FRC LabVIEW Trajectory Library – VI Implementation List

Revision 2.X 5/2/2022 – added implicit model follower and time interpolatable routines.

This documents which Java/C++ WPILIB routines have been duplicated in LabVIEW, and which ones are not needed (for example because all that is needed is a cluster unpack function), and what isn't done....yet...

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program
VI / CTL Totals	923	866	307	876	462	43	12
VI Total (X)	824						
CTL Total (Z)	99						
VI Shell Total (/)	4						
CTRL Shell Total (\)	2						

Doc completed Pct
93.82%
Optimization Pct
50.05%

Optimize legend: S = Subroutine, I = Inline, X = reviewed, nothing done. (In some cases, after sufficient debug and use, additional optimizations could be considered.)

'============
BASE
'============

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
FUNCTION GENERATOR	X		X	X				FunctionGenerator_Add_Value.vi		Similar to interpolated tree map..			
	X		X	X				FunctionGenerator_Add_XY.vi		Similar to interpolated tree map..			
	X		X	X				FunctionGenerator_Calculate.vi		Similar to interpolated tree map..			
	X		X	X				FunctionGenerator_Clear.vi					
	X		X	X				FunctionGenerator_Execute.vi		Similar to interpolated tree map..			
	X		X	X				FunctionGenerator_New.vi		Similar to interpolated tree map..			

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
FUNCTION GENRATOR MATRIX	X		X	X				FunctionGeneratoMatrixr_Add.vi		Similar to interpolated tree map..			
	X		X	X				FunctionGenerator_Calculate.vi		Similar to interpolated tree map..			
	X		X	X				FunctionGenerator_New.vi		Similar to interpolated tree map..			

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
LINEAR FILTER	X	X		X	I			LinearFilter_BackwardFiniteDifference.vi					
	X	X		X	SI			LinearFilter_Calculate.vi					
	X	X	X	X	X			LinearFilter_CutoffFrequency.vi					
	X	X	X	X	I		X	LinearFilter_Execute.vi		Labview style helper			
	X	X		No	I			LinearFilter_Factorial.vi		AN INTERNAL ROUTINE			
	X	X		X	X			LinearFilter_HighPass.vi					
	X	X	X	X	X			LinearFilter_HighPassBW1.vi					
	X	X	X	X	X			LinearFilter_HighPassBW2.vi					
	X	X	X	X	X			LinearFilter_LowPassBW1.vi					

X	X	X	X	X			LinearFilter_LowPassBW2.vi						
X	X		X	X			LinearFilter_MovingAverage.vi						
X	X		X	I			LinearFilter_New.vi						
X	X		X	SI			LinearFilter_Reset.vi						
X	X	X	X	SI			LinearFilter_ResetToValue.vi						
X	X		X	X			LinearFilter_SinglePoleIIR.vi						
X	X	X	X	X			LinearFilter_TimeConst.vi						

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
MEDIAN FILTER	X	X		X	X			MedianFilter_Calculate.vi					
	X	X	X	X	I		X	MedianFilter_Execute.vi		Labview style helper			
	X	X		X	SI			MedianFilter_New.vi					
	X	X		X	SI			MedianFilter_Reset.vi					
	X	X	X	X	SI			MedianFilter_ResetToValue.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
SLEW RATE FILTER	X	X		X	I			SlewRateLimiter_Calculate.vi					
	X	X	X	X	SI			SlewRateLimiter_Close.vi					
	X	X	X	X	I		X	SlewRateLimiter_Execute.vi		Labview style helper			
	X	X	X	X	SI			SlewRateLimiter_GetRate.vi					
	X	X		X	I			SlewRateLimiter_New.vi					
	X	X		X	I			SlewRateLimiter_NewInitialZero.vi					
	X	X		X	I			SlewRateLimiter_Reset.vi					
	X	X		X	SI			SlewRateLimiter_SetRate.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
TIMER	X	X	X	X				Timer_Close.vi		releases semaphore			
	X	X		X			X	Timer_Get.vi					
	X	X	X	X				Timer_GetAndReset.vi					
	X	X	X	No				Timer_GetInternal.vi		Internal (private) only			
	X	X		X			X	Timer_HasPeriodPassed.vi					
	X	X	X	X			X	Timer_HasPeriodPassedOnce.vi					
	X	X		X			X	Timer_New.vi					
	X	X		X			X	Timer_Reset.vi					
	X	X	X	No				Timer_ResetInternal		Internal (private) only			
	X	X		X			X	Timer_Start.vi					
	X	X		X			X	Timer_Stop.vi					
	X	X	X	No				Timer_StopInternal.vi		Internal (private) only			

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
TIME INTERPOLATABLE BOOLEAN	X		X	X				TimeInterpBoolean_AddSample.vi		Update to use create matrix			

	X		X	No				TimeInterpBoolean_CleanUp.vi		Update to use create matrix			
	X		X	X				TimeInterpBoolean_Clear.vi					
	X		X	X				TimeInterpBoolean_GetSample.vi					
	X		X	X				TimeInterpBoolean_New.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
TIME INTERPOLATABLE DOUBLE	X		X	X				TimeInterpDouble_AddSample.vi		Update to use create matrix			
	X		X	No				TimeInterpDouble_CleanUp.vi		Update to use create matrix			
	X		X	X				TimeInterpDouble_Clear.vi					
	X		X	X				TimeInterpDouble_GetSample.vi					
	X		X	X				TimeInterpDouble_New.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
TIME INTERPOLATABLE POSE	X		X	X				TimeInterpPose2d_AddSample.vi		Update to use create matrix			
	X		X	No				TimeInterpPose2d_CleanUp.vi		Update to use create matrix			
	X		X	X				TimeInterpPose2d_Clear.vi					
	X		X	X				TimeInterpPose2d_GetSample.vi					
	X		X	X				TimeInterpPose2d_New.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
TIME INTERPOLATABLE ROTATION	X		X	X				TimeInterpRotation2d_AddSample.vi		Update to use create matrix			
	X		X	No				TimeInterpRotation2d_CleanUp.vi		Update to use create matrix			
	X		X	X				TimeInterpRotation2d_Clear.vi					
	X		X	X				TimeInterpRotation2d_GetSample.vi					
	X		X	X				TimeInterpRotation2d_New.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
DIG SEQ LOGIC	X	X	X	X				DigSeqLogic_On_Delay.vi					
	X	X	X	X				DigSeqLogic_Off_Delay.vi					
	X	X	X	X				DigSeqLogic_One_Shot.vi					
	X	X	X	X				DigSeqLogic_SR_Flip_Flop.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
DEBOUNCER	X	X		X				Debouncer_New.vi					
	X	X		X				Debouncer_Calculate.vi					
	X	X	X	X				Debouncer_Execute.vi					
	X	X		No				Debouncer_Reset.vi					
	X	X		No				Debouncer_HasElapsed.vi					

'============
CONTROLLER
'============

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
ARM FF	X	X		X				ArmFF_Calculate.vi					
	X	X		X				ArmFF_CalculateVelocityOnly.vi					
			X					ArmFF_Execute.vi		LabVIEW style single call			
			X					ArmFF_ExecuteVelocityOnly.vi		LabVIEW style single call			
	X	X		X				ArmFF_MaxAchieveAccel.vi					
	X	X		X				ArmFF_MaxAchieveVelocity.vi					
	X	X		X				ArmFF_MinAchieveAccel.vi					
	X	X		X				ArmFF_MinAchieveVelocity.vi					
	X	X		X				ArmFF_New_ZeroGravity.vi					
	X	X		X				ArmFF_New.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
BANG BANG	X	X		X	SI			BangBang_AtSetpoint.vi					
	X	X		X	SI			BangBang_Calculate_PV.vi					
	X	X		X	SI			BangBang_Calculate_SP_PV.vi					
	X	X	X	X	SI			BangBang_Execute.vi					
	X	X		X	SI			BangBang_GetAll.vi					
	X	X		X	SI			BangBang_GetError.vi					
	X	X		X	SI			BangBang_New.vi					
	X	X		X	SI			BangBang_SetSetpoint.vi					
	X	X		X	SI			BangBang_SetTolerance.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
CONTROLLER UTIL	X	X		X	SI			ControllerUtil_GetModulusError.vi		This was short lived in WPILIB, but still useful here.			

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
ELEV FF	X	X		X				ElevFF_Calculate.vi					
	X	X		X				ElevFF_CalculateVelocityOnly.vi					
			X					ElevFF_Execute.vi		LabVIEW style single call			
			X					ElevFF_ExecuteVelocityOnly.vi		LabVIEW style single call			
	X	X		X				ElevFF_MaxAchieveAccel.vi					
	X	X		X				ElevFF_MaxAchieveVelocity.vi					
	X	X		X				ElevFF_MinAchieveAccel.vi					
	X	X		X				ElevFF_MinAchieveVelocity.vi					
	X	X		X				ElevFF_New_ZeroAccel.vi					
	X	X		X				ElevFF_New.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
HOL_DRV_CTRL	X	X	X	X				HolDrvCtrl_AdvCalculate_Trajectory.vi		Added 1/24/2022			
	X	X	X	X				HolDrvCtrl_AdvCalculate.vi		Added 1/24/2022			
	X	X		X	SI			HolDrvCtrl_AtReference.vi		Added 1/26/21			
	X	X		X	I			HolDrvCtrl_Calculate_Trajectory.vi		Added 1/26/21			
	X	X		X	I			HolDrvCtrl_Calculate.vi		Added 1/26/21			
	X	X	X	X				HolDrvCtrl_Execute_Trajectory.vi		Added 1/24/2022			
	X	X	X	X				HolDrvCtrl_Execute.vi		Future			
	X	X		X	SI			HolDrvCtrl_New.vi		Added 1/26/21			
	X	X	X	X	SI			HolDrvCtrl_PackExecuteSP.vi					
	X	X	X	X				HolDrvCtrl_PackPID.vi		Added 1/24/2022			
	X	X	X	X				HolDrvCtrl_PackProfPID.vi		Added 1/24/2022			
	X	X		X	SI			HolDrvCtrl_SetEnabled.vi		Added 1/26/21			
	X	X		X	SI			HolDrvCtrl_SetTolerance.vi		Added 1/26/21			

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
PID CONTROLLER	X	X	X	X				PIDController_AdvCalculate_FF_Sp_Pv_Per.vi		Advanced PID			
	X	X	X	X				PIDController_AdvCalculate_FF_Sp_Pv.vi		Advanced PID			
	X	X	X	X			X	PIDController_AdvExecute.vi		Labview style helper. Advanced PID			
	X	X		X	SI			PIDController_AtSetpoint.vi					
	X	X		X				PIDController_Calculate_PV.vi					
	X	X		X				PIDController_Calculate_SP_PV.vi					
	X	X		X	SI			PIDController_DisableContinousInput.vi					
	X	X		X	SI			PIDController_EnableContinousInput.vi					
	X	X	X	X			X	PIDController_Execute.vi		Labview style helper			
								PIDController_GetContinuousError.vi		OBSOLETE – Removed			
	X	X		X	SI			PIDController_GetPeriod.vi					
	X	X		X	SI			PIDController_GetPID.vi					
	X	X		X	SI			PIDController_GetPositionError.vi					
	X	X		X	SI			PIDController_GetSetpoint.vi					
	X	X		X	SI			PIDController_GetVelocityError.vi					
	X	X		X	SI			PIDController_IsContinuousInputEnabled.vi					
	X	X		X	I			PIDController_New.vi					
	X	X		X	I			PIDController_NewPeriod.vi					

