

Micro-Ondes

Rappel éle et magnétisme

$$\vec{\text{rot}} \vec{E}(M, t) = - \frac{\partial \vec{B}(M, t)}{\partial t}$$

$$\vec{\text{rot}} \vec{H}(M, t) = \vec{J}(M, t) + \frac{\partial \vec{D}(M, t)}{\partial t}$$

$$\text{div} \vec{D}(M, t) = \rho(M, t)$$

$$\text{div} \vec{B}(M, t) = 0$$

$$\vec{D} = \epsilon \vec{E}$$

$$\vec{B} = \mu \vec{H}$$

$$\vec{J} = \sigma \vec{E}$$

En régime sinusoïdal Pe.

$$\vec{E}(M, t) \rightarrow \vec{E}(M) e^{j\omega t}$$

$$\vec{E} = \text{Re}(\vec{E}(M) e^{j\omega t})$$

$$\vec{H} = \vec{H}(M) e^{j\omega t}$$

$$\vec{B} = \vec{B}(M) e^{j\omega t}$$

$$\vec{D} = \vec{D}(M) e^{j\omega t}$$

Soit des eq de Maxwell pour les prob de rayonnement:

$$\text{div} \vec{B} = 0$$

$$\text{div} \vec{H} = 0 \Rightarrow \exists A \rightarrow \vec{H} = \frac{1}{\mu} \vec{\text{rot}} \vec{A}$$

\vec{A} : potentiel vecteur magnétique

RQ

$$\text{div} \vec{\text{rot}}(\vec{x}) = 0$$

$$\vec{\text{rot}} \text{grad}(\varphi) = 0$$

$$\vec{A}_1 = \vec{A} + \text{grad} \lambda$$

$$\Rightarrow \vec{\text{rot}} \vec{A}_1 = \vec{\text{rot}} \vec{A} + \underbrace{\vec{\text{rot}} \text{grad} \lambda}_0$$

$$\vec{\text{rot}} \vec{E} = -j\omega \mu \vec{H}$$

$$\text{Formule } = -j\omega \mu \frac{1}{\mu} \vec{\text{rot}} \vec{A}$$

$$\alpha \vec{\text{rot}} \vec{H} + \beta \vec{\text{rot}} \vec{B} = \vec{\text{rot}} (\alpha \vec{H} + \beta \vec{B})$$

$$\vec{\text{rot}} (\vec{E} + j\omega \vec{A}) = \vec{0} \Rightarrow \exists V \text{ qu'on se } \vec{E} + j\omega \vec{A} = -\text{grad} V \text{ (car rot grad) } = \vec{0}$$

$$\vec{E} = -\text{grad} V - j\omega \vec{A}$$

Il n'est pas unique $\exists \infty$ de V possible

Ex Formule

$$\vec{\text{rot}} \vec{\text{rot}}(\vec{x}) = \text{grad} \text{div}(\vec{x}) - \Delta \vec{x}$$

$$\vec{\text{rot}} \vec{H} = \vec{J} + j\omega \epsilon \vec{E}$$

$$\text{et comme } \vec{H} = \frac{1}{\mu} \vec{\text{rot}} \vec{A}$$

$$\Rightarrow \vec{\text{rot}} \left(\frac{1}{\mu} \vec{\text{rot}} \vec{A} \right) = \vec{J} + j\omega \epsilon \vec{E}$$

$$\Rightarrow \vec{\text{rot}} \vec{\text{rot}} \vec{A} = \mu (\vec{J} + j\omega \epsilon \vec{E})$$

$$\text{et comme } \vec{E} = -\text{grad} V - j\omega \vec{A}$$

$$\Rightarrow \vec{\text{rot}} \vec{\text{rot}} \vec{A} = \mu (\vec{J} + j\omega \epsilon (-\text{grad} V - j\omega \vec{A}))$$

$$= \mu \text{grad} \text{div}(\vec{A}) - \Delta \vec{A} - \mu j\omega \epsilon \mu \text{grad} V + \omega^2 \epsilon \mu \vec{A}$$

$$\Rightarrow \Delta \vec{A} + \beta^2 \vec{A} = -\mu \vec{J} + j\omega \epsilon \mu \text{grad} V + \text{grad} \text{div}(\vec{A})$$

$$\text{on pose } \text{div} \vec{A} + j\omega \epsilon \mu \text{grad}(\text{div} \vec{A} + j\omega \epsilon \mu \vec{A}) = 0$$

