$ (i.e. you can construct any MVN from standard Normal rvs). Recall that, by the spectral theorem, $\Sigma = U\Lambda U^{\mathsf{T}} = U\Lambda^{1/2}\Lambda^{1/2}U^{\mathsf{T}} = AA^{\mathsf{T}}$, where U is an orthogonal matrix.
- **Sphering:** If $Y \sim \text{MVN}(\mu, \Sigma)$ and Σ is invertible, then $A^{-1}(Y \mu) \sim \text{MVN}(0, I)$, where $\Sigma = AA^{\intercal}$. Alternatively, one can write this as follows: $\Sigma^{-1/2}(Y \mu) \sim \text{MVN}(0, I)$.

4.3 Marginals and conditionals

Let $Y \sim \text{MVN}(\mu, \Sigma)$. Marginal distributions are Normal with the same parameters as in the MVN.

Let

$$\left[\begin{array}{c} Y_1 \\ Y_2 \end{array}\right] \sim \text{MVN}\left(\left[\begin{array}{c} \mu_1 \\ \mu_2 \end{array}\right], \left[\begin{array}{cc} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{array}\right]\right),$$

then

$$Y_1|Y_2 = a \sim \text{MVN}(\mu_1 + \Sigma_{12}\Sigma_{22}^{-1}(a - \mu_2), \Sigma_{11} - \Sigma_{12}\Sigma_{22}^{-1}\Sigma_{21}).$$

5 Chi-square Distribution

Definition: Let Z_j for $j \in \{1, 2, ..., p\}$ be iid N(0, 1), and let $Z = (Z_1, Z_2, ..., Z_p)^{\intercal}$. Then, $X = Z^{\intercal}Z \sim \chi_p^2$.

Noncentral chi-square: Let Z_j for $j \in \{1, 2, ..., p\}$ be iid $N(\mu, 1)$ and let $Z = (Z_1, Z_2, ..., Z_p)^\intercal$. Then, $Z^\intercal Z \sim \chi_p^2(\sum_{j=1}^p \mu_j^2)$.

Quadratic forms and χ^2 distributions: Let $Y \sim \text{MVN}(0, I)$ and let P be a symmetric $n \times n$ matrix of rank k. Then $Y^{\intercal}PY \sim \chi_k^2$ if and only if P is a rank k perpendicular projection

operator (ppo). In the noncentral case, if $Y \sim \text{MVN}(\mu, I)$, then $Y^{\dagger}PY \sim \chi_k^2(\mu^{\dagger}P\mu/2)$ if and only of P is a ppo. Application: let $Y \sim \text{MVN}(\mu, I)$ with $\mu \in C(X)$ and (I - P) be a rank k ppo onto $C(X)^{\perp}$. Then $Y^{\dagger}(I - P)Y \sim \chi_k^2$.

6 A Little Bit of Linear Model Theory

A lot of important results are not even mentioned here. I strongly recommend looking at Faraday's "Practical Regression and ANOVA using R"³ if you think Christensen is too dry and need some extra intuition.

In matrix notation:

$$Y = X\beta + \varepsilon$$

where

- Y is the response variable, which is observable.
- X is the design matrix, also observable.
- β are the unknown coefficients, which we want to estimate.
- ε are the errors, also unobservable.

Assume X is full rank, then the Ordinary Least Squares (OLS) estimator is

$$\hat{\beta}_{OLS} = \arg\min_{\beta} \sum_{i=1}^{n} (Y_i - x_i^{\mathsf{T}} \beta)^2 = \arg\min_{\beta} (Y - X\beta)^{\mathsf{T}} (Y - X\beta) = \arg\min_{\beta} ||Y - X\beta||_2^2 = (X^{\mathsf{T}} X)^{-1} X^{\mathsf{T}} Y.$$

If X is not full rank $\hat{\beta}_{OLS} = (X^{\dagger}X)^{-}X^{\dagger}Y$.

Let $Y|\beta \sim \text{MVN}(X\beta, \sigma^2 I)$. Then $\hat{\beta}_{\text{MLE}} = \hat{\beta}_{\text{OLS}} = \hat{\beta}$. Now, let $\mu = X\beta$. Then $\hat{\mu} = X\hat{\beta} = P_X Y$ is the MLE of μ , where P_X is the ppo onto C(X). On the other hand, the MLE of σ^2 is $\hat{\sigma}^2 = ||(I - P_X)Y||^2/n = e^{\mathsf{T}}e/n$, where $e = (I - P_X)Y$ are the residuals and $(I - P_X)$ is the ppo onto the orthogonal complement of C(X).

6.1 Inference

Again, $Y \mid \beta \sim \text{MVN}(X\beta, \sigma^2 I)$.

The MLE of $\mu = X\beta$ is $\hat{\mu} = P_X Y$, and it is an unbiased estimate:

$$E(\hat{\mu}) = E(P_X Y) = P_X E(Y) = P_X \mu = \mu,$$

because $\mu \in C(X)$.

The residuals $e = (I - P_X)Y$ have mean zero:

$$E(e) = E[(I - P_X)Y] = (I - P_X)E(Y) = (I - P_X)\mu = 0,$$

 $^{^3\}mathrm{Link}$: http://cran.r-project.org/doc/contrib/Faraway-PRA.pdf

because $\mu \perp C(X)^{\perp}$.

