

This documents which Java/C++ WPILIB routines have been duplicated in LabVIEW, and which ones are not needed (for example because all that is needed is a cluster unpack function), and what isn't done....yet...

	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program
VI / CTL Totals	1130	1129	348	1055	653	49	12
VI Total (X)	1012	1012					
CTL Total (Z)	118	117					
VI Shell Total (I)	3						
CTRL Shell Total (I)	2						

Doc completed Pct
99.91%
Optimization Pct
57.79%

Optimize legend: S = Subroutine, I = Inline, X = reviewed, nothing done. (In some cases, after sufficient debug and use, additional optimizations could be considered.)

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BASE

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Category	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program						
ANALOG DELAY	X	X	X	X	I			AnalogDelay_Execute.vi		Similar to interpolated tree map..			
BUMPLESS TRANSFER	X	X	X	X	I			BumplessTransfer_Execute.vi					
FUNCTION GENERATOR	X	X		X	I			FunctionGenerator_Add_Value.vi		Similar to interpolated tree map..			
	X	X		X	I			FunctionGenerator_Add_XY.vi		Similar to interpolated tree map..			
	X	X		X	I			FunctionGenerator_Calculate.vi		Similar to interpolated tree map..			
	X	X		X	SI			FunctionGenerator_Clear.vi					
	X	X	X	X	I			FunctionGenerator_Execute.vi		Similar to interpolated tree map..			
	X	X		X	SI			FunctionGenerator_New.vi		Similar to interpolated tree map..			
FUNCTION GENERATOR MATRIX	X	X	X	X	I			FunctionGeneratorMatrix_Add.vi		Similar to interpolated tree map..			
	X	X	X	X	I			FunctionGeneratorMatrix_Calculate.vi		Similar to interpolated tree map..			
	X	X	X	X	SI			FunctionGeneratorMatrix_New.vi		Similar to interpolated tree map..			

LEAD LAG	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	x
	X	X	X	X	I			LeadLag_Execute.vi						x
LINEAR FILTER	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	x
	X	X		X	I			LinearFilter_BackwardFiniteDifference.vi						x
	X	X		X	SI			LinearFilter_Calculate.vi						x
	X	X	X	X	X			LinearFilter_CutoffFrequency.vi						x
	X	X	X	X	I		X	LinearFilter_Execute.vi		Labview style helper				x
	X	X		No	I			LinearFilter_Factorial.vi		AN INTERNAL ROUTINE				x
	X	X			I			LinearFilter_FiniteDifference.vi						x
	X	X		X	X			LinearFilter_HighPass.vi						x
	X	X	X	X	X			LinearFilter_HighPassBW1.vi						x
	X	X	X	X	X			LinearFilter_HighPassBW2.vi						x
	X	X	X	X	X			LinearFilter_LowPassBW1.vi						x
	X	X	X	X	X			LinearFilter_LowPassBW2.vi						x
	X	X		X	X			LinearFilter_MovingAverage.vi						x
	X	X		X	I			LinearFilter_New.vi						x
	X	X		X	SI			LinearFilter_Reset.vi						x
	X	X	X	X	SI			LinearFilter_ResetToValue.vi						x
	X	X		X	X			LinearFilter_SinglePoleIIR.vi						x
	X	X	X	X	X			LinearFilter_TimeConst.vi						x
MEDIAN FILTER	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	x
	X	X		X	X			MedianFilter_Calculate.vi						x
	X	X	X	X	I		X	MedianFilter_Execute.vi		Labview style helper				x
	X	X		X	SI			MedianFilter_New.vi						x
	X	X		X	SI			MedianFilter_Reset.vi						x
	X	X	X	X	SI			MedianFilter_ResetToValue.vi						x
SLEW RATE FILTER	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	x
	X	X		X	I			SlewRateLimiter_Calculate.vi						x
	X	X	X	X	SI			SlewRateLimiter_Close.vi						x
	X	X	X	X	I		X	SlewRateLimiter_Execute.vi		Labview style helper				x
	X	X	X	X	SI			SlewRateLimiter_GetRate.vi						x
	X	X		X	I			SlewRateLimiter_New.vi						x
	X	X		X	I			SlewRateLimiter_NewInitialZero.vi						x
	X	X		X	I			SlewRateLimiter_Reset.vi						x
	X	X		X	SI			SlewRateLimiter_SetRate.vi						x

x

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
TIMER	X	X	X	X				Timer_Close.vi		releases semaphore			
	X	X		X			X	Timer_Get.vi					
	X	X	X	X				Timer_GetAndReset.vi					
	X	X	X	No				Timer_GetInternal.vi		Internal (private) only			
	X	X		X			X	Timer_HasPeriodPassed.vi					
	X	X	X	X			X	Timer_HasPeriodPassedOnce.vi					
	X	X		X			X	Timer_New.vi					
	X	X		X			X	Timer_Reset.vi					
	X	X	X	No				Timer_ResetInternal		Internal (private) only			
	X	X		X			X	Timer_Start.vi					
	X	X		X			X	Timer_Stop.vi					
	X	X	X	No				Timer_StopInternal.vi		Internal (private) only			

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	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
TIME INTERPOLATABLE BOOLEAN	X	X	X	X	I			TimeInterpBoolean_AddSample.vi		Update to use create matrix			
	X	X	X	No	I			TimeInterpBoolean_CleanUp.vi		Update to use create matrix			
	X	X	X	X	SI			TimeInterpBoolean_Clear.vi					
	X	X	X	X	I			TimeInterpBoolean_GetSample.vi					
								TimeInterpBoolean_GetTimeForValue.vi					
	X	X	X	X	SI			TimeInterpBoolean_New.vi					
	X	X	X	X	SI			TimeInterpBoolean_SetMaxTime.vi					

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	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
TIME INTERPOLATABLE DOUBLE	X	X	X	X	I			TimeInterpDouble_AddSample.vi		Update to use create matrix			
	X	X	X	No	I			TimeInterpDouble_CleanUp.vi		Update to use create matrix			
	X	X	X	X	SI			TimeInterpDouble_Clear.vi					
	X	X	X	X	I			TimeInterpDouble_GetSample.vi					
	X	X	X					TimeInterpDouble_GetTimeForValue.vi					
	X	X	X	X	SI			TimeInterpDouble_New.vi					
	X	X	X	X	SI			TimeInterpDouble_SetMaxTime.vi					

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	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
TIME INTERPOLATABLE POSE2D	X	X	X	X	I			TimeInterpPose2d_AddSample.vi		Update to use create matrix			
	X	X	X	No	I			TimeInterpPose2d_CleanUp.vi		Update to use create matrix			
	X	X	X	X	SI			TimeInterpPose2d_Clear.vi					
	X	X	X	X	I			TimeInterpPose2d_GetSample.vi					
								TimeInterpPose2d_GetTimeForValue.vi					
	X	X	X	X	SI			TimeInterpPose2d_New.vi					
	X	X	X	X	SI			TimeInterpPose2d_SetMaxTime.vi					

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TIME INTERPOLATABLE ROTATION2D	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
	X	X	X	X	/			TimeInterpRotation2d_AddSample.vi		Update to use create matrix			
	X	X	X	No	/			TimeInterpRotation2d_CleanUp.vi		Update to use create matrix			
	X	X	X	X	SI			TimeInterpRotation2d_Clear.vi					
	X	X	X	X	/			TimeInterpRotation2d_GetSample.vi					
								TimeInterpRotation2d_GetTimeForValue.vi					
	X	X	X	X	SI			TimeInterpRotation2d_New.vi					
	X	X	X	X	SI			TimeInterpRotation2d_SetMaxTime.vi					
WAIT ADJUST	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
	X	X	X	X				WaitAdjust.vi					
DIGITAL SEQUENTIAL LOGIC	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
	X	X	X	X				DigSeqLogic_Delay.vi					
	X	X	X	X				DigSeqLogic_On_Delay.vi					
	X	X	X	X				DigSeqLogic_Off_Delay.vi					
	X	X	X	X				DigSeqLogic_One_Shot.vi					
	X	X	X	X				DigSeqLogic_SR_Flip_Flop.vi					
DEBOUNCER	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
	X	X		X				Debouncer_New.vi					
	X	X		X				Debouncer_Calculate.vi					
	X	X	X	X				Debouncer_Execute.vi					
	X	X		No				Debouncer_Reset.vi					
	X	X		No				Debouncer_HasElapsed.vi					
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CONTROLLER													
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ARM FF	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
	X	X		X				ArmFF_Calculate.vi					
	X	X		X				ArmFF_CalculateVelocityOnly.vi					
			X					ArmFF_Execute.vi		LabVIEW style single call			
			X					ArmFF_ExecuteVelocityOnly.vi		LabVIEW style single call			
	X	X		X				ArmFF_MaxAchieveAccel.vi					
	X	X		X				ArmFF_MaxAchieveVelocity.vi					

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CONTROLLER

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	Implemented	Documented	Not WPI/LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
PROFIED PID CONTROLLER	X	X		X	SI			ProfiedPIDController_AtGoal.vi					
	X	X		X	SI			ProfiedPIDController_AtSetpoint.vi					
	X	X		X				ProfiedPIDController_Calculate_Meas_Goal.vi					
	X	X		X				ProfiedPIDController_Calculate_Meas_StateGoal_TrapCnsrt.vi					
	X	X		X				ProfiedPIDController_Calculate_Meas_StateGoal.vi					
	X	X		X				ProfiedPIDController_Calculate_Meas.vi					
	X	X		X	SI			ProfiedPIDController_DisableContInput.vi					
	X	X		X	SI			ProfiedPIDController_EnableContInput.vi					
	X	X	X	X	I			ProfiedPIDController_Execute.vi		Single call LabVIEW style function.			
	X	X		X	SI			ProfiedPIDController_GetGoal.vi					
	X	X		X	SI			ProfiedPIDController_GetPeriod.vi					
	X	X	X	X	SI			ProfiedPIDController_GetPID.vi		WPI/LIB has separate getters.			
	X	X		X	SI			ProfiedPIDController_GetPositionError.vi					
	X	X		X	SI			ProfiedPIDController_GetSetpoint.vi					
	X	X			SI			ProfiedPIDController_GetTolerance.vi					
	X	X		X	SI			ProfiedPIDController_GetVelocityError.vi					
	X	X		X	I			ProfiedPIDController_New.vi					
	X	X		X	I			ProfiedPIDController_NewPeriod.vi					
	X	X		X	SI			ProfiedPIDController_Reset_PosOnly.vi					
	X	X		X	SI			ProfiedPIDController_Reset_PosVel.vi					
	X	X		X	SI			ProfiedPIDController_Reset.vi					
	X	X		X	SI			ProfiedPIDController_SetConstraints.vi					
	X	X		X	SI			ProfiedPIDController_SetGoal_PosOnly.vi					
	X	X		X	SI			ProfiedPIDController_SetGoal.vi					
	X	X		X	SI			ProfiedPIDController_SetIntegratorRange.vi					
	X	X		X	SI			ProfiedPIDController_SetPID.vi					
	X	X		X	SI			ProfiedPIDController_SetTolerance_PosOnly.vi					
	X	X		X	SI			ProfiedPIDController_SetTolerance_PosVel.vi					

	Implemented	Documented	Not WPI/LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
RAMSETE	X	X		X	SI			Ramsete_AtReference.vi	AtReference				
	X	X		X	X			Ramsete_Calculate_Trajectory.vi	calculate_trajectory				
	X	X		X	X			Ramsete_Calculate.vi	calculate				
	X	X	X	X	X			Ramsete_Diff_DO_Eng.vi					
	X	X	X	X	X			Ramsete_Diff_DO_SI.vi					
	X	X	X	X	I			Ramsete_Execute_ENG.vi	Use this one!!				
	X	X	X	X	SI			Ramsete_Execute_PackTuning_ENG.vi					
	X	X	X	X	SI			Ramsete_Execute_PackTuning.vi					
	X	X	X	X	I			Ramsete_Execute.vi					
	X	X		X	SI			Ramsete_New_B_Z.vi	new(b, zeta)				
	X	X		X	SI			Ramsete_New.vi	new				
	X	X		X	SI			Ramsete_SetEnabled.vi	SetEnabled				
	X	X		X	SI			Ramsete_SetTolerance.vi	SetTolerance				
	X	X		X	X			Ramsete_SINC.vi	sinc	internal			

