



MSC

软件部 --- 邵望权

- MMC 相关
- 硬件电路
- 协议 ---SD 卡协议为主
- 硬件逻辑
- 软件实现 ---MMC 子系统

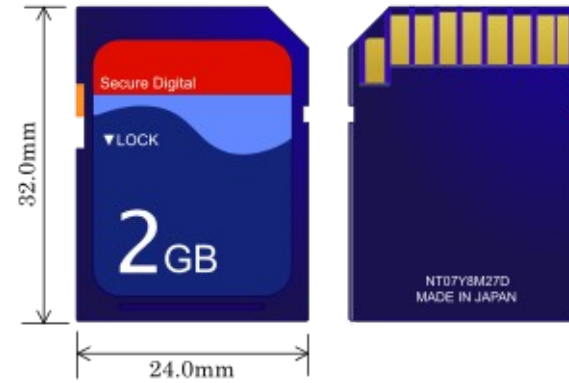
MMC 相关

- MMC (MultiMediaCard)
- MSC (Mobile Storage Controller)
- SD (Secure Digital)
 - SDSC ($\leq 2\text{GB}$)
 - SDHC ($> 2\text{Gb}, \leq 32\text{GB}$)
 - SDXC ($> 32\text{GB}, \leq 2\text{TB}$)
- eMMC (embedded MMC)
- SDIO (Secure Digital Input and Output)

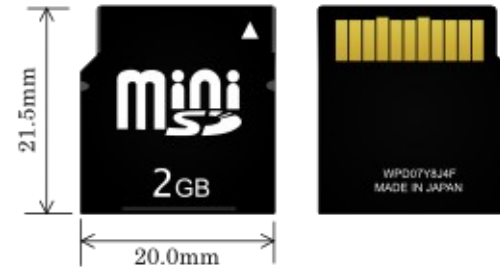
- 详情参考 : https://en.wikipedia.org/wiki/Secure_Digital

规格

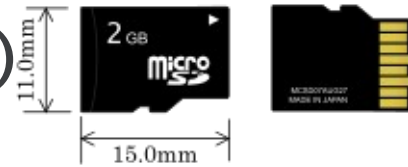
SD 卡



miniSD



microSD--- (TF Card)








BUS 接口







- BUS
 - SPI 模式
 - SD 模式
 - UHS 模式
- UHS (**Ultra High Speed**)

类型	协议
UHS-I	SD version 3.01
UHS-II	SD version 4.0
UHS-III	SD version 6.0

速度模式

Bus interface	Card logo	Bus logo	Bus speed	Spec version
Default Speed	  	—	12.5 MByte/s	1.01
High Speed			25 MByte/s	2.00
UHS-I	 	I	12.5 MByte/s (SDR12) 25 MByte/s (SDR25) 50 MByte/s (SDR50,DDR50) 104 MByte/s (SDR104)	3.01
UHS-II		II	156 MByte/s (FD156) 312 MByte/s (HD312)	4.00/4.10 (X2000)
UHS-III			312 MByte/s (FD312) 624 MByte/s (FD624)	6.0

速度等级

Minimum sequential writing speed	Speed Class	UHS Speed Class	Video Speed Class	Application Performance Class	Application
2 MB/s	 Class 2 (C2)	-	-	-	SD video recording
4 MB/s	 Class 4 (C4)	-	-	-	High-definition video (HD) recording including Full HD (from 720p to 1080p/1080i)
6 MB/s	 Class 6 (C6)	-	V6 Class 6 (V6)	-	
10 MB/s	 Class 10 (C10)	 Class 1 (U1)	V10 Class 10 (V10)	A1 Class 1 (A1)	Full HD (1080p) video recording and consecutive recording of HD stills (High Speed bus, Class C10), real-time broadcasts and large HD video files (UHS bus, Classes U1 and V10) Running applications from the memory card (Class A1 - minimum 1500 read / 500 write operations per second)
30 MB/s	-	 Class 3 (U3)	V30 Class 30 (V30)	-	1080p and 4K video files at 60/120 fps (UHS bus)
60 MB/s	-	-	V60 Class 60 (V60)	-	8K video files at 60/120 fps (UHS bus)
90 MB/s	-	-	V90 Class 90 (V90)	-	

Card



USH-III



BUS 与 Card

[illegible]

