**WizFi360-EVB-Pico**

**Getting Started Guide**

**for AWS IoT Core**

**Version 1.0.0**



<http://www.wiznet.io/>

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# Document Information

## Revision History (Version, Date, Description of change)

|  |  |  |
| --- | --- | --- |
| **Version** | **Date** | **Description of change** |
| V1.0.0 | 2022-06-24 | Initial Release |

# Overview

The WizFi360-EVB-Pico is a microcontroller evaluation board based on the Raspberry Pi RP2040 microcontroller chip and adds Wi-Fi connectivity using WizFi360. The WizFi360-EVB-Pico has the same role as the Raspberry Pi Pico platform and includes WizFi360, so the Wi-Fi function is basically included.

* Raspberry Pi Pico Clone
* Wi-Fi (WizFi360 Wi-Fi Module)

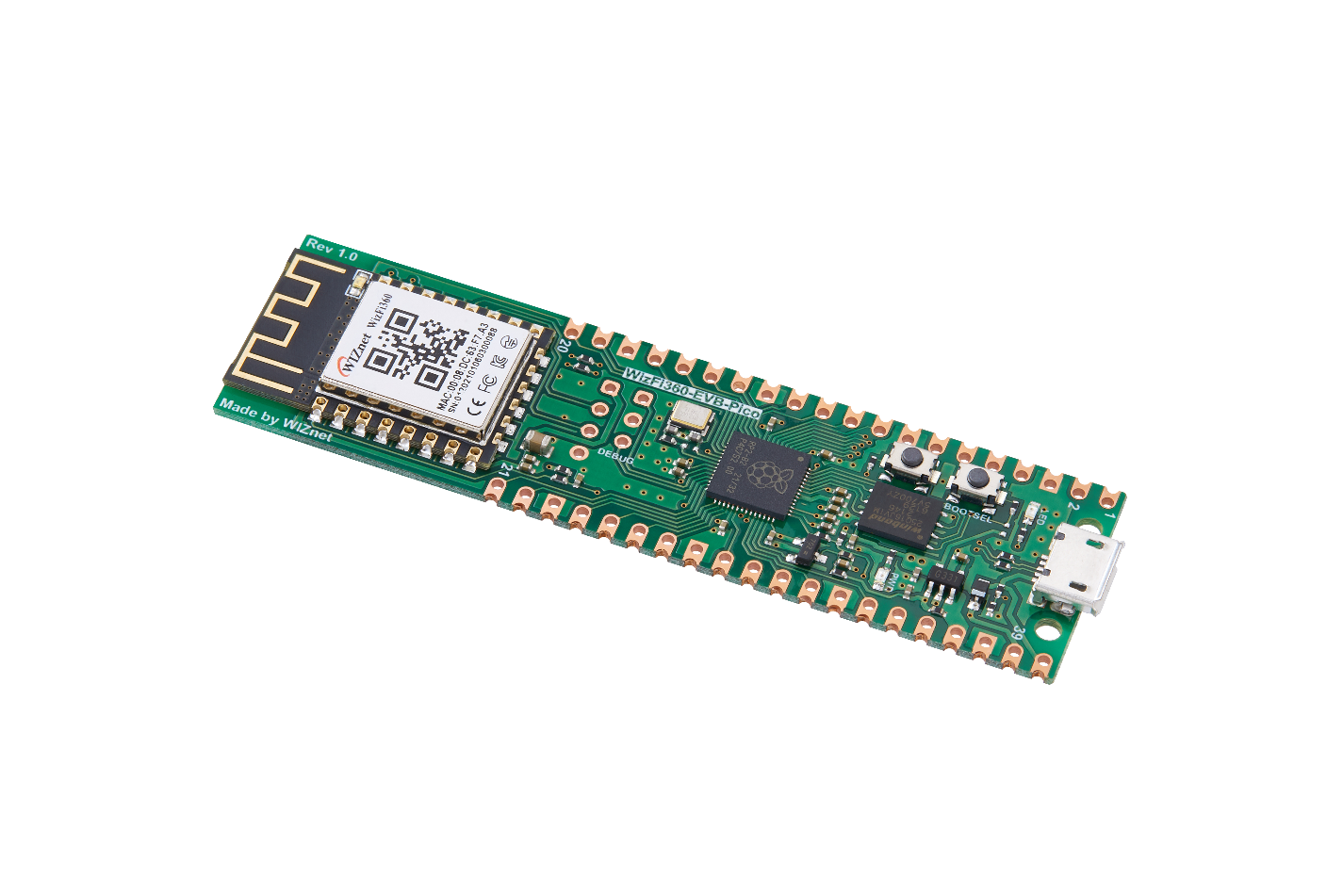


Figure . WizFi360-EVB-Pico

# Hardware Description

## DataSheet

<https://docs.wiznet.io/assets/images/WizFi360-EVB-Pico_SCH_V100-1-44628336cfa4d71657c04fbf4bf9b8c4.png>