	Implemented	Documented	Not WPI/LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
SIMPLE MOTOR FEEDFORWARD	X	X	X	X	SI			SimpleMotorFF_Calculate_CalcAccel.vi					
	X	X		X				SimpleMotorFF_Calculate_NextV_Dt.vi					
	X	X		X	SI			SimpleMotorFF_Calculate.vi	public double calculate(double velocity, double acceleration)				

X	X		X	SI			SimpleMotorFF_CalculateVelocityOnly.vi	public double calculate(double velocity)						
X	X	X					SimpleMotorFF_Ka_AutoTune.vi							
X	X		X	X			SimpleMotorFF_MaxAchieveAccel.vi	public double maxAchievableAcceleration(double maxVoltage, double velocity)						
X	X		X	X			SimpleMotorFF_MaxAchieveVel.vi	public double maxAchievableVelocity(double maxVoltage, double acceleration)						
X	X		X	X			SimpleMotorFF_MinAchieveAccel.vi	public double minAchievableAcceleration(double maxVoltage, double velocity)						
X	X		X	X			SimpleMotorFF_MinAchieveVel.vi	public double minAchievableVelocity(double maxVoltage, double acceleration)						
X	X		X	SI			SimpleMotorFF_New.vi	public SimpleMotorFeedforward(double ks, double kv, double ka)						
X	X	X		SI			SimpleMotorFF_Pack_Ka_Tune_Params.vi							
								public SimpleMotorFeedforward(double ks, double kv)						

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GEOMETRY

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	Implemented	Documented	Not WPI/LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
COORDINATE AXIS	X	X		X	SI			CoordAxis_D.vi					
	X	X		X	SI			CoordAxis_E.vi					
	X	X		X	SI			CoordAxis_N.vi					
	X	X		X	SI			CoordAxis_New.vi					
	X	X		X	SI			CoordAxis_S.vi					
	X	X		X	SI			CoordAxis_U.vi					
	X	X		X	SI			CoordAxis_W.vi					

	Implemented	Documented	Not WPI/LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
COORDINATE SYSTEM	X	X		X	SI	X		CoordSystem_Convert_Pose3d.vi					
	X	X		X	SI			CoordSystem_Convert_Rotation3d.vi					
	X	X		X	SI			CoordSystem_Convert_Translation3d.vi					
	X	X		X	SI			CoordSystem_Convert_Transform3d.vi					
	X	X		X	SI	X		CoordSystem_EDN.vi					
	X	X		X	SI	X		CoordSystem_NED.vi					
	X	X		X	SI	X		CoordSystem_New.vi					
	X	X		X	SI	X		CoordSystem_NWU.vi					

	Implemented	Documented	Not WPI/LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
POSE2D	X	X			SI			Pose2d_Div.VI					
	X	X		X	SI			Pose2d_Equals.VI	boolean equals(other obj)				
	X	X		X	X			Pose2d_Exp.vi	pose2d exp(twist2d twist)				
	X	X		X	SI			Pose2d_getRotation.vi	rotation2d getRotation()	can also use cluster unpack			
	X	X		X	SI			Pose2d_getTranslation.vi	translation2d getTranslation()	can also use cluster unpack			
	X	X	X	X	SI			Pose2d_getXY.vi					
	X	X	X	X	SI			Pose2d_getXYAngle.vi					
	X	X		X	I			Pose2d_Interpolate.vi					
	X	X		X	X			Pose2d_Log.vi	twist2d log(pose2d end)				
	X	X		X	SI			Pose2d_Minus.vi	transform2d minus(pose2d other)				
	X	X		X	SI			Pose2d_New_TRRO.vi	pose2d new(translation2d, rotation2d)				
	X	X		X	SI			Pose2d_New.vi	pose2d new(double x, double y, rotation2d)				
	X	X		X	SI			Pose2d_Plus.vi	pose2d plus(transform2d other)				
	X	X		X	SI			Pose2d_RelativeTo.vi	pose2d relativeto(pose2d other)				
	X	X			SI			Pose2d_Times.vi					

X	X		X	SI			Rotation2d_GetRadians.VI	double getRadians()	use cluster unpack			
X	X		X	SI			Rotation2d_GetRotations.vi					
X	X		X	SI			Rotation2d_GetSin.VI	double getSin()	use cluster unpack			
X	X		X	SI			Rotation2d_GetTan.VI	double getTan()	can calculate			
X	X		X	SI			Rotation2d_Interpolate.vi					
X	X		X	SI			Rotation2d_Minus.vi	rotation2d minus(rotation2d other)				
X	X		X	SI			Rotation2d_Plus.vi	rotation2d plus(rotation2d other)				
X	X		X	SI			Rotation2d_RotateBy.vi	rotation2d rotateby(rotation2d other)				
X	X		X	SI			Rotation2d_Times.vi	rotation2d times(double scalar)				
X	X		X	SI			Rotation2d_UnaryMinus.vi	rotation2d unaryminus()				
								rotation2d new()	can use cluster constant			

ROTATION3D	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
	X	X		X	SI			Rotation3d_Create_AxisAngle.vi					
	X	X		X	SI			Rotation3d_Create_Default.vi					
	X	X		X	SI			Rotation3d_Create_Quaternion.vi					
	X	X		X	I			Rotation3d_Create_InitialFinalVector.vi					
	X	X		X	SI			Rotation3d_Create_RollPitchYaw.vi					
	X	X		X	I			Rotation3d_Create_RotMatrix.vi					
	X	X			SI			Rotation3d_Div.vi					
	X	X		X	SI			Rotation3d_Equals.vi					
	X	X	X	X	SI			Rotation3d_GetAxisAngle.vi					
	X	X		X	SI			Rotation3d_GetQuaternion.vi					
	X	X		X	SI			Rotation3d_GetXYZ.vi					
	X	X		X	SI			Rotation3d_Interpolate.vi					
	X	X		X	SI			Rotation3d_Minus.vi					
	X	X		X	SI			Rotation3d_Plus.vi					
	X	X		X	SI			Rotation3d_RotateBy.vi					
	X	X		X	SI			Rotation3d_Times.vi					
	X	X		X	SI			Rotation3d_ToRotation2d.vi					
	X	X		X	SI			Rotation3d_UnaryMinus.vi					

TRANSFORM2D	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
	X	X		X	SI			Transform2d_Create_PosePose.vi	transform2d new(pose2d, pose2d)				
	X	X		X	SI			Transform2d_Create_TransRot.vi	transform2d new(translation2d, rotation2d)				
	X	X			SI			Transform2d_Div.vi					
	X	X		X	SI			Transform2d_Equals.VI	boolean equals(other transform2d)				
	X	X		X	SI			Transform2d_GetRotation.VI	rotation2d getRotation()	use cluster unpack			
	X	X		X	SI			Transform2d_GetTranslation.VI	translation2d getTranslation()	use cluster unpack			
	X	X	X	X	SI			Transform2d_GetXY.vi					
	X	X	X	X	SI			Transform2d_GetXYAngle.vi					
	X	X		X	SI			Transform2d_Inverse.vi	transform inverse()	new			
	X	X		X	SI			Transform2d_Plus.vi					
	X	X		X	SI			Transform2d_Times.vi	transform2d times(double scalar)				
									transform2d new()	can use cluster constant			

TRANSFORM3D	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
	X	X		X	SI			Transform3d_Create_Default.vi					
	X	X		X	SI			Transform3d_Create_Pose3dPose.3dvi					
	X	X		X	SI			Transform3d_Create_Trans3dRot3d.vi					

X	X			SI			Transform3d_Div.vi					
X	X		X	SI			Transform3d_Equals.VI					
X	X		X	SI			Transform3d_GetRotation3d.VI					
X	X		X	SI			Transform3d_GetTranslation3d.VI					
X	X	X	X	SI			Transform3d_GetXYZ.vi					
X	X		X	SI			Transform3d_Inverse.vi					
X	X		X	SI			Transform3d_Plus.vi					
X	X		X	SI			Transform3d_Times.vi					

TRANSLATION2D	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
	X	X		X	SI			Translation2d_Create_DistAng.vi					
	X	X		X	SI			Translation2d_Create.vi	translation2d new(double x, double y)				
	X	X			SI			Translation2d_Div.vi					
	X	X		X	SI			Translation2d_Equals.vi	boolean equals(translation other)				
	X	X		X	SI			Translation2d_GetAngle.vi					
	X	X		X	SI			Translation2d_GetDistance.vi	double getDistance(translation2d other)				
	X	X		X	SI			Translation2d_GetNorm.VI	double getNorm()	can use cluster unpack			
	X	X		X	SI			Translation2d_GetX.VI	double getX()	can use cluster unpack			
	X	X	X	X	SI			Translation2d_GetXY.VI					
	X	X		X	SI			Translation2d_GetY.VI	double getY()	can use cluster unpack			
	X	X		X	SI			Translation2d_Interpolate.vi					
	X	X		X	SI			Translation2d_Minus.vi	translation2d minus(translation2d other)				
	X	X		X	SI			Translation2d_Plus.vi	translation2d plus(translation2d other)				
	X	X		X	SI			Translation2d_RotateBy.vi	translation2d rotateBy(rotation2d other)				
	X	X		X	SI			Translation2d_Times.vi	translation2d times(double scalar)				
	X	X		X	SI			Translation2d_UnaryMinus.vi	translation2d unaryminus()				
									translation2d new()	can use cluster constant			
									translation2d div(double scalar)	can multiply by 1/scalar			

TRANSLATION3D	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
	X	X		X	SI			Translation3d_Create.vi					
	X	X		X	SI			Translation3d_Create_Default.vi					
	X	X		X	SI			Translation3d_Create_DistAng.vi					
	X	X		X	SI			Translation3d_Div.vi					
	X	X		X	SI			Translation3d_Equals.vi					
	X	X		X	SI			Translation3d_GetDistance.vi					
	X	X		X	SI			Translation3d_GetNorm.VI					
	X	X	X	X	SI			Translation3d_GetXYZ.vi					
	X	X		X	SI			Translation3d_Interpolate.vi					
	X	X		X	SI			Translation3d_Minus.vi					
	X	X		X	SI			Translation3d_Plus.vi					
	X	X		X	SI			Translation3d_RotateBy.vi					
	X	X		X	SI			Translation3d_Times.vi					
	X	X		X	SI			Translation3d_ToTranslation2d.vi					
	X	X		X	SI			Translation3d_UnaryMinus.vi					