	X	X	X	X	SI			PIDController_Pack_AdvLimits.vi					
	X	X	X	X	SI			PIDController_Pack_AdvTuning.vi					
	X	X	X	X	SI			PIDController_Pack_ErrorTolerance.vi					
	X	X	X	X	SI			PIDController_Pack_InputLimits.vi					
	X	X	X	X	SI			PIDController_Pack_Tuning.vi					
	X	X		X	SI			PIDController_Reset.vi					
	X	X		X	SI			PIDController_SetD.vi					
	X	X	X	X	SI			PIDController_SetDerivativeFilter.vi		Advanced PID			
	X	X	X	No				PIDController_SetFeedForward_OBSOLETE_DELETE.vi		Advanced PID, Obsolete – DELETE			
	X	X	X	No				PIDController_SetFFGain_OBSOLETE_DELETE.vi		Advanced PID, Obsolete – DELETE			
	X	X		X	SI			PIDController_SetI.vi					
								PIDController_SetInputRange.vi		OBSOLETE – Removed			
	X	X		X	SI			PIDController_SetIntegratorRange.vi					
	X	X	X	X	SI			PIDController_SetOutputLimits.vi		Advanced PID			
	X	X		X	SI			PIDController_SetP.vi					
	X	X	X	X	SI			PIDController_SetPeriod.vi					
	X	X		X	SI			PIDController_SetPID.vi					
	X	X	X	X	SI			PIDController_SetPIDF.vi		Advanced PID			
	X	X		X	SI			PIDController_SetSetpoint.vi					
	X	X		X	SI			PIDController_SetTolerance.vi					
	X	X		X	SI			PIDController_SetTolerancePandV.vi					

	Implemented	*Documented*	*Not WPILIB*	*Menu Item*	*Execution Optimized*	*Test Routine*	*Sample Program*	VI Name	Function Prototype	Notes	*Code Review*	*Test Program*	*Error Checking*
PROFILED PID CONTROLLER	X	X		X	SI			ProfiledPIDController_AtGoal.vi					
	X	X		X	SI			ProfiledPIDController_AtSetpoint.vi					
	X	X		X				ProfiledPIDController_Calculate_Meas_Goal.vi					
	X	X		X				ProfiledPIDController_Calculate_Meas_StateGoal_TrapCnsrt.vi					
	X	X		X				ProfiledPIDController_Calculate_Meas_StateGoal.vi					
	X	X		X				ProfiledPIDController_Calculate_Meas.vi					
	X	X		X	SI			ProfiledPIDController_DisableContInput.vi					
	X	X		X	SI			ProfiledPIDController_EnableContInput.vi					
	X	X	X	X	I			ProfiledPIDController_Execute.vi		Single call LabVIEW style function.			
	X	X		X	SI			ProfiledPIDController_GetGoal.vi					
	X	X		X	SI			ProfiledPIDController_GetPeriod.vi					
	X	X	X	X	SI			ProfiledPIDController_GetPID.vi		WPILIB has separate getters.			
	X	X		X	SI			ProfiledPIDController_GetPositionError.vi					
	X	X		X	SI			ProfiledPIDController_GetSetpoint.vi					
	X	X		X	SI			ProfiledPIDController_GetVelocityError.vi					
	X	X		X	I			ProfiledPIDController_New.vi					
	X	X		X	I			ProfiledPIDController_NewPeriod.vi					
	X	X		X	SI			ProfiledPIDController_Reset_PosOnly.vi					
	X	X		X	SI			ProfiledPIDController_Reset_PosVel.vi					
	X	X		X	SI			ProfiledPIDController_Reset.vi					
	X	X		X	SI			ProfiledPIDController_SetConstraints.vi					
	X	X		X	SI			ProfiledPIDController_SetGoal_PosOnly.vi					
	X	X		X	SI			ProfiledPIDController_SetGoal.vi					
	X	X		X	SI			ProfiledPIDController_SetIntegratorRange.vi					
	X	X		X	SI			ProfiledPIDController_SetPID.vi					
	X	X		X	SI			ProfiledPIDController_SetTolerance_PosOnly.vi					
	X	X		X	SI			ProfiledPIDController_SetTolerance_PosVel.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
RAMSETE	X	X		X	SI			Ramsete_AtReference.vi	AtReference				
	X	X		X	X			Ramsete_Calculate_Trajectory.vi	calculate_trajectory				
	X	X		X	X			Ramsete_Calculate.vi	calculate				
	X	X	X	X	X			Ramsete_Diff_DO_Eng.vi					
	X	X	X	X	X			Ramsete_Diff_DO_SI.vi					
	X	X	X	X	I			Ramsete_Execute_ENG.vi	Use this one!!				
	X	X	X	X	SI			Ramsete_Execute_PackTuning_ENG.vi					
	X	X	X	X	SI			Ramsete_Execute_PackTuning.vi					
	X	X	X	X	I			Ramsete_Execute.vi					
	X	X		X	SI			Ramsete_New_B_Z.vi	new(b, zeta)				
	X	X		X	SI			Ramsete_New.vi	new				
	X	X		X	SI			Ramsete_SetEnabled.vi	SetEnabled				
	X	X		X	SI			Ramsete_SetTolerance.vi	SetTolerance				
	X	X		X	X			Ramsete_SINC.vi	sinc	internal			

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
SIMPLE MOTOR FEEDFORWARD	X	X	X	X	SI			SimpleMotorFF_Calculate_CalcAccel.vi					
	X	X		X				SimpleMotorFF_Calculate_NextV_Dt.vi					
	X	X		X	SI			SimpleMotorFF_Calculate.vi	public double calculate(double velocity, double acceleration)				
	X	X		X	SI			SimpleMotorFF_CalculateVelocityOnly.vi	public double calculate(double velocity)				
	X	X		X	X			SimpleMotorFF_MaxAchieveAccel.vi	public double maxAchievableAcceleration(double maxVoltage, double velocity)				
	X	X		X	X			SimpleMotorFF_MaxAchieveVel.vi	public double maxAchievableVelocity(double maxVoltage, double acceleration)				
	X	X		X	X			SimpleMotorFF_MinAchieveAccel.vi	public double minAchievableAcceleration(double maxVoltage, double velocity)				
	X	X		X	X			SimpleMotorFF_MinAchieveVel.vi	public double minAchievableVelocity(double maxVoltage, double acceleration)				
	X	X		X	SI			SimpleMotorFF_New.vi	public SimpleMotorFeedforward(double ks, double kv, double ka)				
									public SimpleMotorFeedforward(double ks, double kv)				

'============
GEOMETRY
'============

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
POSE2D	X	X		X	SI			Pose2d_Equals.VI	boolean equals(other obj)				
	X	X		X	X			Pose2d_Exp.vi	pose2d exp(twist2d twist)				
	X	X		X	SI			Pose2d_getRotation.vi	rotation2d getRotation()	can also use cluster unpack			
	X	X		X	SI			Pose2d_getTranslation.vi	translation2d getTranslation()	can also use cluster unpack			
	X	X	X	X	SI			Pose2d_getXY.vi					
	X	X	X	X	SI			Pose2d_getXYAngle.vi					
	X	X		X	I			Pose2d_Interpolate.vi					
	X	X		X	X			Pose2d_Log.vi	twist2d log(pose2d end)				
	X	X		X	SI			Pose2d_Minus.vi	transform2d minus(pose2d other)				
	X	X		X	SI			Pose2d_New_TRRO.vi	pose2d new(translation2d, rotation2d)				
	X	X		X	SI			Pose2d_New.vi	pose2d new(double x, double y, rotation2d)				

	X	X		X	SI			Pose2d_Plus.vi	pose2d plus(transform2d other)				
	X	X		X	SI			Pose2d_RelativeTo.vi	pose2d relativeto(pose2d other)				
	X	X		X	SI			Pose2d_TransformBy.vi	pose2d transformby(transform2d other)				
									pose2d new( )	can use cluster constant			

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
ROTATION2D	X	X		X	SI			Rotation2d_CreateAngle.vi	rotation2d new(double value)				
	X	X		X	SI			Rotation2d_CreateAngleDegrees.vi	rotation2d fromDegrees(double degrees)	convert to radians then create			
	X	X		X	SI			Rotation2d_CreateAngleRotations.vi					
	X	X		X	SI			Rotation2d_CreateXY.vi	rotation2d new(double x, double y)				
	X	X		X	SI			Rotation2d_Equals.vi	boolean equals(rotation2d other)				
	X	X	X	X	SI			Rotation2d_GetAngleCosSin.vi		New 1/26/21			
	X	X		X	SI			Rotation2d_GetCos.VI	double getCos()	use cluster unpack			
	X	X		X	SI			Rotation2d_GetDegrees.VI	double getDegrees()	use cluster unpack, then convert to degree			
	X	X		X	SI			Rotation2d_GetRadians.VI	double getRadians()	use cluster unpack			
	X	X		X	SI			Rotation2d_GetRotations.vi					
	X	X		X	SI			Rotation2d_GetSin.VI	double getSin()	use cluster unpack			
	X	X		X	SI			Rotation2d_GetTan.VI	double getTan()	can calculate			
	X	X		X	SI			Rotation2d_Interpolate.vi					
	X	X		X	SI			Rotation2d_Minus.vi	rotation2d minus(rotation2d other)				
	X	X		X	SI			Rotation2d_Plus.vi	rotation2d plus(rotation2d other)				
	X	X		X	SI			Rotation2d_RotateBy.vi	rotation2d rotateby(rotation2d other)				
	X	X		X	SI			Rotation2d_Times.vi	rotation2d times(double scalar)				
	X	X		X	SI			Rotation2d_UnaryMinus.vi	rotation2d unaryminus( )				
									rotation2d new()	can use cluster constant			

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
TRANSFORM2D	X	X		X	SI			Transform2d_Create_PosePose.vi	transform2d new(pose2d, pose2d)				
	X	X		X	SI			Transform2d_Create_TransRot.vi	transform2d new(translation2d, rotation2d)				
	X	X		X	SI			Transform2d_Equals.VI	boolean equals(other transform2d)				
	X	X		X	SI			Transform2d_GetRotation.VI	rotation2d getRotation()	use cluster unpack			
	X	X		X	SI			Transform2d_GetTranslation.VI	translation2d getTranslation()	use cluster unpack			
	X	X	X	X	SI			Transform2d_GetXY.vi					
	X	X	X	X	SI			Transform2d_GetXYAngle.vi					
	X	X		X	SI			Transform2d_Inverse.vi	transform inverse()	new			
	X	X		X	Si			Transform2d_Plus.vi					
	X	X		X	SI			Transform2d_Times.vi	transform2d times(double scalar)				
									transform2d new( )	can use cluster constant			

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
TRANSLATION2D	X	X		X	SI			Translation2d_Create_DistAng.vi					
	X	X		X	SI			Translation2d_Create.vi	translation2d new(double x, double y)				
	X	X		X	SI			Translation2d_Equals.vi	boolean equals(translation other)				
	X	X		X	SI			Translation2d_GetDistance.vi	double getDistance(translation2d other)				
	X	X		X	SI			Translation2d_GetNorm.VI	double getNorm()	can use cluster unpack			
	X	X		X	SI			Translation2d_GetX.VI	double getX()	can use cluster unpack			
	X	X	X	X	SI			Translation2d_GetXY.VI					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
	X	X		X	SI			Translation2d_GetY.VI	double getY()	can use cluster unpack			
	X	X		X	SI			Translation2d_Interpolate.vi					
	X	X		X	SI			Translation2d_Minus.vi	translation2d minus(translation2d other)				
	X	X		X	SI			Translation2d_Plus.vi	translation2d plus(translation2d other)				
	X	X		X	SI			Translation2d_RotateBy.vi	translation2d rotateBy(rotation2d other)				
	X	X		X	SI			Translation2d_Times.vi	translation2d times(double scalar)				
	X	X		X	SI			Translation2d_UnaryMinus.vi	translation2d unaryminus( )				
									translation2d new()	can use cluster constant			
									translation2d div(double scalar)	can multiply by 1/scalar			

TWIST2D	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
	X	X		X	SI			Twist2d_Create.vi	twist new(x, y, theta)				
	X	X		X	SI			Twist2d_Equals.VI	boolean equals(obj other)				
	X	X	X	X	SI			Twist2d_GetAll.VI					

