```
user@box:~/demo$ sudo pip3 install pyang plantuml
[sudo] password for user:
/usr/local/lib/python3.8/dist-packages/pkg_resources/__init__.py:122: PkgResourcesDeprecationWarning: 0.23ubuntu1 is an
invalid version and will not be supported in a future release
/usr/local/lib/python3.8/dist-packages/pkg_resources/__init__.py:122: PkgResourcesDeprecationWarning: 0.1.36ubuntu1 is
an invalid version and will not be supported in a future release
 warnings.warn(
ollecting pyang
Downloading pyang-2.5.3-py2.py3-none-any.whl (592 kB)
          592 kB 4.3 MB/s
collecting plantuml
Downloading plantuml-0.3.0-py3-none-any.whl (5.8 kB)
user@box:~/demo$ mkdir ~/demo2
user@box:~/demo$ cd ...
user@box:~$ cp ~/iot/lesson9/intrusiondetection.yang ~/demo2
user@box:~$ cd ~/demo2
user@box:~/demo2$ cat intrusiondetection.yang
module intrusiondetection \{
 namespace "http://netconfcentral.org/ns/intrusiondetection";
 prefix "intrusion";
 description
   "YANG module for Intrusion Detection IoT system";
 revision 2014-07-15 {
  description "Intrusion Detection System";
 }
 grouping room {
  leaf doorsensorID {
    type string;
    description
     "ID of door sensor in the room";
  leaf motionsensorID {
    type string;
    description
     "ID of motion sensor in the room";
```

```
container intrusiondetection {
 presence
  "Indicates the service is available";
 description
  "Top-level container for all system objects.";
 leaf systemID {
 type string;
 config false;
 mandatory true;
 description
 "ID of the system";
 }
 leaf systemLocation {
 type string;
 config false;
 mandatory true;
 description
 "The location of the system";
 leaf systemStatus {
 type enumeration {
   enum up {
   value 1;
   description
   "This is powered up";
```

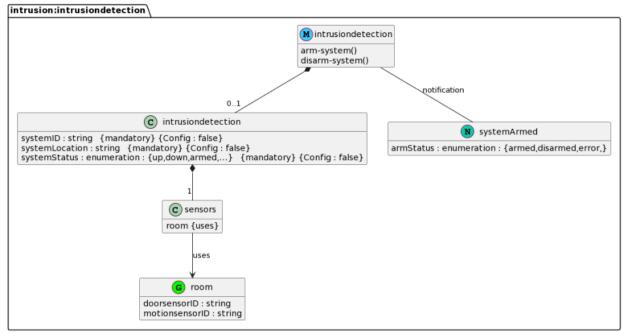
```
enum down {
 value 2;
 description
 "This is powered down";
 enum armed {
 value 3;
 description
 "This is armed";
 enum disarmed {
 value 4;
 description
 "This is disarmed";
}
config false;
mandatory true;
description
"This variable indicates the current state of
 the system.";
 container sensors {
uses room;
config false;
```

```
rpc arm-system {
description
 "Arm the system";
rpc disarm-system {
description
 "Disarm the system";
notification systemArmed {
description
  "Indicates that system has been armed.";
leaf armStatus {
  description
   "Indicates the system arming status";
  type enumeration {
  enum armed {
  description
   "The system was armed.";
  enum disarmed {
  description
   "The system was disarmed.";
  enum error {
  description
    "The system is broken.";
```

```
user@box:~/demo2$ pyang -f yin -o intrusiondetection.yin intrusiondetection.yang
user@box:~/demo2$ cat intrusiondetection.yin
<?xml version="1.0" encoding="UTF-8"?>
<module name="intrusiondetection"
               xmlns="urn:ietf:params:xml:ns:yang:yin:1"
               xmlns:intrusion="http://netconfcentral.org/ns/intrusiondetection">
    <namespace uri="http://netconfcentral.org/ns/intrusiondetection"/>
    <prefix value="intrusion"/>
    <description>
        <text>YANG module for Intrusion Detection IoT system</text>
    </description>
    <revision date="2014-07-15">
        <description>
           <text>Intrusion Detection System</text>
       </description>
    </revision>
    <grouping name="room">
       <leaf name="doorsensorID">
           <type name="string"/>
           <description>
               <text>ID of door sensor in the room</text>
           </description>
       </leaf>
        <leaf name="motionsensorID">
           <type name="string"/>
           <description>
               <text>ID of motion sensor in the room</text>
           </description>