TWIST2D	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
	X	X		X	SI			Twist2d_Create.vi	twist new(x, y, theta)				
	X	X		X	SI			Twist2d_Equals.VI	boolean equals(obj other)				
	X	X	X	X	SI			Twist2d_GetAll.VI					

														x
TWIST3D	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	
	X	X		X	SI	X		Twist3d_Create.vi						x
	X	X		X	SI	X		Twist3d_Equals.VI						x
	X	X	X	X	SI	X		Twist3d_GetAll.VI						x
KINEMATICS														x
														x
CHASSIS SPEEDS	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	
	X	X			SI			ChassisSpeeds_FromFieldRelativeChassisSpeeds.VI						x
	X	X		X	SI			ChassisSpeeds_FromFieldRelativeSpeeds.VI	chassisspeeds fromFieldRelativeSpeeds(double x, double y, double angvel, rotation2d robotangle)					x
	X	X	X	X	SI			ChassisSPeeds_GetXYOmega.vi						x
	X	X		X	SI			ChassisSpeeds_New.vi	chassisspeeds new (double xvel, double yvel, double angvel)					x
									chassisspeeds new ()	can use cluster constant				
DIFFERENTIAL DRIVE KINEMATICS	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	
	X	X		X	I	X		DiffKinematics_New.vi	diffDriveKine new(double trackWidth)					x
	X	X		X	X	X		DiffKinematics_toChassisSpeed.vi	chassisSpeeds toChassisSpeeds(diffDrWheelSpeeds)					x
	X	X		X	SI	X		DiffKinematics_toWheelSpeed.vi	diffDriveWheelSpeed toWheelSpeeds(chassisSpeeds)					x
DIFFERENTIAL DRIVE ODOMETRY	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	
			X					DiffOdometry_Execute.vi		DONT NEED				x
	X	X		X	X			DiffOdometry_Update.vi	pose2d update(rotation2d gyro, double leftdist, double right dist)	Incorporates enhanced reset				x
									diffDrOdom new(rotation gyro, pose initial)					x
									diffDrOdom new(rotation gyro)					x
									void resetPosition(pose2d, rotation2d)	incorporated into "update"				
DIFFERENTIAL DRIVE WHEEL SPEEDS	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	
									diffDrWheelSpeeds new()					x
									diffDrWheelSpeeds new(double leftVel, double rightVel)					x
	X	X		X	X			DiffWheel_Normalize.vi	void normalize(double maxVel)					x

[illegible]

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
MECANUM DRIVE MOTOR VOLTAGE													
	<i>nothing done</i>												

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
MECANUM DRIVE ODOMETRY			X					MecaOdometry_Execute.vi					
	X	X	X	X	X			MecaOdometry_GetKinematics.vi					
	X	X		X				MecaOdometry_GetPose.vi					
	X	X		X				MecaOdometry_New.vi					
	X	X		X				MecaOdometry_NewDefaultPose.vi					
	X	X		X				MecaOdometry_Reset.VI					
	X	X		X				MecaOdometry_Update.vi					
								MecaOdometry_UpdateWithTime.vi		Removed...			

[illegible]

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
MECANUM DRIVE WHEEL SPEEDS	X	X		X	S/			MecaWheel_New.Vi	public MecanumDriveWheelSpeeds(double frontLeftMetersPerSecond, double frontRightMetersPerSecond, double rearLeftMetersPerSecond, double rearRightMetersPerSecond)				
	X	X	X	X	S/			MecaWheel_GetAll.vi					
	X	X		X	X			MecaWheel_Normalize.vi	public void normalize(double attainableMaxSpeedMetersPerSecond)				

SWERVE DRIVE KINEMATICS	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
	X	X	X	X				SwerveKinematics_New4.VI		For 4 module drives			
	X	X	X	X				SwerveKinematics_NewX.VI		uses array as input			
	X	X	X	X				SwerveKinematics_NormalizeWheelSpeeds.vi	public static void normalizeWheelSpeeds(SwerveModuleState[] moduleStates, double attainableMaxSpeedMetersPerSecond)				
	X	X	X	X				SwerveKinematics_ToChassisSpeeds4.VI		For 4 module drives			
	X	X	X	X				SwerveKinematics_ToChassisSpeedsX.VI		uses array as input			
	X	X		X				SwerveKinematics_ToSwerveModuleStates.VI	public SwerveModuleState[] toSwerveModuleStates(ChassisSpeeds chassisSpeeds, Translation2d centerOfRotationMeters)				
	X	X		X				SwerveKinematics_ToSwerveModuleStatesZeroCenter.VI	public SwerveModuleState[] toSwerveModuleStates(ChassisSpeeds chassisSpeeds)				
	X	X		X				SwerveKinematics_ToTwist2d4.VI					
	X	X		X				SwerveKinematics_ToTwist2dX.VI					
								public SwerveDriveKinematics(Translation2d... wheelsMeters)	variable parameters (replace with array and "4" calls)				
								public ChassisSpeeds toChassisSpeeds(SwerveModuleState... wheelStates)	variable parameters (replace with array and "4" calls)				
SWERVE DRIVE ODOMETRY	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
								SwerveOdometry_Execute4.vi					
								SwerveOdometry_ExecuteX.vi					
	X	X		X				SwerveOdometry_GetPosition.VI	public Pose2d getPoseMeters()				
	X	X		X				SwerveOdometry_New.VI	public SwerveDriveOdometry(SwerveDriveKinematics kinematics, Rotation2d gyroAngle, Pose2d initialPose)				
	X	X		X				SwerveOdometry_NewZeroCenter.VI	public SwerveDriveOdometry(SwerveDriveKinematics kinematics, Rotation2d gyroAngle)				
	X	X		X				SwerveOdometry_ResetPosition.VI	public void resetPosition(Pose2d pose, Rotation2d gyroAngle)				
	X	X	X	X				SwerveOdometry_Update4.VI		For 4 module drives			
								SwerveOdometry_UpdateWithTime4.VI		REMOVED			
								SwerveOdometry_UpdateWithTimeX.VI		REMOVED			
X	X	X	X				SwerveOdometry_UpdateX.VI		uses array as input				
								public Pose2d updateWithTime(double currentTimeSeconds, Rotation2d gyroAngle, SwerveModuleState... moduleStates)	variable parameters (replace with array and "4" calls)				
								public Pose2d update(Rotation2d gyroAngle, SwerveModuleState... moduleStates)	variable parameters (replace with array and "4" calls)				
SWERVE DRIVE MODULE POSITIONS	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
	X	X		X	SI			SwerveModulePosition_CompareTo.vi					
	X	X		X	SI			SwerveModulePosition_Get.vi					
	X	X		X	SI			SwerveModulePosition_New.vi					
SWERVE DRIVE MODULE STATE	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
	X	X		X	SI			SwerveModuleState_CompareTo.vi	public int compareTo(SwerveModuleState o)				
	X	X		X	SI			SwerveModuleState_Get.vi					
	X	X		X	SI			SwerveModuleState_New.vi	public SwerveModuleState(double speedMetersPerSecond, Rotation2d angle)				

X	X		X		X		SplineHelp_GetCubicCtrlVectorsFromWayPts.vi	public static Spline.ControlVector[] getCubicControlVectorsFromWaypoints(Pose2d start, Translation2d[] interiorWaypoints, Pose2d end)					
X	X	X	X				SplineHelp_GetCubicCtrlVectorsFromWeightedWayPts.vi						
X	X	X	No				SplineHelp_GetCubicSpline_Calc1.vi		internal				
X	X	X	No				SplineHelp_GetCubicSpline_Calc2.vi		internal				
X	X	X	No				SplineHelp_GetCubicSpline_Calc3.vi		internal				
X	X		X		X		SplineHelp_getCubicSplinesFromControlVectors.vi	public static CubicHermiteSpline[] getCubicSplinesFromControlVectors(Spline.ControlVector start, Translation2d[] waypoints, Spline.ControlVector end)					
X	X		X	SI			SplineHelp_GetQuinticCtrlVector.vi	private static Spline.ControlVector getQuinticControlVector(double scalar, Pose2d point)					
							SplineHelp_GetQuinticCtrlVectorsFromWayPts.vi	public static List<Spline.ControlVector> getQuinticControlVectorsFromWaypoints(List<Pose2d> waypoints)	REMOVED 2762				
							SplineHelp_GetQuinticCtrlVectorsFromWeightedWayPts.vi		REMOVED 2762				
X	X		X				SplineHelp_getQuinticSplinesFromControlVectors.vi	public static QuinticHermiteSpline[] getQuinticSplinesFromControlVectors(Spline.ControlVector[] controlVectors)					
X	X	X	X				SplineHelp_GetQuinticSplinesFromWeightedWayPts.vi		New 2762				
X	X		X				SplineHelp_GetQuinticSplinesFromWayPts.vi		New 2762				
X	X		No				SplineHelp_ThomasAlgorithm.vi	private static void thomasAlgorithm(double[] a, double[] b, double[] c, double[] d, double[] solutionVector)	internal				

SPLINE PARAMETERIZER	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	
	X	X		X				SplineParam_Spline_T0_T1.vi	public static List<PoseWithCurvature> parameterize(Spline spline, double t0, double t1)					x
	X	X		X		X		SplineParam_Spline.vi	public static List<PoseWithCurvature> parameterize(Spline spline)					x
	X	X	X	No				SplineParam_StackGet.vi		internal				x
	X	X	X	No				SplineParam_StackPop.vi		internal				x
	X	X	X	No				SplineParam_StackPush.vi		internal				x

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TRAJECTORY

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TRAJECTORY	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	
	X	X		X				Trajectory_Concatenate.vi						x
	X	X		X				Trajectory_equals.vi	boolean equals(other obj)	FUTURE				x
	X	X		X	SI			Trajectory_GetStates.vi	public List<State> getStates()	not needed, use unpack				x
	X	X		X	SI			Trajectory_GetTotalTime.vi	public double getTotalTimeSeconds()	not needed, use unpack				x
	X	X		No	SI			Trajectory_lerp_double.vi	private static double lerp(double startValue, double endValue, double t)	internal				x
	X	X		No	SI			Trajectory_lerp_Pose.vi	private static Pose2d lerp(Pose2d startValue, Pose2d endValue, double t)	internal				x
	X	X		X	SI			Trajectory_New_Empty.vi						x
	X	X		X	SI			Trajectory_New.vi	public Trajectory(final List<State> states)					x
	X	X		X				Trajectory_RelativeTo.vi	public Trajectory relativeTo(Pose2d pose)					x
	X	X		X				Trajectory_Sample.vi	public State sample(double timeSeconds)					x
	X	X	X	X				Trajectory_SampleReverse.vi		Sample in reverse order. Negate sample.				x
	X	X		X				Trajectory_TransformBy.vi	public Trajectory transformBy(Transform2d transform)					x
									public Pose2d getInitialPose()	can use cluster unpack, array index				x