硬件电路

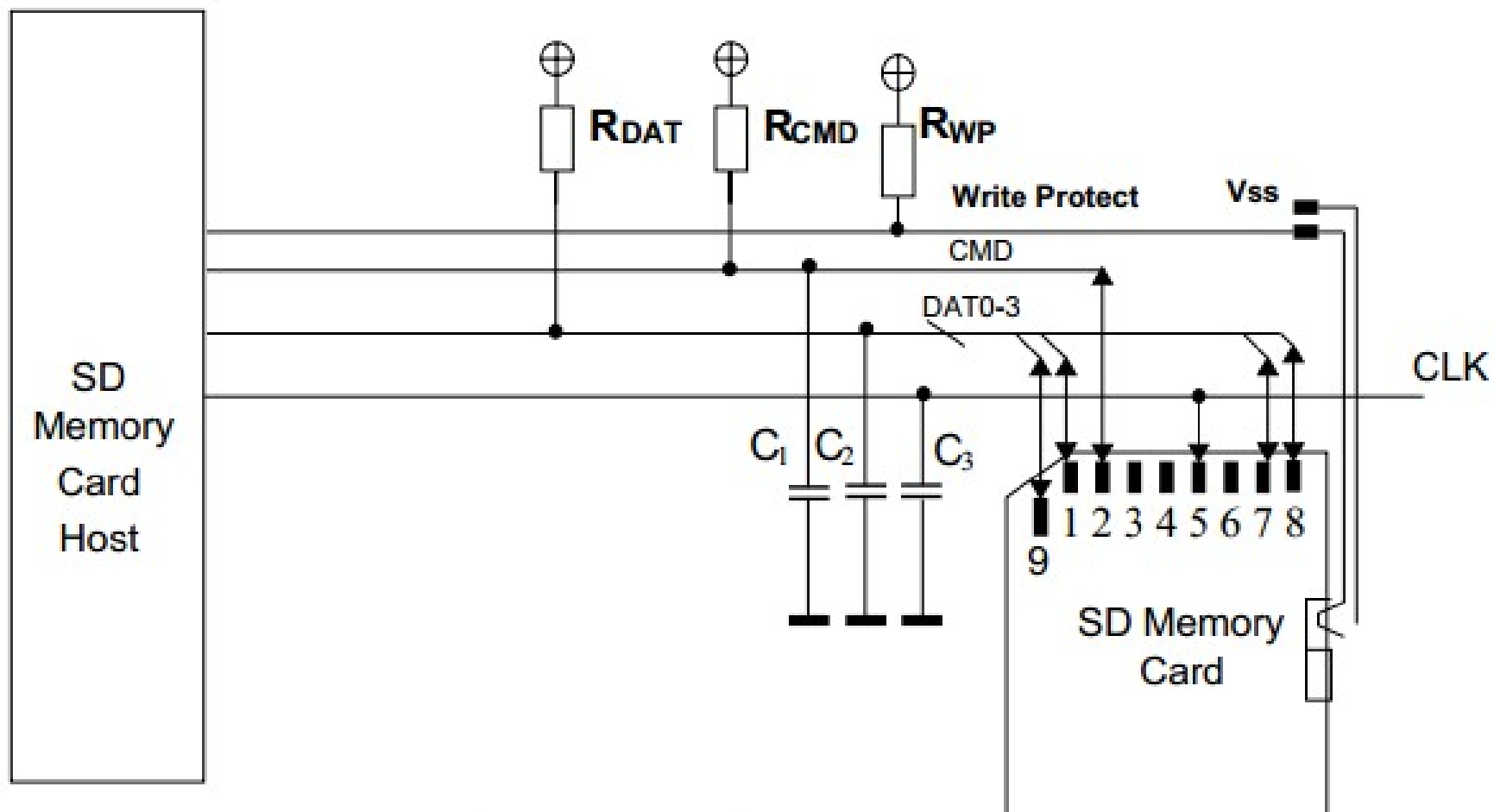


Figure 6-1: Bus Circuitry Diagram

硬件说明

SD pin	microSD pin	Name	I/O	Logic	Description
1	2	DAT3	I/O	PP	SD Serial Data 3
2	3	CMD	I/O	PP, OD	Command, Response
3		VSS	S	S	Ground
4	4	VDD	S	S	Power
5	5	CLK	I	PP	Serial clock
6	6	VSS	S	S	Ground
7	7	DAT0	I/O	PP	SD Serial Data 0
8	8	DAT1 nIRQ	I/O O	PP OD	SD Serial Data 1 (memory cards) Interrupt Period (SDIO cards share pin via protocol)
9	1	DAT2	I/O	PP	SD Serial Data 2

注：

数据方向：I = Input, O = Output.
PP = Push-Pull logic（上拉）
OD = Open-Drain logic（开漏）
S = Power Supply

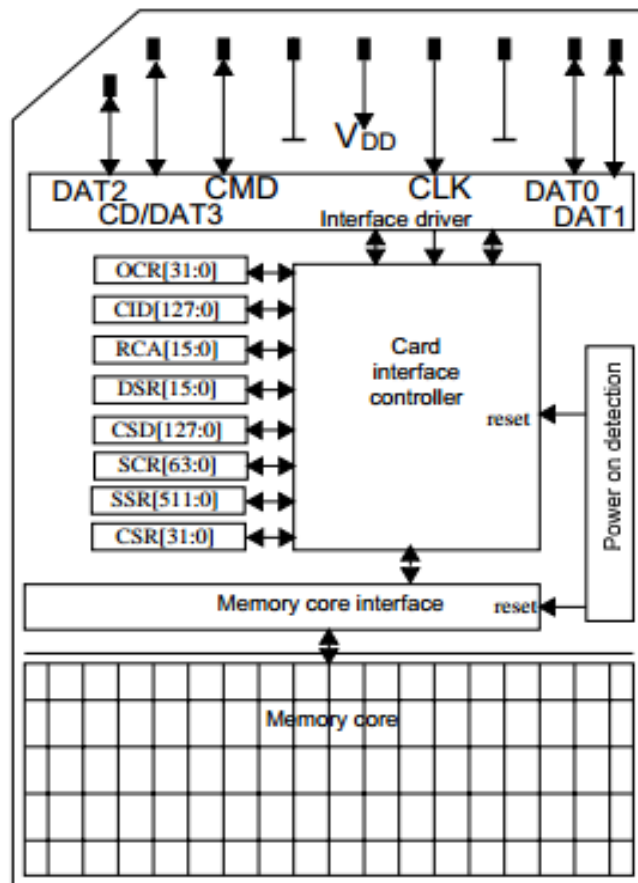


Figure 3-12: SD Memory Card Architecture

Name	Width	Description
CID	128	Card identification number; card individual number for identification (See 5.2). Mandatory.
RCA ¹	16	Relative card address; local system address of a card, dynamically suggested by the card and approved by the host during initialization (See 5.4). Mandatory.
DSR	16	Driver Stage Register; to configure the card's output drivers (See 5.5). Optional.
CSD	128	Card Specific Data; information about the card operation conditions (See 5.3). Mandatory
SCR	64	SD Configuration Register; information about the SD Memory Card's Special Features capabilities (See 5.6). Mandatory
OCR	32	Operation conditions register (See 5.1). Mandatory.
SSR	512	SD Status; information about the card proprietary features (See 4.10.2). Mandatory
CSR	32	Card Status; information about the card status (See 4.10.1). Mandatory

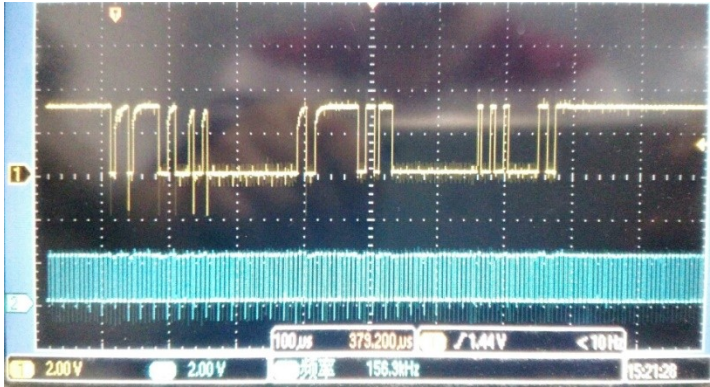
(1) RCA register is not used (available) in SPI mode

Table 3-2: SD Memory Card Registers

电压范围

Parameter	Symbol	Min	Max	Unit	Remark
Supply Voltage	V_{DD}	2.7	3.6	V	
Output High Voltage	V_{OH}	$0.75 \cdot V_{DD}$		V	$I_{OH} = -100\mu A$ $V_{DD\ min}$
Output Low Voltage	V_{OL}		$0.125 \cdot V_{DD}$	V	$I_{OL} = 100\mu A$ $V_{DD\ min}$
Input High Voltage	V_{IH}	$0.625 \cdot V_{DD}$	$V_{DD} + 0.3$	V	
Input Low Voltage	V_{IL}	$V_{SS} - 0.3$	$0.25 \cdot V_{DD}$	V	
Power Up Time			250	ms	From 0V to $V_{DD\ min}$

