

Due Date : February 22nd, 24:00

Instructions

- For all questions, show your work !
- Use a document preparation system such as LaTeX.
- Submit your answers electronically via the course gradescope
- TA for this assignment are : **Andjela Mladenovic (IFT6135B)** and **Ghait Boukachab (IFT6135A)**.

1. **Selection of Activation Function (10 pts)** We will compare two different activation functions in the following question. Recall the definition of $\sigma(x) = \frac{1}{1+e^{-x}}$ and $\tanh(x) = \frac{e^x - e^{-x}}{e^x + e^{-x}}$.
- (2 pts) Find the derivative of the sigmoid function $\sigma'(x)$ and express it in terms of the sigmoid function $\sigma(x)$.
 - (2 pts) Find the derivative of the $\tanh'(x)$ function and express it in terms of the $\tanh(x)$ function.
 - (2 pts) Upper bound the value of $\sigma'(x)$ with a constant (you can use AM–GM inequality).
 - (2 pts) Upper bound the value of $\tanh'(x)$ with a constant (you can use GM-HM inequality or the property that the square of real number is always non-negative).
 - (2 pts) Compare the two upper bounds and explain what impact would this difference have on optimization.

Useful inequalities:

Inequality of Arithmetic and Geometric Means (AM-GM)

$$\frac{x_1 + x_2 + \dots x_n}{n} \geq \sqrt[n]{x_1 x_2 \dots x_n} \quad (1)$$

Inequality of Geometric and Harmonic Means (GM-HM)

$$\sqrt[n]{x_1 x_2 \dots x_n} \geq \frac{n}{\frac{1}{x_1} + \frac{1}{x_2} + \dots \frac{1}{x_n}} \quad (2)$$

The above inequalities hold for any real positive numbers $x_1, x_2, \dots x_n$ with equality if and only if $x_1 = x_2 = \dots = x_n$.

2. **Cross Entropy Properties (12 pts)**

Cross-entropy loss function (a popular loss function) is given by:

$$\text{CE}(p, x) = -x \log(p) - (1 - x) \log(1 - p)$$

.

Please refer to this loss for (a) and (b) parts.

- (2 pts) **Cross Entropy and Maximum Likelihood** For this derivation, we assume that x is binary, i.e. $x \in \{0, 1\}$. Derive the cross-entropy cost function using the maximum likelihood principle for $x \in \{0, 1\}$.

- (b) (2 pts) **Cross Entropy and KL divergence** Suggest a probabilistic interpretation of the cross-entropy cost function when $x \in (0, 1)$. (Hint: KL divergence between two distributions)
- (c) (4 pts) **Discrete distribution - Maximum Entropy** Let X be a random variable which takes n values with probabilities p_1, p_2, \dots, p_n with $p_i > 0, \forall i$. What is the distribution that maximizes entropy $H(X) = -\sum_{i=1}^n p_i \log p_i$? Derive the upper bound for the entropy $H(X)$ expressed as a function of n . (Hint : use Jensen Inequality)
- (d) (4 pts) **Continuous distribution (known mean μ and variance σ^2) - Maximum Entropy** Given mean μ and variance σ^2 , what is the continuous distribution that maximizes differential entropy $h(X) = -\int_x f(x) \log f(x) dx$? Prove it.
3. **Output size and Parameters of Convolution Layers (5 pts)**
 Consider a 3 hidden-layer convolutional neural network. Assume the input is a color image of size 128×128 in the RGB representation. The first layer convolves 64 8×8 kernels with the input, using a stride of 2 and zero-padding of 4. The second layer downsamples the output of the first layer with a 2×2 non-overlapping max pooling. The third layer convolves 128 4×4 kernels with a stride of 2 and zero-padding of 2.
- (a) (3 pts) What is the dimensionality of the output of the third layer?
- (b) (2 pts) Not including the biases, how many parameters are needed for the last layer?