TRAJECTORY_STATE	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	x
	X	X		X	SI			TrajectoryState_Equals.vi	boolean equals(other obj)					x
	X	X	X	X	SI			TrajectoryState_GetAll.vi						x
	X	X		X	SI			TrajectoryState_GetPose.vi						x
	X	X		X				TrajectoryState_Interpolate.vi	State interpolate(State endValue, double i)					x
	X	X		X	SI			TrajectoryState_New.vi	public State(double timeSeconds, double velocityMetersPerSecond, double accelerationMetersPerSecondSq, Pose2d poseMeters, double curvatureRadPerMeter)					x
									public State()					
TRAJECTORY CONFIG	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	x
	X	X		X				TrajectoryConfig_AddConstraint.vi	public TrajectoryConfig addConstraint(TrajectoryConstraint constraint)	Implemented differently, can't duplicate.				x
	X	X		X				TrajectoryConfig_AddConstraints.vi	public TrajectoryConfig addConstraints(List<? extends TrajectoryConstraint> constraints)	Implemented differently, can't duplicate.				x
	X	X		X	SI			TrajectoryConfig_Create.vi	public TrajectoryConfig(double maxVelocityMetersPerSecond, double maxAccelerationMetersPerSecondSq)					x
	X	X		X				TrajectoryConfig_GetCentripetalAccel.vi						x
	X	X	X	X				TrajectoryConfig_GetConstraints.vi	public List<TrajectoryConstraint> getConstraints()	Implemented differently, can't duplicate.				x
	X	X		X				TrajectoryConfig_GetEndVelocity.vi	public double getEndVelocity()	can use cluster unpack				x
	X	X		X				TrajectoryConfig_GetKinematicsDiffDrive.vi						x
	X	X		X				TrajectoryConfig_GetKinematicsMecanumfDrive.vi						x
	X	X		X				TrajectoryConfig_GetKinematicsSwerveDrive.vi						x
	X	X	X	X				TrajectoryConfig_GetMaxVelAccel.vi						x
	X	X		X				TrajectoryConfig_GetStartVelocity.vi	public double getStartVelocity()	can use cluster unpack				x
	X	X		X				TrajectoryConfig_GetVoltageDiffDrive.vi						x
	X	X		X				TrajectoryConfig_IsReversed.vi	public boolean isReversed()	can use cluster unpack				x
	X	X	X	X	SI			TrajectoryConfig_setCentripetalAccel.vi						x
	X	X		X				TrajectoryConfig_SetEndVelocity.vi	public TrajectoryConfig setEndVelocity(double endVelocityMetersPerSecond)					x
	X	X		X	SI			TrajectoryConfig_setKinematicsDiffDrive.vi	public TrajectoryConfig setKinematics(DifferentialDriveKinematics kinematics)					x
	X	X		X	SI			TrajectoryConfig_setKinematicsMecanumfDrive.vi	public TrajectoryConfig setKinematics(MecanumDriveKinematics kinematics)					x
	X	X		X	SI			TrajectoryConfig_setKinematicsSwerveDrive.vi	public TrajectoryConfig setKinematics(SwerveDriveKinematics kinematics)					x
	X	X		X	SI			TrajectoryConfig_setReversed.vi	public TrajectoryConfig setReversed(boolean reversed)					x
	X	X		X				TrajectoryConfig_SetStartVelocity.vi	public TrajectoryConfig setStartVelocity(double startVelocityMetersPerSecond)					x
	X	X	X	X	SI			TrajectoryConfig_setVoltageDiffDrive.vi						x
									public double getMaxVelocity()	Created function to return both				x
									public double getMaxAcceleration()	Created function to return both				x
								NOTE ADD OTHER "SET" ROUTINES FOR OTHER CONSTRAINTS HERE, SINCE NEW CONSTRAINTS ARE SPECIFIC AND NOT GENERIC.						x
TRAJECTORY GENERATE	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	x
	X	X		X				TrajectoryGenerate_Make_Cubic_CtrlVect.vi	public static Trajectory generateTrajectory(Spline.ControlVector initial, List<Translation2d> interiorWaypoints, Spline.ControlVector end, TrajectoryConfig config)	uses cubic splines				x

X	X		X				TrajectoryGenerate_Make_Cubic.vi	public static Trajectory generateTrajectory(Pose2d start, List<Translation2d> interiorWaypoints, Pose2d end, TrajectoryConfig config)	uses cubic splines				x
X	X	X	X				TrajectoryGenerate_Make_Generic.vi	Helper to bring these all together....	Use this one!!!				x
X	X		X				TrajectoryGenerate_Make_Quintic_CtrlVect.vi	public static Trajectory generateTrajectory(ControlVectorList controlVectors, TrajectoryConfig config)	uses quintic splines				x
X	X	X	X				TrajectoryGenerate_Make_Quintic_Weighted.vi		New 2762				x
X	X		X				TrajectoryGenerate_Make_Quintic.vi	public static Trajectory generateTrajectory(List<Pose2d> waypoints, TrajectoryConfig config)	uses quintic splines				x
X	X		X				TrajectoryGenerate_splinePointsFromSplines.vi	public static List<PoseWithCurvature> splinePointsFromSplines(Spline[] splines)					x

TRAJECTORY GENERATE (Control Vector)	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	
									public ControlVectorList(int initialCapacity)	may not need, just data				x
									public ControlVectorList()	may not need, just data				x
									public ControlVectorList(Collection<? extends Spline.ControlVector> collection)	may not need, just data				x
														x
														x

TRAJECTORY PARAMETERIZE	Implemented	Documented	Not WPLIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
	X	X	X	No				TrajectoryParam_calcStuffFwd.vi					
	X	X	X	No				TrajectoryParam_calcStuffRev.vi					
	X	X		No				TrajectoryParam_enforceAccel.vi	private static void enforceAccelerationLimits(boolean reverse, List<TrajectoryConstraint> constraints, ConstrainedState state)	This routines needs to be changed when new constraints are added.			
	X	X	X	No				TrajectoryParam_enforceVelocity.vi		This routines needs to be changed when new constraints are added.			
	X	X		X				TrajectoryParam_timeParam.vi	public static Trajectory timeParameterizeTrajectory(List<PoseWithCurvature> points. List<TrajectoryConstraint> constraints, double startVelocityMetersPerSecond, double endVelocityMetersPerSecond, double maxVelocityMetersPerSecond, double maxAccelerationMetersPerSecondSq, boolean reversed)				

TRAJECTORY PARAMETERIZE CONSTRAINED STATE	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	
	X	X		X				ConstrainedState_New.vi	ConstrainedState(PoseWithCurvature pose, double distanceMeters, double maxVelocityMetersPerSecond, double minAccelerationMetersPerSecondSq, double maxAccelerationMetersPerSecondSq)					x
	X	X	X	X				ConstrainedState_SetMaxAccel.vi						x
	X	X	X	X				ConstrainedState_SetMinAccel.vi						x
	X	X	X	X				ConstrainedState_SetVelAccel.vi						x
	X	X	X	X				ConstrainedState_SetVelocity.vi						x
									ConstrainedState()					x
														x
														x

TRAJECTORY UTIL	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	
	X	X		X				TrajectoryUtil_fromPathWeaverJSON.vi	public static Trajectory fromPathweaverJson(Path path)					x
	X	X	X	X	X			TrajectoryUtil_MakeWeightedWayPoint_ENG.vi						x

DIFF DRIVE VOLTAGE CONSTRAINT

X	X		X				DiffDriveVoltageConstraint_getMaxVelocity.vi	public double getMaxVelocityMetersPerSecond(Pose2d poseMeters, double curvatureRadPerMeter, double velocityMetersPerSecond)	
X	X		X				DiffDriveVoltageConstraint_getMinMaxAccel.vi	public MinMax getMinMaxAccelerationMetersPerSecondSq(Pose2d poseMeters, double curvatureRadPerMeter, double velocityMetersPerSecond)	
X	X		X	SI			DiffDriveVoltageConstraint_New.vi	public DifferentialDriveVoltageConstraint(SimpleMotorFeedforward feedforward, DifferentialDriveKinematics kinematics, double maxVoltage)	

ELLIPTICAL REGION CONSTRAINT

Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes
X	X		X				EllipRegionConstraint_getMaxVelocity.vi		
X	X		X				EllipRegionConstraint_getMinMaxAccel.vi		
X	X		X				EllipRegionConstraint_IsPoseInRegion.vi		
X	X		X				EllipRegionConstraint_New.vi		

JERK CONSTRAINT

Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes
/		X					JerkConstraint_getMaxVelocity.vi	Routine exists, it is just a shell	FUTURE
/		X					JerkConstraint_getMinMaxAccel.vi	Routine exists, it is just a shell	FUTURE
/		X		SI			JerkConstraint_New.vi	Routine exists, it is just a shell	FUTURE

MAX VELOCITY CONSTRAINT

Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes
X	X		X	SI			MaxVelocityConstraint_getMaxVelocity.vi		
X	X		X	SI			MaxVelocityConstraint_getMinMaxAccel.vi		
X	X		X	SI			MaxVelocityConstraint_New.vi		

MECANUM DRIVE KINEMATICS CONSTRAINT

Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes
X	X		X				MecaDriveKinematicsConstraint_getMaxVelocity.vi		
X	X		X				MecaDriveKinematicsConstraint_getMinMaxAccel.vi		
X	X		X	SI			MecaDriveKinematicsConstraint_New.vi		

RECTANGULAR REGION CONSTRAINT

Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes
X	X		X				RectRegionConstraint_getRectRegion.vi		
X	X		X				RectRegionConstraint_getMinMaxAccel.vi		
X	X		X				RectRegionConstraint_IsPoseInRegion.vi		
X	X		X				RectRegionConstraint_New.vi		

SWERVE DRIVE KINEMATICS CONSTRAINT

Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes
X	X		X				SwerveDriveKinematicsConstraint_getMaxVelocity.vi	public double getMaxVelocityMetersPerSecond(Pose2d poseMeters, double curvatureRadPerMeter, double velocityMetersPerSecond)	
X	X		X				SwerveDriveKinematicsConstraint_getMinMaxAccel.vi	public MinMax getMaxMinMaxAccelerationMetersPerSecondSq(Pose2d poseMeters, double curvatureRadPerMeter, double velocityMetersPerSecond)	
X	X		X	SI			SwerveDriveKinematicsConstraint_New.vi	Newpublic SwerveDriveKinematicsConstraint(final SwerveDriveKinematics kinematics, double maxSpeedMetersPerSecond)	Can use cluster pack for now

TRAJECTORY CONSTRAINT

Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes
X	X	X	X				TrajConstraint_GetMaxVelocity.vi		
X	X	X	X				TrajConstraint_GetMinMaxAccel.vi		
X	X	X	X				TrajConstraint_GetType.vi		

TRAJECTORY CONSTRAINT (Min Max)

Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes
X	X		X	SI			Constraint_MinMax_New.vi	Constraint_MinMax_New	
X	X		X	SI			Constraint_MinMax_NewMinMax.VI	Constraint_MinMax_New	

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UTILITY

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THESE ROUTINES ARE SPECIFIC TO LABVIEW. THEY DO NOT HAVE A
JAVA / C++ WPILIB EQUIVALENT

UTIL

Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes
X	X	X	X	SI			Util_ApproxEqual.vi		
X	X	X	X				Util_Array_PoseWCurv_to_XY.vi		
X	X	X	X	SI			Util_CalcDist.vi		
X	X	X	X	SI			Util_GetLibraryVersion.vi		
X	X	X	X	SI			Util_GetLibUsage.vi		
X	X	X	X				Util_GetTime.vi		Once tested completely, this should be optimized!
X	X	X	No	N/A			Util_LibraryGlobals.vi		Global Variables – no block diag.
X	X	X	X				Util_Trajectory_Absolute_To_Relative.vi		
X	X	X	X				Util_Trajectory_ReadFile.vi		
X	X	X	X				Util_Trajectory_to_XY.vi		
X	X	X	No				Util_Trajectory_WriteFile_Config.vi		internal
X	X	X	No				Util_Trajectory_WriteFile_OneState.vi		internal
X	X	X	X				Util_Trajectory_WriteFile_PathFinder.vi		
X	X	X	No				Util_Trajectory_WriteFile_PathFinderConfig.vi		internal
X	X	X	X				Util_Trajectory_WriteFile_Pathweaver.vi		
X	X	X	No				Util_Trajectory_WriteFile_States.vi		internal
X	X	X	No				Util_Trajectory_WriteFile_WayPoints.vi		internal
X	X	X	X				Util_Trajectory_WriteFile.vi		

X	X	X	X				Util_TrajectoryState_Meters_To_Inches.vi		
X	X	X	X				Util_TrajState_to_DiffDrive_WheelPos.vi		
X	X	X	X				Util_DispWaypoint_Eng_To_SI.vi		
X	X	X	X				Util_DispWaypoint_To_CubicInput.vi		
X	X	X	X				Util_DispWaypoint_To_QuinticInput.vi		
X	X	X	X				Util_DispWeightedWaypiont_Eng_To_WeightedWaypoint		
X	X	X	No				Util_DispWeightedWayPoint_To_WeightedWayPoint.vi		Sorry about the confusing name..