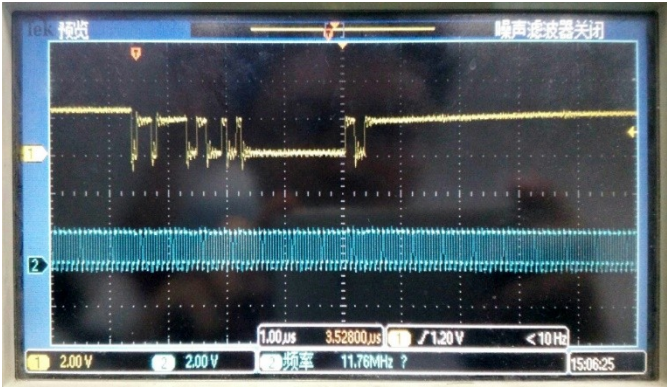
Table 6-2: Threshold Level for High Voltage



正常波形



上拉电阻大引起，但可以正常工作



上拉电阻过大，导致电压无法在规定时间内（2个时钟周期）内达到一定值

上拉电阻的范围：10 ~ 100 kΩ

协议 ---SD 卡协议为主

□ 协议：

- CMD
- CMD + DATA

□ CMD 类型：

- Broadcast commands (bc), no response
- Broadcast commands with response (bcr)
- Addressed (point-to-point) commands (ac)
- Addressed (point-to-point) data transfer commands (adtc)

Command Class

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Command

□ 常规命令：

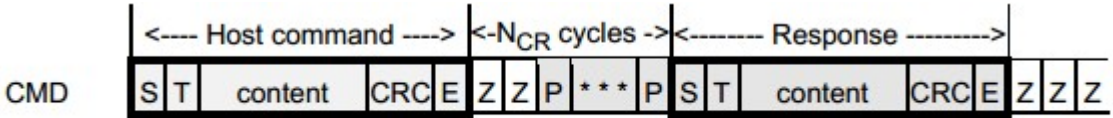


Figure 4-14: SEND_RELATIVE_ADDR Timing

□ 读：CMD17/18

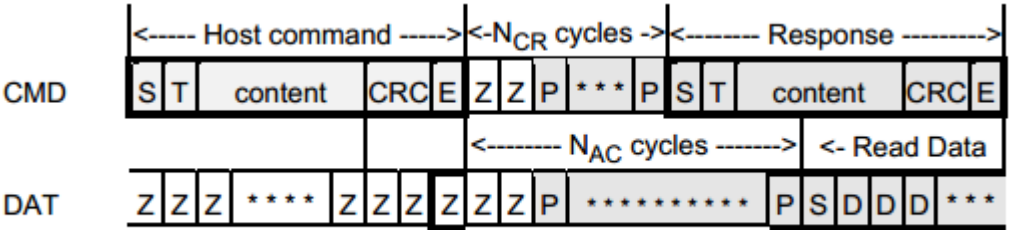


Figure 4-18: Timing of Single Block Read Command

□ 写：CMD24/25

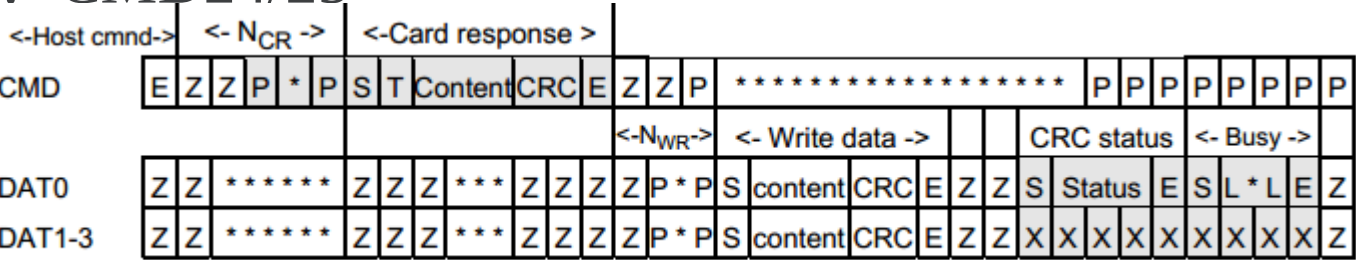


Figure 4-21: Timing of Single Block Write Command

Parameter	Min	Max	Unit
N_{CR}	2	64	clock cycles
N_{ID}	5	5	clock cycles
N_{AC}^1	2	-	clock cycles
N_{RC}	8	-	clock cycles
N_{CC}	8	-	clock cycles
N_{WR}	2	-	clock cycles

1) The maximum read access time for a Standard Capacity SD Memory Card shall be calculated by host as follows:

$N_{ac(max)} = 100 ((TAAC * f_{pp}) + (100 * NSAC))$;

f_{pp} is the interface clock rate and $TAAC$ & $NSAC$ are given in the CSD (Chapter 5.3).

Details of read, write, and erase timeouts are described in 4.6.2

In the case of a High Capacity SD Memory Card, a fixed value (100 ms) shall be used for the maximum read access time.

Table 4-47: Timing Values

- 在写的过程中由于控制器需要等到卡将数据全部写完，才视一次传输完成。
- 而在卡写的过程中，只有数据完全写入后，标志数据传输完成的 busy 位将在 DATA0 返回。同时返回的还有此次写数据后的状态 status(CRC 校验值)。如果 CRC 的校验值大于“010”，将代表数据传输失败。
- CRC Status
 - “010” —— 数据被接受写入卡中
 - “101” —— 由于 CRC 错误，数据不被卡接受
 - “110” —— 由于写错误，数据不被卡接受