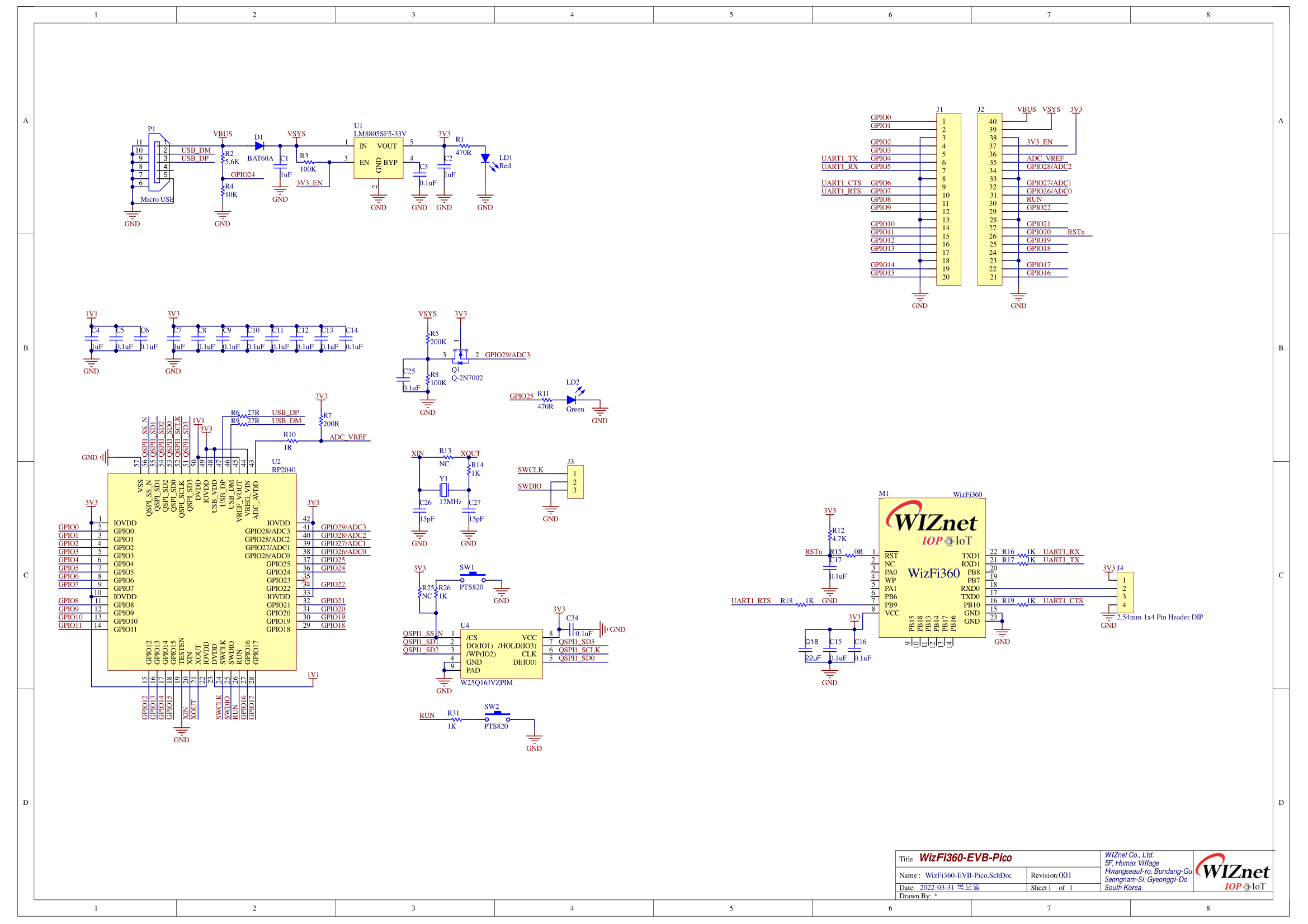


Figure . WizFi360-EVB-Pico schematic

## Standard Kit Contents

* WizFi360-EVB-Pico : 1EA
* 1 x 20 2.54mm pitch pin header : 2EA

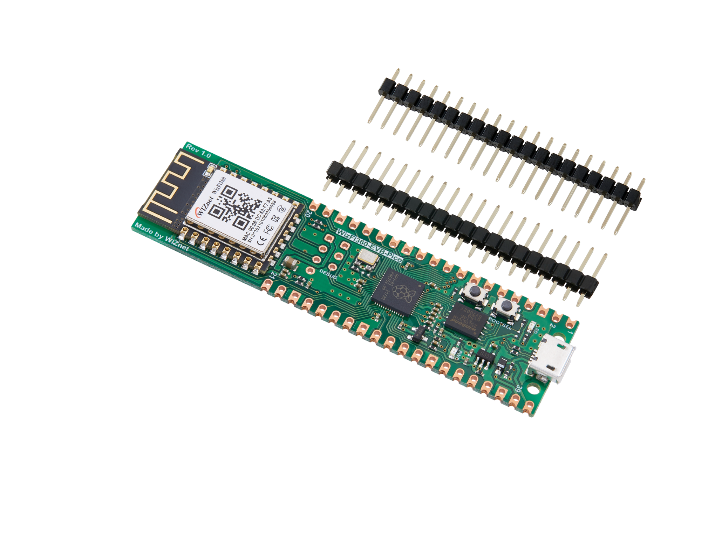


Figure . WizFi360-EVB-Pico package

## User Provided items

* USB type A to USB micro B cable



Figure . USB type A to USB micro B cable

* Desktop or laptop

## 3rd Party purchasable items

None

## Additional Hardware References

<https://docs.wiznet.io/Product/Open-Source-Hardware/wizfi360-evb-pico>

# Set up your Development Environment

## Tools Installation (IDEs, Toolchains, SDKs)

Windows 10 was used during preparation of this guide document. Linux and MacOS user should use compatible software, hardware-wise there is no difference. Please refer to the guide in section 4.4 to find instructions for installing toolchain on Linux and MacOS.

1) Install the Toolchain

To build you will need to install extra tools below.

* [ARM GCC compiler](https://developer.arm.com/tools-and-software/open-source-software/developer-tools/gnu-toolchain/gnu-rm/downloads)
* [CMake](https://cmake.org/download/)
* [Build Tools for Visual Studio](https://visualstudio.microsoft.com/downloads/#build-tools-for-visual-studio-2019)
* [Python 3.9](https://www.python.org/downloads/windows/)
* [Git](https://git-scm.com/download/win)
* [Visual Studio Code](https://code.visualstudio.com/download)

Download the executable installer for each of these from the links above, and then carefully follow the instructions in the following sections to install all six packages on to your Windows computer.

1. Install ARM GCC compiler

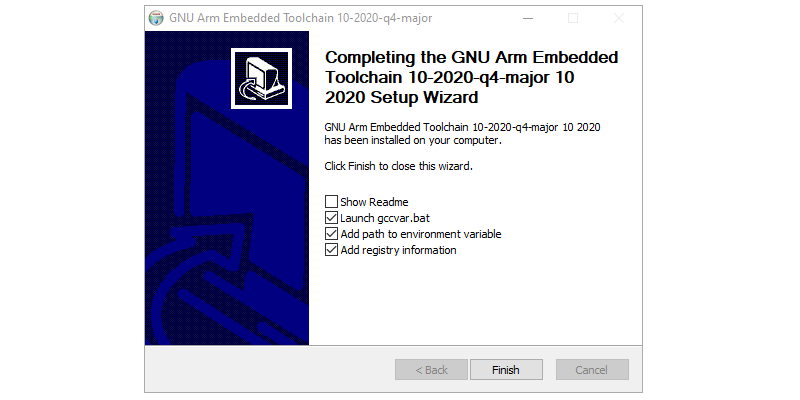


Figure . Install ARM GCC compiler

During installation you should check the box to register the path to the ARM compiler as an environment variable in the Windows shell when prompted to do so.

1. Install CMake

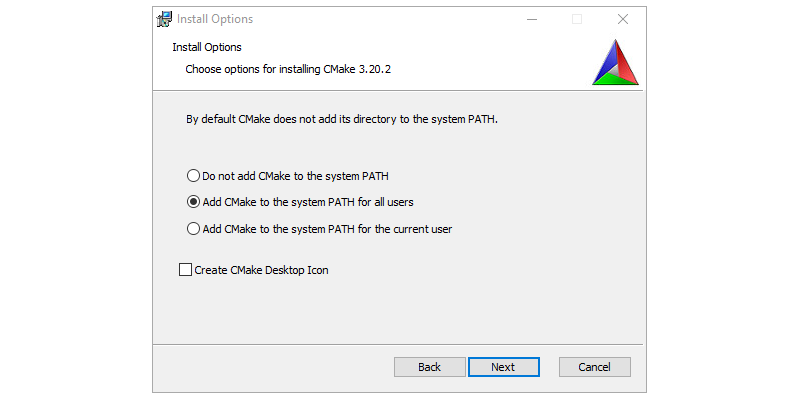


Figure . Install CMake

During the installation add CMake to the system PATH for all users when prompted by the installer.

1. Install Build Tools for Visual Studio

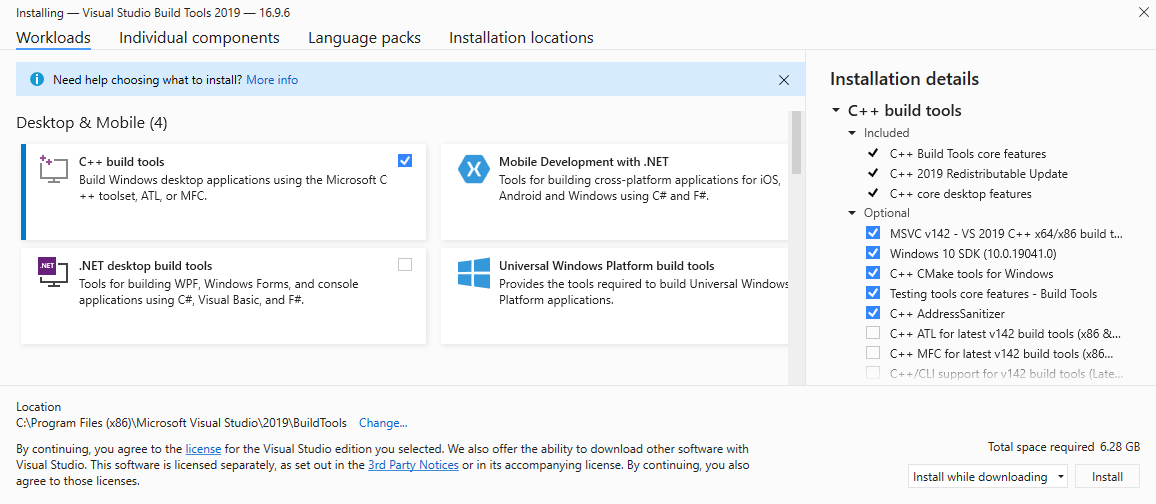


Figure . Install Build Tools for Visual Studio

When prompted by the Build Tools for Visual Studio installer you need to install the C++ build tools only.

1. Install Python 3.9

During the installation, ensure that it's installed 'for all users' and add Python 3.9 to the system PATH when prompted by the installer. You should additionally disable the MAX\_PATH length limit when prompted at the end of the Python installation.

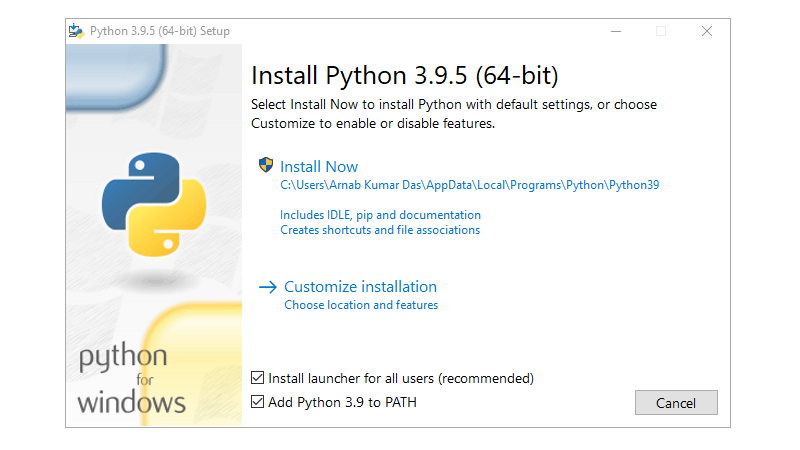


Figure . Install Python

1. Install Git

When installing Git you should ensure that you change the default editor away from vim.