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CONVERSIONS

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	Implemented	Documented	Not WPI/LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes
CONV	X	X	X	X	SI			Conv_AngleDegrees_Heading.vi		
	X	X	X	X	SI			Conv_AngleRadians_Heading.vi		
	X	X	X	X	SI			Conv_Centimeters_Meters.vi		
	X	X	X	X	SI			Conv_Deg_Radians.vi		
	X	X	X	X	SI			Conv_Deg_Rotations.vi		
	X	X	X	X	SI			Conv_Feet_Meters.vi		
	X	X	X	X	SI			Conv_GyroDegrees_Heading.vi		
	X	X	X	X	SI			Conv_Heading_AngleRadians.vi		
	X	X	X	X	SI			Conv_Inches_Meters.vi		
	X	X	X	X	SI			Conv_Kilograms_Pounds.vi		
	X	X	X	X	SI			Conv_Meters_Feet.vi		
	X	X	X	X	SI			Conv_Meters_Inches.vi		
	X	X	X	X	SI			Conv_Pose2d_SI_Eng.vi		
	X	X	X	X	SI			Conv_Pounds_Kilograms.vi		
	X	X	X	X	SI			Conv_Radians_Deg.vi		
	X	X	X	X	SI			Conv_Radians_Rotations.vi		
	X	X	X	X	SI			Conv_Rotations_Deg.vi		
	X	X	X	X	SI			Conv_Rotations_Radians.vi		
	X	X	X	X	SI			Conv_Yards_Meters.vi		

	Implemented	Documented	Not WPI/LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes
UNITS	X	X		X	SI			Units_DegreesToRadians.vi		
	X	X		X	SI			Units_DegreesToRotations.vi		
	X	X		X	SI			Units_FeetToMeters.vi		
	X	X		X	SI			Units_InchesToMeters.vi		
	X	X		X	SI			Units_MetersToFeet.vi		
	X	X		X	SI			Units_MetersToInches.vi		
	X	X		X	SI			Units_MillisecondsToSeconds.vi		
	X	X		X	SI			Units_RadiansPerSecondToRotationsPerMinute.vi		
	X	X		X	SI			Units_RadiansToDegrees.vi		
	X	X		X	SI			Units_RadiansToRotations.vi		
	X	X		X	SI			Units_RotationsPerMinuteToRadiansPerSecond.vi		
	X	X		X	SI			Units_RotationsToDegrees.vi		
	X	X		X	SI			Units_RotationsToRadians.vi		
	X	X		X	SI			Units_SecondsToMilliseconds.vi		

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PATHFINDER UTIL

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THESE ROUTINES ARE SPECIFIC TO LABVIEW. THEY DO NOT HAVE A
JAVA / C++ WPILIB EQUIVALENT

													x	
PATHFINDERUTIL	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes				
	X	X	X	X				PathfinderUtil_Continuous_Heading_Difference.vi					x	
	X	X	X	X				PathfinderUtil_OptimizeTrajectoryStates.vi					x	
	X	X	X	X				PathfinderUtil_ToTrajectory.vi					x	
	X	X	X	X				PathfinderUtil_ToTrajectoryStates.vi					x	
													x	
STATE SPACE MODEL													x	
													x	
DC MOTOR	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	
	X	X		X	SI			DCMotor_GetAndymark9015.vi						x
	X	X		X	SI			DCMotor_GetAndymarkRs775_125.vi						x
	X	X		X	SI			DCMotor_GetBag.vi						x
	X	X		X	SI			DCMotor_GetBanebotsRs550.vi						x
	X	X		X	SI			DCMotor_GetBanebotsRs775.vi						x
	X	X		X	SI			DCMotor_GetCIM.vi						x
	X	X		X	SI			DCMotor_GetCurrent.vi						x
	X	X		X	SI			DCMotor_GetFalcon500.vi						x
	X	X		X	SI			DCMotor_GetMiniCIM.vi						x
	X	X		X	SI			DCMotor_GetNEO.vi						x
	X	X		X	SI			DCMotor_GetNEO550.vi						x
	X	X		X	SI			DCMotor_GetRomiBuiltIn.vi						x
	X	X		X	SI			DCMotor_GetVex775Pro.vi						x
	X	X		X	SI			DCMotor_New.vi						x
	X	X		X	SI			DCMotor_PickMotor.vi						x
														x
	LINEAR SYSTEM ID	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
X		X		X				LinearSystemId_CreateDCMotorSystem.vi						x
X		X		X				LinearSystemId_CreateDriveTrainVelocitySystem.vi		Update to use create matrix				x
X		X		X				LinearSystemId_CreateElevatorSystem.vi		Update to use create matrix				x
X		X		X				LinearSystemId_CreateFlywheelSystem.vi		Update to use create matrix				x
X		X		X				LinearSystemId_CreateSingleJointedArmSystem.vi		Update to use create matrix				x
X		X		X				LinearSystemId_IdentifyDriveTrainSystem.vi		Update to use create matrix				x
X		X		X				LinearSystemId_IdentifyPositionSystem.vi		Update to use create matrix				x
X		X		X				LinearSystemId_IdentifyVelocitySystem.vi		Update to use create matrix				x
														x
STATE SPACE ESTIMATION														x
														x
DIFFERENTIAL DRIVE POSE ESTIMATOR	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	
	X	X		X				DiffDrivePoseEst_AddVisionMeasurement.vi						x

X	X		X			DiffDrivePoseEst_FillStateVector.vi					
X	X		X			DiffDrivePoseEst_GetEstimatedPosition.vi					
X	X		X			DiffDrivePoseEst_Kalman_F_Callback.vi					
X	X		X			DiffDrivePoseEst_Kalman_H_Callback.vi					
X	X		X			DiffDrivePoseEst_New.vi					
X	X		X			DiffDrivePoseEst_ResetPosition.vi					
X	X		X			DiffDrivePoseEst_SetVisionMeasurementStdDevs.vi					
X	X		X			DiffDrivePoseEst_Update.vi					
X	X		X			DiffDrivePoseEst_UpdateWithTime.vi					
X	X		X			DiffDrivePoseEst_VisionCorrect_Callback.vi					
X	X		X			DiffDrivePoseEst_VisionCorrect_Kalman_H_Callback.vi					

EXTENDED KALMAN FILTER	Implemented	Documented	Not WPI/LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
	X	X		X				ExtendedKalmanFilter_Correct_OnlyUY.vi					
	X	X		X				ExtendedKalmanFilter_Correct.vi		Just a shell, not functional!			
	X	X		X				ExtendedKalmanFilter_GetP_Single.vi					
	X	X		X				ExtendedKalmanFilter_GetP.vi					
	X	X		X				ExtendedKalmanFilter_GetXHat_Single.vi					
	X	X		X				ExtendedKalmanFilter_GetXHat.vi					
	X	X		X				ExtendedKalmanFilter_New.vi					
	X	X		X				ExtendedKalmanFilter_Predict.vi					
	X	X		X				ExtendedKalmanFilter_Reset.vi					
	X	X		X				ExtendedKalmanFilter_SetP.vi					
	X	X		X				ExtendedKalmanFilter_SetXHat_Single.vi					
	X	X		X				ExtendedKalmanFilter_SetXHat.vi					

KALMAN FILTER	Implemented	Documented	Not WPI/LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
	X	X		X		X		KalmanFilter_Correct.vi					
	X	X		X				KalmanFilter_GetK					
	X	X		X				KalmanFilter_GetK_Single.vi					
	X	X		X				KalmanFilter_GetXHat					
	X	X		X		X		KalmanFilter_GetXHaT_Single					
	X	X		X		X		KalmanFilter_New.vi					
	X	X		X		X		KalmanFilter_Predict.vi					
	X	X		X				KalmanFilter_Reset.vi					
	X	X		X				KalmanFilter_SetXHat					
	X	X		X		X		KalmanFilter_SetXHat_Single					

KALMAN FILTER LATENCY COMPENSATOR	Implemented	Documented	Not WPI/LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
	X	X		X				KalmanFilterLatencyComp_AddObserverState.vi					
	X	X		X				KalmanFilterLatencyComp_ApplyPastGlobalMeas_FuncGroup.vi					
	X	X		X				KalmanFilterLatencyComp_ApplyPastGlobalMeasurement_UKF.vi					
	X	X		X				KalmanFilterLatencyComp_FindClosestMeasurement.vi					
	X	X		X				KalmanFilterLatencyComp_New.vi					
	X	X		X				KalmanFilterLatencyComp_Observer_New.vi					
	X	X		X				KalmanFilterLatencyComp_Reset.vi					

	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
MECANUM DRIVE POSE ESTIMATOR								MecaDrivePoseEst_AddVisionMeasurement_StdDev.vi					
	X	X		X				MecaDrivePoseEst_AddVisionMeasurement.vi					
	X	X		X				MecaDrivePoseEst_GetEstimatedPosition.vi					
	X	X		No				MecaDrivePoseEst_Kalman_F_Callback.vi					
	X	X		No				MecaDrivePoseEst_Kalman_H_Callback.vi					
	X	X		X				MecaDrivePoseEst_New.vi					
	X	X		X				MecaDrivePoseEst_ResetPosition.vi					
	X	X		X				MecaDrivePoseEst_SetVisionMeasurementStdDevs.vi					
	X	X		X				MecaDrivePoseEst_Update.vi					
	X	X		X				MecaDrivePoseEst_UpdateWithTime.vi					
	X	X		No				MecaDrivePoseEst_VisionCorrect_Callback.vi					
	X	X		No				MecaDrivePoseEst_VisionCorrect_Kalman_H_Callback.vi					

	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
SWERVE DRIVE POSE ESTIMATOR								SwerveDrivePoseEst_AddVisionMeasurement_StdDev.vi					
	X	X		X				SwerveDrivePoseEst_AddVisionMeasurement.vi					
	X	X		X				SwerveDrivePoseEst_GetEstimatedPosition.vi					
	X	X		X				SwerveDrivePoseEst_Kalman_F_Callback.vi					
	X	X		X				SwerveDrivePoseEst_Kalman_H_Callback.vi					
	X	X		X				SwerveDrivePoseEst_New.vi					
	X	X		X				SwerveDrivePoseEst_ResetPosition.vi					
	X	X		X				SwerveDrivePoseEst_SetVisionMeasurementStdDevs.vi					
	X	X		X				SwerveDrivePoseEst_Update.vi					
	X	X		X				SwerveDrivePoseEst_UpdateWithTime.vi					
	X	X		X				SwerveDrivePoseEst_VisionCorrect_Callback.vi					
	X	X		X				SwerveDrivePoseEst_VisionCorrect_Kalman_H_Callback.vi					

	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
UNSCENTED KALMAN FILTER	X	X		X				UnscentedKalmanFilter_Correct_FuncGroup.vi					
	X	X		X				UnscentedKalmanFilter_Correct_OnlyUY.vi					
	X	X		X				UnscentedKalmanFilter_Correct_OnlyUYR.vi					
	X	X		X				UnscentedKalmanFilter_Correct.vi					
	X	X		X				UnscentedKalmanFilter_GetP_Single.vi					
	X	X		X				UnscentedKalmanFilter_GetP.vi					
	X	X		X				UnscentedKalmanFilter_GetXHat_Single.vi					
	X	X		X				UnscentedKalmanFilter_GetXHat.vi					
	X	X		X				UnscentedKalmanFilter_New_Default.vi					
	X	X		X				UnscentedKalmanFilter_New_FuncGroup.vi					
	X	X		X				UnscentedKalmanFilter_New.vi					
	X	X		X				UnscentedKalmanFilter_Predict.vi					
	X	X		X				UnscentedKalmanFilter_Reset.vi					
	X	X		X				UnscentedKalmanFilter_SetP.vi					
	X	X		X				UnscentedKalmanFilter_SetXHat_Single.vi					
	X	X		X				UnscentedKalmanFilter_SetXHat.vi					
	X	X		X				UnscentedKalmanFilter_Transform.vi					

STATE SPACE CONTROL

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
CONTROL AFFINE PLANT INVERSION FEEDFORWARD													
DIFFERENTIAL DRIVE ACCELERATION LIMITER													
	X	X		X		X		DiffDrvAccelLimit_Calculate.vi					
	X	X		X		X		DiffDrvAccelLimit_New.vi					
IMPLICIT MODEL FOLLOWER													
	X	X		X		X		ImplModelFollow_Calculate.vi					
	X	X		X		X		ImplModelFollow_GetU.vi					
	X	X		X		X		ImplModelFollow_GetU_Single.vi					
	X	X		X		X		ImplModelFollow_New.vi					
	X	X		X		X		ImplModelFollow_New_Plant.vi					
	X	X		X		X		ImplModelFollow_Reset.vi					
LINEAR PLANT INVERSION FEEDFORWARD													
	X	X		X				LinearPlntInvFF_Calculate_NextR.vi					
	X	X		X				LinearPlntInvFF_Calculate.vi					
	X	X		X				LinearPlntInvFF_GetR_Single.vi					
	X	X		X				LinearPlntInvFF_GetR.vi					
	X	X		X				LinearPlntInvFF_GetUff_Single.vi					
	X	X		X				LinearPlntInvFF_GetUff.vi					
	X	X		X				LinearPlntInvFF_New_Plant.vi					
	X	X		X				LinearPlntInvFF_New.vi					
	X	X		X				LinearPlntInvFF_Reset_Initial.vi					
	X	X		X				LinearPlntInvFF_Reset_Zero.vi					
LINEAR QUADRATIC REGULATOR													
	X	X		X				LinearQuadraticRegulator_Calculate_NextR.vi					
	X	X						LinearQuadraticRegulator_Calculate.vi					
	X	X		X				LinearQuadraticRegulator_GetK_Single.vi		NOT ORIGINAL...			