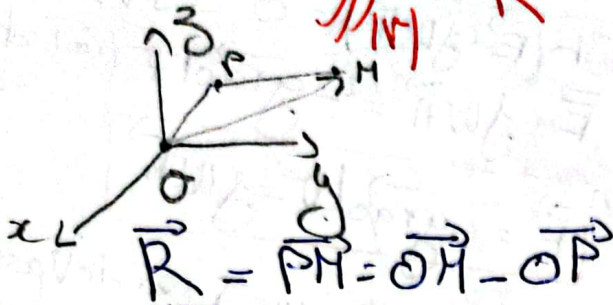
$$\Rightarrow \Delta \vec{A} + \beta^2 \vec{A} = -\mu \vec{J}$$

β : cte de propagation dans le milieu infini (ϵ)

(1)

$$B = \mu \sqrt{\epsilon \mu}$$

$$\Rightarrow \vec{A}(\vec{r}) = \frac{\mu}{4\pi} \iiint_V \frac{\vec{J}(\vec{r}') e^{-j\beta R}}{R} dV'$$



Pour antennes filaires

$$\iiint_V \frac{\vec{J}(\vec{r}') e^{-j\beta R}}{R} dV' \quad \left| \quad \int_{\text{fil}} \frac{\vec{I}(\vec{r}') e^{-j\beta R}}{R} d\vec{r}'$$

Ex
Le vecteur de Poynting
 $\Pi(\vec{r}, t) = \vec{E}(\vec{r}, t) \wedge \vec{H}(\vec{r}, t)$

$$RQ = \frac{1}{2} \vec{E}(\vec{r}) \wedge \vec{H}^*(\vec{r})$$

$$\vec{E}(\vec{r}, t) = \text{Re}(\vec{E}(\vec{r}) e^{j\omega t})$$

$\vec{E} \in \mathbb{C}$, \vec{E}^* sont conjugués
 $\vec{E} + \vec{E}^* = 2 \text{Re}(\vec{E})$

$\beta(\vec{r})$ périodique de période T

$$\langle \beta(\vec{r}) \rangle = \frac{1}{T} \int_t^{t+T} \beta(\vec{r}) dt$$

$$\langle \Pi(\vec{r}, t) \rangle_t = \langle \vec{E}(\vec{r}) e^{j\omega t} + \vec{E}^*(\vec{r}) e^{-j\omega t} \rangle_t$$

$$= \frac{1}{T} \langle \vec{E}(\vec{r}) e^{j\omega t} + \vec{E}^*(\vec{r}) e^{-j\omega t} \rangle_t$$

$$= \text{Re} \left(\frac{1}{2} \vec{E} \wedge \vec{H}^* \right)$$

Dipôle idéal

↳ dipôle idéal
↳ c'est un morceau d'un conducteur droit de petite dimension et mince parcouru par un courant $I_0 e^{j\omega t}$ ou $I_0 e^{-j\omega t}$

Pour le dipôle idéal on suppose

$$\Delta z \ll \lambda \quad \Rightarrow R \approx r$$

$$\Delta z \ll \lambda \quad \text{donc} \quad \frac{e^{-j\beta R}}{R} \approx \frac{e^{-j\beta r}}{r}$$

terme d'amplitude

$$\vec{A}(\vec{r}) = \frac{\mu}{4\pi} \int_{\text{dipole}} \frac{\vec{I}(\vec{r}') e^{-j\beta R}}{R} d\vec{r}'$$

$$A(\vec{r}) = \frac{\mu}{4\pi} \int_{-\Delta z/2}^{\Delta z/2} \frac{I_0 e^{-j\beta r}}{r} dz \vec{k}$$

$$A(\vec{r}) = \frac{\mu I_0 e^{-j\beta r}}{4\pi r} \int_{-\Delta z/2}^{\Delta z/2} dz \vec{k}$$

