

Willian Galvani

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EDUCATION

UFSC

COMPUTERS SCIENCE BACHELOR'S
Incomplete: 2008-2010

5-YEARS DEGREE ON CONTROL AND
AUTOMATION ENGINEERING
(IAA 7.0) (GPA 3)

MERIT-BASED SCHOLARSHIPS: 100%
2011 - 2017

SEAMK

(AUTOMATION ENGINEERING
EXCHANGE STUDENT)
2014-2015

SKILLS

Programming

Python	●●●●●●●●●●
C	●●●●●●●●●●
C++	●●●●●●●●●●
C#	●●●●●●●●●●
LaTeX	●●●●●●●●●●
MATLAB	●●●●●●●●●●
HTML	●●●●●●●●●●
JavaScript	●●●●●●●●●●

Frameworks/Libraries

Arduino	●●●●●●●●●●
Django	●●●●●●●●●●
Ionic	●●●●●●●●●●
OpenCV	●●●●●●●●●●
Qt	●●●●●●●●●●

Others

GIT	●●●●●●●●●●
Inventor	●●●●●●●●●●
Linux	●●●●●●●●●●
Networking	●●●●●●●●●●
SolidWorks	●●●●●●●●●●
Proteus	●●●●●●●●●●
V-REP	●●●●●●●●●●
Eagle	●●●●●●●●●●

1-Shallow knowledge.

2-Able to perform minor changes.

3,4-Able to develop small projects.

5,6-Comfortable with the tool, able to fulfill more complex tasks and projects.

7,8-Understands the inner workings of the tool.

9,10-Comprehensive knowledge regarding the tool's implementation, inner workings, and nuances, able to recreate it given enough time.

PROFESSIONAL EXPERIENCE

NOVARUM SKY

FULL STACK EMBEDDED SOFTWARE ENGINEER.

(PYTHON + RASPBERRY PI + GSTREAMER + ASTERISK + VUE.JS + HTML + CSS)

March 2016 – Now

- Development of auxiliary drone systems for long-range HD video and audio transmission.
- Development of an drone-based inspection system for industrial inspections.
- Design and manufacture of an VTOL fixed-wing aircraft for photogrammetry.

UFSC / FEESC / PETROBRAS

DERIVATIVE FREE OPTIMIZATION FOR AUTOMATIC TUNING OF AN OIL WELL SIMULATOR.

(PYTHON + MATPLOTLIB)

August 2016 – March 2017

- Use of tuners for optimization of black box functions.
- Implementation of derivative free optimization methods in Python.
- Implementation of a software interface between tuners and Petrobras in-house multi-phasic flow simulation software.

INSTITUTO SESI DE INOVAÇÃO

(C + C++ + KINETIS + PYTHON + ASTERISK)

EMBEDDED SOFTWARE DEVELOPMENT.

August 2015 – February 2016

- Embedded Python development on Raspberry PI.
- Embedded C programming on freedom K64f platform.

UFSC - LABORATÓRIO DE CONTROLE DE AUTOMAÇÃO

(PYTHON + QT + ARDUINO)

PROVANT- PROJECT OF AN UNMANNED AERIAL VEHICLE.

July 2012 – June 2014

- Pilot and Developer at ProVant, project of an autonomous Tilt-Rotor aircraft.
- Design and implementation of communication protocol between UAV and ground station.
- Assistance on electrical, electronic, and mechanical projects.
- Design and implementation of a ground station software using Python and Qt.

UFSC - DEPARTAMENT DE AUTOMATION AND SYSTEMS

(PYTHON + DJANGO + JS + CSS + HTML)

WEBSITE DEVELOPMENT AND MAINTENANCE

August 2011 – December 2013

- Development and maintenance of both the Department of Automation and Systems and Control and Automation Engineering course websites.

DEVELOPMENT OF THE ACCESS CONTROL SYSTEM

November 2013 – June 2014

- Development and maintenance of a access control management system interface internal for the department and it's laboratories, interfacing with the built-in software on the controllers.

INTEREST AREAS

- RC Aircraft
- Data Science
- Artificial Intelligence
- Optimization
- Programming
- Mobile Robotics
- Autonomous Vehicles
- Computer Vision
- Software Defined Radio

LANGUAGES

- Portuguese (native)
- English (Toefl IBT 106/120)
- German (novice)

GITHUB

 [GitHub.com/Williangalvani](https://github.com/Williangalvani)

WEBSITE

 GalvanicLoop.com

LINKEDIN

 [Linkedin.com/in/willian-galvani](https://www.linkedin.com/in/willian-galvani)

PROJECTS

UAV DESIGN/ASSEMBLY

- Quadrotors (MultiWii, ArduPilot, KapteinKuk).
- Trirotor (MultiWii).
- Tilt-rotor (MultiWii).
- Fixed-Wing Aircraft.

PROVANT GROUNDSTATION (PYTHON + QT)

- software developed for the PROVANT project, a tilt-rotor developed by UFSC and UFMG.

RPI MULTIWII FPV (PYTHON + QT)

- Experiments on the use of a Wi-Fi network for telemetry, video downlink, and control uplink. All links were implemented in UDP for a reasonable latency.

DRONE TOKEN TRACKER (PYTHON + OPENCV)

- Token tracking system by a quadrotor on the V-Rep simulator.

DIYOSD MULTIWII (ARDUINO + LOW-LEVEL + ELECTRONICS)

- Project of a low-cost OSD using only an Arduino and passive components, heavily execution time sensitive for data manipulation tasks.

AUTONOMOUS SOLAR GLIDER (WIP)

(XFLR5 + 3D-PRINTING + ELECTRONICS)

- Design of an autonomous powered glider, autonomous both for navigation as in power generation.
- Objective of autonomously identifying and taking advantage of thermals.

VOLUNTEER WORK

ROBOTA -UFSC

MOBILE ROBOTICS COMPETITION TEAM.

March 2016 – now

- Development of autonomous robots for competitions.
- Development of open-source solutions and tools for mobile robotics.