SD 初始化流程

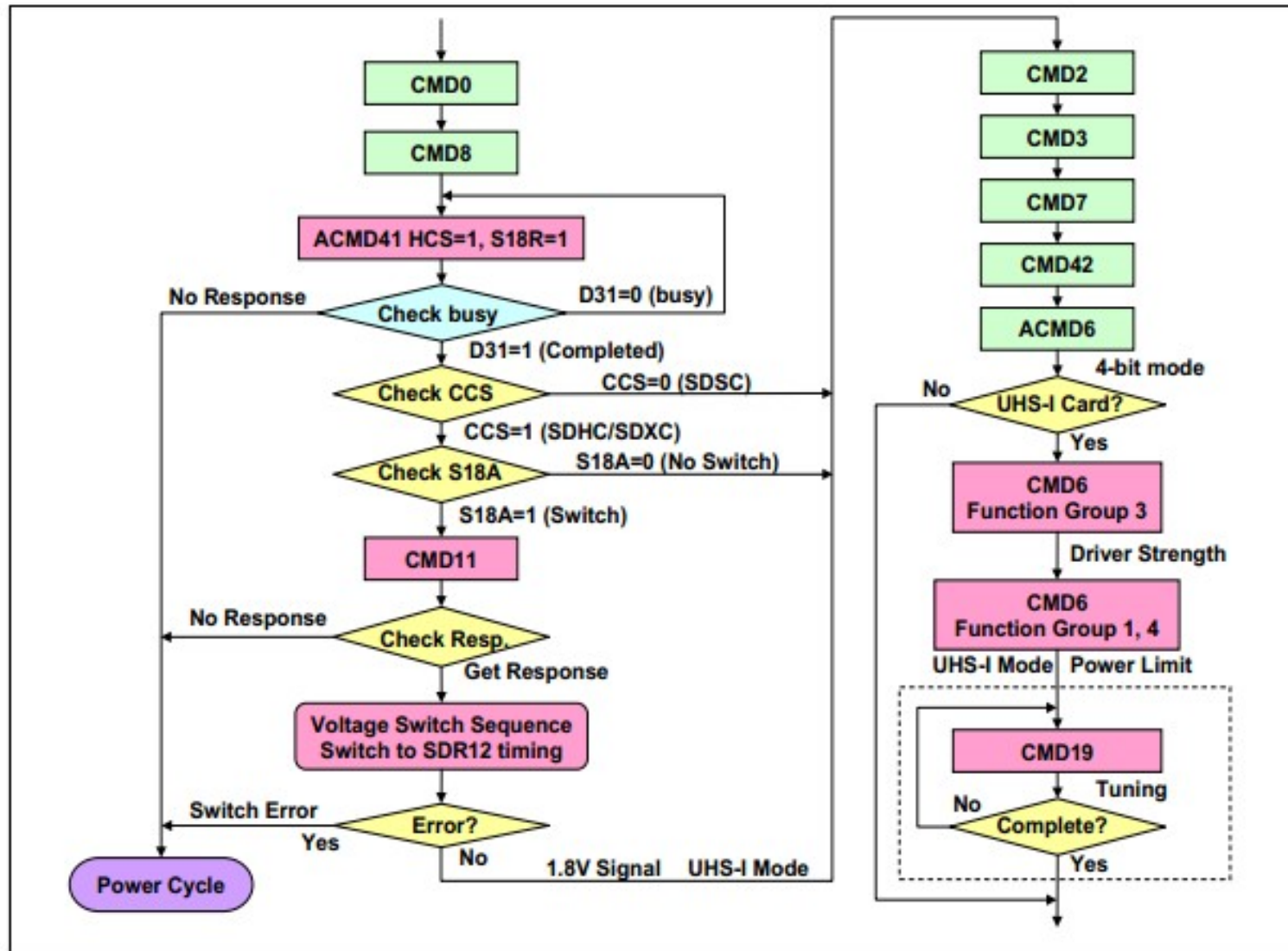