$$\vec{A}(\vec{r}) = \frac{\mu I_0 e^{-j\beta r}}{4\pi r} \Delta z \vec{k}$$

$$\vec{H}(\vec{r}) = ?$$

$$\vec{H}(\vec{r}) = \frac{1}{\mu} \text{rot}(\vec{A}(\vec{r}))$$

on utilise coordonnées sphériques (car $\frac{e^{-j\beta r}}{r}$)

$$RQ \text{ rot}(\beta \vec{u}) = \text{grad} \beta \wedge \vec{u} + \beta \text{rot} \vec{u}$$

$$\text{rot} \vec{k} = \vec{0} \text{ car } \vec{k} \text{ vecteur}$$

$$\text{grad} \beta = \frac{\partial \beta}{\partial r} \vec{u}_r + \frac{1}{r} \frac{\partial \beta}{\partial \theta} \vec{u}_\theta$$

$$+ \frac{1}{r \sin \theta} \frac{\partial \beta}{\partial \phi} \vec{u}_\phi$$

$$\beta = \frac{\mu I_0 \Delta z}{4\pi r} e^{-j\beta r} \text{ dépend de } r$$

$$\begin{aligned} \Rightarrow \vec{\text{grad}} \beta &= \frac{\partial \beta}{\partial r} \vec{u}_r \quad \left(\frac{\beta' - \beta}{r} + \frac{\beta}{r^2} \right) \\ &= \frac{\mu I_0 \Delta z}{4\pi} \frac{\partial}{\partial r} \left(\frac{e^{-j\beta r}}{r} \right) \vec{u}_r \\ &= \frac{\mu I_0 \Delta z}{4\pi} \left(-\frac{j\beta r e^{-j\beta r}}{r^2} + \frac{1}{r^2} e^{-j\beta r} \right) \vec{u}_r \\ &= -\frac{\mu I_0 \Delta z e^{-j\beta r}}{4\pi r^2} (1 + j\beta r) \vec{u}_r \end{aligned}$$

$$\begin{aligned} \vec{H}(\vec{r}) &= \frac{1}{\mu} \text{rot}(\vec{A}(\vec{r})) \\ &= \frac{1}{\mu} \text{grad}(\vec{A} \wedge \vec{u}) + \beta \text{rot}(\vec{u}) \quad \text{rot } \vec{K} = 0 \\ &= \frac{1}{\mu} \frac{-\mu I_0 \Delta z e^{-j\beta r}}{4\pi r^2} |\vec{u}_r \wedge \vec{K}| (1 + j\beta r) \end{aligned}$$

1. Rappel sur les coordonnées

1 - Système cartésien

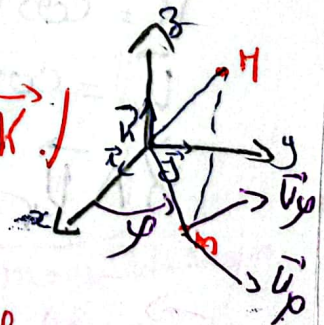
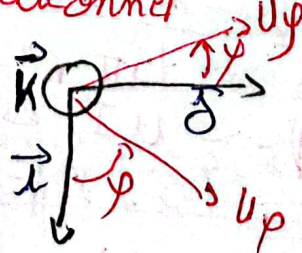
$$\vec{OM} = \vec{Om} + \vec{mM} \\ = x\vec{i} + y\vec{j} + z\vec{k}$$

$$d\vec{r} = dx\vec{i} + dy\vec{j} + dz\vec{k}$$

2 - Système cylindrique (ρ, φ, z) ($\vec{u}_\rho, \vec{u}_\varphi, \vec{K}$)

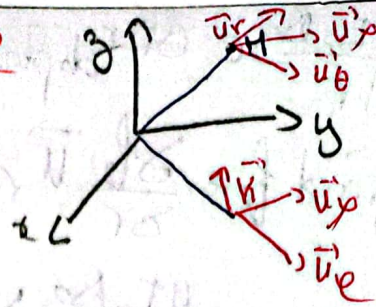
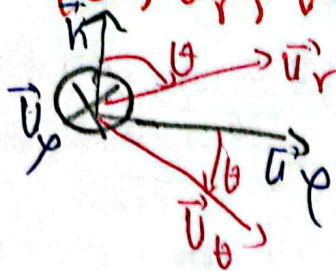
	\vec{u}_ρ	\vec{u}_φ	\vec{K}
\vec{i}	$\cos \varphi$	$-\sin \varphi$	0
\vec{j}	$\sin \varphi$	$\cos \varphi$	0
\vec{k}	0	0	1

