Application Note

LOOPBACK Example

Version 1.0.0

For more information, visit our website at http://www.wiznet.io

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1 Introduction

This Application Note covers the implementation of Loopback on WIZnet's TOE Chip. The Loopback implementation includes TCP server, TCP client, and UDP.

2 Github Link

https://github.com/WIZnet-ioNIC/WIZnet-PICO-C/tree/main/examples/loopback

3 Applicable products

Raspberry Pi Pico & WIZnet Ethernet HAT

W5100S-EVB-Pico

W5500-EVB-Pico

W55RP20-EVB-Pico

W5100S-EVB-Pico2

W5500-EVB-Pico2

4 How to Test Loopback Example

4.1 Step 1: Prepare software

The following serial terminal programs are required for Loopback example test, download and install from below links.

- **Tera Term**
- **Hercules**

4.2 Step 2: Prepare hardware

If you are using W5100S-EVB-Pico, W5500-EVB-Pico, W55RP20-EVB-Pico, W5100S-EVB-Pico2 or W5500-EVB-Pico2, you can skip '1. Combine...'

1. Combine WIZnet Ethernet HAT with Raspberry Pi Pico.
2. Connect ethernet cable to WIZnet Ethernet HAT, W5100S-EVB-Pico, W5500-EVB-Pico, W55RP20-EVB-Pico, W5100S-EVB-Pico2 or W5500-EVB-Pico2 ethernet port.
3. Connect Raspberry Pi Pico, W5100S-EVB-Pico or W5500-EVB-Pico to desktop or laptop using 5 pin micro USB cable. W55RP20-EVB-Pico, W5100S-EVB-Pico2 or W5500-EVB-

Pico2 require a USB Type-C cable.

4.3   Step 3: Setup Loopback Example

To test the Loopback example, minor settings shall be done in code.

1.   Setup SPI port and pin in 'w5x00_spi.h' in 'WIZnet-PICO-C/port/ioLibrary_Driver/' directory.

Setup the SPI interface you use.

- If you use the W5100S-EVB-Pico, W5500-EVB-Pico, W5100S-EVB-Pico2 or W5500-EVB-Pico2,

```
/* SPI */
#define SPI_PORT spi0

#define PIN_SCK 18
#define PIN_MOSI 19
#define PIN_MISO 16
#define PIN_CS 17
#define PIN_RST 20
```

- If you want to test with the Loopback example using SPI DMA, uncomment USE_SPI_DMA.

```
/* Use SPI DMA */
//#define USE_SPI_DMA // if you want to use SPI DMA, uncomment.
```

- If you use the W55RP20-EVB-Pico,

```
/* SPI */
#define USE_SPI_PIO

#define PIN_SCK 21
#define PIN_MOSI 23
#define PIN_MISO 22
#define PIN_CS 20
#define PIN_RST 25
```

2.   Setup network configuration such as IP in ' w5x00_loopback.c', which is the Loopback example in 'WIZnet-PICO-C/examples/loopback' directory.

- Setup IP, other network settings to suit your network environment.

```
/* Network */
static wiz_NetInfo g_net_info =
    {
        .mac = {0x00, 0x08, 0xDC, 0x12, 0x34, 0x56}, // MAC address
        .ip = {192, 168, 11, 2},                     // IP address
```

```
        .sn = {255, 255, 255, 0},                    // Subnet Mask
        .gw = {192, 168, 11, 1},                     // Gateway
        .dns = {8, 8, 8, 8},                         // DNS server
        .dhcp = NETINFO_ STATIC              // DHCP enable/disable
};
```

3. Setup loopback configuration in 'w5x00_loopback.c' in 'WIZnet-PICO-C/examples/loopback/' directory.

```
/* Port */
#define PORT_LOOPBACK 5000
```

4. In directory 'WIZnet-PICO-C\libraries\ioLibrary_Driver\Application\loopback', 'loopback.h' contains functions defined for testing TCP server, TCP client, and UDP.

```
/* TCP server Loopback test example */
int32_t loopback_tcps(uint8_t sn, uint8_t* buf, uint16_t port);


/* TCP client Loopback test example */
int32_t loopback_tcpc(uint8_t sn, uint8_t* buf, uint8_t* destip, uint16_t
destport);


/* UDP Loopback test example */
int32_t loopback_udps(uint8_t sn, uint8_t* buf, uint16_t port);
```

5. Setup the loopback test to be performed in 'w5x00_loopback.c' in 'WIZnet-PICO-C/examples/loopback/ directory'. For the TCP client loopback, destip and destport need to be configured additionally.

```
/* TCP server loopback test */
if ((retval = loopback_udps(SOCKET_LOOPBACK
                                    , g_loopback_buf, PORT_LOOPBACK)) < 0)
{
    printf(" Loopback error : %d\n", retval);
    while (1);
}
```

4.4   Step 4: Build

1. After completing the Loopback example configuration, click 'build' in the status bar at the bottom of Visual Studio Code or press the 'F7' button on the keyboard to build.
2. When the build is completed, 'w5x00_loopback.uf2' is generated in 'WIZnet-PICO-C/build/examples/loopback' directory.

