## Chapter 5: outline

- 5.1 introduction
- 5.2 routing protocols
- link state
- distance vector
- 5.3 intra-AS routing in the Internet: OSPF
- 5.4 routing among the ISPs: BGP

- 5.5 The SDN control plane
- 5.6 ICMP: The Internet Control Message Protocol
- 5.7 Network management and SNMP

### Detour:

See Supplemental Materials on Dijkstra Algorithm

### A link-state routing algorithm

#### Dijkstra's algorithm

- Centralized: network topology, link costs known
  - at Controller or
  - to all nodes
    - accomplished via "link state broadcast"
    - all nodes have same info
- computes least cost paths from one node ('source") to all other nodes
  - gives forwarding table for that node
- iterative: after k iterations, know least cost path to k dest.'s

#### notation:

- C(X,y): link cost from node x to y; = ∞ if not direct neighbors
- D(V): current value of cost of path from source to dest. v
- P(V): predecessor node along path from source to v
- N': set of nodes whose least cost path definitively known

## Dijsktra's algorithm

```
Initialization:
   N' = \{u\}
   for all nodes v
   if v adjacent to u
       then D(v) = c(u,v)
   else D(v) = \infty
   Loop
    find w not in N' such that D(w) is a minimum
10 add w to N'
11 update D(v) for all v adjacent to w and not in N':
      D(v) = \min(D(v), D(w) + c(w,v))
13 /* new cost to v is either old cost to v or known
     shortest path cost to w plus cost from w to v */
15 until all nodes in N'
```

## Dijkstra's algorithm: example

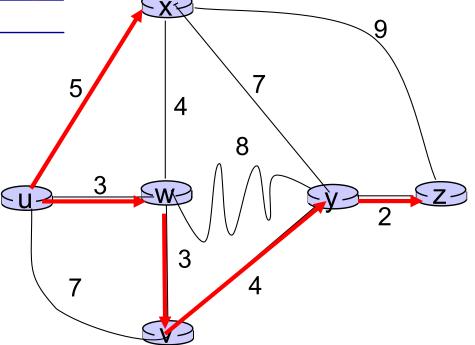
		D( <b>v</b> )	D(w)	D(x)	D(y)	$D(\mathbf{z})$
Ste	) N'	p(v)	p(w)	p(x)	p(y)	p(z)
0	u	7,u	(3,u)	5,u	∞	∞
1	uw	6,w		5,u	) 11,W	$\infty$
2	uwx	6,w			11,W	14,x
3	uwxv				10,V	14,x
4	uwxvy					(12,y)
5	uwxvyz					

#### 8 Loop

- 9 find w not in S such that d(w) is a minimum
- 10 add w to S
- 11 Update d(v) for all v adjacent to w and not in S:
- 2 d(v) = min(d(v), d(w) + c(w,v))
- 13 /\* new cost to v is either old cost to v or known
- 14 shortest path cost to w plus cost from w to v \*/
- 15 until all nodes in S

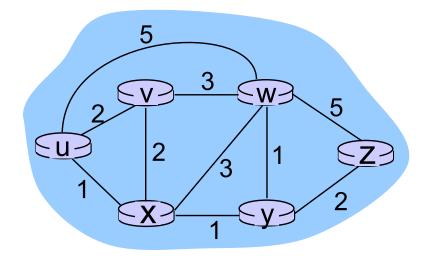
#### notes:

- construct shortest path tree by tracing predecessor nodes
- ties can exist (can be broken arbitrarily)



# Dijkstra's algorithm: another example

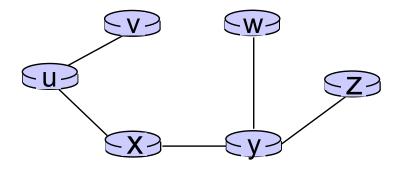
Step	N'	D(v),p(v)	D(w),p(w)	D(x),p(x)	D(y),p(y)	D(z),p(z)
0	U	2,u	5,u	1,u	∞	∞
1	ux <del>←</del>	2,u	4,x		2,x	∞
2	uxy <mark>←</mark>	2,u	3,y			4,y
3	uxyv		3,y			4,y
4	uxyvw <b>←</b>					4,y
5	uxyvwz <b>←</b>					



<sup>\*</sup> Check out the online interactive exercises for more examples: http://gaia.cs.umass.edu/kurose\_ross/interactive/

# Dijkstra's algorithm: example (2)

resulting shortest-path tree from u:



#### resulting forwarding table in u:

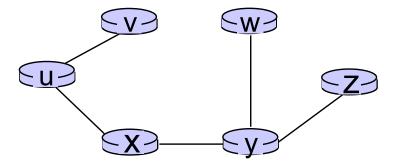
destination	link	distance	
V	(u,v)	1	
X	(u,x)	1	
у	(u,x)	2	
W	(u,x)	3	
Z	(u,x)	3	

Network Layer: Control Plane 5-20

### Dijkstra's algorithm "reversed":

compute distances from all nodes to a destination

Resulting shortest-path tree to u:



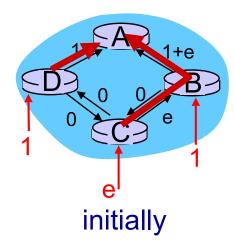
## Dijkstra's algorithm, discussion

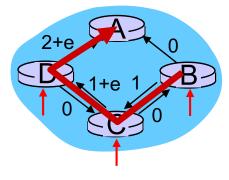
#### algorithm complexity: n nodes

- each iteration: need to check all nodes, w, not in N
- n(n+1)/2 comparisons:  $O(n^2)$
- more efficient implementations possible: O(nlogn)

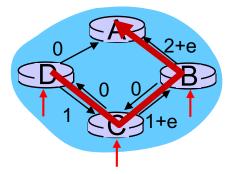
#### oscillations possible:

e.g., support link cost equals amount of carried traffic:

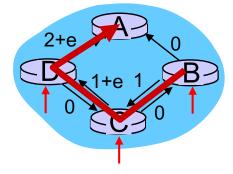




given these costs, find new routing.... resulting in new costs



given these costs, find new routing....



given these costs, find new routing.... resulting in new costs resulting in new costs

# I-clicker:Dijkstra

Q3: Which one of the following is false

A: Dijkstra computes the shortest paths from one source to
all destinations
$\square$ B: Dijkstra computers the shortest paths from all sources to all destinations
☐ C: Dijkstra requires knowledge of the full network topology
☐ D: We can use Dijkstra to create entries in the Forwarding
Table
☐ E: Dijkstra runs in the Control Plane