       </leaf>
    </grouping>
    <container name="intrusiondetection">
       ence value="Indicates the service is available"/>
user@box:~/demo2$ pyang -f uml -o intrusiondetection.uml intrusiondetection.yang --uml-no=stereotypes,annotation,typede
user@box:~/demo2$ cat intrusiondetection.uml
 Download plantuml from http://plantuml.sourceforge.net/
Generate png with java -jar plantuml.jar <file>
 'If Java spits out memory error increase heap size with java -Xmx1024m -jar plantuml.jar <file>@startuml img/intrusiondetection.png
nide empty fields
 Output in img/<module>.png
hide empty methods
 nide <<case>> circle
 nide <<augment>> circle
 nide <<choice>> circle
hide <<leafref>> stereotype
hide <<leafref>> circle
hide stereotypes
page 1x1
 itle intrusiondetection
Title intrusiondetection
package "intrusion:intrusiondetection" as intrusion_intrusiondetection {
class "intrusiondetection" as intrusiondetection << (M, #33CCFF) module>>
class "room" as intrusiondetection_I_room_grouping <<(G,Lime) grouping>>
intrusiondetection_I_room_grouping: doorsensorID: string
intrusiondetection_I_room_grouping: motionsensorID: string
class "intrusiondetection" as intrusiondetection_I_intrusiondetection <<container>>
intrusiondetection *- - "0..1" intrusiondetection_I intrusiondetection
intrusiondetection_I_intrusiondetection: systemID: string {mandatory} {Config: false}
intrusiondetection_I_intrusiondetection: systemLocation: string {mandatory} {Config: false}
intrusiondetection_I_intrusiondetection: systemStatus: enumeration: {up,down,armed,...} {mandatory} {Config: false}
e}
 lass "sensors" as intrusiondetection_I_intrusiondetection_I_sensors <<container>>
Intrusiondetection_I_intrusiondetection *-- "1" intrusiondetection_I_intrusiondetection_I_sensors
Intrusiondetection_I_intrusiondetection_I_sensors : room {uses}
```

```
iser@box:~/demo2$ cat intrusiondetection.uml
Download plantuml from http://plantuml.sourceforge.net/
Generate png with java -jar plantuml.jar <file>
  Output in img/<module>.png
  If Java spits out memory error increase heap size with java -Xmx1024m -jar plantuml.jar <file>
  startuml img/intrusiondetection.png
  nide empty fields
  nide empty methods
  nide <<case>> circle
  nide <<augment>> circle
  nide <<choice>> circle
nide <<leafref>> stereotype
  nide <<leafref>> circle
  nide stereotypes
page 1x1
  Title intrusiondetection
Title intrusiondetection
package "intrusion:intrusiondetection" as intrusion_intrusiondetection {
class "intrusiondetection" as intrusiondetection << (M, #33CCFF) module>>
class "room" as intrusiondetection_I_room_grouping <<(G,Lime) grouping>>
intrusiondetection_I_room_grouping: doorsensorID: string
intrusiondetection_I_room_grouping: motionsensorID: string
intrusiondetection_I_room_grouping: motionsensorID: string
class "intrusiondetection" as intrusiondetection_I_intrusiondetection <<container>>
intrusiondetection *-- "0..1" intrusiondetection_I_intrusiondetection
intrusiondetection_I_intrusiondetection: systemID: string {mandatory} {Config: false}
intrusiondetection_I_intrusiondetection: systemIocation: string {mandatory} {Config: false}
intrusiondetection_I_intrusiondetection: systemStatus: enumeration: {up,down,armed,...} {mandatory} {Config: false}
 class "sensors" as intrusiondetection_I_intrusiondetection_I_sensors <<container>>
intrusiondetection_I_intrusiondetection *-- "1" intrusiondetection_I_intrusiondetection_I_sensors
intrusiondetection_I_intrusiondetection_I_sensors : room {uses}
 intrusiondetection : arm-system()
  nide stereotypes
Title intrusiondetection
package "intrusion:intrusiondetection" as intrusion_intrusiondetection {
class "intrusiondetection" as intrusiondetection << (M, #33CCFF) module>>