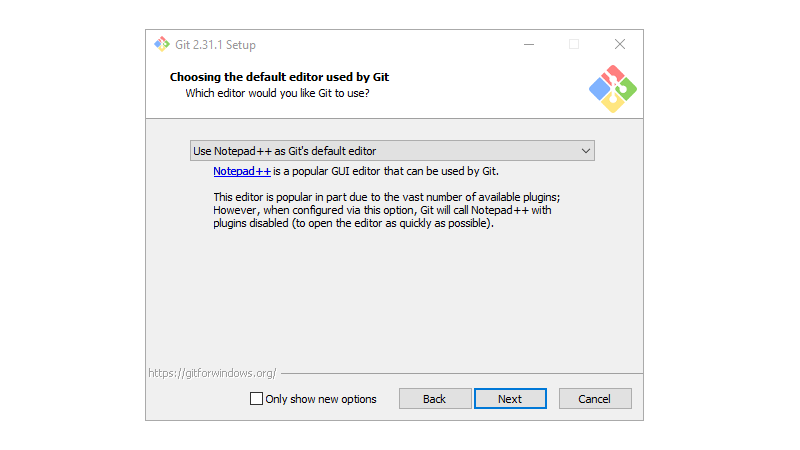


Figure . Install Git

1. Install Visual Studio Code

During the installation add Visual Studio Code to the system PATH.

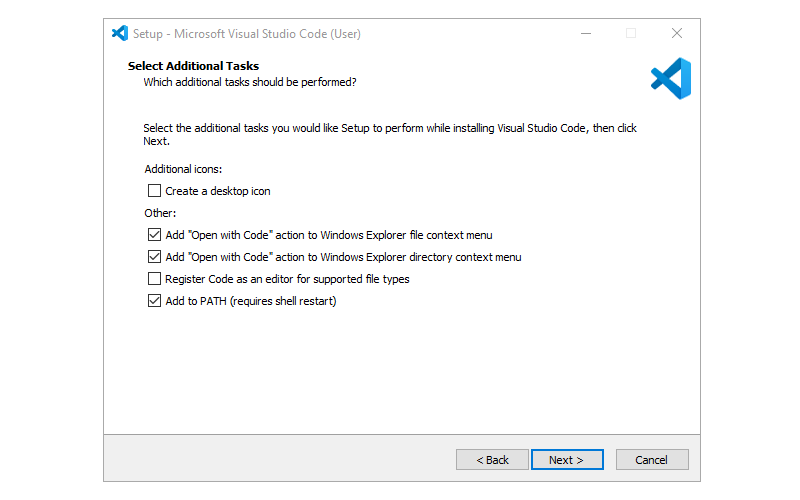


Figure . Install Visual Studio Code

2) Clone the Raspberry Pi Pico SDK and WIZnet example repository using below commands

* SDK : <https://github.com/raspberrypi/pico-sdk>
* Example : <https://github.com/Wiznet/WizFi360-EVB-Pico-AWS-C>

|  |
| --- |
| // create a project directory  D:\>mkdir RP2040  D:\>cd RP2040  // get the SDK  D:\RP2040> git clone -b master https://github.com/raspberrypi/pico-sdk.git  D:\RP2040> cd pico-sdk  D:\RP2040\pico-sdk> git submodule update --init  // get the example  D:\RP2040\pico-sdk> cd ..  D:\RP2040> git clone -b main https://github.com/Wiznet/WizFi360-EVB-Pico-AWS-C.git  D:\RP2040> cd WizFi360-EVB-Pico-AWS-C  D:\RP2040\ WizFi360-EVB-Pico-AWS-C > git submodule update --init |

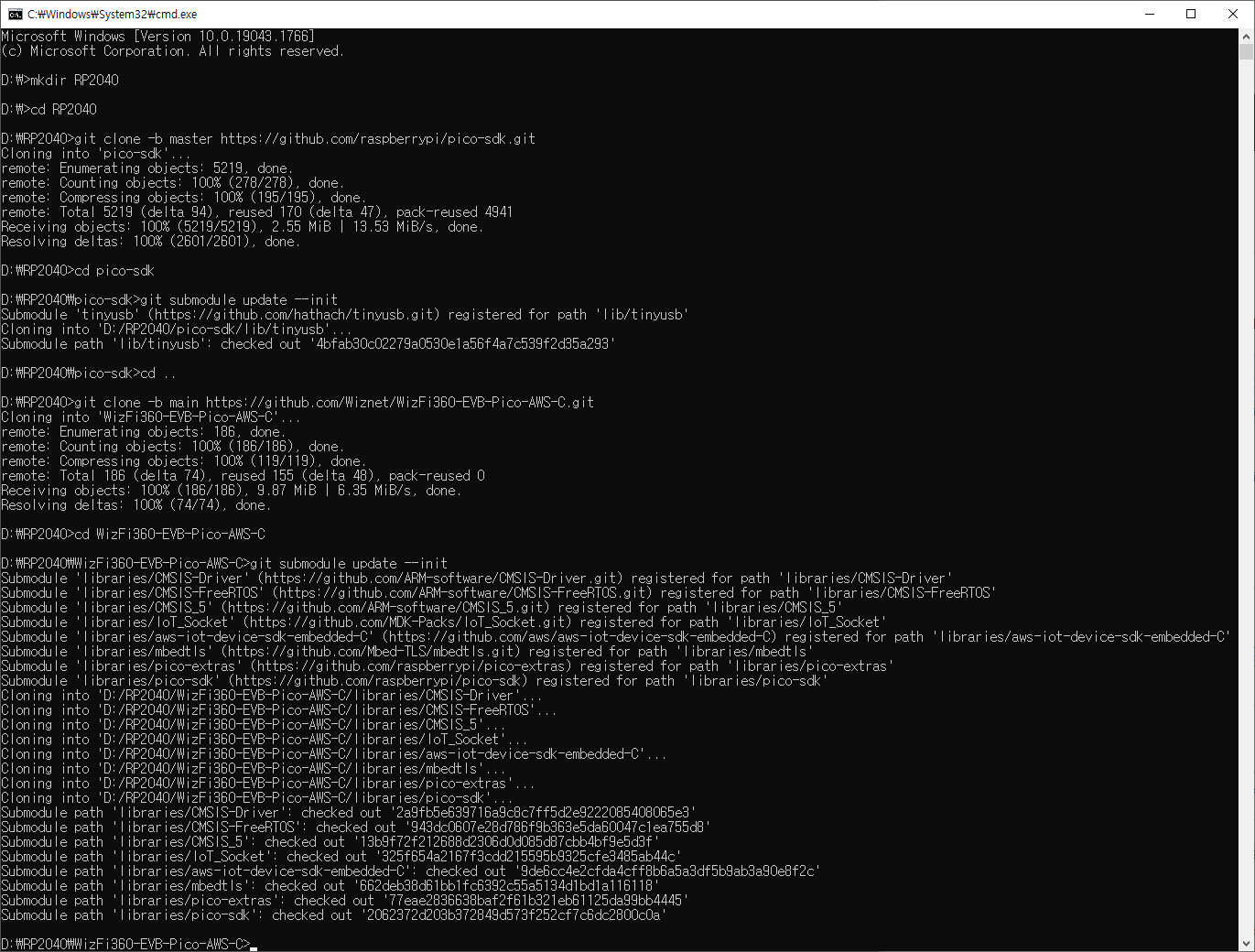


Figure . Get the SDK and example

3) Set up Visual Studio Code

1. Open a new Visual Studio 2019 Developer Command Prompt
2. Run the below command to open Visual Studio Code

|  |
| --- |
| D:> code |

1. Opening Visual Studio Code from Developer Command Prompt
2. Open Extensions

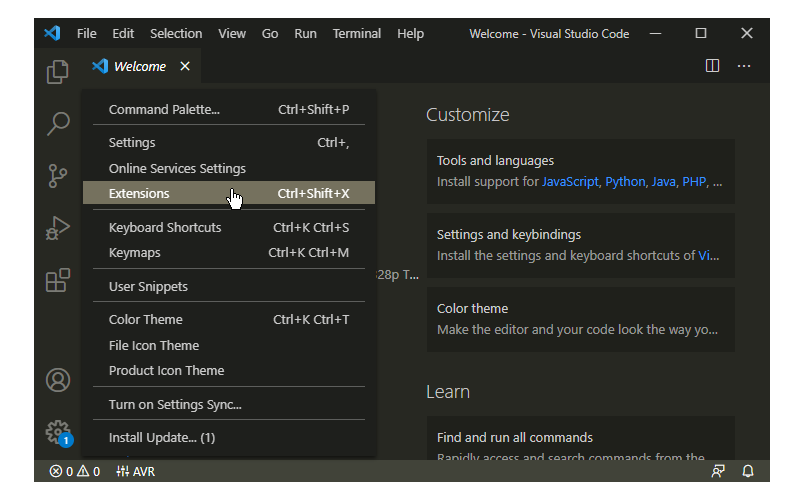


Figure . Install Extensions in Visual Studio Code

1. Install some tools
   * CMake Tools
   * C/C++
2. Open CMake Tools Extension Settings
3. Scroll down and set up some items
   * Add Cmake: Configure Environment Item as PICO\_SDK\_PATH
   * Add Cmake: Configure Environment Value as D:\RP2040\pico-sdk
   * Add Cmake: Generator as NMake Makefiles