'============
KINEMATICS
'============

CHASSIS SPEEDS	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
	X	X		X	SI			ChassisSpeeds_FromFieldRelativeSpeeds.VI	chassisspeeds fromFieldRelativeSpeeds(double x, double y, double angvel, rotation2d robotangle)				
	X	X	X	X	SI			ChassisSPeeds_GetXYOmega.vi					
	X	X		X	SI			ChassisSpeeds_New.vi	chassisspeeds new (double xvel, double yvel, double angvel)				
									chassisspeeds new ()	can use cluster constant			

DIFFERENTIAL DRIVE KINEMATICS	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
	X	X		X	I	X		DiffKinematics_New.vi	diffDriveKine new(double trackWidth)				
	X	X		X	X	X		DiffKinematics_toChassisSpeed.vi	chassisSpeeds toChassisSpeeds(diffDrWheelSpeeds)				
	X	X		X	SI	X		DiffKinematics_toWheelSpeed.vi	diffDriveWheelSpeed toWheelSpeeds(chassisSpeeds)				

DIFFERENTIAL DRIVE ODOMETRY	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
			X					DiffOdometry_Execute.vi		DONT NEED			
	X	X		X	X			DiffOdometry_Update.vi	pose2d update(rotation2d gyro, double leftdist, double right dist)	Incorporates enhanced reset			
									diffDrOdom new(rotation gyro, pose initial)				
									diffDrOdom new(rotation gyro)				
									void resetPosition(pose2d, rotation2d)	incorporated into “update”			
									pose2d getPoseMeters()				

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
DIFFERENTIAL DRIVE WHEEL SPEEDS									diffDrWheelSpeeds new()				
									diffDrWheelSpeeds new(double leftVel, double rightVel)				
	X	X		X	X			DiffWheel_Normalize.vi	void normalize(double maxVel)				

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
MECANUM DRIVE KINEMATICS	X	X		X	I			MecaKinematics_New.vi					
	X	X		X	X			MecaKinematics_SetInverseKinematics.vi					
	X	X		X	X			MecaKinematics_ToChassisSpeeds.vi					
	X	X		X	X			MecaKinematics_ToWheelSpeeds.vi					
	X	X		X	X			MecaKinematics_ToWheelSpeedsZeroCenter.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
MECANUM DRIVE MOTOR VOLTAGE													

nothing done

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
MECANUM DRIVE ODOMETRY			X					MecaOdometry_Execute.vi					
	X	X		X				MecaOdometry_GetPose.vi					
	X	X		X				MecaOdometry_New.vi					
	X	X		X				MecaOdometry_NewDefaultPose.vi					
	X	X		X				MecaOdometry_Reset.VI					
	X	X		X				MecaOdometry_Update.vi					
	X	X		X				MecaOdometry_UpdateWithTime.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
MECANUM DRIVE WHEEL SPEEDS	X	X		X	SI			MecaWheel_New.Vi	public MecanumDriveWheelSpeeds(double frontLeftMetersPerSecond, double frontRightMetersPerSecond, double rearLeftMetersPerSecond, double rearRightMetersPerSecond)				
	X	X		X	X			MecaWheel_Normalize.vi	public void normalize(double attainableMaxSpeedMetersPerSecond)				

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
SWERVE DRIVE KINEMATICS	X	X	X	X				SwerveKinematics_New4.VI		For 4 module drives			
	X	X	X	X				SwerveKinematics_NewX.VI		uses array as input			
	X	X	X	X				SwerveKinematics_NormalizeWheelSpeeds.vi	public static void normalizeWheelSpeeds(SwerveModuleState[] moduleStates, double attainableMaxSpeedMetersPerSecond)				
	X	X	X	X				SwerveKinematics_ToChassisSpeeds4.VI		For 4 module drives			
	X	X	X	X				SwerveKinematics_ToChassisSpeedsX.VI		uses array as input			
	X	X		X				SwerveKinematics_ToSwerveModuleStates.VI	public SwerveModuleState[] toSwerveModuleStates(ChassisSpeeds chassisSpeeds, Translation2d centerOfRotationMeters)				
	X	X		X				SwerveKinematics_ToSwerveModuleStatesZeroCenter.VI	public SwerveModuleState[] toSwerveModuleStates(ChassisSpeeds chassisSpeeds)				
									public SwerveDriveKinematics(Translation2d... wheelsMeters)	variable parameters (replace with array and “4” calls)			
									public ChassisSpeeds toChassisSpeeds(SwerveModuleState... wheelStates)	variable parameters (replace with array and “4” calls)			

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
SWERVE DRIVE ODOMETRY								SwerveOdometry_Execute4.vi					
								SwerveOdometry_ExecuteX.vi					
	X	X		X				SwerveOdometry_GetPosition.VI	public Pose2d getPoseMeters()				
	X	X		X				SwerveOdometry_New.VI	public SwerveDriveOdometry(SwerveDriveKinematics kinematics, Rotation2d gyroAngle, Pose2d initialPose)				
	X	X		X				SwerveOdometry_NewZeroCenter.VI	public SwerveDriveOdometry(SwerveDriveKinematics kinematics, Rotation2d gyroAngle)				
	X	X		X				SwerveOdometry_ResetPosition.VI	public void resetPosition(Pose2d pose, Rotation2d gyroAngle)				
	X	X	X	X				SwerveOdometry_Update4.VI		For 4 module drives			
	X	X	X	X				SwerveOdometry_UpdateWithTime4.VI		For 4 module drives			
	X	X	X	X				SwerveOdometry_UpdateWithTimeX.VI		uses array as input			
	X	X	X	X				SwerveOdometry_UpdateX.VI		uses array as input			
									public Pose2d updateWithTime(double currentTimeSeconds, Rotation2d gyroAngle, SwerveModuleState... moduleStates)	variable parameters (replace with array and “4” calls)			
									public Pose2d update(Rotation2d gyroAngle, SwerveModuleState... moduleStates)	variable parameters (replace with array and “4” calls)			

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
SWERVE DRIVE MODULE STATE	X	X		X	SI			SwerveModuleState_CompareTo.vi	public int compareTo(SwerveModuleState o)				
				X	SI			SwerveModuleState_Get.vi					
	X	X		X	SI			SwerveModuleState_New.vi	public SwerveModuleState(double speedMetersPerSecond, Rotation2d angle)				
	X	X		X	SI			SwerveModuleState_Optimize.vi	public SwerveModuleState optimize(SwerveModuleState desired, Rotation2d angle)				

'============
SPLINE
'============

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
CUBIC HERMITE SPLINE									protected SimpleMatrix getCoefficients()	not needed, use cluster unpack			
	X	X		X				CubicHermiteSpline_getControlVectorFromArrays.vi	private SimpleMatrix getControlVectorFromArrays(double[] initialVector, double[] finalVector)				
	X	X		X				CubicHermiteSpline_makeHermiteBasis.vi	private SimpleMatrix makeHermiteBasis()				
	X	X		X				CubicHermiteSpline_New.vi	public CubicHermiteSpline(double[] xInitialControlVector, double[] xFinalControlVector, double[] yInitialControlVector, double[] yFinalControlVector)				

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
POSE WITH CURVATURE	X	X		X	S/			PoseWithCurve_New.vi	public PoseWithCurvature(Pose2d poseMeters, double curvatureRadPerMeter)				
									public PoseWithCurvature()	can use cluster constant			
									public Pose2d poseMeters	not needed, use cluster unpack			
									public double curvatureRadPerMeter..	not needed, use cluster unpack			

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
QUINTIC HERMITE SPLINE	X	X		X				QuinticHermiteSpline_getControlVectorFromArrays.vi	private SimpleMatrix getControlVectorFromArrays(double[] initialVector, double[] finalVector)				
	X	X		X				QuinticHermiteSpline_makeHermiteBasis.vi	private SimpleMatrix makeHermiteBasis()				
	X	X		X				QuinticHermiteSpline_New.vi	public QuinticHermiteSpline(double[] xInitialControlVector, double[] xFinalControlVector, double[] yInitialControlVector, double[] yFinalControlVector)				
									protected SimpleMatrix getCoefficients()	not needed, use cluster unpack			

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
SPLINE (Abstract class)	X	X		X				Spline_getPoint.vi	public PoseWithCurvature getPoint(double t)				
									Spline(int degree)				
									public static class ControlVector				
									public ControlVector(double[] x, double[] y)	implemented as data structure			

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
SPLINE HELPER	X	X		X	S/			SplineHelp_GetCubicCtrlVector.vi	private static Spline.ControlVector getCubicControlVector(double scalar, Pose2d point)				

	X	X		X		X		SplineHelp_GetCubicCtrlVectorsFromWayPts.vi	public static Spline.ControlVector[] getCubicControlVectorsFromWaypoints(Pose2d start, Translation2d[] interiorWaypoints, Pose2d end)				
	X	X	X	X				SplineHelp_GetCubicCtrlVectorsFromWeightedWayPts.vi					
	X	X	X	No				SplineHelp_GetCubicSpline_Calc1.vi		internal			
	X	X	X	No				SplineHelp_GetCubicSpline_Calc2.vi		internal			
	X	X	X	No				SplineHelp_GetCubicSpline_Calc3.vi		internal			
	X	X		X		X		SplineHelp_getCubicSplinesFromControlVectors.vi	public static CubicHermiteSpline[] getCubicSplinesFromControlVectors(Spline.ControlVector start, Translation2d[] waypoints, Spline.ControlVector end)				
	X	X		X	SI			SplineHelp_GetQuinticCtrlVector.vi	private static Spline.ControlVector getQuinticControlVector(double scalar, Pose2d point)				
								SplineHelp_GetQuinticCtrlVectorsFromWayPts.vi	public static List<Spline.ControlVector> getQuinticControlVectorsFromWaypoints(List<Pose2d> waypoints)	REMOVED 2762			
								SplineHelp_GetQuinticCtrlVectorsFromWeightedWayPts.vi		REMOVED 2762			
	X	X		X				SplineHelp_getQuinticSplinesFromControlVectors.vi	public static QuinticHermiteSpline[] getQuinticSplinesFromControlVectors(Spline.ControlVector[] controlVectors)				
	X	X	X	X				SplineHelp_GetQuinticSplinesFromWeightedWayPts.vi		New 2762			
	X	X		X				SplineHelp_GetQuinticSplinesFromWayPts.vi		New 2762			
	X	X		No				SplineHelp_ThomasAlgorithm.vi	private static void thomasAlgorithm(double[] a, double[] b, double[] c, double[] d, double[] solutionVector)	internal			

	Implemented	*Documented*	*Not WPILIB*	*Menu Item*	*Execution Optimized*	*Test Routine*	*Sample Program*	VI Name	Function Prototype	Notes	*Code Review*	*Test Program*	*Error Checking*
SPLINE PARAMETERIZER	X	X		X				SplineParam_Spline_T0_T1.vi	public static List<PoseWithCurvature> parameterize(Spline spline, double t0, double t1)				
	X	X		X		X		SplineParam_Spline.vi	public static List<PoseWithCurvature> parameterize(Spline spline)				
	X	X	X	No				SplineParam_StackGet.vi		internal			
	X	X	X	No				SplineParam_StackPop.vi		internal			
	X	X	X	No				SplineParam_StackPush.vi		internal			

'============
TRAJECTORY
'============

	Implemented	*Documented*	*Not WPILIB*	*Menu Item*	*Execution Optimized*	*Test Routine*	*Sample Program*	VI Name	Function Prototype	Notes	*Code Review*	*Test Program*	*Error Checking*
TRAJECTORY	X	X		X				Trajectory_Concatenate.vi					
	X	X		X				Trajectory_equals.vi	boolean equals(other obj)	FUTURE			
	X	X		X	SI			Trajectory_GetStates.vi	public List<State> getStates()	not needed, use unpack			
	X	X		X	SI			Trajectory_GetTotalTime.vi	public double getTotalTimeSeconds()	not needed, use unpack			
	X	X		No	SI			Trajectory_lerp_double.vi	private static double lerp(double startValue, double endValue, double t)	internal			
	X	X		No	SI			Trajectory_lerp_Pose.vi	private static Pose2d lerp(Pose2d startValue, Pose2d endValue, double t)	internal			
	X	X		X	SI			Trajectory_New_Empty.vi					
	X	X		X	SI			Trajectory_New.vi	public Trajectory(final List<State> states)				
	X	X		X				Trajectory_RelativeTo.vi	public Trajectory relativeTo(Pose2d pose)				
	X	X		X				Trajectory_Sample.vi	public State sample(double timeSeconds)				
	X	X	X	X				Trajectory_SampleReverse.vi		Sample in reverse order. Negate sample.			
	X	X		X				Trajectory_TransformBy.vi	public Trajectory transformBy(Transform2d transform)				
									public Pose2d getInitialPose()	can use cluster unpack, array index			

