

$$T = \frac{1}{2} m \dot{x}_1^2 + \frac{1}{2} m \dot{x}_2^2 = \frac{1}{2} \sum_{i,j} T_{ij} \dot{x}_i \dot{x}_j$$

$$T_{11} = m \quad T_{22} = m \quad ; \quad T_{12} = T_{21} = 0$$

$$V = \frac{1}{2} K x_1^2 + \frac{3}{2} K (l - l')^2 + \frac{1}{2} K x_2^2 = \frac{1}{2} [K x_1^2 + 3K (x_2 - x_1)^2 + K x_2^2]$$

$$V = \frac{1}{2} [4K x_1^2 + 4K x_2^2 - 6K x_1 x_2]$$

$$V_{11} = 4K \quad ; \quad V_{22} = 4K \quad ; \quad V_{12} = -3K \quad ; \quad V_{21} = -3K$$

$$\begin{vmatrix} V_{11} - \omega^2 T_{11} & V_{12} - \omega^2 T_{12} \\ V_{21} - \omega^2 T_{21} & V_{22} - \omega^2 T_{22} \end{vmatrix} = 0$$

$$\begin{vmatrix} 4K - \omega^2 m & -3K \\ -3K & 4K - \omega^2 m \end{vmatrix} = (4K - \omega^2 m)^2 - 9K^2 = 0$$

$$7K^2 - 8K\omega^2 m + \omega^4 m^2 = 0$$

$$x^2 m^2 - 8Kx m + 7K^2 = 0$$

$$\omega^2 = \frac{7K}{m} \quad ; \quad \frac{K}{m}$$

modos normales:

$$\sum_j (V_{ij} - \omega^2 T_{ij}) a_j = 0$$

$$\begin{pmatrix} 4 & -3 \\ -3 & 4 \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = \begin{pmatrix} 7K \\ 7K \end{pmatrix}$$

$$\rightarrow \begin{cases} -4a_1 - 3a_2 = 7a_1 \\ -3a_1 + 4a_2 = 7a_2 \end{cases}$$

$$\begin{cases} -7a_1 - 3a_2 = 0 \\ -3a_1 - 3a_2 = 0 \end{cases}$$

$$\begin{cases} a_2 = -a_1 \\ a_2 = -a_1 \end{cases}$$

$$a_1 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

en oposición de fase

$$\begin{pmatrix} 4 & -3 \\ -3 & 4 \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix}$$

$$\begin{cases} 4a_1 - 3a_2 = a_1 \\ -3a_1 + 4a_2 = a_2 \end{cases}$$

$$\begin{cases} 3a_1 - 3a_2 = 0 \\ -3a_1 + 3a_2 = 0 \end{cases}$$

$$\begin{cases} a_2 = a_1 \\ a_2 = a_1 \end{cases}$$

$$a_2 = a_1$$

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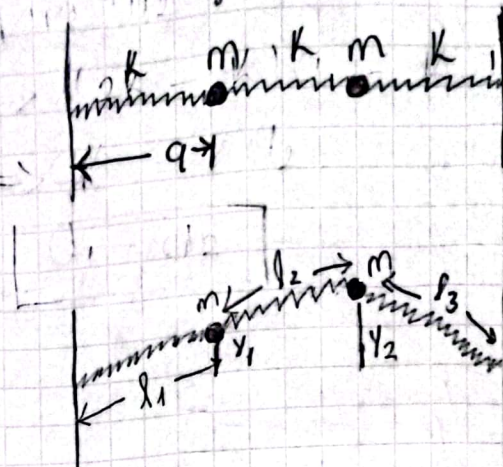
$$a_2 = a_1$$

$$a_2 = a_1$$

$$a_2 = a_1$$

$$a_2 = a_1$$

②



T_0 : Tension de los resortes inicialmente

$$T = \frac{1}{2}m(\dot{y}_1 + \dot{y}_2)$$

$$T_{11} = m \quad T_{22} = m$$

$$T_{12} = T_{21} = 0$$

$$l_1 = \sqrt{a^2 + y_1^2}$$

$$l_2 = \sqrt{a^2 + (y_2 - y_1)^2}$$

$$l_3 = \sqrt{a^2 + y_2^2}$$

Dado que $y_i \ll a$, podemos expandir y aproximar el sistema.

$$l_1 = a \left(1 + \left(\frac{y_1}{a} \right)^2 \right)^{1/2} \approx a \left(1 + \frac{1}{2} \left(\frac{y_1}{a} \right)^2 \right) = a + \frac{y_1^2}{2a}$$

$$l_2 = a \left(1 + \frac{(y_2 - y_1)^2}{a^2} \right)^{1/2} \approx a \left(1 + \frac{1}{2} \frac{(y_2 - y_1)^2}{a^2} \right) = a + \frac{(y_2 - y_1)^2}{2a}$$

$$l_3 = a \left(1 + \left(\frac{y_2}{a} \right)^2 \right)^{1/2} \approx a \left(1 + \frac{1}{2} \left(\frac{y_2}{a} \right)^2 \right) = a + \frac{y_2^2}{2a}$$