X	X		X		X		LinearQuadraticRegulator_GetK.vi								
X	X		X				LinearQuadraticRegulator_GetR_Single.vi								
X	X		X				LinearQuadraticRegulator_GetR.vi								
X	X		X				LinearQuadraticRegulator_GetU_Single.vi								
X	X		X				LinearQuadraticRegulator_GetU.vi								
X	X		X		X		LinearQuadraticRegulator_LatencyCompensate.vi			Routine exists, but it only has interger raise matrix to power.					
X	X		X				LinearQuadraticRegulator_New_ELMS.vi								
X	X		X				LinearQuadraticRegulator_New_N.vi								
							LinearQuadraticRegulator_New_Raw.vi								
X	X		X		X		LinearQuadraticRegulator_New_SystemELMS.vi								
X	X		X				LinearQuadraticRegulator_New.vi								
X	X		X				LinearQuadraticRegulator_Reset.vi								

	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
LINEAR SYSTEM	X	X		X	I			LinearSystem_CalculateX.vi					
	X	X		X	I			LinearSystem_CalculateY.vi					
	X	X		X	SI			LinearSystem_GetA.vi					
	X	X		X	SI			LinearSystem_GetAElement.vi					
	X	X		X	SI			LinearSystem_GetB.vi					
	X	X		X	SI			LinearSystem_GetBElement.vi					
	X	X		X	SI			LinearSystem_GetC.vi					
	X	X		X	SI			LinearSystem_GetCElement.vi					
	X	X		X	SI			LinearSystem_GetD.vi					
	X	X		X	SI			LinearSystem_GetDElement.vi					
	X	X		X	SI			LinearSystem_New.vi					

	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
LINEAR SYSTEM LOOP	X	X		X				LinearSystemLoop_ClampInput.vi					
	X	X		X				LinearSystemLoop_Correct.vi					
								LinearSystemLoop_GetClampFunction.vi					
	X	X		X				LinearSystemLoop_GetController.vi					
	X	X		X				LinearSystemLoop_GetError_Single.vi					
	X	X		X				LinearSystemLoop_GetError.vi					
	X	X		X				LinearSystemLoop_GetFeedForward.vi					
	X	X		X				LinearSystemLoop_GetNextR_Single.vi					
	X	X		X				LinearSystemLoop_GetNextR.vi					
	X	X		X				LinearSystemLoop_GetObserver.vi					
	X	X		X				LinearSystemLoop_GetU_Row.vi					
	X	X		X				LinearSystemLoop_GetU.vi					
	X	X		X				LinearSystemLoop_GetXHat_Single.vi					
	X	X		X				LinearSystemLoop_GetXHat.vi					
								LinearSystemLoop_New_BBB					
								LinearSystemLoop_New_LinearSystem_ClampFunc					
	X	X		X				LinearSystemLoop_New_LinearSystem_ClampVal.vi					
	X	X		X				LinearSystemLoop_New.vi					
	X	X		X				LinearSystemLoop_Predict.vi					
	X	X		X				LinearSystemLoop_Reset.vi					
								LinearSystemLoop_SetClampFunction.vi					
								LinearSystemLoop_SetNextR_Some.vi					
	X	X		X				LinearSystemLoop_SetNextR.vi					
								LinearSystemLoop_SetXHat_Single.vi					
								LinearSystemLoop_SetXHat.vi					

LTV DIFFERENTIAL DRIVE CONTROLLER	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	x
	X	X		X				LTVDiffDriveCtrl_Calculate.vi						x
	X	X		X				LTVDiffDriveCtrl_New.vi						x
	X	X		X				LTVDiffDriveCtrl_Calculate_TrajState.vi						x
	X	X		X				LTVDiffDriveCtrl_Calculate_SetTolerance.vi						x
	X	X		X				LTVDiffDriveCtrl_Calculate_AtReference.vi						x
														x
LTV UNICYCLE CONTROLLER	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	x
	X	X		X		X		LTVUnicycleCtrl_AtReference.vi						x
	X	X		X		X		LTVUnicycleCtrl_Calculate_TrajState.vi						x
	X	X		X		X		LTVUnicycleCtrl_Calculate.vi						x
	X	X		X		X		LTVUnicycleCtrl_New.vi						x
	X	X		X		X		LTVUnicycleCtrl_SetEnabled.vi						x
	X	X		X		X		LTVUnicycleCtrl_SetTolerance.vi						x
STATE SPACE UTILITIES	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	x
	X	X		X				StateSpaceUtil_Check_Stabalizable.vi		Internal routine				x
CALLBACK HELPER	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	x
	X	X	X	X				CallbackHelp_MatrixMinus.vi						x
	X	X	X	X				CallbackHelp_MatrixMult_CoerceSizeB.vi						x
	X	X	X	X				CallbackHelp_MatrixMult.vi						x
	X	X	X	X				CallbackHelp_MatrixPlus.vi						x
DISCRETIZATION	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	x
	X	X		X		X		Discretization_DiscretizeA.vi						x
	X	X		X		X		Discretization_DiscretizeAB.vi						x
	X	X		X		X		Discretization_DiscretizeABTaylor.vi						x
	X	X		X		X		Discretization_DiscretizeAQ.vi						x
	X	X		X		X		Discretization_DiscretizeAQTaylor.vi						x
	X	X		X				Discretization_DiscretizeR.vi						x
STATE SPACE UTIL	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	x
	X	X	X	No				StateSpaceUtil_Check_Stabalizable.vi		Internal routine				x

X	X		X			StateSpaceUtil_ClampInputMaxMagnitude.vi		Routine exists, it is just a shell			
X	X		X			StateSpaceUtil_IsDetectable.vi					
X	X		X			StateSpaceUtil_IsStabalizable.vi					
X	X		X		X	StateSpaceUtil_MakeCostMatrix.vi					
X	X		X		X	StateSpaceUtil_MakeCovarianceMatrix.vi					
X	X		X			StateSpaceUtil_MakeWhiteNoiseVector.vi					
X	X		X			StateSpaceUtil_NomalizeInputVector.vi					
X	X		X			StateSpaceUtil_PoseTo3dVector.vi					
X	X		X			StateSpaceUtil_PoseTo4dVector.vi					
X	X		X			StateSpaceUtil_PoseToVector.vi					

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SIMULATION

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	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
BATTERY SIM	X	X		X	SI			BatterySim_CalculateDefaultBatteryLoadedVoltage.vi					
	X	X		X	SI			BatterySim_CalculateLoadedVoltage.vi					
DC MOTOR SIM	X	X		X				DCMotorSim_getAngularPositionRad.vi					
	X	X		X				DCMotorSim_getAngularPositionRotations.vi					
	X	X		X				DCMotorSim_getAngularVelocityRadPerSec.vi					
	X	X		X				DCMotorSim_getAngularVelocityRPM.vi					
	X	X		X				DCMotorSim_GetCurrentDrawAmps.vi					
	X	X		X				DCMotorSim_New_MOI.vi					
	X	X		X				DCMotorSim_New_Plant.vi					
	X	X		X				DCMotorSim_SetInputVoltage.vi					
	X	X		X				DCMotorSim_Update.vi					
DIFFERENTIAL DRIVE TRAIN SIM	X	X		X				DiffDriveTrainSim_ClampInput.vi					
	X	X		X				DiffDriveTrainSim_CreateKitbotSim_EstMass.vi					
	X	X		X				DiffDriveTrainSim_CreateKitbotSim_EstMassMOI.vi					
	X	X		X				DiffDriveTrainSim_CreateKitbotSim.vi					
	X	X		X				DiffDriveTrainSim_GetCurrentDrawAmps.vi					
	X	X		X				DiffDriveTrainSim_GetCurrentGearing.vi					
	X	X		X				DiffDriveTrainSim_GetDynamics.vi					
	X	X		X				DiffDriveTrainSim_GetHeading.vi					
	X	X		X				DiffDriveTrainSim_GetLeftCurrentDrawAmps.vi					
	X	X		X				DiffDriveTrainSim_GetLeftPositionMeters.vi					
	X	X		X				DiffDriveTrainSim_GetLeftVelocityMetersPerSecond.vi					
	X	X		X				DiffDriveTrainSim_GetOutput_Single.vi					
	X	X		X				DiffDriveTrainSim_GetPose.vi					
	X	X		X				DiffDriveTrainSim_GetRightCurrentDrawAmps.vi					
	X	X		X				DiffDriveTrainSim_GetRightPositionMeters.vi					
	X	X		X				DiffDriveTrainSim_GetRightVelocityMetersPerSecond.vi					
	X	X		X				DiffDriveTrainSim_GetState_Single.vi					
	X	X		X				DiffDriveTrainSim_GetState.vi					

X	X		X			DiffDriveTrainSim_KitBotWheelSize.vi					
X	X		X			DiffDriveTrainSim_New_Mass_MOI.vi					
X	X		X			DiffDriveTrainSim_New.vi					
X	X		X			DiffDriveTrainSim_SetCurrentGearing.vi					
X	X		X			DiffDriveTrainSim_SetInputs.vi					
X	X		X			DiffDriveTrainSim_SetPose.vi					
X	X		X			DiffDriveTrainSim_SetState.vi					
X	X		X			DiffDriveTrainSim_ToughBoxMiniGearRatio.vi					
X	X		X			DiffDriveTrainSim_ToughBoxMiniMotor.vi					
X	X		X			DiffDriveTrainSim_Update.vi					

ELEVATOR SIM	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
	X	X		X				ElevatorSim_GetCurrentDraw.vi					
	X	X		X				ElevatorSim_GetPositionMeters.vi					
	X	X		X				ElevatorSim_GetVelocityMetersPerSecond.vi					
	X	X		X				ElevatorSim_HasHitLowerLimit.vi					
	X	X		X				ElevatorSim_HasHitUpperLimit.vi					
								ElevatorSim_New_LinSys_NoNoise.vi					
								ElevatorSim_New_LinSys.vi					
								ElevatorSim_New_NoNoise.vi					
	X	X		X				ElevatorSim_New.vi					
	X	X	X	No				ElevatorSim_RKF45_Func.vi					
	X	X		X				ElevatorSim_SetInputVoltage.vi					
	X	X		X				ElevatorSim_SetState.vi					
	X	X	X	X				ElevatorSim_Update.vi		Needed because this doesn't extend.			
	X	X		X				ElevatorSim_UpdateX.vi					
	X	X		X				ElevatorSim_WouldHitLowerLimit.vi					
	X	X		X				ElevatorSim_WouldHitUpperLimit.vi					