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
TRAJECTORY_STATE	X	X		X	SI			TrajectoryState_Equals.vi	boolean equals(other obj)				
	X	X	X	X	SI			TrajectoryState_GetAll.vi					
	X	X		X	SI			TrajectoryState_GetPose.vi					
	X	X		X				TrajectoryState_Interpolate.vi	State interpolate(State endValue, double i)				
	X	X		X	SI			TrajectoryState_New.vi	public State(double timeSeconds, double velocityMetersPerSecond, double accelerationMetersPerSecondSq, Pose2d poseMeters, double curvatureRadPerMeter)				
									public State()				

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
TRAJECTORY CONFIG	X	X		X	SI			TrajectoryConfig_Create.vi	public TrajectoryConfig(double maxVelocityMetersPerSecond, double maxAccelerationMetersPerSecondSq)				
	X	X	X	X	SI			TrajectoryConfig_setCentripetalAccel.vi					
	X	X		X	SI			TrajectoryConfig_setKinematicsDiffDrive.vi	public TrajectoryConfig setKinematics(DifferentialDriveKinematics kinematics)				
	X	X		X	SI			TrajectoryConfig_setKinematicsMecanumfDrive.vi	public TrajectoryConfig setKinematics(MecanumDriveKinematics kinematics)				
	X	X		X	SI			TrajectoryConfig_setKinematicsSwerveDrive.vi	public TrajectoryConfig setKinematics(SwerveDriveKinematics kinematics)				
	X	X		X	SI			TrajectoryConfig_setReversed.vi	public TrajectoryConfig setReversed(boolean reversed)				
	X	X	X	X	SI			TrajectoryConfig_setVoltageDiffDrive.vi					
									public TrajectoryConfig addConstraint(TrajectoryConstraint constraint)	Implemented differently, can't duplicate.			
									public TrajectoryConfig addConstraints(List<? extends TrajectoryConstraint> constraints)	Implemented differently, can't duplicate.			
									public double getStartVelocity()	can use cluster unpack			
									public TrajectoryConfig setStartVelocity(double startVelocityMetersPerSecond)				
									public double getEndVelocity()	can use cluster unpack			
									public TrajectoryConfig setEndVelocity(double endVelocityMetersPerSecond)				
									public double getMaxVelocity()	can use cluster unpack			
									public double getMaxAcceleration()	can use cluster unpack			
									public List<TrajectoryConstraint> getConstraints()	Implemented differently, can't duplicate.			
									public boolean isReversed()	can use cluster unpack			
									NOTE ADD OTHER "SET" ROUTINES FOR OTHER CONTRAINTS HERE, SINCE NEW CONTRAINTS ARE SPECIFIC AND NOT GENERIC.				

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
TRAJECTORY GENERATE	X	X		X				TrajectoryGenerate_Make_Cubic_CtrlVect.vi	public static Trajectory generateTrajectory(Spline.ControlVector initial, List<Translation2d> interiorWaypoints, Spline.ControlVector end, TrajectoryConfig config)	uses cubic splines			
	X	X		X				TrajectoryGenerate_Make_Cubic.vi	public static Trajectory generateTrajectory(Pose2d start, List<Translation2d> interiorWaypoints, Pose2d end, TrajectoryConfig config)	uses cubic splines			
	X	X	X	X				TrajectoryGenerate_Make_Generic.vi	Helper to bring these all together….	Use this one!!!			

	X	X		X				TrajectoryGenerate_Make_Quintic_CtrlVect.vi	public static Trajectory generateTrajectory(ControlVectorList controlVectors, TrajectoryConfig config)	uses quintic splines			
	X	X	X	X				TrajectoryGenerate_Make_Quintic_Weighted.vi		New 2762			
	X	X		X				TrajectoryGenerate_Make_Quintic.vi	public static Trajectory generateTrajectory(List<Pose2d> waypoints, TrajectoryConfig config)	uses quintic splines			
	X	X		X				TrajectoryGenerate_splinePointsFromSplines.vi	public static List<PoseWithCurvature> splinePointsFromSplines(Spline[] splines)				

	Implemented	*Documented*	*Not WPILIB*	*Menu Item*	*Execution Optimized*	*Test Routine*	*Sample Program*	VI Name	Function Prototype	Notes	*Code Review*	*Test Program*	*Error Checking*
TRAJECTORY GENERATE (Control Vector)									public ControlVectorList(int initialCapacity)	may not need, just data			
									public ControlVectorList()	may not need, just data			
									public ControlVectorList(Collection<? extends Spline.ControlVector> collection)	may not need, just data			

	Implemented	*Documented*	*Not WPILIB*	*Menu Item*	*Execution Optimized*	*Test Routine*	*Sample Program*	VI Name	Function Prototype	Notes	*Code Review*	*Test Program*	*Error Checking*
TRAJECTORY PARAMETERIZE	X	X	X	*No*				TrajectoryParam_calcStuffFwd.vi					
	X	X	X	*No*				TrajectoryParam_calcStuffRev.vi					
	X	X		*No*				TrajectoryParam_enforceAccel.vi	private static void enforceAccelerationLimits(boolean reverse, List<TrajectoryConstraint> constraints, ConstrainedState state)	This routines needs to be changed when new constraints are added.			
	X	X	X	*No*				TrajectoryParam_enforceVelocity.vi		This routines needs to be changed when new constraints are added.			
	X	X		X				TrajectoryParam_timeParam.vi	public static Trajectory timeParameterizeTrajectory(List<PoseWithCurvature> points. List<TrajectoryConstraint> constraints, double startVelocityMetersPerSecond, double endVelocityMetersPerSecond, double maxVelocityMetersPerSecond, double maxAccelerationMetersPerSecondSq, boolean reversed)				

	Implemented	*Documented*	*Not WPILIB*	*Menu Item*	*Execution Optimized*	*Test Routine*	*Sample Program*	VI Name	Function Prototype	Notes	*Code Review*	*Test Program*	*Error Checking*
TRAJECTORY PARAMETERIZE CONSTRAINED STATE	X	X		X				ConstrainedState_New.vi	ConstrainedState(PoseWithCurvature pose, double distanceMeters, double maxVelocityMetersPerSecond, double minAccelerationMetersPerSecondSq, double maxAccelerationMetersPerSecondSq)				
	X	X	X	X				ConstrainedState_SetMaxAccel.vi					
	X	X	X	X				ConstrainedState_SetMinAccel.vi					
	X	X	X	X				ConstrainedState_SetVelAccel.vi					
	X	X	X	X				ConstrainedState_SetVelocity.vi					
									ConstrainedState()				

	Implemented	*Documented*	*Not WPILIB*	*Menu Item*	*Execution Optimized*	*Test Routine*	*Sample Program*	VI Name	Function Prototype	Notes	*Code Review*	*Test Program*	*Error Checking*
TRAJECTORY UTIL	X	X		X				TrajectoryUtil_fromPathWeaverJSON.vi	public static Trajectory fromPathweaverJson(Path path)				
	X	X	X	X	X			TrajectoryUtil_MakeWeightedWayPoint_ENG.vi					

	X	X	X	X	X			TrajectoryUtil_MakeWeightedWayPoint.vi				
	X	X		X				TrajectoryUtil_toPathWeaverJSON.vi	public static void toPathweaverJson(Trajectory trajectory, Path path)			
									public static Trajectory deserializeTrajectory(String json)			
									public static String serializeTrajectory(Trajectory trajectory)			

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes
TRAPEZOID PROFILE	X	X		X				TrapProfConstraint_New.vi		
	X	X		X				TrapProfile_Calculate.vi		
	X	X		No				TrapProfile_Direct.vi		Private, remove from menu
	X	X	X	X				TrapProfile_Execute.vi		
	X	X	X	X	SI			TrapProfile_Execute_AtGoal.vi		
	X	X		X				TrapProfile_IsFinished.vi		
	X	X		X				TrapProfile_New_DefInitial.vi		
	X	X		X				TrapProfile_New.vi		
	X	X		No				TrapProfile_ShouldFlipAcceleration.vi		Private, remove from menu
	X	X		X				TrapProfile_TimeLeftUntil.vi		
	X	X		X				TrapProfile_TotalTime.vi		
	X	X		X				TrapProfState_Equals.vi		
	X	X		X				TrapProfState_New.vi		

'============
TRAJECTORY CONSTRAINT
'============

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes
CENTRIPETAL ACCELERATION CONSTRAINT	X	X		X				CentripetalAccelConstraint_getMaxVelocity.vi	public double getMaxVelocityMetersPerSecond(Pose2d poseMeters, double curvatureRadPerMeter, double velocityMetersPerSecond)	
	X	X		X				CentripetalAccelConstraint_getMinMaxAccel.vi	public MinMax getMinMaxAccelerationMetersPerSecondSq(Pose2d poseMeters, double curvatureRadPerMeter, double velocityMetersPerSecond)	
	X	X		X	SI			CentripetalAccelConstraint_New.vi	public CentripetalAccelerationConstraint(double maxCentripetalAccelerationMetersPerSecondSq)	Can use cluster pack for now

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes
DIFF DRIVE KINEMATIC CONSTRAINT	X	X		X				DiffDriveKinematicsConstraint_getMaxVelocity.vi	public double getMaxVelocityMetersPerSecond(Pose2d poseMeters, double curvatureRadPerMeter, double velocityMetersPerSecond)	
	X	X		X				DiffDriveKinematicsConstraint_getMinMaxAccel.vi	public MinMax getMinMaxAccelerationMetersPerSecondSq(Pose2d poseMeters, double curvatureRadPerMeter, double velocityMetersPerSecond)	
	X	X		X	SI			DiffDriveKinematicsConstraint_New.vi	public DifferentialDriveKinematicsConstraint(final DifferentialDriveKinematics kinematics, double maxSpeedMetersPerSecond)	

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes
DIFF DRIVE VOLTAGE CONSTRAINT	X	X		X				DiffDriveVoltageConstraint_getMaxVelocity.vi	public double getMaxVelocityMetersPerSecond(Pose2d poseMeters, double curvatureRadPerMeter, double velocityMetersPerSecond)	
	X	X		X				DiffDriveVoltageConstraint_getMinMaxAccel.vi	public MinMax getMinMaxAccelerationMetersPerSecondSq(Pose2d poseMeters, double curvatureRadPerMeter, double velocityMetersPerSecond)	
	X	X		X	SI			DiffDriveVoltageConstraint_New.vi	public DifferentialDriveVoltageConstraint(SimpleMotorFeedforward feedforward, DifferentialDriveKinematics kinematics, double maxVoltage)	

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes
JERK CONSTRAINT	/		X					JerkConstraint_getMaxVelocity.vi	Routine exists, it is just a shell	FUTURE
	/		X					JerkConstraint_getMinMaxAccel.vi	Routine exists, it is just a shell	FUTURE
	/		X		SI			JerkConstraint_New.vi	Routine exists, it is just a shell	FUTURE

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes
MECANUM DRIVE KINEMATICS CONSTRAINT	X	X		X				MecaDriveKinematicsConstraint_getMaxVelocity.vi		
	X	X		X				MecaDriveKinematicsConstraint_getMinMaxAccel.vi		
	X	X		X	SI			MecaDriveKinematicsConstraint_New.vi		

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes
SWERVE DRIVE KINEMATICS CONSTRAINT	X	X		X				SwerveDriveKinematicsConstraint_getMaxVelocity.vi	public double getMaxVelocityMetersPerSecond(Pose2d poseMeters, double curvatureRadPerMeter, double velocityMetersPerSecond)	
	X	X		X				SwerveDriveKinematicsConstraint_getMinMaxAccel.vi	public MinMax getMinMaxAccelerationMetersPerSecondSq(Pose2d poseMeters, double curvatureRadPerMeter, double velocityMetersPerSecond)	
	X	X		X	SI			SwerveDriveKinematicsConstraint_New.vi	Newpublic SwerveDriveKinematicsConstraint(final SwerveDriveKinematics kinematics, double maxSpeedMetersPerSecond)	Can use cluster pack for now

TRAJECTORY CONSTRAINT

Interface class - nothing done (not needed)

Revision 2.X 5/2/2022 – added implicit model follower and time interpolatable routines.

