Homework3 Report

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1. (1%) 請說明你實作的 CNN model, 其模型架構、訓練過程和準確率為何?

Using TensorFlow bac	ckend.	
Layer (type)	Output Shape	Param #
conv2d_1 (Conv2D)	(None, 48, 48, 64)	640
batch_normalization	_1 (Batch (None, 48, 4	8, 64) 256
dropout_1 (Dropout)	(None, 48, 48, 64) 0
conv2d_2 (Conv2D)	(None, 48, 48, 64)	36928
batch_normalization	_2 (Batch (None, 48, 4	8, 64) 256
max_pooling2d_1 (Max	xPooling2 (None, 24, 2	24, 64) 0
dropout_2 (Dropout)	(None, 24, 24, 64) 0
conv2d_3 (Conv2D)	(None, 24, 24, 128	73856
batch_normalization	_3 (Batch (None, 24, 2	4, 128) 512
dropout_3 (Dropout)	(None, 24, 24, 12	8) 0
conv2d_4 (Conv2D)	(None, 24, 24, 128	147584
batch_normalization	_4 (Batch (None, 24, 2	4, 128) 512
max_pooling2d_2 (Max	xPooling2 (None, 12, 1	12, 128) 0
dropout_4 (Dropout)	(None, 12, 12, 12	8) 0
conv2d_5 (Conv2D)	(None, 12, 12, 256	3) 295168
batch_normalization	_5 (Batch (None, 12, 1	2, 256) 1024
dropout_5 (Dropout)	(None, 12, 12, 25	6) 0
conv2d_6 (Conv2D)	(None, 12, 12, 256	5) 590080
batch_normalization	_6 (Batch (None, 12, 1	2, 256) 1024
dropout_6 (Dropout)	(None, 12, 12, 25	6) 0
conv2d_7 (Conv2D)	(None, 12, 12, 256	5) 590080
batch_normalization	_7 (Batch (None, 12, 1	2, 256) 1024
max_pooling2d_3 (Max	xPooling2 (None, 6, 6,	256) 0
dropout_7 (Dropout)	(None, 6, 6, 256)	0
conv2d_8 (Conv2D)	(None, 6, 6, 512)	1180160
batch_normalization	_8 (Batch (None, 6, 6,	512) 2048
dropout_8 (Dropout)	(None, 6, 6, 512)	0
conv2d_9 (Conv2D)	(None, 6, 6, 512)	2359808

batch_normalization_9	(Batch (None, 6, 6,	512)	2048
dropout_9 (Dropout)	(None, 6, 6, 512)	0	
conv2d_10 (Conv2D)	(None, 6, 6, 512)	235	59808
batch_normalization_1	0 (Batc (None, 6, 6,	512)	2048
max_pooling2d_4 (MaxP	ooling2 (None, 3, 3,	512)	0
dropout_10 (Dropout)	(None, 3, 3, 512)	0	
conv2d_11 (Conv2D)	(None, 3, 3, 512)	235	59808
batch_normalization_1	1 (Batc (None, 3, 3,	512)	2048
dropout_11 (Dropout)	(None, 3, 3, 512)	0	
conv2d_12 (Conv2D)	(None, 3, 3, 512)	235	59808
batch_normalization_1	2 (Batc (None, 3, 3,	512)	2048
dropout_12 (Dropout)	(None, 3, 3, 512)	0	
conv2d_13 (Conv2D)	(None, 3, 3, 512)	235	59808
batch_normalization_1	3 (Batc (None, 3, 3,	512)	2048
max_pooling2d_5 (MaxP	ooling2 (None, 1, 1,	512)	0
dropout_13 (Dropout)	(None, 1, 1, 512)) 0	
flatten_1 (Flatten)	(None, 512)	0	
dense_1 (Dense)	(None, 256)	13132	8
batch_normalization_le	4 (Batc (None, 256)		1024
dropout_14 (Dropout)	(None, 256)	0	
dense_2 (Dense)	(None, 256)	65792	
batch_normalization_1	5 (Batc (None, 256)		1024
dropout_15 (Dropout)	(None, 256)	0	
dense_3 (Dense)	(None, 64)	16448	
batch_normalization_1	6 (Batc (None, 64)		256
dropout_16 (Dropout)	(None, 64)	0	
	(None, 7)	455	
Total params: 14,946,75 Trainable params: 14,93	9 37,159		=======
Non-trainable params:	9,000		