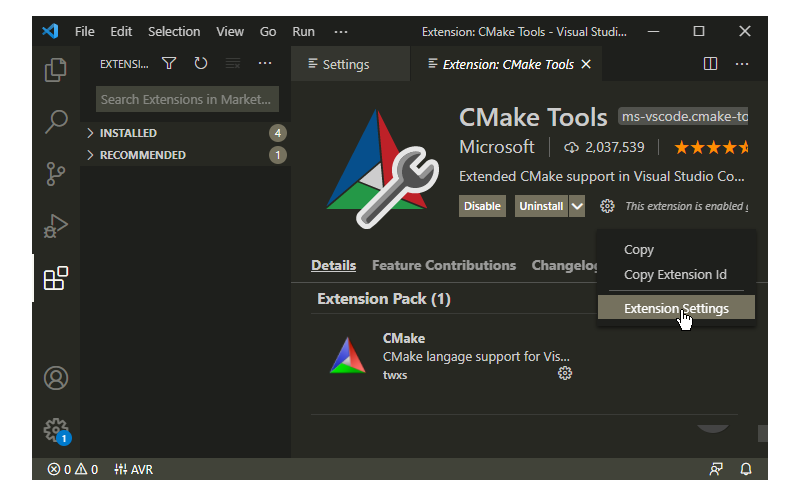


Figure . CMake Tools Extension Settings in Visual Studio Code



Figure . Add CMake Configure Environment path

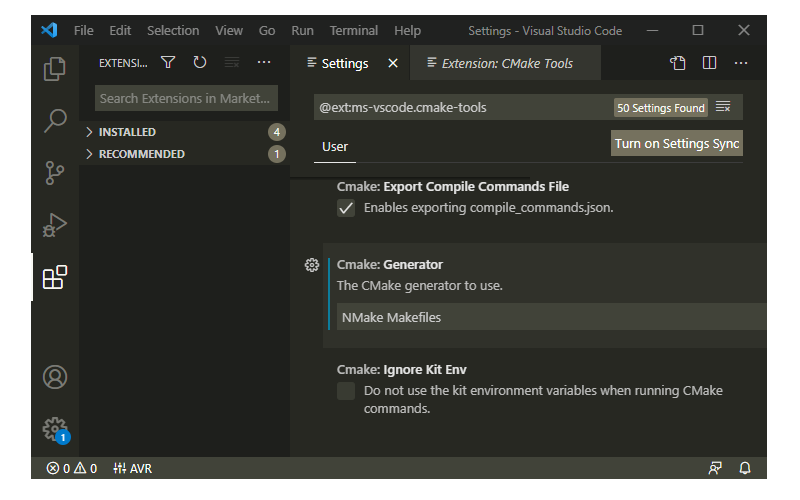


Figure . Add CMake Generator name

1. Add folder WizFi360-EVB-Pico-AWS-C to Visual Studio Code
2. Visual Studio Code will scan for kits
3. Select 'Yes' when asked: Would you like to configure project WizFi360-EVB-Pico-AWS-C?
4. Select 'Yes' if you like to configure the project upon opening
5. Click CMake in the bottom bar to select the kit WizFi360-EVB-Pico-AWS-C
6. Select Debug / Release based on your preference
7. Visual Studio Code will save all file and configure the project
8. Click on Build to build all examples, if no error Build will finish with exit code 0

## Other software required to develop and debug applications for the device

Serial terminal program is required for operation check and debugging.

* [Tera Term](https://osdn.net/projects/ttssh2/releases/)

You may use your preferred serial terminal program.

## Other pre-requisites

None

## Additional Software References

Refer to the '9.2. Building on MS Windows' section of 'Getting started with Raspberry Pi Pico' document below to set up the development environment.

* [Getting started with Raspberry Pi Pico](https://datasheets.raspberrypi.com/pico/getting-started-with-pico.pdf)

And refer to the links below for instructions how to setup environment and proceed with tests.

* [Getting Started with AWS IoT SDK Examples](https://github.com/Wiznet/WizFi360-EVB-Pico-AWS-C/blob/main/getting_started.md)
* [Connect AWS IoT through MQTT](https://github.com/Wiznet/WizFi360-EVB-Pico-AWS-C/tree/main/examples/aws_mqtt_demo)