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes
TRAJECTORY CONSTRAINT (Min Max)	X	X		X	SI			Constraint_MinMax_New.vi	Constraint_MinMax_New	
	X	X		X	SI			Constraint_MinMax_NewMinMax.VI	Constraint_MinMax_New	

'============
UTILITY
'============
THESE ROUTINES ARE SPECIFIC TO LABVIEW. THEY DO NOT HAVE A
JAVA / C++ WPILIB EQUIVALENT

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes
UTIL	X	X	X	X	SI			Util_ApproxEqual.vi		
	X	X	X	X				Util_Array_PoseWCurv_to_XY.vi		
	X	X	X	X	SI			Util_CalcDist.vi		
	X	X	X	X	SI			Util_GetLibraryVersion.vi		
	X	X	X	X	SI			Util_GetLibUsage.vi		
	X	X	X	X				Util_GetTime.vi		Once tested completely, this should be optimized!
	X	X	X	No	N/A			Util_LibraryGlobals.vi		Global Variables – no block diag.
	X	X	X	X				Util_Trajectory_Absolute_To_Relative.vi		
	X	X	X	X				Util_Trajectory_ReadFile.vi		
	X	X	X	X				Util_Trajectory_to_XY.vi		
	X	X	X	No				Util_Trajectory_WriteFile_Config.vi		internal
	X	X	X	No				Util_Trajectory_WriteFile_OneState.vi		internal
	X	X	X	X				Util_Trajectory_WriteFile_PathFinder.vi		
	X	X	X	No				Util_Trajectory_WriteFile_PathFinderConfig.vi		internal
	X	X	X	X				Util_Trajectory_WriteFile_Pathweaver.vi		
	X	X	X	No				Util_Trajectory_WriteFile_States.vi		internal
	X	X	X	No				Util_Trajectory_WriteFile_WayPoints.vi		internal
	X	X	X	X				Util_Trajectory_WriteFile.vi		
	X	X	X	X				Util_TrajectoryState_Meters_To_Inches.vi		
	X	X	X	X				Util_TrajState_to_DiffDrive_WheelPos.vi		
	X	X	X	X				Util_DispWaypoint_Eng_To_SI.vi		
	X	X	X	X				Util_DispWaypoint_To_CubicInput.vi		
	X	X	X	X				Util_DispWaypoint_To_QuinticInput.vi		
	X	X	X	X				Util_DispWeightedWaypiont_Eng_To_WeightedWaypoint		
	X	X	X	No				Util_DispWeightedWayPoint_To_WeightedWayPoint.vi		Sorry about the confusing name..

'============
CONVERSIONS
'============
THESE ROUTINES ARE SPECIFIC TO LABVIEW. THEY DO NOT HAVE A
JAVA / C++ WPILIB EQUIVALENT

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes
CONV	X	X	X	X	SI			Conv_AngleDegrees_Heading.vi		
	X	X	X	X	SI			Conv_AngleRadians_Heading.vi		
	X	X	X	X	SI			Conv_Centimeters_Meters.vi		

	X	X	X	X	SI			Conv_Deg_Radians.vi		
	X	X	X	X	SI			Conv_Deg_Rotations.vi		
	X	X	X	X	SI			Conv_Feet_Meters.vi		
	X	X	X	X	SI			Conv_GyroDegrees_Heading.vi		
	X	X	X	X	SI			Conv_Heading_AngleRadians.vi		
	X	X	X	X	SI			Conv_Inches_Meters.vi		
	X	X	X	X	SI			Conv_Kilograms_Pounds.vi		
	X	X	X	X	SI			Conv_Meters_Feet.vi		
	X	X	X	X	SI			Conv_Meters_Inches.vi		
	X	X	X	X	SI			Conv_Pose2d_SI_Eng.vi		
	X	X	X	X	SI			Conv_Pounds_Kilograms.vi		
	X	X	X	X	SI			Conv_Radians_Deg.vi		
	X	X	X	X	SI			Conv_Radians_Rotations.vi		
	X	X	X	X	SI			Conv_Rotations_Deg.vi		
	X	X	X	X	SI			Conv_Rotations_Radians.vi		
	X	X	X	X	SI			Conv_Yards_Meters.vi		

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes
UNITS	X	X		X	SI			Units_DegreesToRadians.vi		
	X	X		X	SI			Units_DegreesToRotations.vi		
	X	X		X	SI			Units_FeetToMeters.vi		
	X	X		X	SI			Units_InchesToMeters.vi		
	X	X		X	SI			Units_MetersToFeet.vi		
	X	X		X	SI			Units_MetersToInches.vi		
	X	X		X	SI			Units_MillisecondsToSeconds.vi		
	X	X		X	SI			Units_RadiansPerSecondToRotationsPerMinute.vi		
	X	X		X	SI			Units_RadiansToDegrees.vi		
	X	X		X	SI			Units_RadiansToRotations.vi		
	X	X		X	SI			Units_RotationsPerMinuteToRadiansPerSecond.vi		
	X	X		X	SI			Units_RotationsToDegrees.vi		
	X	X		X	SI			Units_RotationsToRadians.vi		
	X	X		X	SI			Units_SecondsToMilliseconds.vi		

'============
PATHFINDER UTIL
'============
THESE ROUTINES ARE SPECIFIC TO LABVIEW. THEY DO NOT HAVE A
JAVA / C++ WPILIB EQUIVALENT

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes
PATHFINDERUTIL	X	X	X	X				PathfinderUtil_Continuous_Heading_Difference.vi		
	X	X	X	X				PathfinderUtil_OptimizeTrajectoryStates.vi		
	X	X	X	X				PathfinderUtil_ToTrajectory.vi		
	X	X	X	X				PathfinderUtil_ToTrajectoryStates.vi		

'============
STATE SPACE MODEL
'============

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
DC MOTOR	X	X		X	SI			DCMotor_GetAndymark9015.vi					
	X	X		X	SI			DCMotor_GetAndymarkRs775_125.vi					
	X	X		X	SI			DCMotor_GetBag.vi					
	X	X		X	SI			DCMotor_GetBanebotsRs550.vi					
	X	X		X	SI			DCMotor_GetBanebotsRs775.vi					
	X	X		X	SI			DCMotor_GetCIM.vi					
	X	X		X	SI			DCMotor_GetCurrent.vi					
	X	X		X	SI			DCMotor_GetFalcon500.vi					
	X	X		X	SI			DCMotor_GetMiniCIM.vi					
	X	X		X	SI			DCMotor_GetNEO.vi					
	X	X		X	SI			DCMotor_GetNEO550.vi					
	X	X		X	SI			DCMotor_GetRomiBuiltIn.vi					
	X	X		X	SI			DCMotor_GetVex775Pro.vi					
	X	X		X	SI			DCMotor_New.vi					
	X	X		X	SI			DCMotor_PickMotor.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
LINEAR SYSTEM ID	X	X		X				LinearSystemId_CreateDCMotorSystem.vi					
	X	X		X				LinearSystemId_CreateDriveTrainVelocitySystem.vi		Update to use create matrix			
	X	X		X				LinearSystemId_CreateElevatorSystem.vi		Update to use create matrix			
	X	X		X				LinearSystemId_CreateFlywheelSystem.vi		Update to use create matrix			
	X	X		X				LinearSystemId_CreateSingleJointedArmSystem.vi		Update to use create matrix			
	X	X		X				LinearSystemId_IdentifyDriveTrainSystem.vi		Update to use create matrix			
	X	X		X				LinearSystemId_IdentifyPositionSystem.vi		Update to use create matrix			
	X	X		X				LinearSystemId_IdentifyVelocitySystem.vi		Update to use create matrix			

'============
STATE SPACE ESTIMATION
'============

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
DIFFERENTIAL DRIVE POSE ESTIMATOR	X	X		X				DiffDrivePoseEst_AddVisionMeasurement.vi					
	X	X		X				DiffDrivePoseEst_FillStateVector.vi					
	X	X		X				DiffDrivePoseEst_GetEstimatedPosition.vi					
	X	X		X				DiffDrivePoseEst_Kalman_F_Callback.vi					
	X	X		X				DiffDrivePoseEst_Kalman_H_Callback.vi					
	X	X		X				DiffDrivePoseEst_New.vi					
	X	X		X				DiffDrivePoseEst_ResetPosition.vi					
	X	X		X				DiffDrivePoseEst_SetVisionMeasurementStdDevs.vi					
	X	X		X				DiffDrivePoseEst_Update.vi					
	X	X		X				DiffDrivePoseEst_UpdateWithTime.vi					
	X	X		X				DiffDrivePoseEst_VisionCorrect_Callback.vi					
	X	X		X				DiffDrivePoseEst_VisionCorrect_Kalman_H_Callback.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
EXTENDED KALMAN FILTER	X	X		X				ExtendedKalmanFilter_Correct_OnlyUY.vi					
	X	X		X				ExtendedKalmanFilter_Correct.vi		Just a shell, not functional!			
	X	X		X				ExtendedKalmanFilter_GetP_Single.vi					
	X	X		X				ExtendedKalmanFilter_GetP.vi					
	X	X		X				ExtendedKalmanFilter_GetXHat_Single.vi					
	X	X		X				ExtendedKalmanFilter_GetXHat.vi					
	X	X		X				ExtendedKalmanFilter_New.vi					
	X	X		X				ExtendedKalmanFilter_Predict.vi					
	X	X		X				ExtendedKalmanFilter_Reset.vi					
	X	X		X				ExtendedKalmanFilter_SetP.vi					
	X	X		X				ExtendedKalmanFilter_SetXHat_Single.vi					
	X	X		X				ExtendedKalmanFilter_SetXHat.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
KALMAN FILTER	X	X		X		X		KalmanFilter_Correct.vi					
	X	X		X				KalmanFilter_GetK					
	X	X		X				KalmanFilter_GetK_Single.vi					
	X	X		X				KalmanFilter_GetXHat					
	X	X		X		X		KalmanFilter_GetXHaT_Single					
	X	X		X		X		KalmanFilter_New.vi					
	X	X		X		X		KalmanFilter_Predict.vi					
	X	X		X				KalmanFilter_Reset.vi					
	X	X		X				KalmanFilter_SetXHat					
	X	X		X		X		KalmanFilter_SetXHat_Single					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
KALMAN FILTER LATENCY COMPENSATOR	X	X		X				KalmanFilterLatencyComp_AddObserverState.vi					
	X	X		X				KalmanFilterLatencyComp_ApplyPastGlobalMeas_FuncGroup.vi					
	X	X		X				KalmanFilterLatencyComp_ApplyPastGlobalMeasurement_UKF.vi					
	X	X		X				KalmanFilterLatencyComp_FindClosestMeasurement.vi					
	X	X		X				KalmanFilterLatencyComp_New.vi					
	X	X		X				KalmanFIlterLatencyComp_Observer_New.vi					
	X	X		X				KalmanFilterLatencyComp_Reset.vi					

Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
SWERVE DRIVE POSE ESTIMATOR								SwerveDrivePoseEst_AddVisionMeasurement_StdDev.vi					
	X	X		X				SwerveDrivePoseEst_AddVisionMeasurement.vi					
	X	X		X				SwerveDrivePoseEst_GetEstimatedPosition.vi					
	X	X		X				SwerveDrivePoseEst_Kalman_F_Callback.vi					
	X	X		X				SwerveDrivePoseEst_Kalman_H_Callback.vi					
	X	X		X				SwerveDrivePoseEst_New.vi					
	X	X		X				SwerveDrivePoseEst_ResetPosition.vi					
	X	X		X				SwerveDrivePoseEst_SetVisionMeasurementStdDevs.vi					
	X	X		X				SwerveDrivePoseEst_Update.vi					
	X	X		X				SwerveDrivePoseEst_UpdateWithTime.vi					
	X	X		X				SwerveDrivePoseEst_VisionCorrect_Callback.vi					
	X	X		X				SwerveDrivePoseEst_VisionCorrect_Kalman_H_Callback.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
UNSCENTED KALMAN FILTER	X	X		X				UnscentedKalmanFilter_Correct_FuncGroup.vi					
	X	X		X				UnscentedKalmanFilter_Correct_OnlyUY.vi					
	X	X		X				UnscentedKalmanFilter_Correct_OnlyUYR.vi					
	X	X		X				UnscentedKalmanFilter_Correct.vi					
	X	X		X				UnscentedKalmanFilter_GetP_Single.vi					
	X	X		X				UnscentedKalmanFilter_GetP.vi					
	X	X		X				UnscentedKalmanFilter_GetXHat_Single.vi					
	X	X		X				UnscentedKalmanFilter_GetXHat.vi					
	X	X		X				UnscentedKalmanFilter_New_Default.vi					
	X	X		X				UnscentedKalmanFilter_New_FuncGroup.vi					
	X	X		X				UnscentedKalmanFilter_New.vi					
	X	X		X				UnscentedKalmanFilter_Predict.vi					
	X	X		X				UnscentedKalmanFilter_Reset.vi					
	X	X		X				UnscentedKalmanFilter_SetP.vi					
	X	X		X				UnscentedKalmanFilter_SetXHat_Single.vi					
	X	X		X				UnscentedKalmanFilter_SetXHat.vi					
	X	X		X				UnscentedKalmanFilter_Transform.vi					

'============
STATE SPACE CONTROL
'============

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
CONTROL AFFINE PLANT INVERSION FEEDFORWARD													

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
DIFFERENTIAL DRIVE ACCELERATION LIMITER	X			X		X		DiffDrvAccelLimit_Calculate.vi					
	X			X		X		DiffDrvAccelLimit_New.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
IMPLICIT MODEL FOLLOWER	X			X		X		ImplModelFollow_Calculate.vi					
	X			X		X		ImplModelFollow_GetU.vi					
	X			X		X		ImplModelFollow_GetU_Single.vi					
	X			X		X		ImplModelFollow_New.vi					
	X			X		X		ImplModelFollow_New_Plant.vi					
	X			X		X		ImplModelFollow_Reset.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
LINEAR PLANT INVERSION FEEDFORWARD	X	X		X				LinearPlntInvFF_Calculate_NextR.vi					
	X	X		X				LinearPlntInvFF_Calculate.vi					
	X	X		X				LinearPlntInvFF_GetR_Single.vi					
	X	X		X				LinearPlntInvFF_GetR.vi					
	X	X		X				LinearPlntInvFF_GetUff_Single.vi					
	X	X		X				LinearPlntInvFF_GetUff.vi					
	X	X		X				LinearPlntInvFF_New_Plant.vi					
	X	X		X				LinearPlntInvFF_New.vi					
	X	X		X				LinearPlntInvFF_Reset_Initial.vi					
	X	X		X				LinearPlntInvFF_Reset_Zero.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
LINEAR QUADRATIC REGULATOR	X	X		X				LinearQuadraticRegulator_Calculate_NextR.vi					
	X	X		X				LinearQuadraticRegulator_Calculate.vi					
	X	X		X				LinearQuadraticRegulator_GetK_Single.vi		NOT ORIGINAL…			
	X	X		X		X		LinearQuadraticRegulator_GetK.vi					
	X	X		X				LinearQuadraticRegulator_GetR_Single.vi					
	X	X		X				LinearQuadraticRegulator_GetR.vi					
	X	X		X				LinearQuadraticRegulator_GetU_Single.vi					
	X	X		X				LinearQuadraticRegulator_GetU.vi					
	/	X		X		X		LinearQuadraticRegulator_LatencyCompensate.vi		Routine exists, but it only has interger raise matrix to power.			
	X	X		X				LinearQuadraticRegulator_New_ELMS.vi					
	X	X		X				LinearQuadraticRegulator_New_N.vi					
								LinearQuadraticRegulator_New_Raw.vi					
	X	X		X		X		LinearQuadraticRegulator_New_SystemELMS.vi					
	X	X		X				LinearQuadraticRegulator_New.vi					
	X	X		X				LinearQuadraticRegulator_Reset.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
LINEAR SYSTEM	X	X		X	I			LinearSystem_CalculateX.vi					
	X	X		X	I			LinearSystem_CalculateY.vi					
	X	X		X	SI			LinearSystem_GetA.vi					
	X	X		X	SI			LinearSystem_GetAElement.vi					
	X	X		X	SI			LinearSystem_GetB.vi					
	X	X		X	SI			LinearSystem_GetBElement.vi					
	X	X		X	SI			LinearSystem_GetC.vi					
	X	X		X	SI			LinearSystem_GetCElement.vi					
	X	X		X	SI			LinearSystem_GetD.vi					
	X	X		X	SI			LinearSystem_GetDElement.vi					
	X	X		X	SI			LinearSystem_New.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
LINEAR SYSTEM LOOP	X	X		X				LinearSystemLoop_ClampInput.vi					
	X	X		X				LinearSystemLoop_Correct.vi					
								LinearSystemLoop_GetClampFunction.vi					
	X	X		X				LinearSystemLoop_GetController.vi					
	X	X		X				LinearSystemLoop_GetError_Single.vi					
	X	X		X				LinearSystemLoop_GetError.vi					
	X	X		X				LinearSystemLoop_GetFeedForward.vi					
	X	X		X				LinearSystemLoop_GetNextR_Single.vi					
	X	X		X				LinearSystemLoop_GetNextR.vi					
	X	X		X				LinearSystemLoop_GetObserver.vi					
	X	X		X				LinearSystemLoop_GetU_Row.vi					
	X	X		X				LinearSystemLoop_GetU.vi					
	X	X		X				LinearSystemLoop_GetXHat_Single.vi					
	X	X		X				LinearSystemLoop_GetXHat.vi					
								LinearSystemLoop_New_BBB					
								LinearSystemLoop_New_LinearSystem_ClampFunc					
	X	X		X				LinearSystemLoop_New_LinearSystem_ClampVal.vi					
	X	X		X				LinearSystemLoop_New.vi					
	X	X		X				LinearSystemLoop_Predict.vi					
	X	X		X				LinearSystemLoop_Reset.vi					
								LinearSystemLoop_SetClampFunction.vi					
								LinearSystemLoop_SetNextR_Some.vi					
	X	X		X				LinearSystemLoop_SetNextR.vi					
								LinearSystemLoop_SetXHat_Single.vi					
								LinearSystemLoop_SetXHat.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
LTV DIFFERENTIAL DRIVE CONTROLLER	X			X				LTVDiffDriveCtrl_Calculate.vi					
	X			X				LTVDiffDriveCtrl_New.vi					
	X			X				LTVDiffDriveCtrl_Calculate_TrajState.vi					

	X			X				LTVDiffDriveCtrl_Calculate_SetTolerance.vi				
	X			X				LTVDiffDriveCtrl_Calculate_AtReference.vi				

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
LTV UNICYCLE CONTROLLER	X			X		X		LTVUnicycleCtrl_AtReference.vi					
	X		X	X		X		LTVUnicycleCtrl_Calculate_Orig.vi		This one computes a new LQR each time.			
	X		X	X		X		LTVUnicycleCtrl_Calculate_TrajState_Orig.vi		This one computes a new LQR each time.			
	X			X		X		LTVUnicycleCtrl_Calculate_TrajState.vi					
	X			X		X		LTVUnicycleCtrl_Calculate.vi					
	X			X		X		LTVUnicycleCtrl_New.vi					
	X			X		X		LTVUnicycleCtrl_SetEnabled.vi					
	X			X		X		LTVUnicycleCtrl_SetTolerance.vi					

'============
STATE SPACE UTILITIES
'============

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
CALLBACK HELPER	X	X	X	X				CallbackHelp_MatrixMinus.vi					
	X	X	X	X				CallbackHelp_MatrixMult_CoerceSizeB.vi					
	X	X	X	X				CallbackHelp_MatrixMult.vi					
	X	X	X	X				CallbackHelp_MatrixPlus.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
DISCRETIZATION	X	X		X		X		Discretization_DiscretizeA.vi					
	X	X		X		X		Discretization_DiscretizeAB.vi					
	X	X		X		X		Discretization_DiscretizeABTaylor.vi					
	X	X		X		X		Discretization_DiscretizeAQ.vi					
	X	X		X		X		Discretization_DiscretizeAQTaylor.vi					
	X	X		X				Discretization_DiscretizeR.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
STATE SPACE UTIL	X	X	X	No				StateSpaceUtil_Check_Stabalizable.vi		Internal routine			
	X	X		X				StateSpaceUtil_ClampInputMaxMagnitude.vi		Routine exists, it is just a shell			
	X	X		X				StateSpaceUtil_IsDetectable.vi					

X	X		X				StateSpaceUtil_IsStabalizable.vi					
X	X		X		X		StateSpaceUtil_MakeCostMatrix.vi					
X	X		X		X		StateSpaceUtil_MakeCovarianceMatrix.vi					
X	X		X				StateSpaceUtil_MakeWhiteNoiseVector.vi					
X	X		X				StateSpaceUtil_NomalizeInputVector.vi					
X	X		X				StateSpaceUtil_PoseTo3dVector.vi					
X	X		X				StateSpaceUtil_PoseTo4dVector.vi					
X	X		X				StateSpaceUtil_PoseToVector.vi					

'============
SIMULATION
'============

BATTERY SIM

Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
X	X		X	SI			BatterySim_CalculateDefaultBatteryLoadedVoltage.vi					
X	X		X	SI			BatterySim_CalculateLoadedVoltage.vi					

DC MOTOR SIM

Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
X	X		X				DCMotorSim_getAngularPositionRad.vi					
X	X		X				DCMotorSim_getAngularPositionRotations.vi					
X	X		X				DCMotorSim_getAngularVelocityRadPerSec.vi					
X	X		X				DCMotorSim_getAngularVelocityRPM.vi					
X	X		X				DCMotorSim_GetCurrentDrawAmps.vi					
X	X		X				DCMotorSim_New_MOI.vi					
X	X		X				DCMotorSim_New_Plant.vi					
X	X		X				DCMotorSim_SetInputVoltage.vi					
X	X		X				DCMotorSim_Update.vi					

DIFFERENTIAL DRIVE TRAIN SIM

Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
X	X		X				DiffDriveTrainSim_ClampInput.vi					
X	X		X				DiffDriveTrainSim_CreateKitbotSim_EstMass.vi					
X	X		X				DiffDriveTrainSim_CreateKitbotSim_EstMassMOI.vi					
X	X		X				DiffDriveTrainSim_CreateKitbotSim.vi					
X	X		X				DiffDriveTrainSim_GetCurrentDrawAmps.vi					
X	X		X				DiffDriveTrainSim_GetCurrentGearing.vi					
X	X		X				DiffDriveTrainSim_GetDynamics.vi					
X	X		X				DiffDriveTrainSim_GetHeading.vi					
X	X		X				DiffDriveTrainSim_GetLeftCurrentDrawAmps.vi					
X	X		X				DiffDriveTrainSim_GetLeftPositionMeters.vi					
X	X		X				DiffDriveTrainSim_GetLeftVelocityMetersPerSecond.vi					
X	X		X				DiffDriveTrainSim_GetOutput_Single.vi					
X	X		X				DiffDriveTrainSim_GetPose.vi					
X	X		X				DiffDriveTrainSim_GetRightCurrentDrawAmps.vi					
X	X		X				DiffDriveTrainSim_GetRightPositionMeters.vi					
X	X		X				DiffDriveTrainSim_GetRightVelocityMetersPerSecond.vi					