The residuals are correlated:

$$Cov(e) = Cov[(I - P_X)Y] = \sigma^2(I - P_X)(I - P_X) = \sigma^2(I - P_X).$$

Therefore $e \sim \text{MVN}(0, \sigma^2(I - P_X))$ by the affine property of the MVN.

Now we find the expectation of the MLE of σ^2 , which is $\hat{\sigma}^2 = e^{\dagger}e/n = ||(I - P_X)Y||^2/n$:

$$E(||(I - P_X)Y||^2) = E[Y^{\mathsf{T}}(I - P_X)Y] = \sigma^2 \text{tr}(I - P_X) + \mu^{\mathsf{T}}(I - P_X)\mu = \sigma^2(n - r(X)),$$

Therefore, the MLE is biased, but $e^{\dagger}e/(n-r(X))$ is unbiased.

Let $Y|\beta \sim \text{MVN}(X\beta, \sigma^2 I)$. The MLE for β is $\hat{\beta} = (X^{\intercal}X)^- X^{\intercal}Y$. We take the Moore-Penrose generalized inverse. Then, the distribution of $\hat{\beta}$ is MVN because it's just a linear combination of Y, which is MVN.

Taking expectations,

$$E(\hat{\beta}) = (X^{\mathsf{T}}X)^{-}X^{\mathsf{T}}X\beta,$$

and the variance is

$$Cov(\hat{\beta}) = \sigma^2(X^{\mathsf{T}}X)^- X^{\mathsf{T}}X(X^{\mathsf{T}}X)^- = \sigma^2(X^{\mathsf{T}}X)^-,$$

because if A^- is a Moore-Penrose generalized inverse, then it is symmetric and $A^-AA^- = A^-$ (reflexive).

Therefore

$$\hat{\beta} \sim \text{MVN}((X^\intercal X)^- X^\intercal X \beta, \sigma^2 (X^\intercal X)^-)$$

If X full rank,

$$\hat{\beta} \sim \text{MVN}(\beta, \sigma^2(X^{\mathsf{T}}X)^{-1}).$$

The standard error for a particular component is $\operatorname{se}(\hat{\beta}_i) = \sqrt{(X^{\intercal}X)_{ii}^{-1}\sigma}$.

6.2 Gauss-Markov Theorem

- Gauss-Markov says that OLS has minimum variance in the class of all linear unbiased estimators.
- Requires just first and second moments, no normality required.
- Under normality assumption, OLS = MLE has minimum variance out of all unbiased estimators, not just the linear ones.
- However, we can find estimators with smaller MSE if we allow some bias.

7 Bayesian Linear Regression

As usual, we have

$$Y = X\beta + \varepsilon,$$

and assume that ε is normal, yielding

$$Y \mid \beta, \phi \sim \text{MVN}(X\beta, \phi^{-1}I),$$

where ϕ is the precision (a scalar).

Since we're Bayesians now, we need to specify priors on β and ϕ .

A convenient (conjugate) choice of priors is

$$\beta \mid \phi \sim \text{MVN}(b_0, \Phi_0^{-1}/\phi)$$

 $\phi \sim \text{Gamma}(v_0/2, SS_0/2).$

Posteriors are

$$\beta \mid \phi, Y \sim \text{MVN}(b_n, \Phi_n^{-1}/\phi)$$

 $\phi \mid Y \sim \text{Ga}(v_n/2, SS_n/2),$

where

$$b_n = (X^{\mathsf{T}}X + \Phi_0)^{-1}(X^{\mathsf{T}}X\hat{\beta}_{\text{OLS}} + \Phi_0 b_0) = (X^{\mathsf{T}}X + \Phi_0)^{-1}(X^{\mathsf{T}}y + \Phi_0 b_0)$$

$$\Phi_n = (X^{\mathsf{T}}X + \Phi_0)$$

$$v_n = v_0 + n$$

$$SS_n = SS_0 + Y^{\mathsf{T}}Y + b_0^{\mathsf{T}}\Phi_0 b_0 - b_n^{\mathsf{T}}\Phi_n b_n$$

7.1 Marginal of β and predictive distribution, all t

The following theorem is really useful for deriving marginal distributions.

Theorem: Let $\theta \mid \phi \sim \text{MVN}(m, \Sigma/\phi)$ and $\phi \sim \text{Gamma}(\nu/2, \nu \hat{\sigma}^2/2)$. Then $\theta \sim t_{\nu}(m, \hat{\sigma}^2 \Sigma)$ with density

$$p(\theta) \propto \left[1 + \frac{1}{\nu} \frac{(\theta - m)^{\mathsf{T}} \Sigma^{-1} (\theta - m)}{\hat{\sigma}^2}\right]^{-(p + \nu)/2}.$$

Trick for predictives: Recall that $\beta \mid \phi, Y \sim \text{MVN}(b_n, \phi^{-1}\Phi_n^{-1})$ and $\phi \mid Y \sim \text{Ga}(v_n/2, SS_n/2)$. Then the new data $Y^* = X^*\beta + \varepsilon^* | \phi, Y \sim \text{MVN}(X^*b_n, \phi^{-1}(X^*\Phi_n^{-1}X^{*\intercal} + I))$. Using the previous theorem, $Y^* \mid Y \sim t_{v_n}(X^*b_n, \hat{\sigma}^2(X^*\Phi_n^{-1}X^{*\intercal} + I))$, where $\hat{\sigma}_n^2 = SS_n/v_n$.