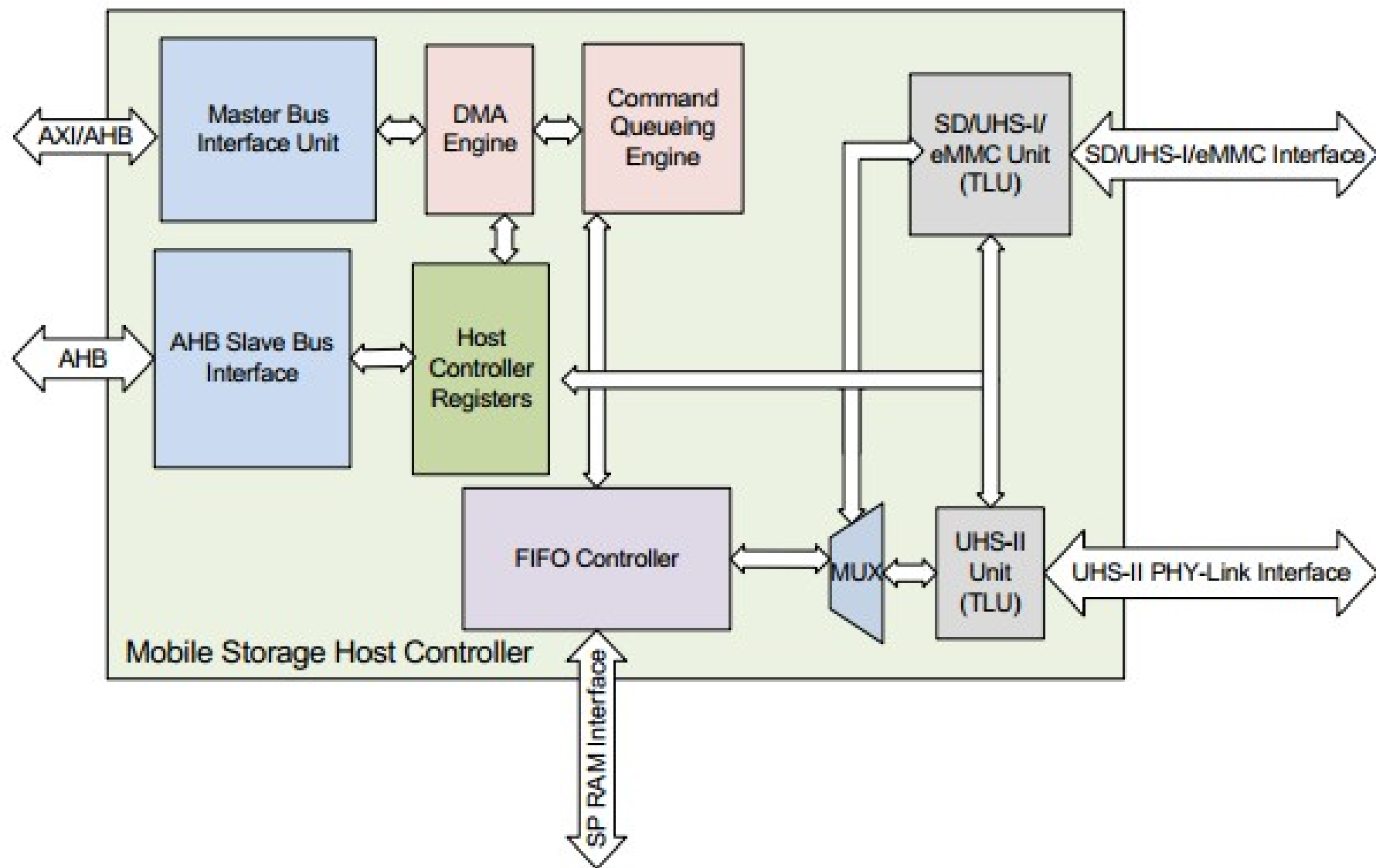
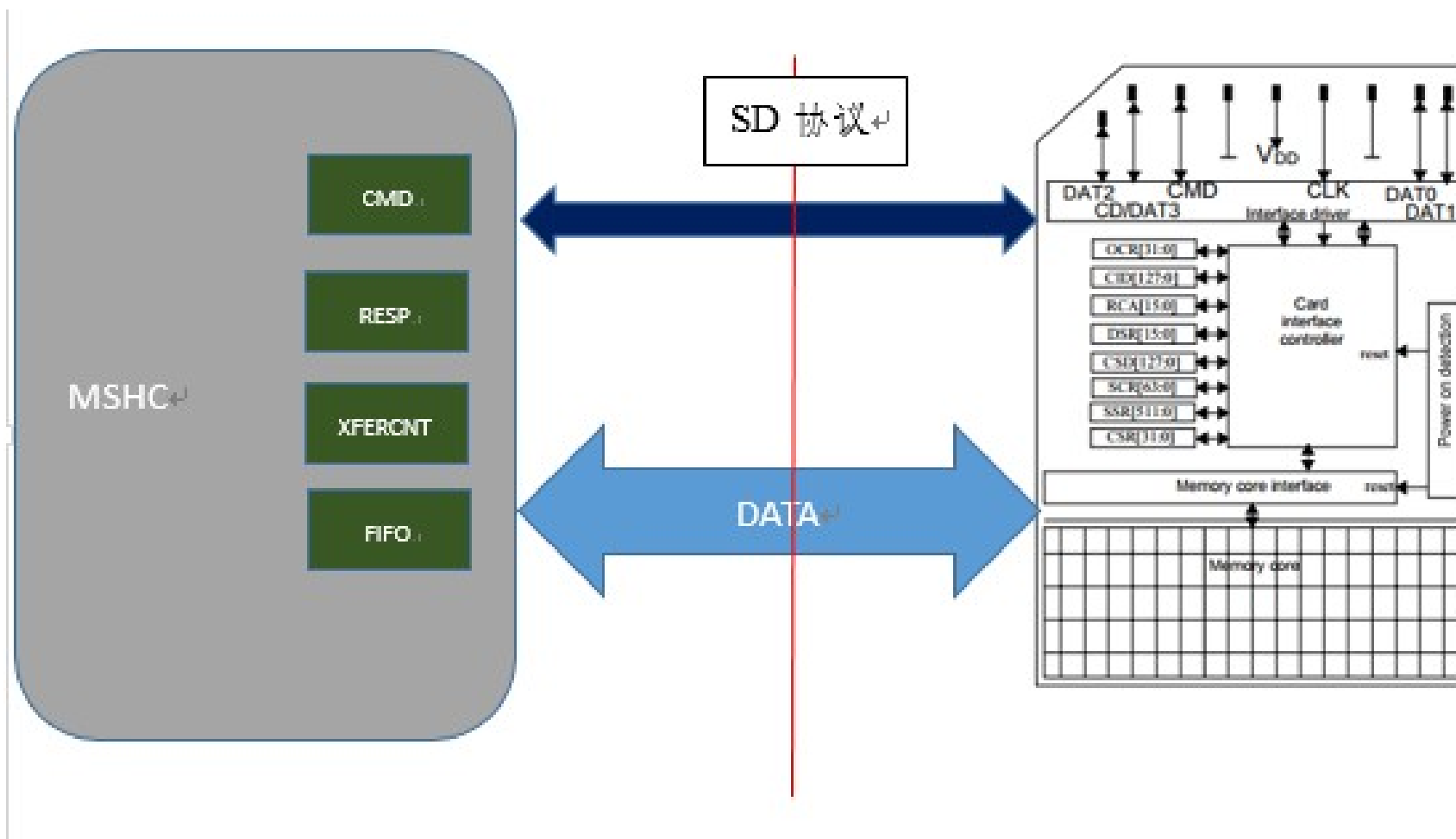