← matrice rotationnelle



$$\text{Volume } dV = d\rho d\varphi dz$$

3 - Colonne sphérique ($\theta, \vec{u}_r, \vec{u}_\theta, \vec{u}_\varphi$)



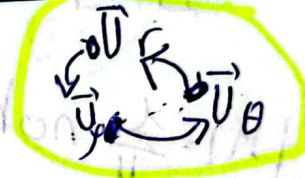
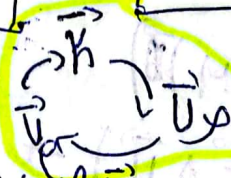
$$T_1$$

\vec{u}_θ	\vec{u}_r	\vec{u}_θ	\vec{u}_φ
\vec{u}_θ	$\cos \theta$	$-\sin \theta$	0
\vec{u}_φ	$\sin \theta$	$\cos \theta$	0
\vec{u}_φ	0	0	1

$$T_2$$

\vec{u}_φ	\vec{u}_φ	\vec{u}_φ	\vec{u}_φ
\vec{u}_φ	$\cos \varphi$	$-\sin \varphi$	0
\vec{u}_φ	$\sin \varphi$	$\cos \varphi$	0
\vec{u}_φ	0	0	1

Par exemple



$$T_2 \rightarrow \vec{u}_\varphi = \cos \varphi \vec{u}_\varphi - \sin \varphi \vec{u}_\varphi$$

$$T_1 \rightarrow \vec{u}_\varphi = \cos \varphi (\sin \theta \vec{u}_r \cos \theta \vec{u}_\theta) - \sin \varphi \vec{u}_\varphi$$

$$\vec{u}_\varphi \wedge \vec{u}_r = \cos \varphi \cdot \cos \theta \cdot \vec{u}_\theta \wedge \vec{u}_r - \sin \varphi \vec{u}_\varphi \wedge \vec{u}_r$$

$$= \cos \theta \vec{u}_\varphi? - \sin \varphi \vec{u}_\theta$$

$$\vec{u}_\theta \wedge \vec{u}_r = ?$$

$$\vec{u}_\theta = \cos \theta \vec{u}_r - \sin \theta \vec{u}_\theta$$

$$\vec{u}_r = \cos \theta \vec{u}_\theta + \sin \theta \vec{u}_\varphi$$

$$\vec{u}_\theta \wedge \vec{u}_r = \cos \theta \vec{u}_r \wedge \vec{u}_\theta + \cos \theta \vec{u}_r \wedge \vec{u}_\varphi + \sin \theta \vec{u}_\theta \wedge \vec{u}_r + \sin \theta \vec{u}_\theta \wedge \vec{u}_\varphi$$

$$= \cos \theta \vec{u}_r \wedge \vec{u}_\varphi - \sin \theta \vec{u}_\theta \wedge \vec{u}_\varphi$$

$$\vec{H}(M) = \frac{-\mu I_0 \Delta z e^{-j\beta r}}{4\pi r^2} |\vec{u}_r \wedge \vec{u}_\theta| (1 + j\beta r) \vec{u}_r$$

$$\vec{H}(M) = \frac{-\mu I_0 \Delta z e^{-j\beta r}}{4\pi r^2} (1 + j\beta r) \sin \theta \vec{u}_\varphi$$

$$= H_r \vec{u}_\varphi$$

Ex $Mq \vec{E}(M) = \frac{1}{j\omega\epsilon} \frac{I_0 \Delta z e^{-j\beta r}}{4\pi r^3} \{ 2 \cos \theta (1 + j\beta r) \vec{U}_r + (1 + j\beta r - \beta r) \sin \theta \}$

ona $rot \vec{H}(M) = j\omega\epsilon \vec{E}(M)$

et $\vec{H}(M) = \frac{I_0 \Delta z e^{-j\beta r}}{4\pi r^2} (1 + j\beta r) \sin \theta \vec{U}_\theta$