以上是我的 CNN 模型架構,主要是參考了 VGG-16 的架構,並加入漸進式的 dropout layer、batch normalization layer 及對某幾層的 filters 數進行 了調整而得出。

在訓練開始前,我取了 10%的資料作為 validation data,其餘的資料則利用了 image data augmentation 的技巧對圖片進行了旋轉、平移、縮放等不同方式 的 前 處 理 , 增 加 訓 練 資 料 的 數 量 。 接 著 再 利 用 我 的 模 型 架 構 在 batch_size=128,epochs=300 的情況下進行訓練。在每層 layer,我都是以 padding='same',kernel_initializer='glorot_normal',activation='relu'作為基本的設定。

在訓練過程中,我利用 keras 的 ModelCheckpoint 來幫助我找出所有 epochs 中 validation test 中結果最好的 model。最後分別取得了 Public Score = 0.65422 及 Private Score = 0.65923 的準確度。

2. (1%) 承上題,請用與上述 CNN 接近的參數量,實做簡單的 DNN model,其模型架構、訓練過程和準確率為何?試與上題結果做比較,並說明你觀察到了什麼?

Layer (type)	Output Shape	Paran	
flatten_1 (Flatten)	(None, 2304)	0	
dense_1 (Dense)	(None, 256)	590080)
batch_normalization	_1 (Batch (None, 256)		1024
dropout_1 (Dropout)	(None, 256)	0	
dense_2 (Dense)	(None, 256)	65792	
batch_normalization	_2 (Batch (None, 256)		1024
dropout_2 (Dropout)	(None, 256)	0	
dense_3 (Dense)	(None, 512)	131584	l .
batch_normalization	_3 (Batch (None, 512)		2048
dropout_3 (Dropout)	(None, 512)	0	
dense_4 (Dense)	(None, 512)	262656	3
batch_normalization	_4 (Batch (None, 512)		2048
dropout_4 (Dropout)	(None, 512)	0	
dense_5 (Dense)	(None, 1024)	52531	2
batch_normalization	_5 (Batch (None, 1024)		4096
dropout_5 (Dropout)	(None, 1024)	0	
dense_6 (Dense)	(None, 1024)	10496	00

batch_normalization_6	(Batch (None, 1024	1)	4096
dropout_6 (Dropout)	(None, 1024)	0	
dense_7 (Dense)	(None, 1024)	10496	00
batch_normalization_7	(Batch (None, 1024	1)	4096
dropout_7 (Dropout)	(None, 1024)	0	
dense_8 (Dense)	(None, 2048)	20992	00
batch_normalization_8	(Batch (None, 2048	3)	8192
dropout_8 (Dropout)	(None, 2048)	0	
dense_9 (Dense)	(None, 2048)	41963	52
batch_normalization_9	(Batch (None, 2048	3)	8192
dropout_9 (Dropout)	(None, 2048)	0	
dense_10 (Dense)	(None, 2048)	41963	352
batch_normalization_1	.0 (Batch (None, 20	18)	8192
dropout_10 (Dropout)	(None, 2048)	0	
dense_11 (Dense)	(None, 7)	14343	
		======	
 Total params: 14,223,87	79		
Trainable params: 14,2			
Non-trainable params: 21,5	504		

以上是我的 DNN 模型架構,跟 CNN 架構一樣擁有漸進式的 dropout layer 及 batch normalization layer。

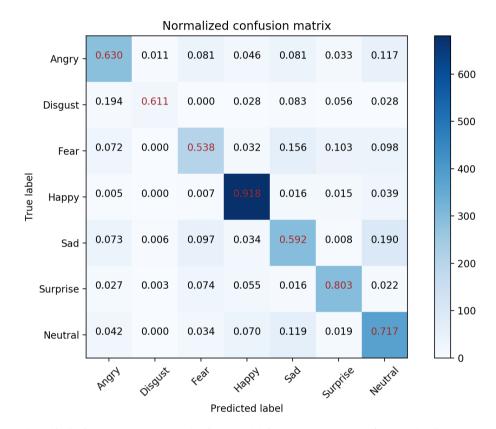
訓練過程與 CNN 大同小異,10%的資料作為 validation data,其餘的資料則利用了 image data augmentation 的技巧對圖片進行了旋轉、平移、縮放等不同方式的前處理,增加訓練資料的數量。