4.5 Step 5: Upload and Run

1. While pressing the BOOTSEL button of Raspberry Pi Pico, W5100S-EVB-Pico, W5500-EVB-Pico, W55RP20-EVB-Pico, W5100S-EVB-Pico2 or W5500-EVB-Pico2 power on the board, the USB mass storage 'RPI-RP2' is automatically mounted.
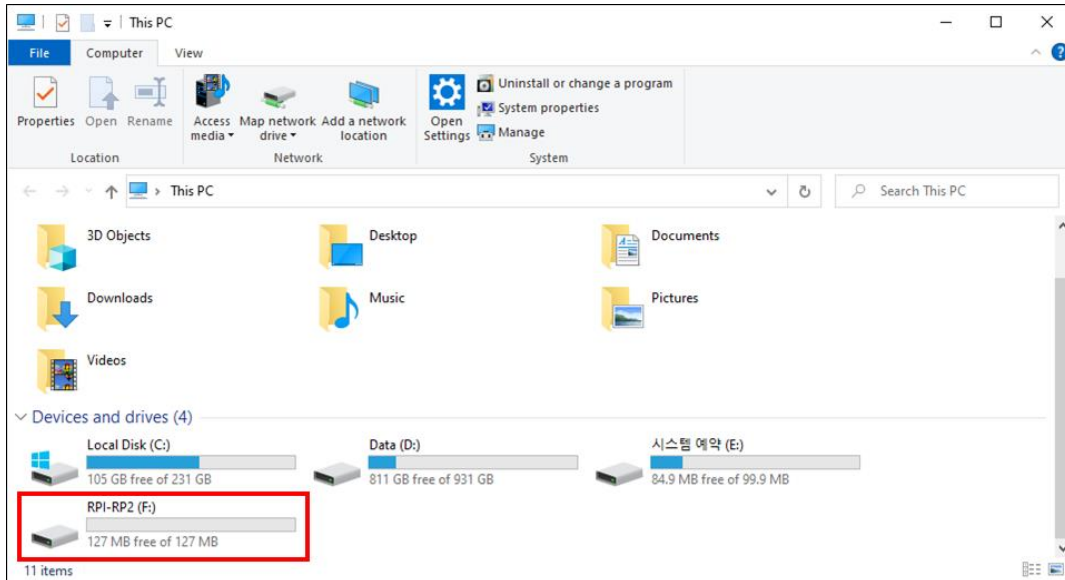

Figure 1. USB mass storage

2. Drag and drop ' w5x00_loopback.uf2' onto the USB mass storage device 'RPI-RP2'.
3. Connect to the serial COM port of Raspberry Pi Pico, W5100S-EVB-Pico, W5500-EVB-Pico, W55RP20-EVB-Pico, W5100S-EVB-Pico2 or W5500-EVB-Pico2 with Tera Term.
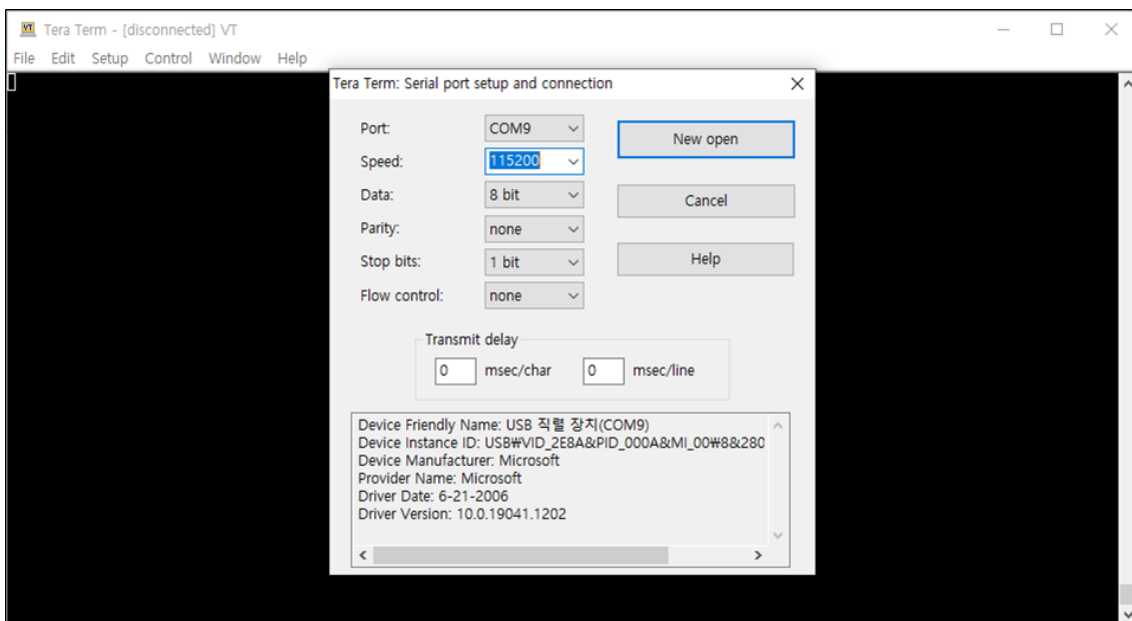

