Ver 19

This version is the start of a new variant for encoderless, push to scopes.

The eFinder itself uses the same hardware as mainstream eFinder, raspberry pi, camera and hand pad. A different screen menu structure reflects the lack of Nexus DSC.

It does not not connect to a Nexus DSC

It requires a GPS USB dongle.

After it has started it listens on port 4060 for a SkySafari connection over LAN or Wifi. It then provides latest solved RA & Dec to SkySafari up to a rate of about 4 per second.

It has the ability to save a solved position, and then display the delta from that saved position to any future solves.

Its early in development!

In development….

Save all temporary files to ramdisk.

Add a 9 DOF sensor to allow automatic triggering of solve attempts when the scope has a) moved and b)is now stationary.