# Set up your hardware

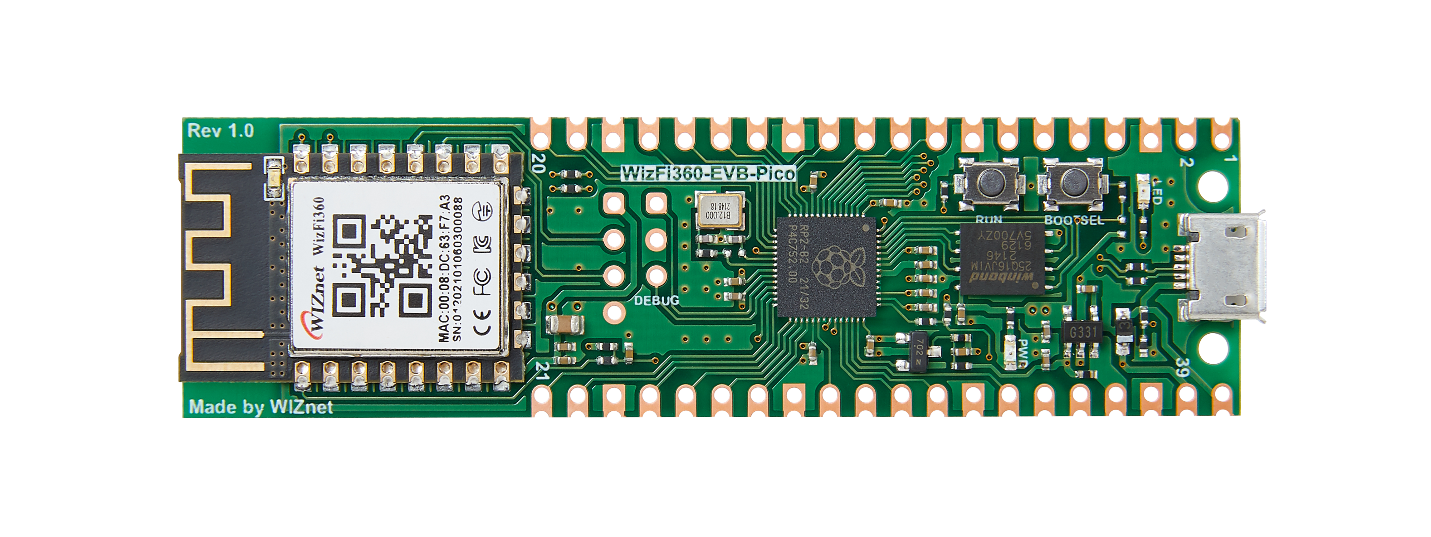


Figure . WizFi360-EVB-Pico front

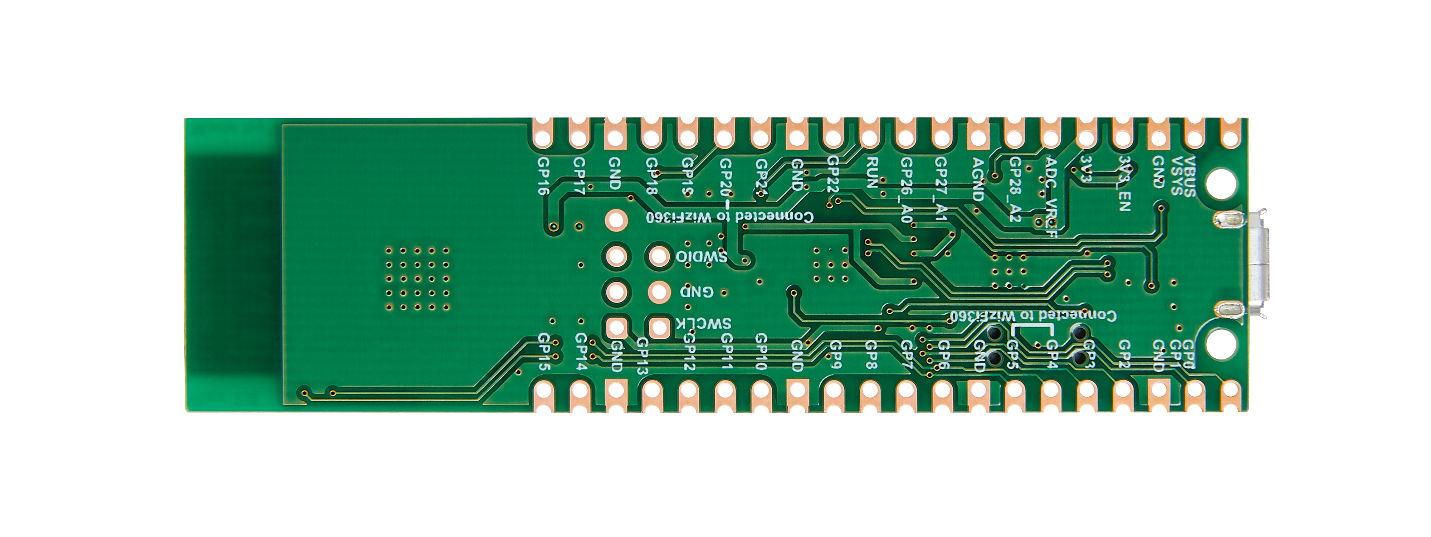


Figure . WizFi360-EVB-Pico back

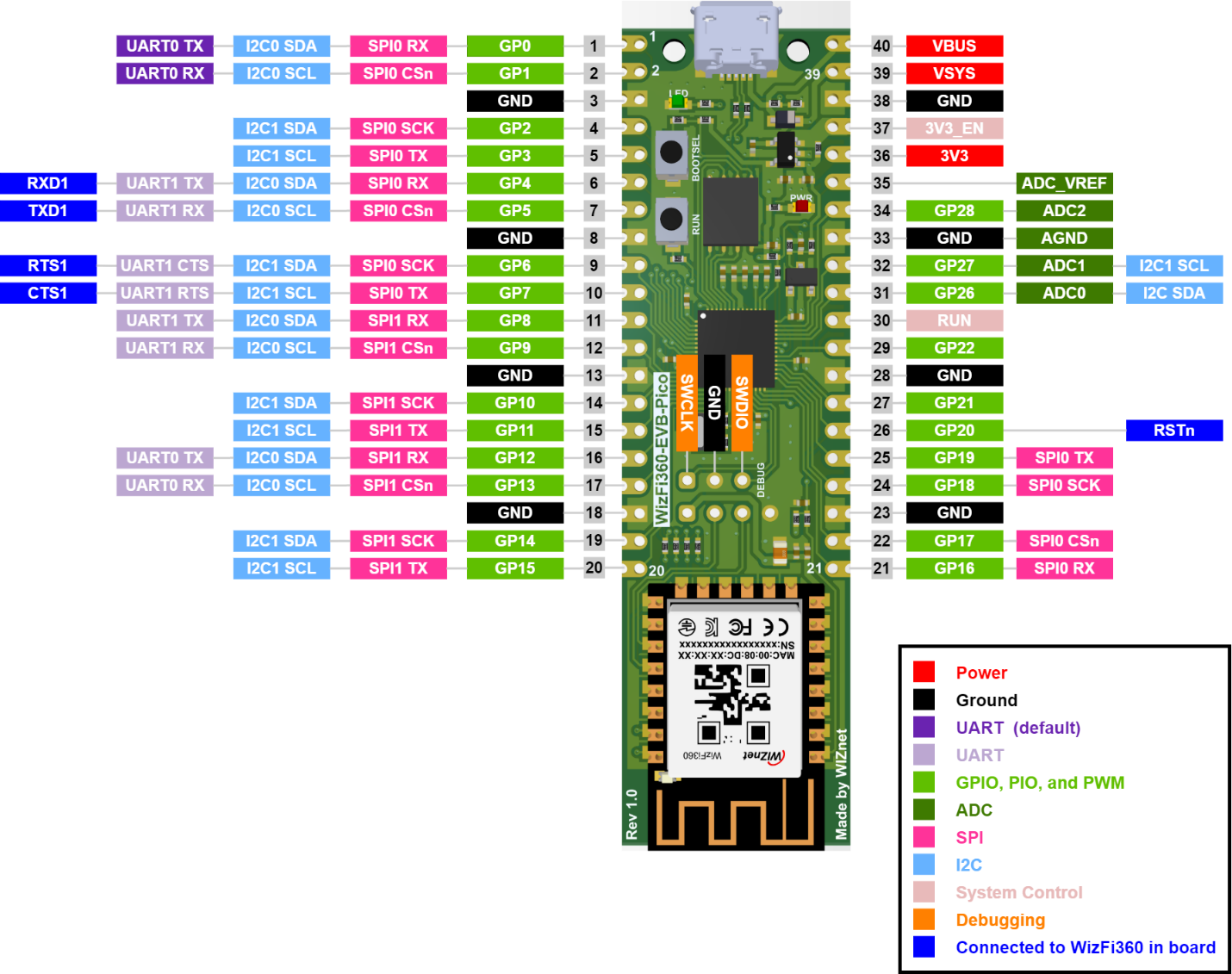


Figure . WizFi360-EVB-Pico pin-out

WizFi360-EVB-Pico pin-out is directly connected to the GPIO of RP2040 as shown in the picture above. It has the same pinout as the Raspberry Pi Pico board. However, GPIO4, GPIO5, GPIO6, GPIO7, GPIO20 are connected to WizFi360 inside the board. These pins enable UART communication with WizFi360 to use Wi-Fi function. If you are using the Wi-Fi function, these pins cannot be used for any other purpose.

The RP2040 GPIO used inside WizFi360-EVB-Pico is as follows.

|  |  |  |
| --- | --- | --- |
| **I/O** | **Pin name** | **Description** |
| O | GPIO4 | Connected to RXD1 on WizFi360 |
| I | GPIO5 | Connected to TXD1 on WizFi360 |
| O | GPIO6 | Connected to RTS1 on WizFi360 |
| I | GPIO7 | Connected to CTS1 on WizFi360 |
| O | GPIO20 | Connected to RST on WizFi360 |
| I | GPIO24 | VBUS sense - high if VBUS is present, else low |
| O | GPIO25 | Connected to user LED |
| I | GPIO29 | Used in ADC mode (ADC3) to measure VSYS/3 |

Apart from GPIO and ground pins, there are 7 other pins on the main 40-pin interface.

|  |  |  |
| --- | --- | --- |
| **Pin no.** | **Pin name** | **Description** |
| PIN40 | VBUS | Micro-USB input voltage, connected to micro-USB port pin 1. Nominally 5V. |
| PIN39 | VSYS | Main system input voltage, which can vary in the allowed range 4.3V to 5.5V, and is used by the on-board LDO to generate the 3.3V. |
| PIN37 | 3V3\_EN | Connects to the on-board LDO enable pin. To disable the 3.3V (which also de-powers the RP2040 and WizFi360), short this pin low. |
| PIN36 | 3V3 | Main 3.3V supply to RP2040 and WizFi360, generated by the on-board LDO. |
| PIN35 | ADC\_VREF | ADC power supply (and reference) voltage, and is generated on WizFi360-EVB-Pico by filtering the 3.3V supply. |
| PIN33 | AGND | Ground reference for GPIO26-29. |
| PIN30 | RUN | RP2040 enable pin, To reset RP2040, short this pin low. |

# Setup your AWS account and Permissions

Refer to the instructions at [Set up your AWS Account](https://docs.aws.amazon.com/iot/latest/developerguide/setting-up.html). Follow the steps outlined in these sections to create your account and a user and get started:

* Sign up for an AWS account and
* Create a user and grant permissions.
* Open the AWS IoT console

Pay special attention to the Notes.

# Create Resources in AWS IoT

Refer to the instructions at [Create AWS IoT Resources](https://docs.aws.amazon.com/iot/latest/developerguide/create-iot-resources.html). Follow the steps outlined in these sections to provision resources for your device:

* Create an AWS IoT Policy
* Create a thing object

Pay special attention to the Notes.

# Provision the Device with credentials

You need to enter the root certificate, client certificate and private key that were downloaded earlier.

Root certificate uses the RSA 2048 bit key, Amazon Root CA 1, and does not use the public key.

Device certificate and key can be set in 'mqtt\_certificate.h' in 'WizFi360-EVB-Pico-AWS-C/examples/aws\_mqtt\_demo/' directory.

|  |
| --- |
| uint8\_t mqtt\_root\_ca[] =  "-----BEGIN CERTIFICATE-----\r\n"  "...\r\n"  "-----END CERTIFICATE-----\r\n";  uint8\_t mqtt\_client\_cert[] =  "-----BEGIN CERTIFICATE-----\r\n"  "...\r\n"  "-----END CERTIFICATE-----\r\n";  uint8\_t mqtt\_private\_key[] =  "-----BEGIN RSA PRIVATE KEY-----\r\n"  "...\r\n"  "-----END RSA PRIVATE KEY-----\r\n"; |



Figure . Set up certificates

# Build the demo

1. Click 'build' in the status bar at the bottom of Visual Studio Code or press the 'F7' button on the keyboard to build.
2. When the build is completed, 'aws\_mqtt\_demo.uf2' is generated in 'WizFi360-EVB-Pico-AWS-C/build/examples/aws\_mqtt\_demo/' directory.