FLYWHEEL SIM	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
	X	X		X				FlyWheelSim_GetAngularVelocityRadPerSec.vi					
	X	X		X				FlyWheelSim_GetAngularVelocityRPM.vi					
	X	X		X				FlyWheelSim_GetCurrentDrawAmps					
								FlyWheelSim_New_LinSys		Future			
								FlyWheelSim_New_LinSys_MOI_NoNoise		Future			
								FlyWheelSim_New_LinSys_NoNoise		Future			
	X	X		X				FlyWheelSim_New_MOI.vi					
	X	X		X				FlyWheelSim_SetInput.vi					
	X	X		X				FlyWheelSim_SetState.vi					
	X	X		X				FlyWheelSim_Update.vi					

LINEAR SYSTEM SIM	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
	X	X		X				LinearSystemSim_ClampInput.vi					
								LinearSystemSim_GetCurrentDrawAmps.vi		DONT IMPLEMENT...			
	X	X		X				LinearSystemSim_GetOutput_Single.vi					
	X	X		X				LinearSystemSim_GetOutput.vi					
	X	X		X				LinearSystemSim_New					
								LinearSystemSim_New_NoNoise.vi					

X	X		X			LinearSystemSim_SetInput_Array.vi		Doesn't use clamp ?			
X	X		X			LinearSystemSim_SetInput_Single.vi					
X	X		X			LinearSystemSim_SetInput.vi					
X	X		X			LinearSystemSim_Setstate.vi					
X	X		X			LinearSystemSim_Update.vi					
X	X		No			LinearSystemSim_UpdateX.vi					
X	X	X	No			LinearSystemSim_UpdateY.vi					

	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
SINGLE JOINT ARM SIM	X	X		X				SngJntArmSim_EsitmateMOI.vi					
	X	X		X				SngJntArmSim_GetAngleRads.vi					
	X	X		X				SngJntArmSim_GetCurrentDraw.vi					
	X	X		X				SngJntArmSim_GetVelocityRadsPerSec.vi					
	X	X		X				SngJntArmSim_HasHitLowerLimit.vi					
	X	X		X				SngJntArmSim_HasHitUpperLimit.vi					
	X	X		X				SngJntArmSim_New.vi					
	X	X		No				SngJntArmSim_Rkf45_Func.vi					
	X	X		X				SngJntArmSim_SetInputVoltage.vi					
	X	X		X				SngJntArmSim_SetState.vi					
	X	X		X				SngJntArmSim_Update.vi					
	X	X		X				SngJntArmSim_UpdateX.vi					
	X	X		X				SngJntArmSim_WouldHitLowerLimit.vi					
	X	X		X				SngJntArmSim_WouldHitUpperLimit.vi					

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MATRIX UTILITIES

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	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
MAT BUILDER	X	X		X	SI			MatBuilder_Create.vi					
	X	X		X	SI			MatBuilder_Fill.vi					

	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
MATRIX	X	X		X	SI			Matrix_AssignBlock.vi					
	X	X		X	SI			Matrix_Block.vi					
								Matrix_ChangeBoundsUnchecked.vi					
	X	X		X	SI			Matrix_Create.vi					
								Matrix_Det.vi					
	X	X		X	SI			Matrix_Diag.vi					
								Matrix_Div_Scalar.vi		labview has function			
								Matrix_ElementPower.vi					
	X	X		X	SI			Matrix_ElementSum.vi					
								Matrix_ElementTimes.vi					
								Matrix_Equals.vi					
	X	X		X	I			Matrix_Exp.vi					
	X	X		X	SI			Matrix_ExtractColumnVector.vi					
	X	X		X	SI			Matrix_ExtractFrom.vi					
								Matrix_ExtractMatrix.vi					
	X	X		X	SI			Matrix_ExtractRowVector.vi					

X	X		X	SI			Matrix_Fill.vi							
							Matrix_Get.vi			labview has function				
X	X		X	I			Matrix_Ident.vi			WPILIB calls this EYE				
							Matrix_Inv.vi							
X	X		X	SI			Matrix_IsEqual.vi							
							Matrix_IsIdentical.vi							
X	X		X	I			Matrix_LLTDecompose.vi							
							Matrix_Max.vi							
							Matrix_MaxAbs.vi							
							Matrix_Mean.vi							
							Matrix_MinInternal.vi							
							Matrix_Minus_Matrix.vi							
							Matrix_Minus_Scalar.vi							
X	X		X	I			Matrix_NormF.vi							
							Matrix_NormIndP1.vi							
							Matrix_Plus_Matrix.vi							
							Matrix_Plus_Scalar.vi							
X	X		X	I			Matrix_Pow.vi			THIS NEEDS WORK!!!!				
X	X		X	SI			Matrix_SetColumn.vi							
X	X		X	SI			Matrix_SetRow.vi		THERE ARE LOTS OF OTHER MATRIX FUNCTIONS THAT SHOULD BE INCLUDED HERE FOR ISOLATION.					
							Matrix_Solve.vi							
							Matrix_Times_Matrix.vi							
							Matrix_Times_Scalar.vi							
							Matrix_Trace.vi							
X	X		X	SI			Matrix_Transpose.vi							
X	X	X	X				Matrix_WithinTolerance.vi							

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	
SIMPLE MATRIX	X	X		X	SI			SimpleMatrix_ExtractMatrix.vi		NOTE Matrix also has an ExtractMatrix with different calling parameters.... YUK.				x
														x
														x
														x
														x

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	
MATRIX HELPER	X	X	X	X	SI			MatrixHelper_CooerceSize.vi						x
	X	X	X	X	SI			MatrixHelper_MultCooerceBSize.vi						x
	X	X	X	X	SI			MatrixHelper_Zero.vi						x
														x
														x

	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	
VECTOR BUILDER	X	X		X	SI			VecBuilder_1x1Fill.vi						x
	X	X		X	SI			VecBuilder_2x1Fill.vi						x
	X	X		X	SI			VecBuilder_3x1Fill.vi						x
	X	X		X	SI			VecBuilder_4x1Fill.vi						x
	X	X		X	SI			VecBuilder_5x1Fill.vi						x
	X	X		X	SI			VecBuilder_6x1Fill.vi						x
	X	X		X	SI			VecBuilder_7x1Fill.vi						x
	X	X		X	SI			VecBuilder_8x1Fill.vi						x
								VecBuilder_9x1Fill.vi						x

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MATH

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NUMERICAL INTEGRATION	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	x
	X	X		X	I			NumIntegrate_Func_Ax_Bu_K.vi		NOT USED. Should this be used or abandoned???				x
	X	X		X				NumIntegrate_Rk4_Dbl_X_U.vi						x
	X	X		X				NumIntegrate_Rk4_Dbl_X.vi						x
	X	X		X				NumIntegrate_Rk4_Mat_X_U.vi						x
	X	X		X				NumIntegrate_Rk4_Mat_X.vi						x
	X	X		No	SI			NumIntegrate_Rkdp_Func_A.vi						x
	X	X		No	SI			NumIntegrate_Rkdp_Func_B1.vi						x
	X	X		No	SI			NumIntegrate_Rkdp_Func_B1B2.vi						x
	X	X		No	SI			NumIntegrate_Rkdp_Func_B2.vi						x
	X	X		No	I			Numintegrate_Rkdp_Impl.vi						x
	X	X		X				NumIntegrate_RKDP_Mat_X_U.vi		New replacement for RKF45				x
	X	X		No	SI			NumIntegrate_Rkf45_Func_A.vi						x
	X	X		No	SI			NumIntegrate_Rkf45_Func_B1.vi						x
	X	X		No	SI			NumIntegrate_Rkf45_Func_B1B2.vi						x
	X	X		No	SI			NumIntegrate_Rkf45_Func_B2.vi						x
								NumIntegrate_RKf45_Func_Bs.vi		Removed. Replaced with newer functions.				x
								NumIntegrate_RKf45_Func_Ch.vi		Removed. Replaced with newer functions.				x
								NumIntegrate_RKf45_Func_Ct.vi		Removed. Replaced with newer functions.				x
	X	X		No	I			NumIntegrate_Rkf45_Impl.vi						x
	X	X		X				NumIntegrate_Rkf45_Mat_X_U.vi		Note that this Feinberg method has been changed and a Dormand Price method has been implemented.... TODO Removed. Never used.				x
								NumIntegrate_RKf45_New.vi						x
RUNGE KUTTA TIME VARYING	X	X	X	X	SI			NumIntegrate_Trap_Dbl.vi						x
	X	X	X	X	I			NumIntegrate_Trap_Mat.vi						x
NUMERICAL JACOBIAN	Implemented	Documented	Not WPILIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking	x
	X	X		X				NumJacobian_U.vi						x
RICCATI	X	X		X				Riccati_Check_Detectable.vi		Routine exists, it is just a shell				x
	X	X		X				Riccati_Check_Stabilizable.vi		Not really done !!!				x
								Riccati_DARE_Choose.vi		Intended to allow DARE method testing.				x

X	X	X	X		X		Riccati_DARE_Iterate.vi					
X	X	X	X		X		Riccati_DARE_StructDoubling.vi					
X	X		X				Riccati_DARE_N.vi					
X	X		X		X		Riccati_DARE.vi					
X	X		X				Riccati_Input_Check.vi					

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VISION

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	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
COMPUTER VISION UTILITIES	X	X		X				CompVisionUtil_CalculateDistanceToTarget.vi					
	X	X		X				CompVisionUtil_EstimateCameraToTarget.vi					
	X	X		X				CompVisionUtil_EstimateFieldToCamera.vi					
	X	X		X				CompVisionUtil_EstimateFieldToRobot.vi					
	X	X		X				CompVisionUtil_EstimateFieldToRobot_Alt.vi					
	X	X		X				CompVisionUtil_ObjectToRobotPose.vi					

	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
APRIL TAG	X	X		X	SI			AprilTag_Equals.vi					
	X	X	X	X	SI			AprilTag_GetAll.vi					
	X	X		X	SI			AprilTag_New.vi					

	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
APRIL TAG FIELD LAYOUT	X	X		X	SI			AprilTagFieldLayout_GetField.vi					
	X	X		X	SI			AprilTagFieldLayout_GetOriginPosition.vi					
	X	X		X	SI			AprilTagFieldLayout_GetTagPose.vi					
	X	X		X	SI			AprilTagFieldLayout_GetTags.vi					
	X	X		X	SI			AprilTagFieldLayout_New.vi					
	X	X		X	SI			AprilTagFieldLayout_New2022.vi					
	X	X		X	SI			AprilTagFieldLayout_New2023.vi					
	X	X		X	SI			AprilTagFieldLayout_NewSelect.vi					
	X	X		X	SI			AprilTagFieldLayout_SetOrigin.vi					
	X	X		X	SI			AprilTagFieldLayout_SetOrigin_Position.vi					

	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
APRIL TAG POSE ESTIMATE	X	X		X	SI			AprilTagPoseEstimate_GetAll.vi					
	X	X		X	SI			AprilTagPoseEstimate_GetAmbiguity.vi					
	X	X		X	SI			AprilTagPoseEstimate_New.vi					

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COMMUNICATIONS

	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes	Code Review	Test Program	Error Checking
NETWORK UDP	X	X	X	X	SI			NetworkUDP_Close.vi					
	X	X	X	X	I			NetworkUDP_Receive.vi					
	X	X	X	X	I			NetworkUDP_Send.vi					

