Appendix

Main.py

```
import numpy as np
import tensorflow as tf
from algorithms.dataloader import Handler
from algorithms.cnn import CNNclassifier
# Global params
NUM_LABELS = 10
BATCH_SIZE = 50
# Add the optional arguments
tf.app.flags.DEFINE_string('train', None,
    'file containing the training data (labels & features).')
tf.app.flags.DEFINE_string('test', None,
    'file containing just the test data.')
tf.app.flags.DEFINE_integer('num_epochs', 1,
    Number of examples to separate from the training '
    'data for the validation set.')
tf.app.flags.DEFINE_boolean('verbose', False,'Produce verbose output.')
FLAGS = tf.app.flags.FLAGS
def main(argv=None):
   handler = Handler (FLAGS)
    handler.extract_train_and_validation_data(NUM_LABELS)
   handler.extract_test_data()
    \# Get the training, validation and testing data
   train_X, train_y = handler.get_train_data()
   val_X, val_y = handler.get_validation_data()
   test_X = handler.get_test_data()
    # Get the shape of the training data.
   train_size = handler.get_train_num_samples()
   num_features = handler.get_num_features()
    # Load model and initialize tensorflow session
   model = CNNclassifier(FLAGS)
   model.form_input_graph(num_features, NUM_LABELS)
   model.load_model()
   model.initialize_session()
   model.fit(train_X,train_y, val_X, val_y,batch_size=50)
    # Make prediction on test data
    test_prediction = model.predict(test_X)
```

algorithms/cnn.py

```
import tensorflow.python.platform
import tensorflow as tf
import numpy as np
class CNNclassifier:
   def __init__(self, FLAGS):
        # Get the number of epochs for training.
       self.num_epochs = FLAGS.num_epochs
    def form_input_graph(self, num_features, num_labels):
        # Feed training sample and labels to the graph
       self.num_features = num_features
       self.num_labels = num_labels
       self.x = tf.placeholder("float", shape=[None, num_features])
       self.y_ = tf.placeholder("float", shape=[None,num_labels])
    def load_model(self):
       self.__add_convolutional_layers()
       self.__add_fully_connected_layers()
       self.__add_optimizer()
       self.__add_metrics()
   def __add_convolutional_layers(self):
        ###### 1st layer CNN
       # initialize weight and bias of CNN
       self.W_conv1 = self.weight_variable([5, 5, 1, 32])
       self.b_conv1 = self.bias_variable([32])
       # reshape x to a 4d tensor
       self.x_image = tf.reshape(\
           self.x, [-1,28,self.num_features/28,1])
       \# add cnn layer with RELU
       self.h_conv1 = tf.nn.relu(self.conv2d(\
           self.x_image, self.W_conv1) + self.b_conv1)
       # add max pooling
       self.h_pool1 = self.max_pool_2x2(self.h_conv1)
       ###### 2nd Layer CNN
        # initialize weight and bias of CNN
       self.W_conv2 = self.weight_variable([5, 5, 32, 64])
       self.b_conv2 = self.bias_variable([64])
       \# add cnn layer with RELU
       self.h_conv2 = tf.nn.relu(self.conv2d(\
```