模型架構在 batch_size=128,epochs=300 的情況下進行訓練。在每層 layer,我都是以 padding='same',activation='relu'作為基本的設定。

在訓練過程中,也利用 keras 的 ModelCheckpoint 來幫助我找出所有 epochs 中 validation test 中結果最好的 model。最後分別取得了 Public Score = 0.30844 及 Private Score = 0.32153 的準確度。

與 CNN 比較,根據我的 model 檔案紀錄,我發現 DNN 會在比較短時間內出現收斂的情況。其次 DNN 的運算速度比 CNN 快很多,這是因為在卷積過程中會有很多的運算。最後很明顯的 DNN 的準確度遠不及 CNN。

3. (1%) 觀察答錯的圖片中,哪些 class 彼此間容易用混? 並說明你觀察到了什麼? 「繪出 confusion matrix 分析]



很明顯的看的出來,disgust 比較容易誤判成 angry、sad 容易誤判成 neutral、fear 跟 neutral 容易誤判成 sad。

我有去 data set 中找出容易被誤判的幾類照片來觀察,發現有些照片比較起來看下去第一瞬間真的不好判斷說應該要分到哪一類,所以程式分不出來我覺得也是正常的。

-----Handwritten question-----

4. (1.5%, each 0.5%) CNN time/space complexity:
For a. b. Given a CNN model as

```
model = Sequential()
        model.add(Conv2D(filters=6,
                          strides=(3, 3),
        """Layer A"""
                          padding ="valid",
                          kernel size=(2,2),
                          input shape=(8,8,5),
                          activation='relu'))
        model.add(Conv2D(filters=4,
                          strides=(2, 2),
        """Laver B"""
                          padding ="valid",
                          kernel size=(2,2),
                          activation='relu'))
       And for the c. given the parameter as:
        kernel size = (k,k);
        channel size = c;
        input shape of each layer = (n,n);
       padding = p;
        strides = (s,s);
     a. How many parameters are there in each layer (Hint:
        you may consider whether the number of parameter is
        related with)
       Laver A:
             2*2*6*5 + 6 = 126
        Laver B:
             2*2*4*6 + 4 = 100
     b. How many multiplications/additions are needed for a
        forward pass (each layer).
        Layer A:
             multiplications : 2*2*5*3*3*6 = 1080
             additions : (2*2*5 - 1)*3*3*6 = 1026
        Laver B:
             multiplications : 2*2*6*1*1*4 = 96
             additions : (2*2*6 - 1)*1*1*4 = 92
     c. What is the time complexity of convolutional neural
        networks? (note: you must use big-O upper bound, and
        there are l(lower case of L) layer, you can use
       \square \square, \square \square-1as lth and l-1th layer)
5. (1.5%, each 0.5%) PCA practice: Problem statement: Given 10
  samples in 3D
  space. (1,2,3), (4,8,5), (3,12,9), (1,8,5), (5,14,2), (7,4,1), (
  9, 8, 9), (3, 8, 1), (11, 5, 6), (10, 11, 7)
     a. (1) What are the principal axes?
```

b. (2) Compute the principal components for each sample.

```
(7.18658682, 1.37323947),

(0.75871342, -0.94399334),

(-3.07034019, -4.45059025),

(2.60849751, -2.97853006),

(-1.82299166, -4.75401212),

(3.35457763, 3.91896138),

(-4.41464321, 2.55604371),

(3.46569126, -1.73131477),

(-2.31359638, 6.03371503),

(-5.75249521, 0.97648096)

c. (3) Reconstruction error if reduced to 2D.(Calculate the L2-norm)
```