TYPE DEFINITIONS

TypeDef	Implemented	Documented	Not WPI LIB	Menu Item	Execution Optimized	Test Routine	Sample Program	VI Name	Function Prototype	Notes
	Z	Z	X	X	N/A			AprilTag.ctf		
	Z	Z	X	X	N/A			AprilTagFieldLayout.ctf		
	Z	Z	X	X	N/A			AprilTagFieldLayoutOriginPosition_ENUM.ctf		
	Z	Z	X	X	N/A			AprilTagPoseEstimate.ctf		
	Z	Z	X	X	N/A			AprilTagFields_ENUM.ctf		
	Z	Z	X	X	N/A			ARM_FF.CTL		
	Z	Z	X	X	N/A			BANG_BANG.CTL		
	I		X	X	N/A			BIcon-Matrix_FUNC_TYPE.CTL		NOT USED. Should this be deleted or abandoned???
	Z	Z	X	X	N/A			CALLBACK_FUNC_TYPE.CTL		
	Z	Z	X	X	N/A			CHASSIS_SPEEDS.CTL		
	Z	Z	X	X	N/A			CONSTRAINED_STATE.CTL		
	Z	Z	X	X	N/A			COORDINATE_AXIS.CTL		
	Z	Z	X	X	N/A			COORDINATE_SYSTEM.CTL		
	Z	Z	X	X	N/A			DCMOTOR_TYPES_ENUM.CTL		
	Z	Z	X	X	N/A			DCMOTOR.CTL		
	Z	Z	X	X	N/A			DCMOTOR_SIM.CTL		
	Z	Z	X	X	N/A			DEBOUNCER_TYPE_ENUM.ctf		
	Z	Z	X	X	N/A			DEBOUNCER.CTL		
	Z	Z	X	X	N/A			DIFF_DRIVE_ACCEL_LIMIT.CTL		
	Z	Z	X	X	N/A			DIFF_DRIVE_KINEMATICS.CTL		
	Z	Z	X	X	N/A			DIFF_DRIVE_Kitbot_WheelSize_ENUM.ctf		
	Z	Z	X	X	N/A			DIFF_DRIVE_Pose_EST.ctf		
	Z	Z	X	X	N/A			DIFF_DRIVE_ToughBoxMini_GearChoice_ENUM.ctf		
	Z	Z	X	X	N/A			DIFF_DRIVE_ToughBoxMini_MotorChoice_ENUM.ctf		
	Z	Z	X	X	N/A			DIFF_DRIVE_TRAIN_SIM_STATE_ENUM.CTL		
	Z	Z	X	X	N/A			DIFF_DRIVE_TRAIN_SIM.ctf		
	Z	Z	X	X	NA			DISPLAY_WAYPOINT.ctf		Was UTIL_WAYPOINT.VI
	Z	Z	X	X	NA			DISPLAY_WEIGHTED_WAYPOINT.ctf		New V1.5. was UTIL_WEIGHTED_WAYPOINT.VI
	Z	Z	X	X	N/A			ELEV_FF.CTL		
	Z	Z	X	X	N/A			ELEVATOR_SIM.CTL		
	Z	Z	X	X	N/A			EXTENDED_KALMAN_CORRECT_FUNC_GROUP.CTL		
	Z		X	X	N/A			EXTENDED_KALMAN_FILTER.CTL		
	Z	Z	X	X	N/A			FLYWHEEL_SIM.ctf		
	Z	Z	X	X	N/A			FUNCTION_GENERATOR.ctf		
	Z	Z	X	X	N/A			FUNCTION_GENERATOR_MATRIX.ctf		
	Z	Z	X	X	N/A			HOLONOMIC_DRV_CTRL.CTL		New 1/26/21
	Z	Z	X	X	N/A			TIME_INTERPOLATABLE_BOOLEAN.CTL		
	Z	Z	X	X	N/A			TIME_INTERPOLATABLE_DOUBLE.CTL		
	Z	Z	X	X	N/A			TIME_INTERPOLATABLE_POSE2D.CTL		
	Z	Z	X	X	N/A			TIME_INTERPOLATABLE_ROTATION2D.CTL		

WPILib LabVIEW Math Library – VI Implementation List

Revision 3.X 1/11/2023 – renamed library. Added additional documentation.

Z	Z	X	X	N/A		KALMAN_FILTER_LATENCY_COMP_FUNC_GROUP.CTL			x
Z	Z	X	X	N/A		KALMAN_FILTER_LATENCY_COMP.CTL			x
Z	Z	X	X	N/A		KALMAN_FILTER.ctf			x
Z	Z	X	X	N/A		LINEAR_FILTER.CTL			x
Z	Z	X	X	N/A		LINEAR_PLANT_INV_FF.ctf			x
Z	Z	X	X	N/A		LINEAR_QUADRATIC_REGULATOR.ctf			x
Z	Z	X	X	N/A		LINEAR_SYSTEM_LOOP.ctf			x
Z	Z	X	X	N/A		LINEAR_SYSTEM_SIM.ctf			x
Z	Z	X	X	N/A		LINEAR_SYSTEM.ctf			x
Z	Z	X	X	N/A		LTV_DIFF_DRIVE_CTRL.ctf			x
Z	Z	X	X	N/A		LTV_DIFF_DRIVE_CTRL_STATE_ENUM.ctf			x
Z	Z	X	X	N/A		LTV_UNICYCLE_CONTROLLER.CTL			x
N/A		N/A		N/A		LTV_UNICYCLE_CONTROLLER_INPUT_ENUM.ctf		OBSOLETE – Removed	x
Z	Z	X	X	N/A		LTV_UNICYCLE_CONTROLLER_STATE_ENUM.ctf			x
Z	Z	X	X	N/A		MECA_DRIVE_KINEMATICS.CTL			x
Z	Z	X	X	N/A		MECA_DRIVE_ODOMETRY.CTL			x
Z	Z	X	X	N/A		MECA_DRIVE_POSE_EST.CTL			x
Z	Z	X	X	N/A		MECA_WHEEL_POSITIONS.CTL			x
Z	Z	X	X	N/A		MECA_WHEEL_SPEEDS.CTL			x
Z	Z	X	X	N/A		MEDIAN_FILTER.CTL			x
Z	Z	X	X	N/A		MERWE_SCALED_SIGMA_PTS.ctf			x
Z	Z	X	X	N/A		OBSERVER_SNAP_LIST_ITEM.CTL			x
Z	Z	X	X	N/A		OBSERVER_SNAPSHOT.CTL			x
Z	Z	X	X	N/A		PARAM_STACK_ITEM.CTL			x
Z	Z	X	X	N/A		PARAM_STACK.CTL			x
Z	Z	X	X	N/A		PID_ADV_LIMITS.CTL			x
Z	Z	X	X	N/A		PID_ADV_TUNING.CTL			x
Z	Z	X	X	N/A		PID_CONTROLLER.CTL			x
Z	Z	X	X	N/A		PID_ERROR_TOLERANCE.CTL			x
Z	Z	X	X	N/A		PID_INPUT_LIMITS.CTL			x
Z	Z	X	X	N/A		PID_TUNING.CTL			x
Z	Z	X	X	N/A		POSE2D.CTL			x
Z	Z	X	X	N/A		POSE3D.CTL			x
Z	Z	X	X	N/A		POSEwCURVATURE.CTL			x
Z	Z	X	X	N/A		PROFILED_PID_CONTROLLER.CTL			x
Z	Z	X	X	N/A		QUATERNION.CTL			x
Z	Z	X	X	N/A		RAMSETE_EXE_TUNING.CTL			x
Z	Z	X	X	N/A		RAMSETE.CTL			x
Z	Z	X	X	N/A		ROTATION2D.CTL			x
Z	Z	X	X	N/A		ROTATION3D.CTL			x
Z	Z	X	X	N/A		SIMPLE_MOTOR_FF.CTL			x
Z	Z	X		N/A		SIMPLE_MOTOR_FF_KA_TUNE_PARAMS.CTL			x
Z	Z	X	X	N/A		SINGLE_JOINT_ARM_SIM.CTL			x
Z	Z	X	X	N/A		SLEW_RATE_LIMITER.CTL			x
Z	Z	X	X	N/A		SPLINE_CTRL_VECTOR.CTL			x
Z	Z	X	X	N/A		SPLINE.CTL			x
Z	Z	X	X	N/A		SWERVE_DRIVE_KINEMATICS.CTL			x
Z	Z	X	X	N/A		SWERVE_DRIVE_MODULE_POSITION.CTL			x
Z	Z	X	X	N/A		SWERVE_DRIVE_MODULE_STATE.CTL			x
Z	Z	X	X	N/A		SWERVE_DRIVE_ODOMETRY.CTL			x
Z	Z	X	X	N/A		SWERVE_DRIVE_Pose_EST.CTL			x
Z	Z	X	X	N/A		TIMER.CTL			x
Z	Z	X	X	N/A		TRAJ_CONFIG.CTL			x
Z	Z	X	X	N/A		TRAJ_CONSTRAINT_CENTRIPETAL_ACCEL.CTL			x
Z	Z	X	X	N/A		TRAJ_CONSTRAINT_DIIF_DRIVE_KINEMATICS.CTL			x
Z	Z	X	X	N/A		TRAJ_CONSTRAINT_DIIF_DRIVE_VOLTAGE.CTL			x
Z	Z	X	X	N/A		TRAJ_CONSTRAINT_ELLIP_REGION.CTL			x
I		X		N/A		TRAJ_CONSTRAINT_JERK.CTL		Routine exists, it is just a shell	x
Z	Z	X	X	N/A		TRAJ_CONSTRAINT_MAX_VELOCITY.CTL			x
Z	Z	X	X	N/A		TRAJ_CONSTRAINT_MECA_DRIVE_KINEMATICS.CTL			x
Z	Z	X	X	N/A		TRAJ_CONSTRAINT_MINMAX.CTL			x
Z	Z	X	X	N/A		TRAJ_CONSTRAINT_RECT_REGION.CTL			x
Z	Z	X	X	N/A		TRAJ_CONSTRAINT_SWERVE_DRIVE_KINEMATICS.CTL			x
Z	Z	X	X	N/A		TRAJ_STATE.CTL			x
Z	Z	X	X	N/A		TRAJECTORY_SPLINE_TYPE_ENUM.CTL			x
Z	Z	X	X	N/A		TRAJECTORY.CTL			x
Z	Z	X	X	N/A		TRANSFORM2D.CTL			x
Z	Z	X	X	N/A		TRANSFORM3D.CTL			x
Z	Z	X	X	N/A		TRANSLATION2D.CTL			x
Z	Z	X	X	N/A		TRANSLATION3D.CTL			x

Z	Z	X	X	N/A			TRAPEZOID_PROFILE_CONSTRAINT.CTL		
Z	Z	X	X	N/A			TRAPEZOID_PROFILE_STATE.CTL		
Z	Z	X	X	N/A			TRAPEZOID_PROFILE.CTL		
Z	Z	X	X	N/A			TWIST2D.CTL		
Z	Z	X	X	N/A			TWIST3D.CTL		
Z	Z	X	X	N/A			UNSCENTED_KALMAN_CORRECT_FUNC_GROUP.CTL		
Z	Z	X	X	N/A			UNSCENTED_KALMAN_FILTER.ctf		
Z	Z	X	X	N/A			UNSCENTED_KALMAN_NEW_FUNC_GROUP.CTL		
Z	Z	X	X	N/A			UTIL_PATHFINDER_CONFIG.CTL		
N/A		N/A		N/A			WAYPOINTS.CTL	Delete – obsolete	
Z	Z	X	X	NA			WEIGHTED_WAYPOINT.CTL	New V1.5	
N/A		N/A		N/A			X_Y_HEADINGS.CTL	Delete – obsolete	
Z	Z	X	X	N/A			X_Y_PAIR.CTL		

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