Figure 4-6 : UHS-I Host Initialization Flow Chart

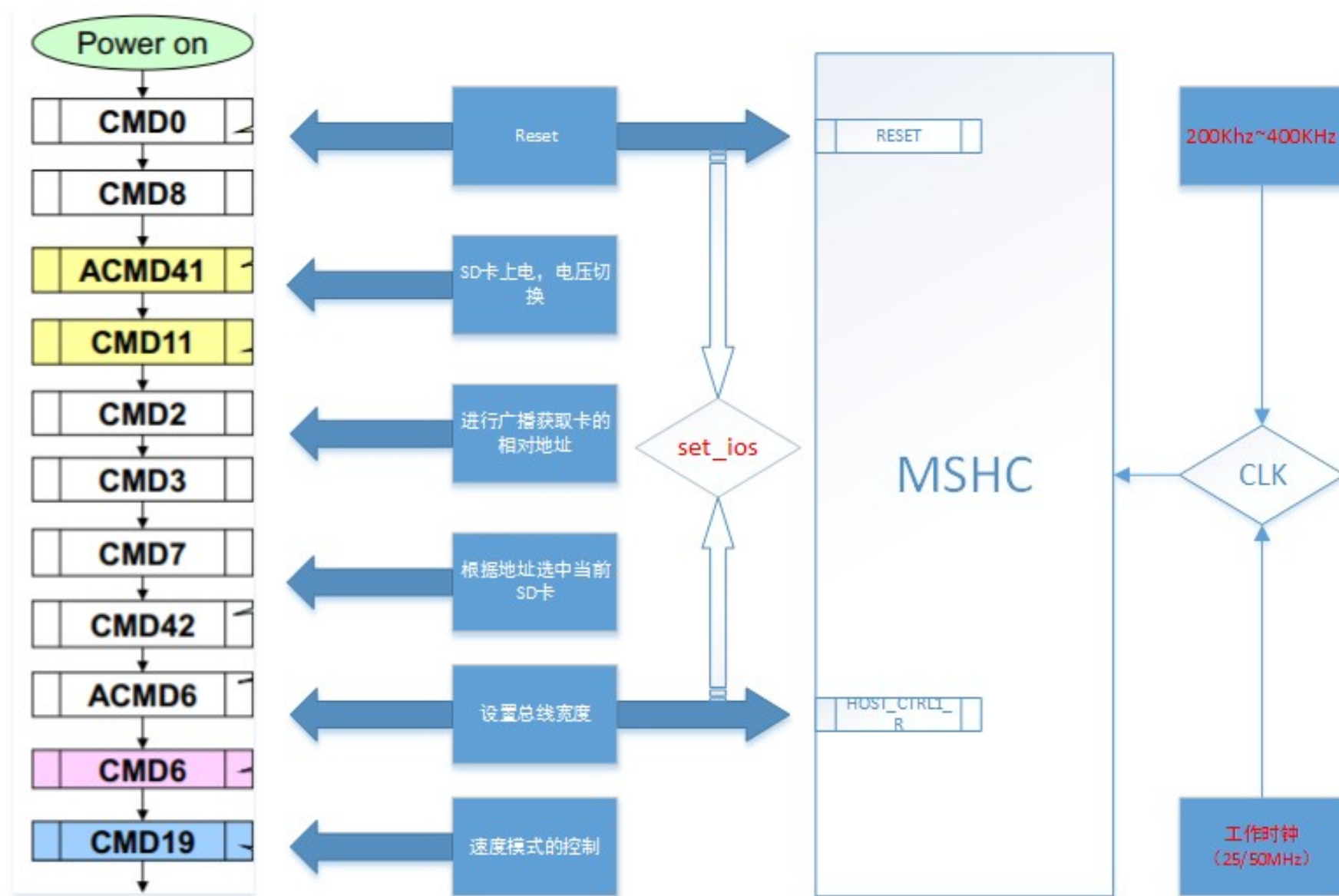
X2000 控制器结构图



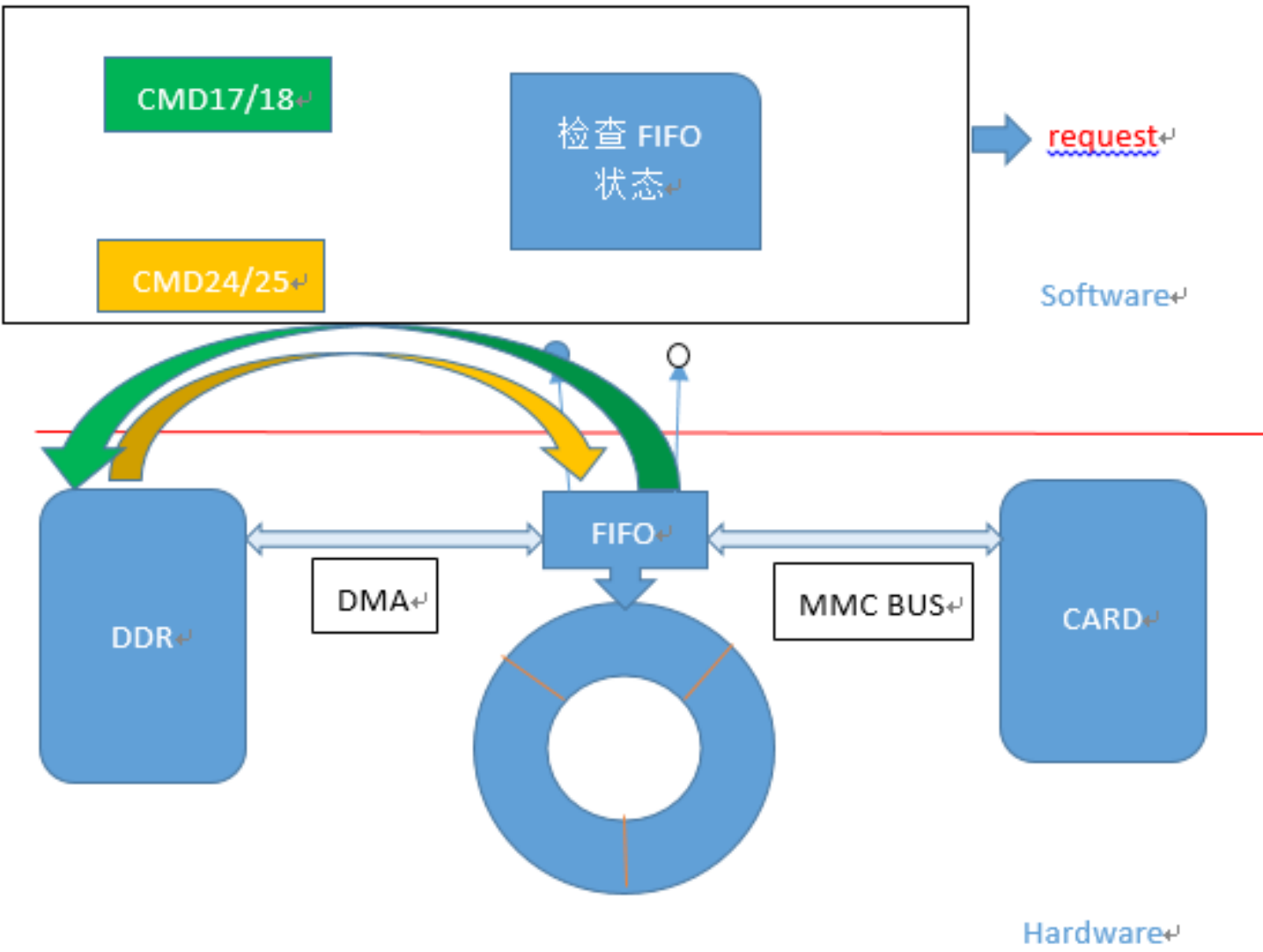
初始化



初始化流程



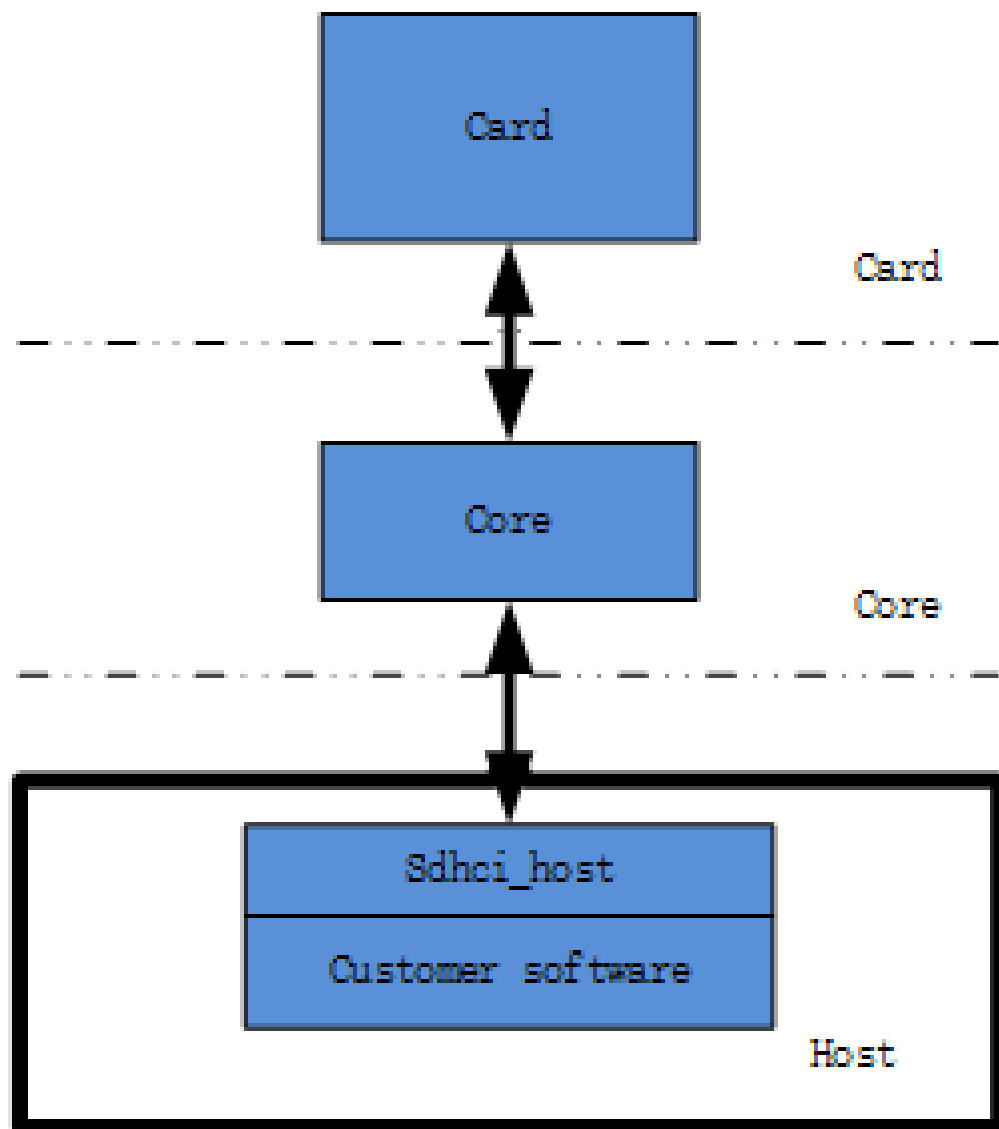
数据传输