Figure 2. Tera Term

4. Reset your board.

5. If the Loopback example works normally on Raspberry Pi Pico, W5100S-EVB-Pico, W5500-EVB-Pico, W55RP20-EVB-Pico, W5100S-EVB-Pico2 or W5500-EVB-Pico2, you can see the network information of Raspberry Pi Pico, W5100S-EVB-Pico, W5500-EVB-Pico, W55RP20-EVB-Pico, W5100S-EVB-Pico2 or W5500-EVB-Pico2 and the Loopback is open.
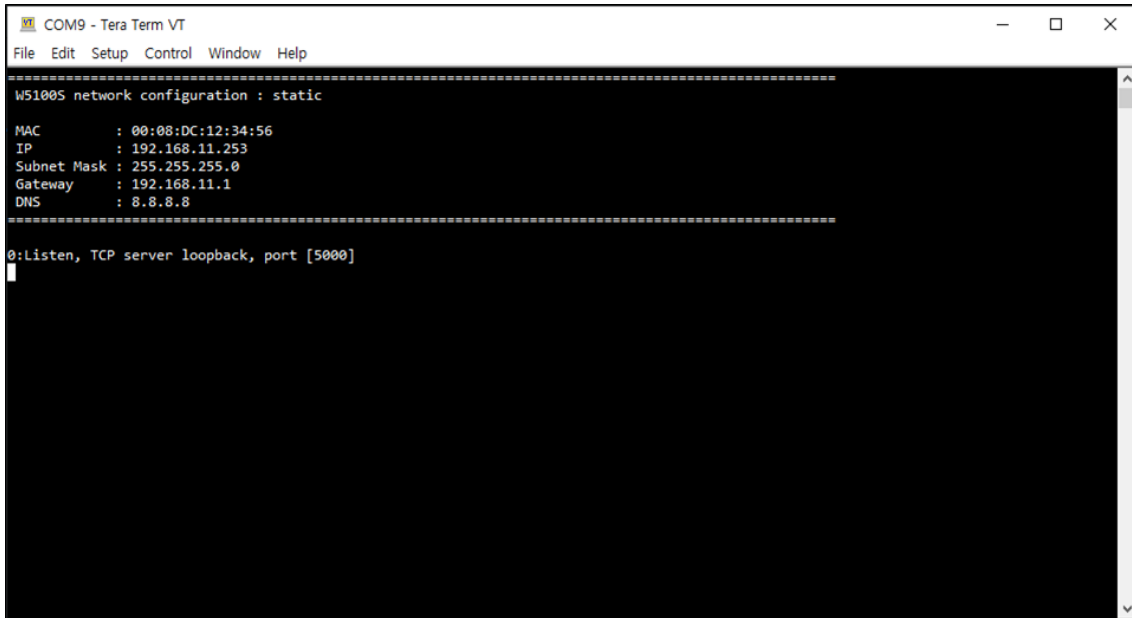