# Run the demo

1. While pressing the BOOTSEL button of WizFi360-EVB-Pico power on the board, the USB mass storage 'RPI-RP2' is automatically mounted.

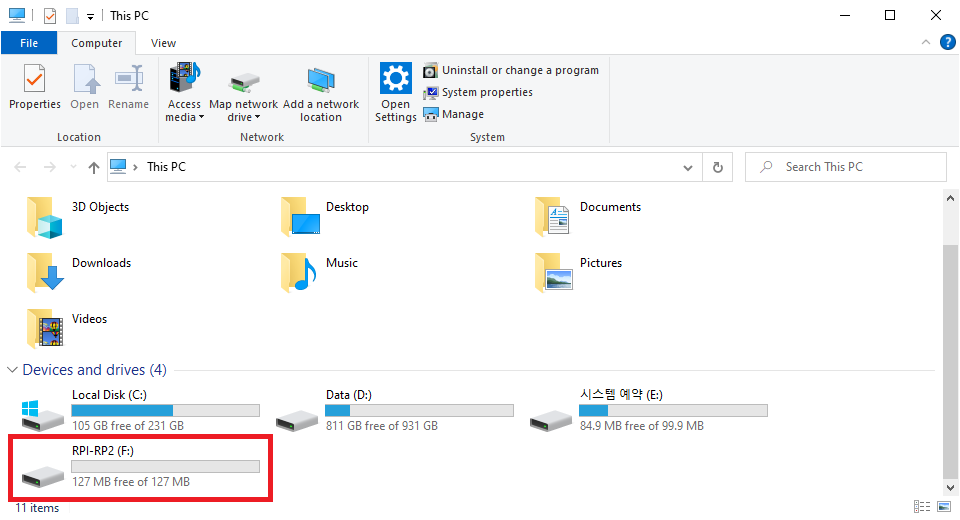


Figure . Automatically mounted USB mass storage 'RPI-RP2'

1. Drag and drop 'aws\_iot\_mqtt.uf2' onto the USB mass storage device 'RPI-RP2'.
2. Connect to the serial COM port of WizFi360-EVB-Pico with Tera Term.

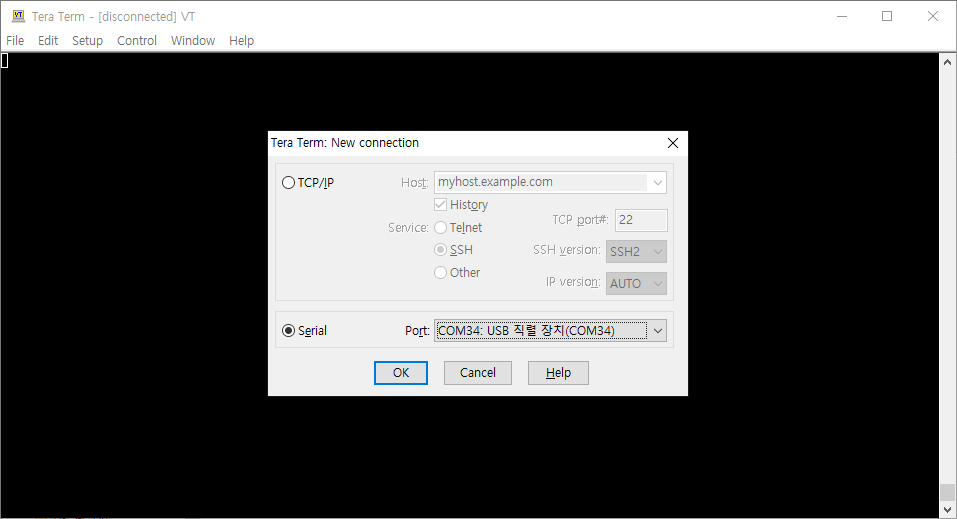


Figure . Connect to the serial COM port of WizFi360-EVB-Pico

1. When connecting to the serial COM port of WizFi360-EVB-Pico, use following settings to set up the serial port.

* Baud rate : 115,200
* Data bit : 8
* Parity bit : none
* Stop bit : 1
* Flow control : none

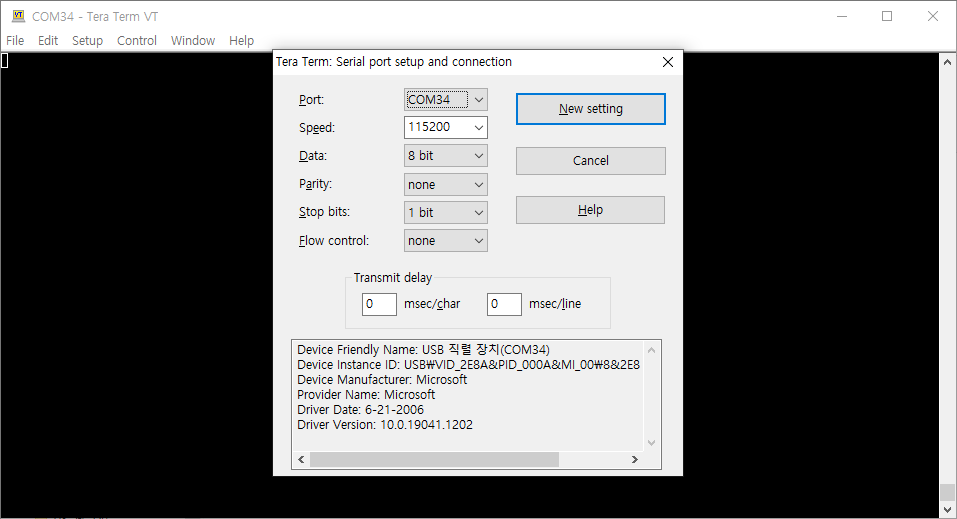


Figure . Set up serial port

1. Reset your board.
2. If the Connect AWS IoT through MQTT example works normally on WizFi360-EVB-Pico, you can see the network information of WizFi360-EVB-Pico, connecting to the AWS IoT and publishing the message.