$rot \vec{H}(M) = \frac{\vec{U}_r}{r \sin \theta} \left(\frac{\partial}{\partial \theta} \left| \frac{I_0 \Delta z e^{-j\beta r}}{4\pi r} (1 + j\beta r) \sin^2 \theta \right| + \frac{\vec{U}_\theta}{r} \left| \frac{\partial}{\partial r} \left| \frac{I_0 \Delta z e^{-j\beta r}}{(1 + j\beta r)} \right| \right| \right)$

$\vec{E}(M) = \frac{1}{j\omega\epsilon} \frac{I_0 \Delta z e^{-j\beta r}}{4\pi r^3}$

Ex $sr \gg \lambda \Rightarrow \beta r \gg 1, \beta = \frac{2\pi}{\lambda}, \beta = \omega\epsilon\mu$
 $\vec{H}(M) = \frac{I_0 \Delta z e^{-j\beta r}}{4\pi r^2} (1 + j\beta r) \sin \theta \vec{U}_\theta$

$\vec{H}(M) = j\beta \frac{I_0 \Delta z e^{-j\beta r}}{4\pi r^2} \sin \theta \vec{U}_\theta$

$\vec{E}(M) = \frac{1}{j\omega\epsilon} \frac{I_0 \Delta z e^{-j\beta r}}{4\pi r^3}$

$\vec{E}(M) = j\omega\mu \frac{I_0 \Delta z e^{-j\beta r}}{4\pi r} \sin \theta \vec{U}_\theta$

On RQ

$\vec{E} = E_\theta \vec{U}_\theta \left\{ \vec{E} \perp \vec{H} \right.$

$H = H_\phi \vec{U}_\phi \left. \right\}$

$\frac{E_\theta}{H_\phi} = \frac{j\omega\mu}{j\beta} = \frac{\omega\mu}{\omega\sqrt{\epsilon\mu}} = \sqrt{\frac{\mu}{\epsilon}} = \eta$

$\sqrt{\frac{\mu}{\epsilon}} = \eta$

impédance intrinsèque au milieu (ϵ, μ)

ds l'air $\epsilon = 120\pi \Omega$

Ex Vect de Poynting

$\vec{H} = \frac{1}{2} \vec{E} \wedge \vec{H}^*$

$= \frac{1}{2} \left(\frac{j\omega\mu I_0 \Delta z e^{-j\beta r}}{4\pi r} \sin \theta \vec{U}_\theta \right) \wedge \left(\frac{j\beta I_0 \Delta z e^{j\beta r}}{4\pi r} \sin \theta \vec{U}_\theta \right)$

(3)

$$= \frac{1}{2} |\vec{J}|^2 (\mu\beta) \cdot \left| \frac{I_0 \Delta z}{4\pi r} \right|^2 \frac{\sin^2 \theta}{r^2} \hat{u}_r$$

$$\vec{\Pi} = \frac{1}{2} \mu\beta \left(\frac{I_0 \Delta z}{4\pi r} \right)^2 \sin^2 \theta \hat{u}_r$$

Ex

Puissance moyenne Rayonne? $d\vec{s} = r^2 \sin \theta d\theta d\phi \hat{u}_r$

$$P = \text{Re} \int_{\text{sphere}} \vec{\Pi} \cdot d\vec{s}$$

$$P = \text{Re} \left(\int_{\text{sphere}} \frac{1}{2} \mu\beta \left(\frac{I_0 \Delta z}{4\pi r} \right)^2 \sin^2 \theta \hat{u}_r \cdot r^2 \sin \theta d\theta d\phi \hat{u}_r \right)$$

$$= \text{Re} \left(\frac{1}{2} \mu\beta \left(\frac{I_0 \Delta z}{4\pi} \right)^2 \int_0^\pi \sin^3 \theta d\theta \int_0^{2\pi} d\phi \right)$$

$$= \text{Re} \left(\frac{\mu\beta}{2} \left(\frac{I_0 \Delta z}{4\pi} \right)^2 \left[\frac{4}{3} \right] [2\pi - 0] \right)$$



$$= \text{Re} \left(\mu\beta \frac{1}{12\pi} (I_0 \Delta z)^2 \right)$$

$$= \frac{\mu\beta}{12\pi} (I_0 \Delta z)^2$$