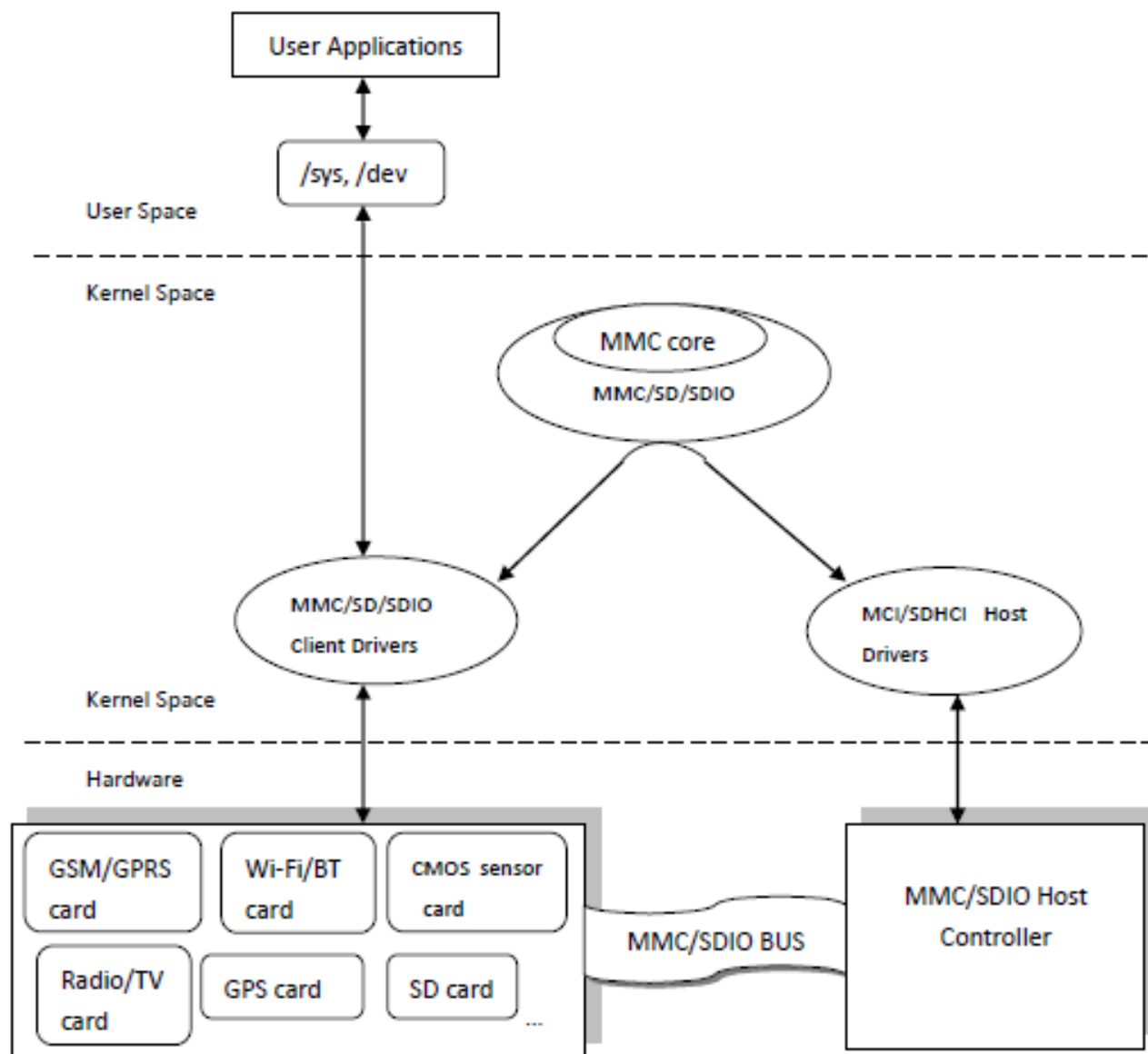
软件实现 ---MMC 子系统

- MMC 子系统代码 drivers/mmc ，共三个目录：
 - Card ：存放闪存卡（块设备）的相关驱动
 - Core ：整个 MMC 的核心层，这部分完成不同协议和规范的实现，为 host 层和设备驱动层提供接口函数。
 - Host ：针对不同主机端的 SDHC、MMC 控制器的驱动；