	X	X		X				DiffDriveTrainSim_GetState_Single.vi				
	X	X		X				DiffDriveTrainSim_GetState.vi				
	X	X		X				DiffDriveTrainSim_KitBotWheelSize.vi				
	X	X		X				DiffDriveTrainSim_New_Mass_MOI.vi				
	X	X		X				DiffDriveTrainSim_New.vi				
	X	X		X				DiffDriveTrainSim_SetCurrentGearing.vi				
	X	X		X				DiffDriveTrainSim_SetInputs.vi				
	X	X		X				DiffDriveTrainSim_SetPose.vi				
	X	X		X				DiffDriveTrainSim_SetState.vi				
	X	X		X				DiffDriveTrainSim_ToughBoxMiniGearRatio.vi				
	X	X		X				DiffDriveTrainSim_ToughBoxMiniMotor.vi				
	X	X		X				DiffDriveTrainSim_Update.vi				

	Implemented	*Documented*	*Not WPILIB*	*Menu Item*	*Execution Optimized*	*Test Routine*	*Sample Program*	VI Name	Function Prototype	Notes	*Code Review*	*Test Program*	*Error Checking*
ELEVATOR SIM	X	X		X				ElevatorSim_GetCurrentDraw.vi					
	X	X		X				ElevatorSim_GetPositionMeters.vi					
	X	X		X				ElevatorSim_GetVelocityMetersPerSecond.vi					
	X	X		X				ElevatorSim_HasHitLowerLimit.vi					
	X	X		X				ElevatorSim_HasHitUpperLimit.vi					
								ElevatorSim_New_LinSys_NoNoise.vi					
								ElevatorSim_New_LinSys.vi					
								ElevatorSim_New_NoNoise.vi					
	X	X		X				ElevatorSim_New.vi					
	X	X	X	*No*				ElevatorSim_RKF45_Func.vi					
	X	X		X				ElevatorSim_SetInputVoltage.vi					
	X	X		X				ElevatorSim_SetState.vi					
	X	X	X	X				ElevatorSim_Update.vi		Needed because this doesn't extend.			
	X	X		X				ElevatorSim_UpdateX.vi					
	X	X		X				ElevatorSim_WouldHitLowerLimit.vi					
	X	X		X				ElevatorSim_WouldHitUpperLimit.vi					

	Implemented	*Documented*	*Not WPILIB*	*Menu Item*	*Execution Optimized*	*Test Routine*	*Sample Program*	VI Name	Function Prototype	Notes	*Code Review*	*Test Program*	*Error Checking*
FLYWHEEL SIM	X	X		X				FlyWheelSim_GetAngularVelocityRadPerSec.vi					
	X	X		X				FlyWheelSim_GetAngularVelocityRPM.vi					
	X	X		X				FlyWheelSim_GetCurrentDrawAmps					
								FlyWheelSim_New_LinSys		Future			
								FlyWheelSim_New_LinSys_MOI_NoNoise		Future			
								FlyWheelSim_New_LinSys_NoNoise		Future			
	X	X		X				FlyWheelSim_New_MOI.vi					
	X	X		X				FlyWheelSim_SetInput.vi					
	X	X		X				FlyWheelSim_SetState.vi					
	X	X		X				FlyWheelSim_Update.vi					

	Implemented	*Documented*	*Not WPILIB*	*Menu Item*	*Execution Optimized*	*Test Routine*	*Sample Program*	VI Name	Function Prototype	Notes	*Code Review*	*Test Program*	*Error Checking*

Revision 2.X 5/2/2022 – added implicit model follower and time interpolatable routines.

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
LINEAR SYSTEM SIM	X	X		X				LinearSystemSim_ClampInput.vi					
								LinearSystemSim_GetCurrentDrawAmps.vi		DONT IMPLEMENT…			
	X	X		X				LinearSystemSim_GetOutput_Single.vi					
	X	X		X				LinearSystemSim_GetOutput.vi					
	X	X		X				LinearSystemSim_New					
								LinearSystemSim_New_NoNoise.vi					
	X	X		X				LinearSystemSim_SetInput_Array.vi		Doesn't use clamp ?			
	X	X		X				LinearSystemSim_SetInput_Single.vi					
	X	X		X				LinearSystemSim_SetInput.vi					
	X	X		X				LinearSystemSim_Setstate.vi					
	X	X		X				LinearSystemSim_Update.vi					
	X	X		No				LinearSystemSim_UpdateX.vi					
	X	X	X	No				LinearSystemSim_UpdateY.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
SINGLE JOINT ARM SIM	X	X		X				SngJntArmSim_EsitmateMOI.vi					
	X	X		X				SngJntArmSim_GetAngleRads.vi					
	X	X		X				SngJntArmSim_GetCurrentDraw.vi					
	X	X		X				SngJntArmSim_GetVelocityRadsPerSec.vi					
	X	X		X				SngJntArmSim_HasHitLowerLimit.vi					
	X	X		X				SngJntArmSim_HasHitUpperLimit.vi					
	X	X		X				SngJntArmSim_New.vi					
	X	X		No				SngJntArmSim_Rkf45_Func.vi					
	X	X		X				SngJntArmSim_SetInputVoltage.vi					
	X	X		X				SngJntArmSim_SetState.vi					
	X	X		X				SngJntArmSim_Update.vi					
	X	X		X				SngJntArmSim_UpdateX.vi					
	X	X		X				SngJntArmSim_WouldHitLowerLimit.vi					
	X	X		X				SngJntArmSim_WouldHitUpperLimit.vi					

'============
MATRIX UTILITIES
'============

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
MAT BUILDER	X	X		X	SI			MatBuilder_Create.vi					
	X	X		X	SI			MatBuilder_Fill.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
MATRIX	X	X		X	SI			Matrix_AssignBlock.vi					
	X	X		X	SI			Matrix_Block.vi					
								Matrix_ChangeBoundsUnchecked.vi					
	X	X		X	SI			Matrix_Create.vi					
								Matrix_Det.vi					
	X	X		X	SI			Matrix_Diag.vi					

							Matrix_Div_Scalar.vi		labview has function			
							Matrix_ElementPower.vi					
X	X		X	SI			Matrix_ElementSum.vi					
							Matrix_ElementTimes.vi					
							Matrix_Equals.vi					
X	X		X	I			Matrix_Exp.vi					
X	X		X	SI			Matrix_ExtractColumnVector.vi					
X	X		X	SI			Matrix_ExtractFrom.vi					
							Matrix_ExtractMatrix.vi					
X	X		X	SI			Matrix_ExtractRowVector.vi					
X	X		X	SI			Matrix_Fill.vi					
							Matrix_Get.vi		labview has function			
X	X		X	I			Matrix_Ident.vi		WPILIB calls this EYE			
							Matrix_Inv.vi					
X	X		X	SI			Matrix_IsEqual.vi					
							Matrix_IsIdentical.vi					
X	X		X	I			Matrix_LLTDecompose.vi					
							Matrix_Max.vi					
							Matrix_MaxAbs.vi					
							Matrix_Mean.vi					
							Matrix_MinInternal.vi					
							Matrix_Minus_Matrix.vi					
							Matrix_Minus_Scalar.vi					
X	X		X	I			Matrix_NormF.vi					
							Matrix_NormIndP1.vi					
							Matrix_Plus_Matrix.vi					
							Matrix_Plus_Scalar.vi					
X	X		X	I			Matrix_Pow.vi		THIS NEEDS WORK!!!!			
X	X		X	SI			Matrix_SetColumn.vi					
X	X		X	SI			Matrix_SetRow.vi	THERE ARE LOTS OF OTHER MATRIX FUNCTIONS THAT SHOULD BE INCLUDED HERE FOR ISOLATION.				
							Matrix_Solve.vi					
							Matrix_Times_Matrix.vi					
							Matrix_Times_Scalar.vi					
							Matrix_Trace.vi					
X	X		X	SI			Matrix_Transpose.vi					
X		X	X				Matrix_WithinTolerance.vi					

SIMPLE MATRIX

Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
X	X		X	SI			SimpleMatrix_ExtractMatrix.vi		NOTE Matrix also has an ExtractMatrix with different calling parameters…. YUK.			

MATRIX HELPER

Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
X	X	X	X	SI			MatrixHelper_CooerceSize.vi					
X	X	X	X	SI			MatrixHelper_MultCooerceBSize.vi					
X	X	X	X	SI			MatrixHelper_Zero.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
VECTOR BUILDER	X	X		X	SI			VecBuilder_1x1Fill.vi					
	X	X		X	SI			VecBuilder_2x1Fill.vi					
	X	X		X	SI			VecBuilder_3x1Fill.vi					
	X	X		X	SI			VecBuilder_4x1Fill.vi					
	X	X		X	SI			VecBuilder_5x1Fill.vi					
	X	X		X	SI			VecBuilder_6x1Fill.vi					
	X	X		X	SI			VecBuilder_7x1Fill.vi					
	X	X		X	SI			VecBuilder_8x1Fill.vi					
								VecBuilder_9x1Fill.vi					
								VecBuilder_10x1Fill.vi					
	X	X	X	X	SI			VecBuilder_ArrayBy1Fill.vi					

'============
MATH
'============

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
ANGLE STATISTICS	X	X	X	X	X			AngleStats_AngleAdd_CallbackHelp.vi					
	X	X		X	I	X		AngleStats_AngleAdd.vi					
	X	X	X	X	X			AngleStats_AngleMean_CallbackHelp.vi					
	X	X		X	I	X		AngleStats_AngleMean.vi					
	X	X	X	X	X			AngleStats_AngleResidual_CallbackHelp.vi					
	X	X		X	I	X		AngleStats_AngleResidual.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
MATH UTILITY	X	X		X	SI			MathUtil_AngleModulus.vi					
	X	X		X	SI			MathUtil_ApplyDeadband.vi					
	X	X		X	SI			MathUtil_Clamp_Int.vi					
	X	X		X	SI			MathUtil_Clamp.vi					
	X	X		X	SI			MathUtil_InputModulus.vi					
	X	X		X	Si			MathUtil_Interpolate.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
MERWE SCALED SIGMA POINTS	X	X		X	I			MerweScSigPts_ComputeWeights.vi					
	X	X		X	SI			MerweScSigPts_GetNumSigmas.vi					
	X	X		X	SI			MerweScSigPts_GetWc_Single.vi					

