

```
1) int BellmanFord ( Graph *src, Graph *dest ) {  
    int min = INT_MAX;
```

```
    int count = 0;
```

```
    while (g != dest) {
```

```
        g → next;
```

```
        count += g → distance;
```

```
    }
```

```
    if (count < min)
```

```
        return count;
```

```
}
```



```

2) bool greedy(S[0..n-1], n) {
    int day = 0;
    for (int i = 0; i < n; i++) {
        input = S[i].d - S[i].p;
        if (input < day)
            return impossible;
        day += S[i].p;
    }
    return possible;
}

```

3

Greedy has a run-time of $O(n)$.
 Worst case input = 1 at every loop.

3) No. The given algorithm is a comparison based algorithm which would mean that it would have a lower bound of $\Omega(n \log n)$, which is not linear. Therefore, we should not believe in Professor X.

```
4) bool np(V, E, B) {  
    int counter = 0;  
    for (int i = 0; i < V; i++) {  
        for (int j = 0; j < V; j++) {  
            if (i != j && i, j ∈ E) ← if i and j share  
                counter++;           an edge  
        }  
    }  
    if (counter == B)  
        return true;  
    return false;  
}
```

Cannot be solved in NP, as this has run-time of $O(V^2)$ and not K^n .

5)

V, E, \cancel{E}

bool $p(V, E) \Leftarrow$

for (int $i = 0; i \leq V; i++$) \Leftarrow

for (int $j = 0; j \leq V; j++$) \Leftarrow

for (int $k = 0; k \leq V; k++$) \Leftarrow

if ($i \neq j \neq k$) \Leftarrow

if i, j, k all share
an edge \Leftarrow

if ($(i, j) \in E \ \&\& \ (j, k) \in E \ \&\& \ (i, k) \in E$)

return true;

}

}

return false;

}

This algorithm has a run-time of $O(V^3)$, which is in polynomial time, and is thus in P .