4. MLP Mixer (16 pts)

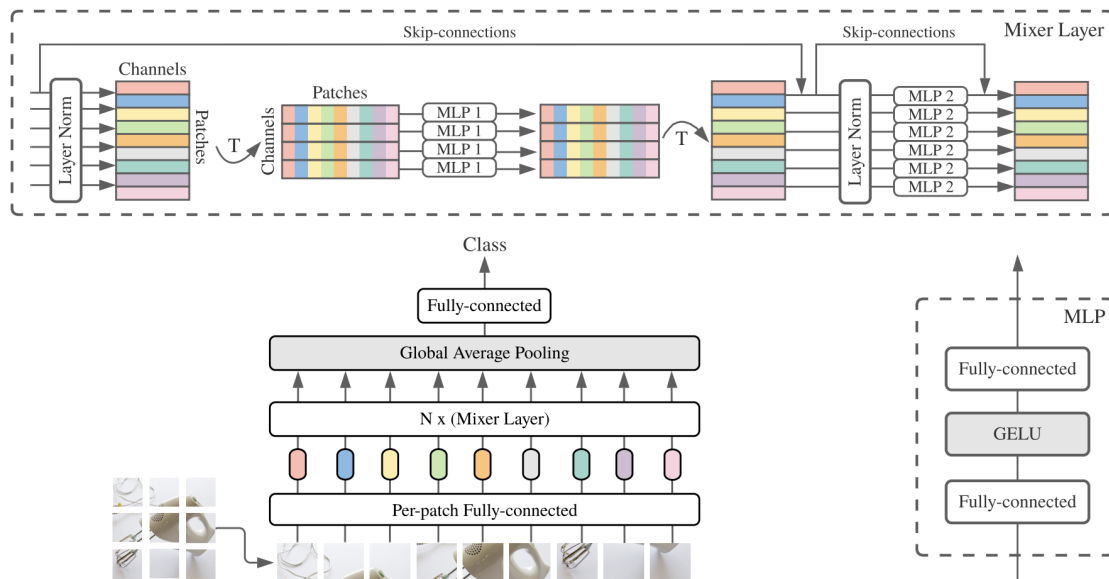


FIGURE 1 – (Borrowed from the MLP-Mixer paper.) MLP-Mixer consists of per-patch linear embeddings, Mixer layers, and a classifier head. Mixer layers contain one token-mixing MLP and one channel-mixing MLP, each consisting of two fully-connected layers and a GELU nonlinearity. Other components include : skip-connections, dropout, and layer norm on the channels.

- (a) (2 pts) **MLP Mixer Dimensions** Let's assume that Mixer architecture is being applied to an input image of size 64×64 . The Mixer's output is of size 16×128 . Determine the patch resolution P , number of patches S , as hidden dimension C (channels).
- (b) (2 pts) **MLP Mixer Complexity** Show that the computational complexity of the MLP Mixer is linear in terms of number of input patches.
- (c) (6 pts) **Input Transformation - Channel Mixing MLP** Consider the following scenario : The original input image A is of size 9×9 . We convert the input image into non-overlapping patches of size 3×3 , and then linearly project all patches with the same projection matrix. The result of these operations is a matrix X of size 9×6 . Then we apply the *channel-mixing MLP* that acts on rows of X , and is shared across all rows. The result of this operation is matrix U size 9×6 . Now consider a modified image A such that $A_{\text{modified}} = PA$, where we define matrix P in the following manner:

$$P = \begin{bmatrix} e_{\pi(1)} \\ e_{\pi(2)} \\ \vdots \\ e_{\pi(9)} \end{bmatrix} \quad (3)$$

Here e_k is k -th basis vector and π represents the permutation of indices from $1 \dots 9$. Find all possible P such that by permuting rows of U_{modified} we can get back matrix U .

- (d) (6 pts) Select one of your solutions for P and find P_{reverse} such that $P_{\text{reverse}}U_{\text{modified}} = U$.

5. Gradient Descent Convergence (12 pts)

- (a) (6 pts) **Convex Function Convergence** Consider the following function:

$$f(x) = \begin{cases} \frac{3}{4}(1-x)^2 - 2(1-x) & \text{if } x > 1 \\ \frac{3}{4}(1+x)^2 - 2(1+x) & \text{if } x < -1 \\ x^2 - 1 & \text{otherwise} \end{cases} \quad (4)$$

Show that f is a convex function. Find its unique minimizer and its gradient. Consider the following algorithm : $x_t = x_{t-1} - \eta f'(x_{t-1})$ where $\eta = 1$. Will this algorithm converge to a stationary point if it starts at point x_0 , where $x_0 > 1$? Why or why not?

- (b) (6 pts) **Prove Convergence of Gradient Descent to Stationary Point in Non-Convex case** Suppose we are trying to minimize the function $F(w)$ that is L -smooth. Let F_* be the minimal function value (i.e. the value at the global minima). Using $\eta = \frac{1}{L}$, prove that gradient descent will "almost" converge to a stationary point in a bounded (and polynomial) number of steps. Precisely,

$$\min_{k < K} \|\nabla F(w^{(k)})\|^2 \leq \frac{2L}{K} (F(w^{(0)}) - F_*) \quad (5)$$

Hints:

- i. L -smoothness implies that:

$$F(w^{(k+1)}) \leq F(w^{(k)}) - \eta \|\nabla F(w^{(k)})\|^2 + \frac{1}{2} \eta^2 L \|\nabla F(w^{(k)})\|^2 \quad (6)$$

Combine this with $\eta = \frac{1}{L}$

- ii. Use the fact that the minimum of a sequence of elements is less than the average of the sequence.