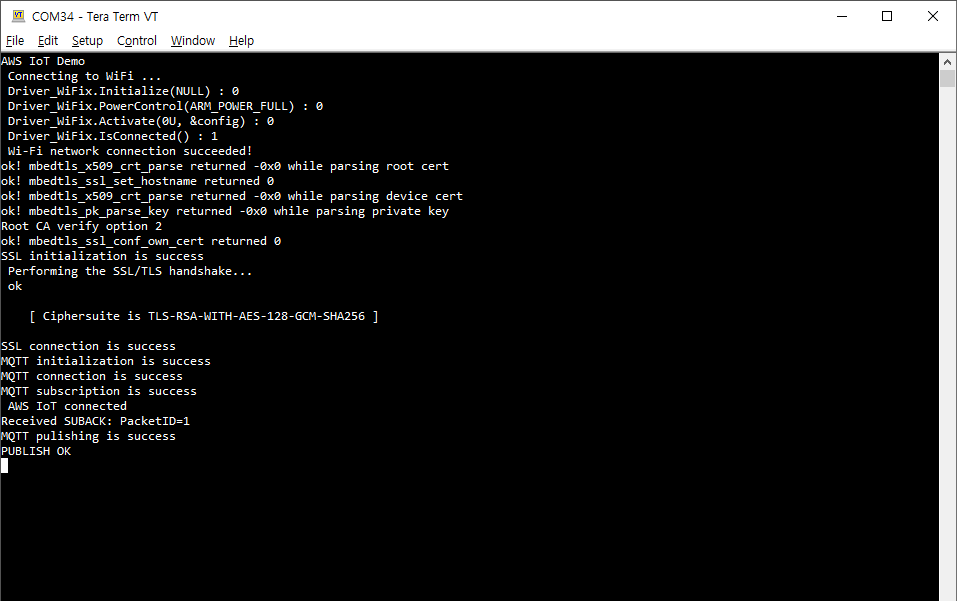


Figure . Publish the message from WizFi360-EVB-Pico

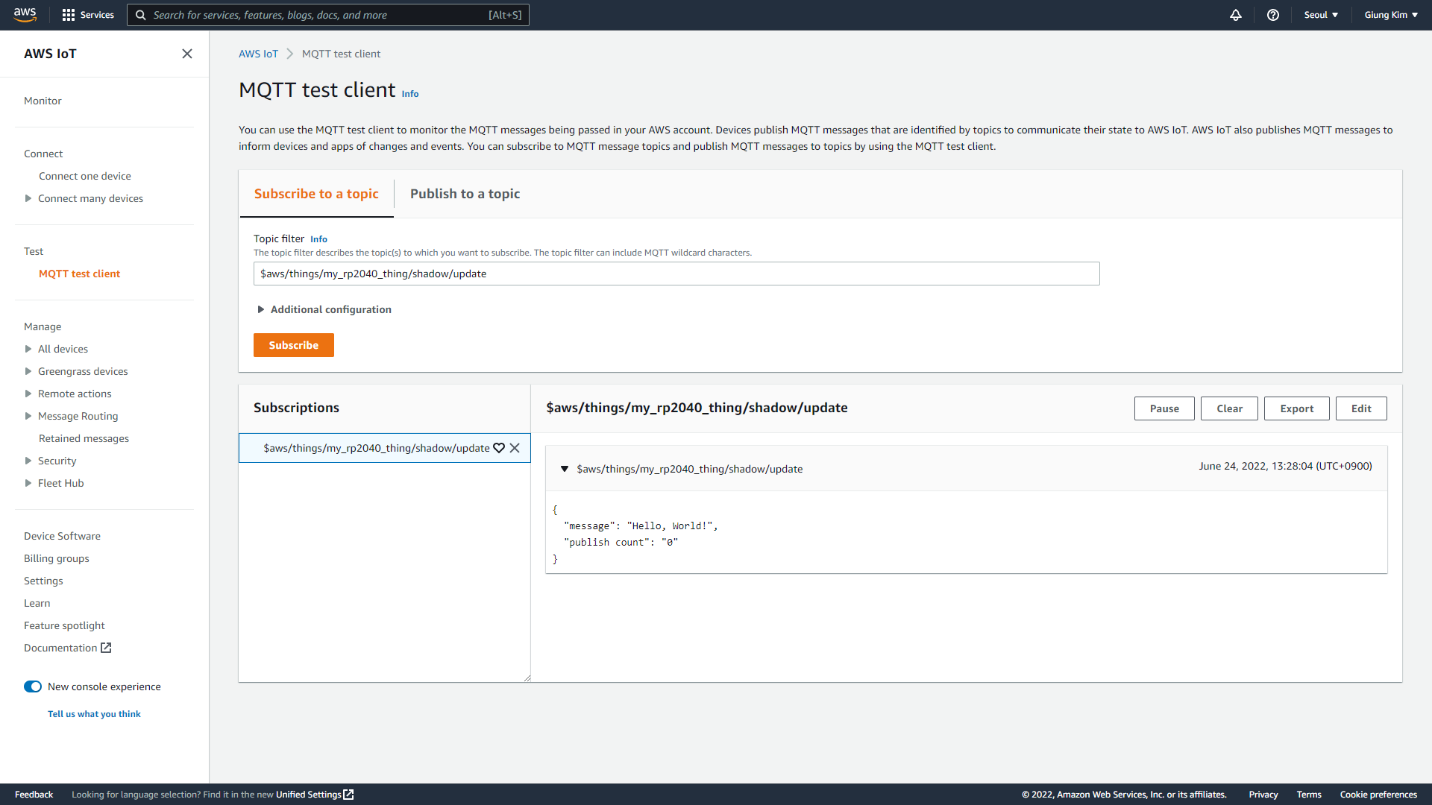


Figure . Receive the message about subscribed topic from IoT Core

1. If you publish the message through the test function in AWS IoT Core to the subscribe topic, you can see that the WizFi360-EVB-Pico receive the message about the subscribe topic.