X	X		X	SI			MerweScSigPts_GetWc.vi					
X	X		X	SI			MerweScSigPts_GetWm_Single.vi					
X	X		X	SI			MerweScSigPts_GetWm.vi					
X	X		X	I			MerweScSigPts_New_Default.vi					
X	X		X	I			MerweScSigPts_New.vi					
X	X		X	I			MerweScSigPts_SigmaPoints.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
NUMERICAL INTEGRATION	X	X		X	I			NumIntegrate_Func_Ax_Bu_K.vi		NOT USED. Should this be used or abandoned???			
	X	X		X				NumIntegrate_Rk4_Dbl_X_U.vi					
	X	X		X				NumIntegrate_Rk4_Dbl_X.vi					
	X	X		X				NumIntegrate_Rk4_Mat_X_U.vi					
	X	X		X				NumIntegrate_Rk4_Mat_X.vi					
	X	X		No	SI			NumIntegrate_Rkdp_Func_A.vi					
	X	X		No	SI			NumIntegrate_Rkdp_Func_B1.vi					
	X	X		No	SI			NumIntegrate_Rkdp_Func_B1B2.vi					
	X	X		No	SI			NumIntegrate_Rkdp_Func_B2.vi					
	X	X		No	I			Numintegrate_Rkdp_Impl.vi					
	X	X		X				NumIntegrate_RKDP_Mat_X_U.vi		New replacement for RKF45			
	X	X		No	SI			NumIntegrate_Rkf45_Func_A.vi					
	X	X		No	SI			NumIntegrate_Rkf45_Func_B1.vi					
	X	X		No	SI			NumIntegrate_Rkf45_Func_B1B2.vi					
	X	X		No	SI			NumIntegrate_Rkf45_Func_B2.vi					
								NumIntegrate_RKf45_Func_Bs.vi		Removed. Replaced with newer functions.			
								NumIntegrate_RKf45_Func_Ch.vi		Removed. Replaced with newer functions.			
								NumIntegrate_RKf45_Func_Ct.vi		Removed. Replaced with newer functions.			
	X	X		No	I			NumIntegrate_Rkf45_Impl.vi					
	X	X		X				NumIntegrate_Rkf45_Mat_X_U.vi		Note that this Feinberg method has been changed and a Dormand Price method has been implemented.... TODO			
								NumIntegrate_RKf45_New.vi		Removed. Never used.			
	X	X	X	X	SI			NumIntegrate_Trap_Dbl.vi					
	X	X	X	X	I			NumIntegrate_Trap_Mat.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
RUNGE KUTTA TIME VARYING	X	X		No				RungeKuttaTimeVarying_RK4_Mat_T_Y.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
NUMERICAL JACOBIAN	X	X		X				NumJacobian_U.vi					
	X	X		X				NumJacobian_X.vi					

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
RICCATI	X	X		X				Riccati_Check_Detectable.vi		Routine exists, it is just a shell			
	X	X		X				Riccati_Check_Stabilizable.vi		Not really done !!!			
	X	X	X	X		X		Riccati_DARE_Iterate.vi					
	X		X	X		X		Riccati_DARE_StructDoubling.vi					
	X	X		X				Riccati_DARE_N.vi					
	X	X		X		X		Riccati_DARE.vi					
	X	X		X				Riccati_Input_Check.vi					

'============
VISION
'============

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
COMPUTER VISION UTILITIES	X	X		X				CompVisionUtil_CalculateDistanceToTarget.vi					
	X	X		X				CompVisionUtil_EstimateCameraToTarget.vi					
	X	X		X				CompVisionUtil_EstimateFieldToCamera.vi					
	X	X		X				CompVisionUtil_EstimateFieldToRobot.vi					
	X	X		X				CompVisionUtil_EstimateFieldToRobot_Alt.vi					

'============
TYPE DEFINITIONS
'============

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
TypeDef	Z	X	X	X	N/A			ARM_FF.CTL					
	Z	X	X	X	N/A			BANG_BANG.CTL					
	\		X	X	N/A			BICon-Matrix_FUNC_TYPE.CTL		NOT USED. Should this be deleted or abandoned???			
	Z	X	X	X	N/A			CALLBACK_FUNC_TYPE.CTL					
	Z	X	X	X	N/A			CHASSIS_SPEEDS.CTL					
	Z	X	X	X	N/A			CONTRAINED_STATE.CTL					
	Z	X	X	X	N/A			DCMOTOR_TYPES_ENUM.CTL					
	Z	X	X	X	N/A			DCMOTOR.CTL					
	Z	X	X	X	N/A			DCMOTOR_SIM.CTL					
	Z	X	X	X	N/A			DEBOUNCER_TYPE_ENUM.Ctl					
	Z	X	X	X	N/A			DEBOUNCER.CTL					
	Z	X	X	X	N/A			DIFF_DRIVE_ACCEL_LIMIT.CTL					
	Z	X	X	X	N/A			DIFF_DRIVE_KINEMATICS.CTL					
	Z	X	X	X	N/A			DIFF_DRIVE_Kitbot_WheelSize_ENUM.ctl					
	Z	X	X	X	N/A			DiFF_DRIVE_Pose_EST.ctl					
	Z	X	X	X	N/A			DIFF_DRIVE_ToughBoxMini_GearChoice_ENUM.ctl					
	Z	X	X	X	N/A			DIFF_DRIVE_ToughBoxMini_MotorChoice_ENUM.ctl					
	Z	X	X	X	N/A			DIFF_DRIVE_TRAIN_SIM_STATE_ENUM.CTL					

Z	X	X	X	N/A			DIFF_DRIVE_TRAIN_SIM.ctl		
Z	X	X	X	NA			DISPLAY_WAYPOINT.ctl		Was UTIL_WAYPOINT.VI
Z	X	X	X	NA			DISPLAY_WEIGHTED_WAYPOINT.ctl		New V1.5. was UTIL_WEIGHTED_WAYPOINIT.VI
Z	X	X	X	N/A			ELEV_FF.CTL		
Z	X	X	X	N/A			ELEVATOR_SIM.CTL		
Z	X	X	X	N/A			EXTENDED_KALMAN_CORRECT_FUNC_GROUP.CTL		
Z		X	X	N/A			ExTENDED_KALMAN_FILTER.CTL		
Z	X	X	X	N/A			FLYWHEEL_SIM.ctl		
Z	X	X	X	N/A			FUNCTION_GENERATOR.ctl		
Z	X	X	X	N/A			FUNCTION_GENERATOR_MATRIX.ctl		
Z	X	X	X	N/A			HOLONOMIC_DRV_CTRL.CTL		New 1/26/21
Z	X	X	X	N/A			TIME_INTERPOLATABLE_BOOLEAN.CTL		
Z	X	X	X	N/A			TIME_INTERPOLATABLE_DOUBLE.CTL		
Z	X	X	X	N/A			TIME_INTERPOLATABLE_POSE2D.CTL		
Z	X	X	X	N/A			TIME_INTERPOLATABLE_ROTATION2D.CTL		
Z	X	X	X	N/A			KALMAN_FILTER_LATENCY_COMP_FUNC_GROUP.CTL		
Z	X	X	X	N/A			KALMAN_FILTER_LATENCY_COMP.CTL		
Z	X	X	X	N/A			KALMAN_FILTER.ctl		
Z	X	X	X	N/A			LINEAR_FILTER.CTL		
Z	X	X	X	N/A			LINEAR_PLANT_INV_FF.ctl		
Z	X	X	X	N/A			LINEAR_QUADRATIC_REGULATOR.ctl		
Z	X	X	X	N/A			LINEAR_SYSTEM_LOOP.ctl		
Z	X	X	X	N/A			LINEAR_SYSTEM_SIM.ctl		
Z	X	X	X	N/A			LINEAR_SYSTEM.ctl		
Z		X	X	N/A			LTV_DIFF_DRIVE_CTRL.ctl		
Z		X	X	N/A			LTV_DIFF_DRIVE_CTRL_STATE_ENUM.ctl		
Z		X	X	N/A			LTV_UNICYCLE_CONTROLLER.CTL		
Z		X	X	N/A			LTV_UNICYCLE_CONTROLLER_INPUT_ENUM.ctl		
Z		X	X	N/A			LTV_UNICYCLE_CONTROLLER_STATE_ENUM.ctl		
Z	X	X	X	N/A			MECA_DRIVE_KINEMATICS.CTL		
Z	X	X	X	N/A			MECA_DRIVE_ODOMETRY.CTL		
Z	X	X	X	N/A			MECA_WHEEL_SPEEDS.CTL		
Z	X	X	X	N/A			MEDIAN_FILTER.CTL		
Z	X	X	X	N/A			MERWE_SCALED_SIGMA_PTS.ctl		
Z	X	X	X	N/A			OBSERVER_SNAP_LIST_ITEM.CTL		
Z	X	X	X	N/A			OBSERVER_SNAPSHOT.CTL		
Z	X	X	X	N/A			PARAM_STACK_ITEM.CTL		
Z	X	X	X	N/A			PARAM_STACK.CTL		
Z	X	X	X	N/A			PID_ADV_LIMITS.CTL		
Z	X	X	X	N/A			PID_ADV_TUNING.CTL		
Z	X	X	X	N/A			PID_CONTROLLER.CTL		
Z	X	X	X	N/A			PID_ERROR_TOLERANCE.CTL		
Z	X	X	X	N/A			PID_INPUT_LIMITS.CTL		
Z	X	X	X	N/A			PID_TUNING.CTL		
Z	X	X	X	N/A			POSE2D.CTL		
Z	X	X	X	N/A			POSEwCURVATURE.CTL		
Z	X	X	X	N/A			PROFILED_PID_CONTROLLER.CTL		
Z	X	X	X	N/A			RAMSETE_EXE_TUNING.CTL		
Z	X	X	X	N/A			RAMSETE.CTL		
Z	X	X	X	N/A			ROTATION2D.CTL		
Z	X	X	X	N/A			SIMPLE_MOTOR_FF.CTL		
Z	X	X	X	N/A			SINGLE_JOINT_ARM_SIM.CTL		
Z	X	X	X	N/A			SLEW_RATE_LIMITER.CTL		
Z	X	X	X	N/A			SPLINE_CTRL_VECTOR.CTL		
Z	X	X	X	N/A			SPLINE.CTL		
Z	X	X	X	N/A			SWERVE_DRIVE_KINEMATICS.CTL		
Z	X	X	X	N/A			SWERVE_DRIVE_MODULE_STATE.CTL		
Z	X	X	X	N/A			SWERVE_DRIVE_ODOMETRY.CTL		
Z	X	X	X	N/A			SWERVE_DRIVE_Pose_EST.CTL		
Z	X	X	X	N/A			TIMER.CTL		
Z	X	X	X	N/A			TRAJ_CONFIG.CTL		
Z	X	X	X	N/A			TRAJ_CONSTRAINT_CENTRIPETAL_ACCEL.CTL		
Z	X	X	X	N/A			TRAJ_CONSTRAINT_DIIF_DRIVE_KINEMATICS.CTL		
Z	X	X	X	N/A			TRAJ_CONSTRAINT_DIIF_DRIVE_VOLTAGE.CTL		

\		X		N/A			TRAJ_CONSTRAINT_JERK.CTL		Routine exists, it is just a shell
Z	X	X	X	N/A			TRAJ_CONSTRAINT_MECA_DRIVE_KINEMATICS.CTL		
Z	X	X	X	N/A			TRAJ_CONSTRAINT_MINMAX.CTL		
Z	X	X	X	N/A			TRAJ_CONSTRAINT_SWERVE_DRIVE_KINEMATICS.CTL		
Z	X	X	X	N/A			TRAJ_STATE.CTL		
Z	X	X	X	N/A			TRAJECTORY_SPLINE_TYPE_ENUM.CTL		
Z	X	X	X	N/A			TRAJECTORY.CTL		
Z	X	X	X	N/A			TRANSFORM2D.CTL		
Z	X	X	X	N/A			TRANSLATION2D.CTL		
Z	X	X	X	N/A			TRAPEZOID_PROFILE_CONSTRAINT.CTL		
Z	X	X	X	N/A			TRAPEZOID_PROFILE_STATE.CTL		
Z	X	X	X	N/A			TRAPEZOID_PROFILE.CTL		
Z	X	X	X	N/A			TWIST2D.CTL		
Z	X	X	X	N/A			UNSCENTED_KALMAN_CORRECT_FUNC_GROUP.CTL		
Z	X	X	X	N/A			UNSCENTED_KALMAN_FILTER.ctl		
Z	X	X	X	N/A			UNSCENTED_KALMAN_NEW_FUNC_GROUP.CTL		
Z	X	X	X	N/A			UTIL_PATHFINDER_CONFIG.CTL		
N/A		N/A		N/A			WAYPOINTS.CTL		Delete – obsolete
Z	X	X	X	NA			WEIGHTED_WAYPOINT.CTL		New V1.5
N/A		N/A		N/A			X_Y_HEADINGS.CTL		Delete – obsolete
Z	X	X	X	N/A			X_Y_PAIR.CTL		