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Object detector using Arduino uno & ultrasonic sensor HC-sr04



March 05, 2017

It is simple object detector project using arduino ultrasonic module

Parts list--

Bread board

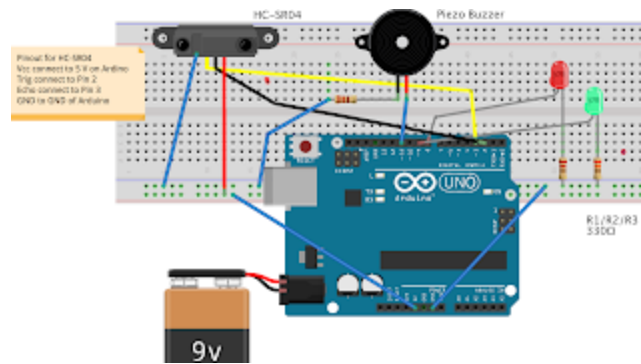
LED (RED & GREEN)

Resistor -220 ohms

Male to male jumper wire

arduino uno

arduino ultrasonic module (HC-SR04)



HC-SR04 connection

VCC--5V

GND--GND

TRIG-- D2

ECHO-D3

LED RED -- D8

GND via resistor

LED GREEN-- D9

GND via resistor

PIEZO BUZZER --D11

GND--GND

Supply 9V Battery

Object detector using ultraso...



ARDUINO CODE :-

```
//Ultrasonic Sensor
```

```
//Pins connected to the ultrasonic sensor
```

```
#define trigPin 2
```

```
#define echoPin 3
```

```
//LED pins
```

```
#define ledGreen 9
```

```
#define ledRed 8
```

```
//Pin connected to the piezo buzzer
```

```
#define alarm 11
```

```
int range = 5;//range in inches
```

```
void setup() {
```

```
  // initialize serial communication:
```

```
  Serial.begin(9600);
```

```
  //initialize the sensor pins
```

```
  pinMode(trigPin, OUTPUT);
```

```
  pinMode(echoPin, INPUT);
```

```
  //initialize LED pins
```

```
  pinMode(ledGreen, OUTPUT);
```

```
  pinMode(ledRed, OUTPUT);
```

```
  //set LEDs
```

```
  digitalWrite(ledGreen, HIGH);
```

```
digitalWrite(ledRed, LOW);

}

void loop()
{
  // establish variables for duration of the ping,
  // and the distance result in inches and centimeters:
  long duration, inches, cm;

  // The PING))) is triggered by a HIGH pulse of 2 or more microseconds.
  // Give a short LOW pulse beforehand to ensure a clean HIGH pulse:
  digitalWrite(trigPin, LOW);
  delayMicroseconds(2);
  digitalWrite(trigPin, HIGH);
  delayMicroseconds(5);
  digitalWrite(trigPin, LOW);

  // Take reading on echo pin
  duration = pulseIn(echoPin, HIGH);

  // convert the time into a distance
  inches = microsecondsToInches(duration);
  cm = microsecondsToCentimeters(duration);

  Serial.print(inches);
  Serial.print("in, ");
  Serial.print(cm);
  Serial.print("cm");
  Serial.println();

  if(inches < 5) {
    Serial.println("DANGER");
    digitalWrite(ledGreen, LOW);
    digitalWrite(ledRed, HIGH);
    tone(alarm, 2000);
    delay(100);
  } else {
    Serial.println("GOOD");
    digitalWrite(ledGreen, HIGH);
    digitalWrite(ledRed, LOW);
  }
}
```

```
    noTone(alarm);
    delay(100);
}

delay(200);
}

long microsecondsToInches(long microseconds)
{
    // According to Parallax's datasheet for the PING))) there are
    // 73.746 microseconds per inch (i.e. sound travels at 1130 feet per
    // second). This gives the distance travelled by the ping, outbound
    // and return, so we divide by 2 to get the distance of the obstacle.
    // See: http://www.parallax.com/dl/docs/prod/acc/28015-PING-v1.3.pdf
    return microseconds / 74 / 2;
}

long microsecondsToCentimeters(long microseconds)
{
    // The speed of sound is 340 m/s or 29 microseconds per centimeter.
    // The ping travels out and back, so to find the distance of the
    // object we take half of the distance travelled.
    return microseconds / 29 / 2;
}
```

arduino

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