Para hallar los desplazamientos de los resortes hacemos $l_i - a = X_i$:

$$X_1 = \frac{y_1^2}{2a} \quad ; \quad X_2 = \frac{(y_2 - y_1)^2}{2a} \quad ; \quad X_3 = \frac{y_2^2}{2a}$$

Debido a que $y_i \ll a$ podemos suponer que los desplaz. sean lo suficientemente pequeños como para que la tensión T_0 no cambie.

$$\Rightarrow V = \frac{1}{2} k X^2 \rightarrow \frac{1}{2} T_0 X$$

$$V = \frac{L T_0}{2a} (y_1^2 + y_2^2 + (y_2 - y_1)^2) = \frac{1}{2a} T_0 (2y_1^2 + 2y_2^2 - 2y_1 y_2)$$

$$V_{11} = \frac{2T_0}{a} ; \quad V_{22} = \frac{2T_0}{a} ; \quad V_{12} = V_{21} = -\frac{T_0}{a}$$

$$\begin{vmatrix} \frac{2T_0}{a} - \omega^2 m & -\frac{T_0}{a} \\ -\frac{T_0}{a} & \frac{2T_0}{a} - \omega^2 m \end{vmatrix} = 0$$

$$\left(\frac{2T_0}{a} - \omega^2 m \right)^2 - \left(\frac{T_0}{a} \right)^2 = 0$$

$$\frac{2T_0}{a} - \omega^2 m = \pm \frac{T_0}{a}$$

$$\frac{2T_0}{a} \mp \frac{T_0}{a} = \omega^2 m$$

$$\frac{T_0}{a m} = \omega^2$$

$$\frac{3T_0}{a m} = \omega^2$$

$$\omega_1 = \sqrt{\frac{T_0}{a m}}$$

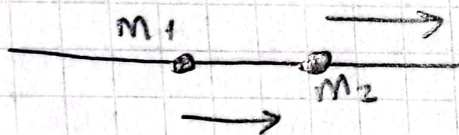
$$\omega_2 = \sqrt{\frac{3T_0}{a m}}$$

Los modos se hallan:

$$\sum_j (V_{ij} - \omega^2 T_{ij}) a_{ij} = 0$$

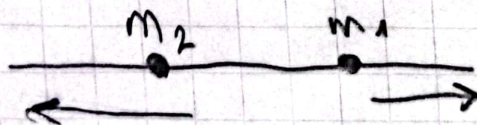
$$i=1 : \left(\frac{2T_0}{a} - \frac{T_0}{a} \right) a_1 + \frac{T_0}{a} a_2 = 0$$

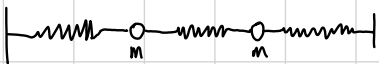
$$a_1 = a_2$$



$$i=2 : -\frac{T_0}{a} a_1 + \left(\frac{2T_0}{a} - \frac{3T_0}{a} \right) a_2 = 0$$

$$a_1 = -a_2$$





$$V = \frac{1}{2} K (n_1^2 + n_2^2 - 2 n_1 n_2) - \frac{2 \epsilon q^2}{r^3} (n_2 - n_1)$$

$$T = \frac{1}{2} m \dot{n}_1^2 + \frac{1}{2} m \dot{n}_2^2$$

$$\det |V - \omega^2 T| = 0$$

$$\det \begin{vmatrix} 2K + M - \omega^2 m & -K + M \\ -K + M & 2K + M - \omega^2 m \end{vmatrix} = 0$$

$$(2K + M - \omega^2 m)^2 = (K + M)^2$$

$$2K + M - \omega^2 m = \pm (K + M)$$

$$\omega^2 = \frac{2K + M \pm (K + M)}{m}$$

$$\omega_1 = \sqrt{\frac{K}{m}}$$

$$\omega_2 = \sqrt{\frac{3K + 2M}{m}}$$

$$\begin{pmatrix} 2K + M & -K - M \\ -K - M & 2K + M \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = \omega_1^2 m \begin{pmatrix} a_1 \\ a_2 \end{pmatrix}$$

$$(2K + M)a_1 + (-K - M)a_2 = \omega_1^2 m a_1 \rightarrow \text{Resolviendo, sería:}$$

$$(-K - M)a_1 + (2K + M)a_2 = \omega_1^2 m a_2$$

Primer modo de oscilación

$$a_1 = a_2 \rightarrow \text{Están en fase}$$

Segundo modo de oscilación

$$a_2 = -a_1 \rightarrow \text{Van en direcciones opuestas } \Downarrow$$