X2000 MSHC 驱动软件结构



软件框架



数据结构

```
struct mmc_host {  
    struct device      *parent; \  
    struct device      class_dev;  
    int                index;  
    const struct mmc_host_ops *ops;  
    struct mmc_ios      ios; /* current io bus settings */  
    struct mmc_card     *card; /* device attached to this host */  
    const struct mmc_bus_ops *bus_ops; /* current bus driver */  
    . . .  
  
    unsigned long      private[0] ____cacheline_aligned;  
};
```

代码：[include/linux/mmc/host.h](#)

□ MMC 驱动的实现主要有两个“线程”

- 初始化（热插拔）
 - `INIT_DELAYED_WORK(&host->detect, mmc_rescan)`
- 数据传输
 - `kthread_run(mmc_queue_thread, mq, "mmcqd/%d%s", host->index, subname ? subname : "");`

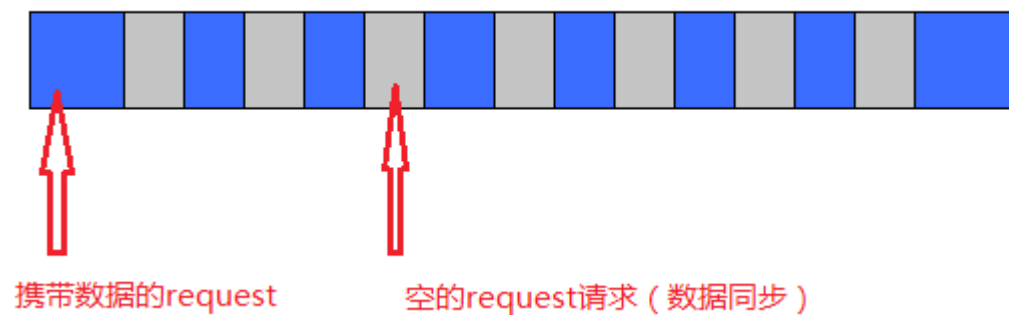
□ 三个接口

- `mmc_add_host(struct mmc_host *host)`
- `void (*set_ios)(struct mmc_host *host, struct mmc_ios *ios);`
- `void (*request)(struct mmc_host *host, struct mmc_request *req);`

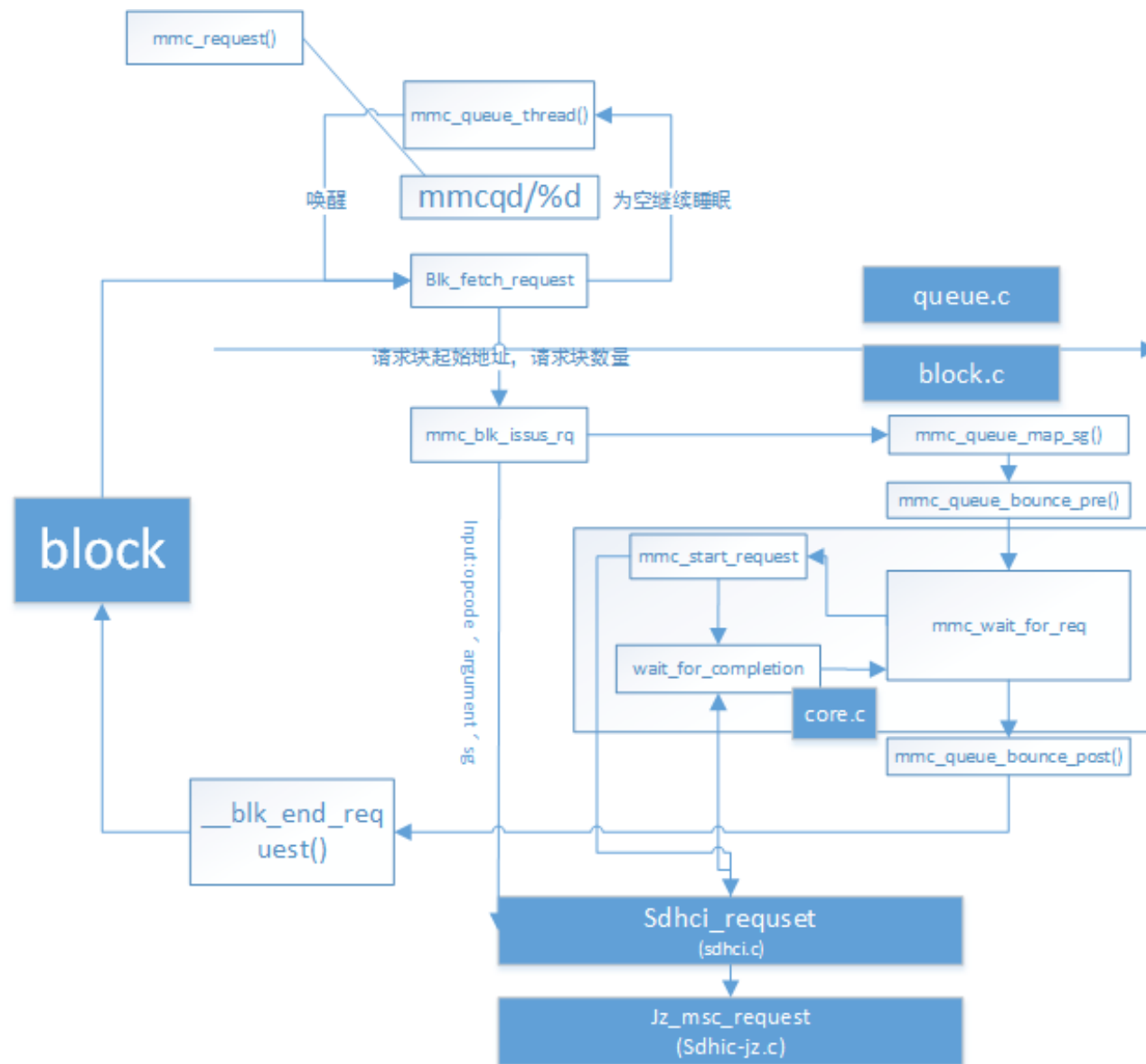
数据传输—request 处理

□ Request 请求队列

Block 将文件系统层传入的数据按照一定的策略进行组合，最后形成一个队列。



数据传输—request 处理





谢谢！