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self.h_pool1, self.W_conv2) + self.b_conv2)
    # add max pooling
   self.h_pool2 = self.max_pool_2x2(self.h_conv2)
def weight_variable(self,shape):
 initial = tf.truncated_normal(shape, stddev=0.1)
 return tf.Variable(initial)
def bias_variable(self, shape):
 initial = tf.constant(0.1, shape=shape)
 return tf.Variable(initial)
def conv2d(self, x, W):
 return tf.nn.conv2d(\
   x, W, strides=[1, 1, 1, 1], padding='SAME')
def max_pool_2x2(self, x):
 return tf.nn.max_pool(x, ksize=[1, 2, 2, 1],
   strides=[1, 2, 2, 1], padding='SAME')
def __add_fully_connected_layers(self):
    ##### Densely Connected layer - 1 (relu)
   self.W_fc1 = self.weight_variable([7 * 7 * 64, 1024])
   self.b_fc1 = self.bias_variable([1024])
   self.h_pool2_flat = tf.reshape(self.h_pool2, [-1, 7*7*64])
   self.h_fc1 = tf.nn.relu(tf.matmul(\
        self.h_pool2_flat, self.W_fc1) + self.b_fc1)
   ##### Dropout layer
   self.keep_prob = tf.placeholder(tf.float32)
   self.h_fc1_drop = tf.nn.dropout(self.h_fc1, self.keep_prob)
   ##### Densely Conected layer -2 (softmax)
   self.W_fc2 = self.weight_variable([1024, self.num_labels])
   self.b_fc2 = self.bias_variable([self.num_labels])
   self.y_conv=tf.nn.softmax(tf.matmul(\
        self.h_fc1_drop, self.W_fc2) + self.b_fc2)
def __add_optimizer(self):
    # Loss function
   self.cross_entropy = tf.reduce_mean(\
       -tf.reduce_sum(self.y_ * tf.log(self.y_conv),
            reduction_indices=[1]))
   # Optimizer
   self.learning_rate = 5e-4
   self.optimizer = tf.train.AdamOptimizer(\
        self.learning_rate).minimize(self.cross_entropy)
def __add_metrics(self):
   self.correct_prediction = tf.equal(\
       tf.argmax(self.y_conv,1), tf.argmax(self.y_,1))
   self.accuracy = tf.reduce_mean(tf.cast(\
       self.correct_prediction, tf.float32))
   prediction=tf.argmax(self.y_conv,1)
```

```
def initialize_session(self):
    ## Create and initialize the interactive session
    self.sess = tf.InteractiveSession()
    self.sess.run(tf.initialize_all_variables())
def fit(self, train_X, train_y, val_X, val_y, batch_size=50):
    train_size = train_X.shape[0]
    # Iterate and train.
    for step in xrange(self.num_epochs * train_size // batch_size):
        offset = (step * batch_size) % train_size
        batch_data = train_X[offset:(offset + batch_size), :]
        batch_labels = train_y[offset:(offset + batch_size)]
        # Train
        {\tt self.sess.run(self.optimizer,feed\_dict=\{} \setminus
            self.x: batch_data, self.y_: batch_labels, \
            self.keep_prob: 0.5})
        if(step % 10 == 0):
            print 'Step Count:', step
            # Get a validation accuracy
            print 'Validation Acc: ',self.sess.run(self.accuracy, \
                feed_dict={self.x: val_X, self.y_: val_y, \
                self.keep_prob: 1.0})
def predict(self, test_X):
    self.test_prediction = self.sess.run(self.prediction,
                    feed_dict={self.x: test_X, self.keep_prob: 1.0}
    return self.test_prediction
```

algorithms/dataloader.py

```
import numpy as np
import pandas as pd
from sklearn.cross_validation import train_test_split
from sklearn import preprocessing
class Handler:
    def __init__(self, FLAGS):
        # Be verbose?
        self.verbose = FLAGS.verbose
        # Get the data.
        self.train_data_filename = FLAGS.train
        self.test_data_filename = FLAGS.test
    def extract_train_and_validation_data(self,num_labels):
        data = pd.read_csv(self.train_data_filename, header=0).values
        # convert to Numpy array forms
        feature_vec = data[0::,1::]
        labels = data[0::,0]
```

```
# mean normalize features
    min_max_scaler = preprocessing.MinMaxScaler()
    feature_vec = min_max_scaler.fit_transform(feature_vec.T).T
    # convert to one hot form for labels
    labels_onehot = (np.arange(num_labels) == labels[:, None]).
                                        astype(\
        np.float32)
    \# divide data into train and validation data
    self.train_X, self.val_X, self.train_y, self.val_y =
                                        train_test_split(\
        feature_vec, labels_onehot, test_size=0.2, random_state=42)
def extract_test_data(self):
    feature_vec = pd.read_csv(self.test_data_filename, header=0).
    # mean normalize features
    min_max_scaler = preprocessing.MinMaxScaler()
    feature_vec = min_max_scaler.fit_transform(feature_vec.T).T
    self.test_X = feature_vec
def get_train_data(self):
    return self.train_X, self.train_y
def get_validation_data(self):
    return self.val_X, self.val_y
def get_test_data(self):
    return self.test_X
def get_train_num_samples(self):
    return self.train_X.shape[0]
def get_num_features(self):
    return self.train_X.shape[1]
def store_results(self, result, outfile):
    # Predict result for test data
    df = pd.DataFrame()
    df['ImageId'] = np.arange(1, self.test_X.shape[0] + 1)
    df['Label'] = result
    df.to_csv(outfile, index=False)
```