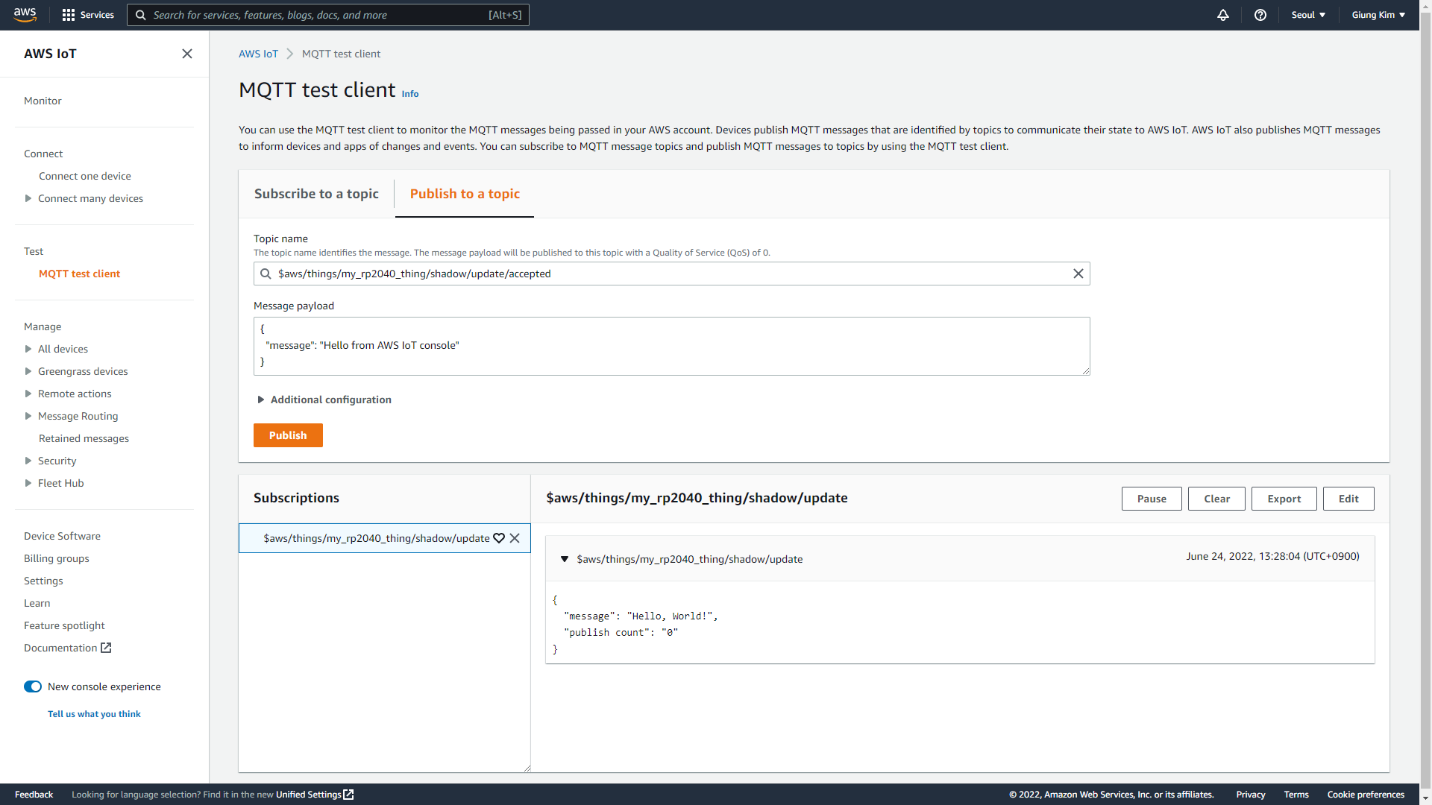


Figure . Publish the message from IoT Core

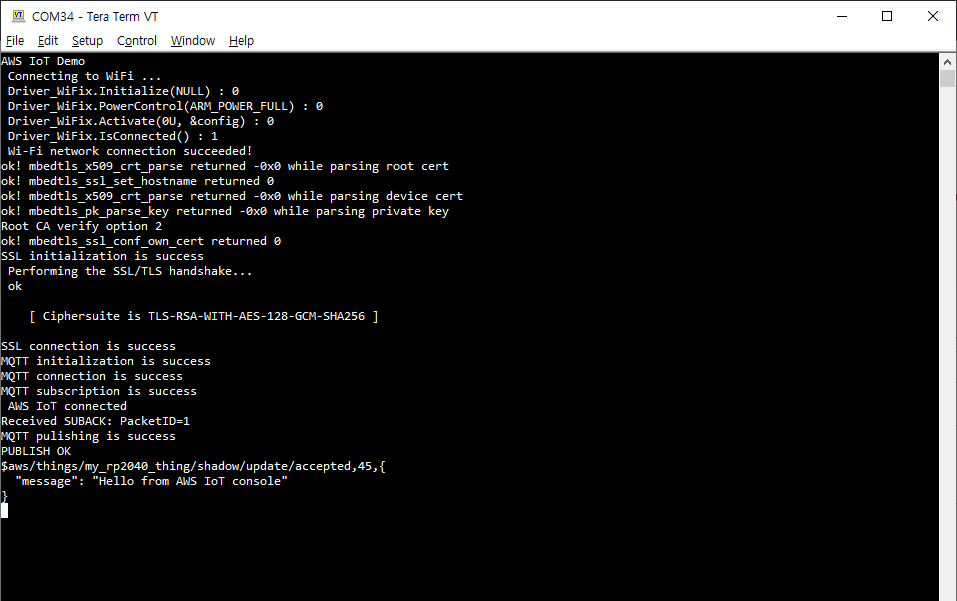


Figure . Receive the message about subscribed topic from WizFi360-EVB-Pico

# Debugging

1. Connect to the serial COM port of WizFi360-EVB-Pico with Tera Term to view logs and debugging.

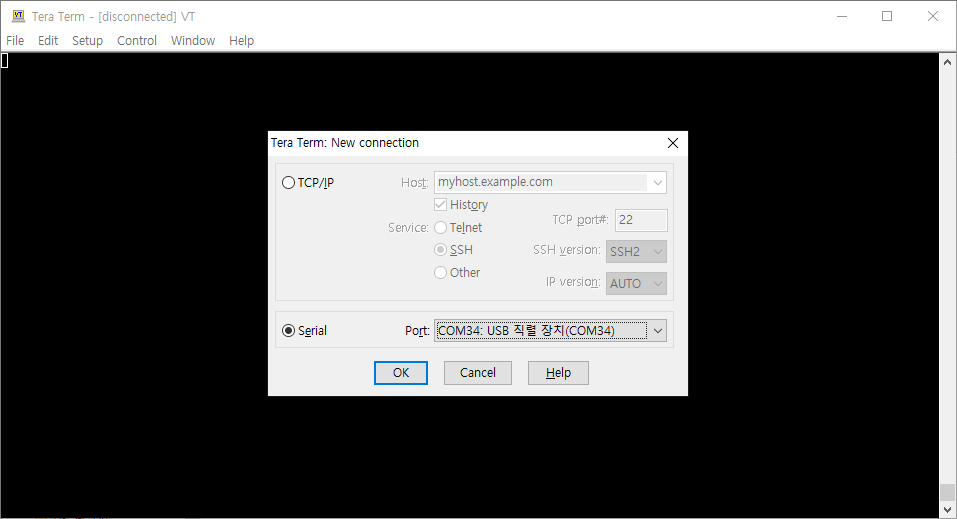


Figure . Connect to the serial COM port of WizFi360-EVB-Pico

1. When connecting to the serial COM port of WizFi360-EVB-Pico, use following settings to set up the serial port.

* Baud rate : 115,200
* Data bit : 8
* Parity bit : none
* Stop bit : 1
* Flow control : none

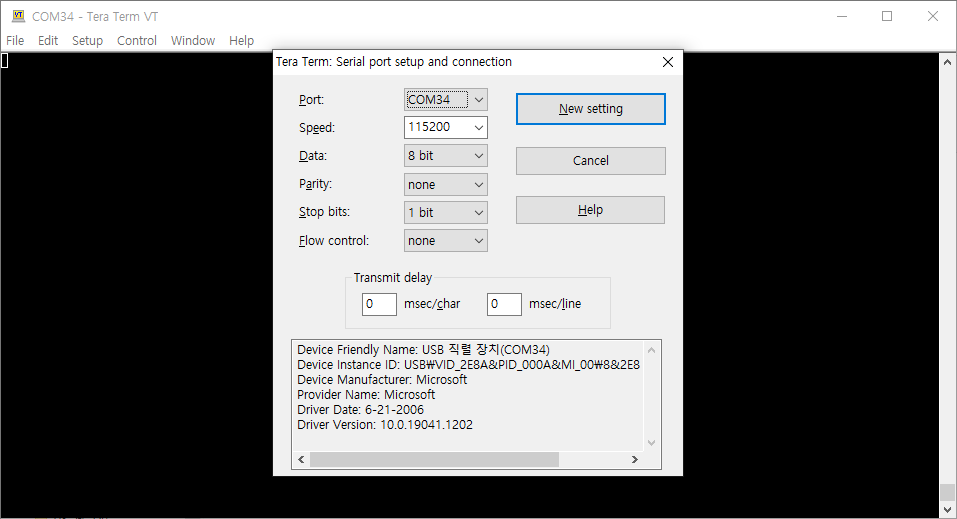


Figure . Set up serial port

1. If everything works normally, you can see the Wi-Fi- connection log, publishing the message at intervals of 10 seconds and receiving the message about the subscribe topic through logs.

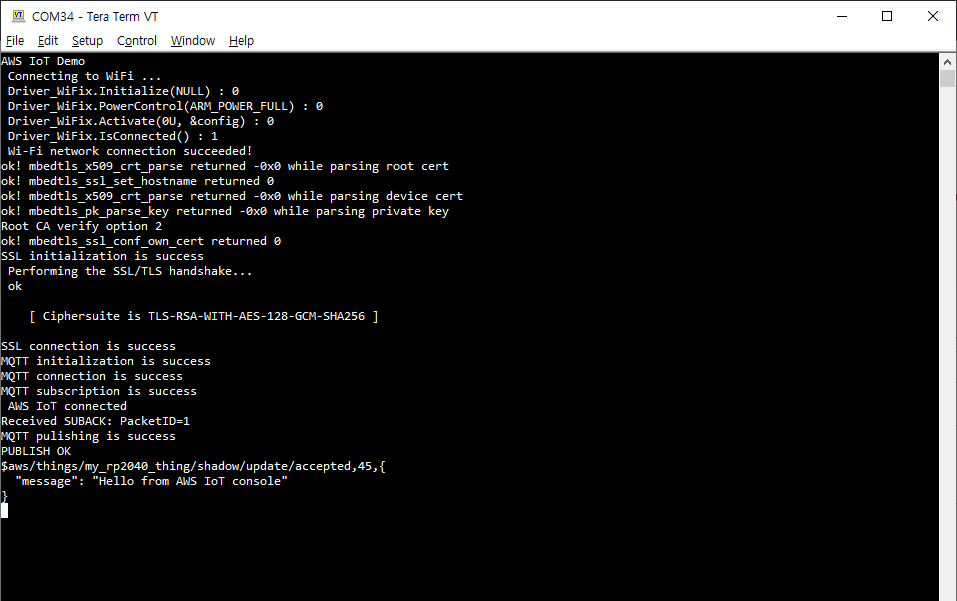


Figure . works normally

1. If there occurs any problem, the error log is printed showing function what the problem has occurred.

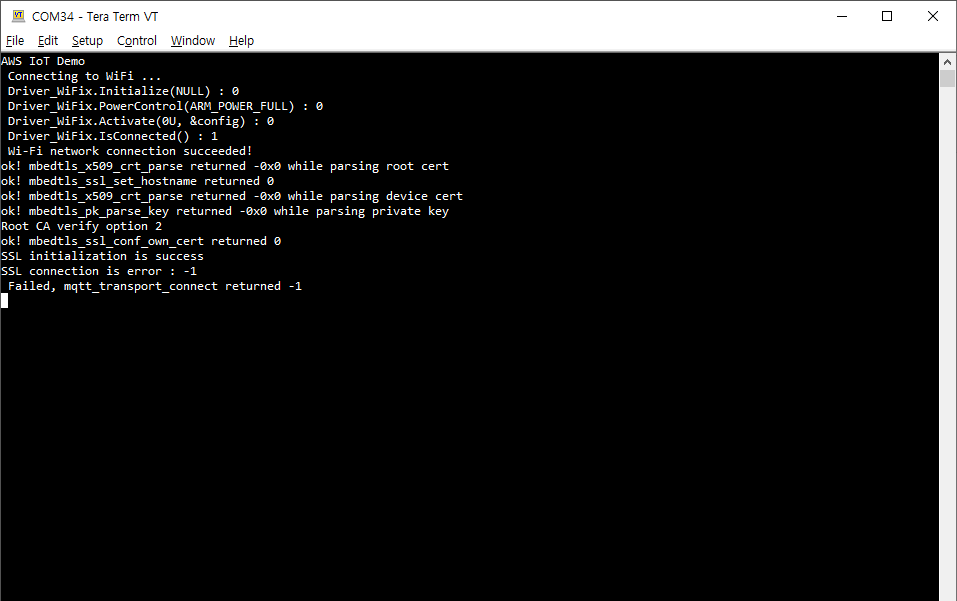


Figure . Failed to connect to IoT Core

# Troubleshooting

If you have any questions or problems while using the WizFi360-EVB-Pico examples, please leave them at the link below.

* [WIZnet Developer Forum](https://forum.wiznet.io/)
* [WizFi360-EVB-Pico-C Issues](https://github.com/Wiznet/WizFi360-EVB-Pico-C/issues)
* [WizFi360-EVB-Pico-AWS-C Issues](https://github.com/Wiznet/WizFi360-EVB-Pico-AWS-C/issues)