class "intrusiondetection" as intrusiondetection << (M, #33CCFF) module>>
class "room" as intrusiondetection_I_room_grouping <<(G,Lime) grouping>>
intrusiondetection_I_room_grouping : doorsensorID : string
intrusiondetection_I_room_grouping : motionsensorID : string
class "intrusiondetection" as intrusiondetection_I_intrusiondetection <<container>>
intrusiondetection *-- "0..1" intrusiondetection_I_intrusiondetection
intrusiondetection *-- "0..1" intrusiondetection_I_intrusiondetection
intrusiondetection_I_intrusiondetection : systemID : string {mandatory} {Config : false}
intrusiondetection_I_intrusiondetection : systemLocation : string {mandatory} {Config : false}
intrusiondetection_I_intrusiondetection : systemStatus : enumeration : {up,down,armed,...} {mandatory} {Config : false}
 Title intrusiondetection
class "sensors" as intrusiondetection_I_intrusiondetection_I_sensors <<container>> intrusiondetection_I_intrusiondetection *-- "1" intrusiondetection_I_intrusiondetection_I_sensors intrusiondetection_I_intrusiondetection_I_sensors : room {uses}
 intrustondetection : arm-system()
intrusiondetection : arm-system()
intrusiondetection : disarm-system()
class "systemArmed" as intrusiondetection_I_systemArmed << (N,#00D1B2) notification>>
intrusiondetection -- intrusiondetection_I_systemArmed : notification
  ntrusiondetection I systemArmed : armStatus : enumeration : {armed,disarmed,error,}
 {\sf intrusion detection\_I\_intrusion detection\_I\_sensors} --> {\sf intrusion detection\_I\_room\_grouping} : {\sf uses}
  enter footer
   <size:20> UML Generated : 2022-05-14 22:35 </size>
  endfooter
  iser@box:~/demo2$ python3 -m plantuml intrusiondetection.uml
  [{'filename': 'intrusiondetection.uml', 'gen_success': True}]
```

intrusiondetection



UML Generated: 2022-05-14 22:35

```
user@box:-/demo2$ pip3 install qiskit[visualization]
//usr/local/lib/python3.8/dist-packages/pkg_resources/_init__.py:122: PkgResourcesDeprecationWarning: 0.23ubuntu1 is an invalid version and will not be supported in a future release
warnings.warn(
//usr/local/lib/python3.8/dist-packages/pkg_resources/_init__.py:122: PkgResourcesDeprecationWarning: 0.1.36ubuntu1 is an invalid version and will not be supported in a future release
warnings.warn(
Collecting qiskit[visualization]
Downloading qiskit[visualization]
Downloading qiskit[visualization]
Downloading qiskit[visualization]
Downloading qiskit[visualization]
Downloading qiskit[visualization]
16.5 MB 1.2 MB/s
Collecting qiskit[visualization]
18.0 MB 1.2 MB/s
Collecting qiskit[visualization]
18.0 MB 159 kB/s
Collecting qiskit[visualization]
18.0 MB 159 kB/s
Collecting qiskit[visualization]
18.0 MB 159 kB/s
Collecting qiskit[visualization]
18.0 MB 19.5 MB/s
Collecting qiskit[visualization]
19.0 MB 19.5 MB/s
Collecting qiskit[visualization]
19.0 MB 19.0 MB/s
Collecting qiskit[visualization]
11.3 MB 4.9 MB/s
Collecting pybot[visualization]
11.3 MB 4.9 MB/s
Collecting pybot[visualization]
12.3 kB 2.5 6 MB/s
Collecting pylatexenc=1.1 (2.1 kB)
Requirement already satisfied: pillow=4.2.1 in /usr/lib/python3/dist-packages (from qiskit[visualization]) (7.0.0)
Collecting pylatexenc=2.10.tar.gz (162 kB)

user@box:-/tot/lesson95 python3 qiskit ignis.example.py
qiskit ignis example.py of: DeprecationWarning: The qiskit.tignis package is deprecated and has been supersceded by the qiskit-experiments project. Refer to the migration guide: https://github.com/qiskit-qiskit-qinis#migration-guide on how to rigrate to the new project.
From qiskit.ignis.exerification.randomized_benchmarking import randomized_benchmarking_seq, RBFitter
2.6 After seed 3, EPC 0.005093
After seed 3
```