Figure 3. Network Info and Open loopback server

6. Connect to the open loopback server using Hercules TCP client. When connecting to the loopback server, you need to enter is the IP that was configured in Step 3, the port is 5000 by default.
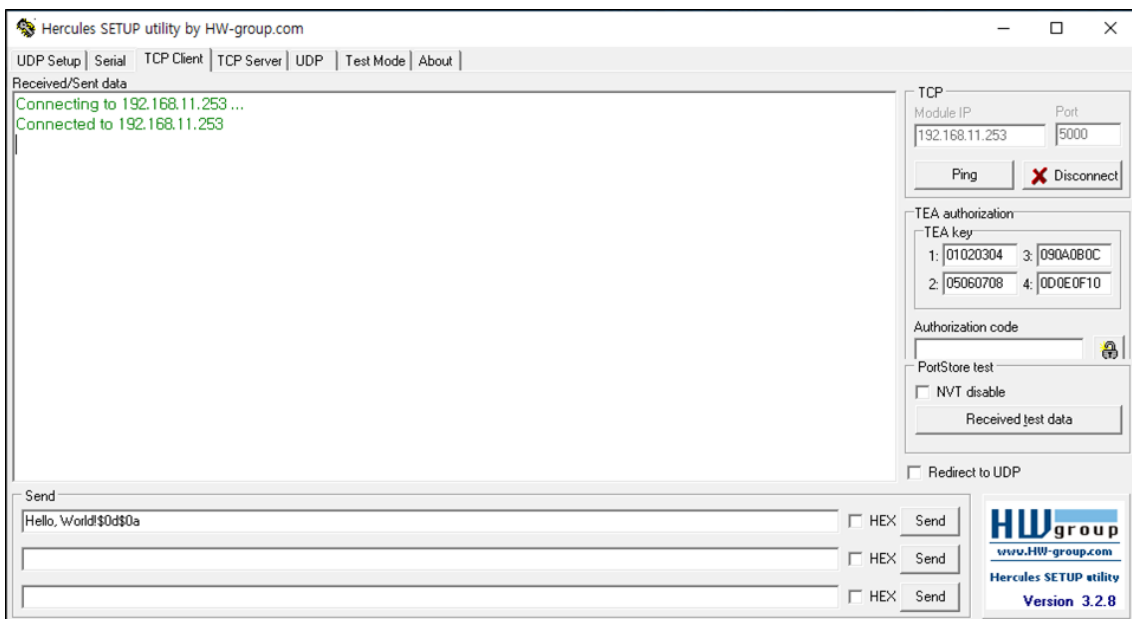

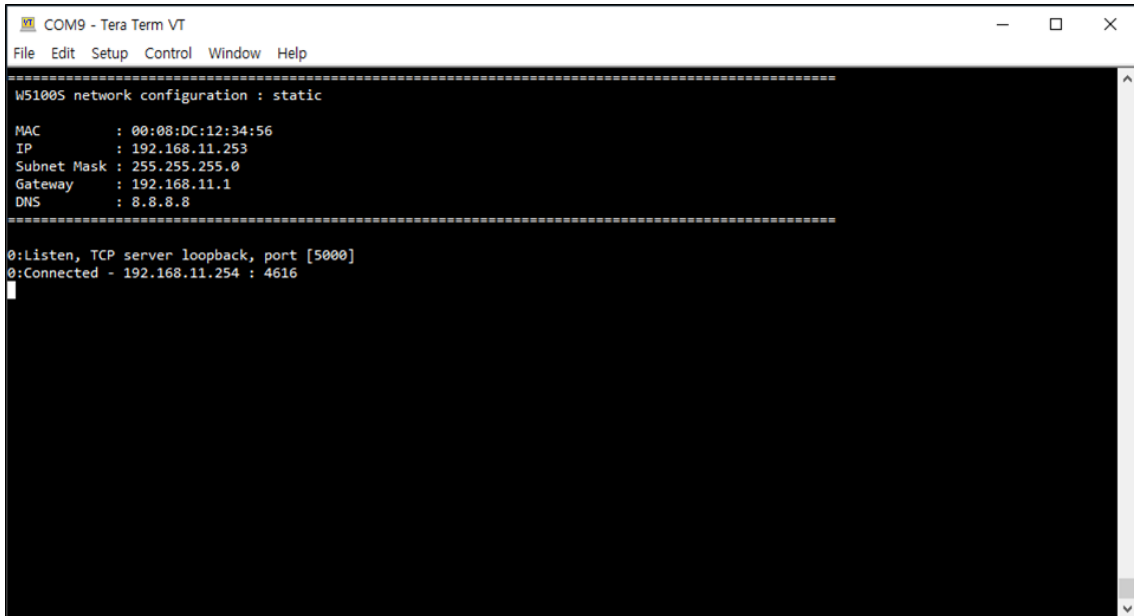Figure 4. Connect to loopback server using Hercules TCP client 1

Figure 5. Connect to loopback server using Hercules TCP client 2

7. Once connected if you send data to the loopback server, you should be able to receive back the sent message.
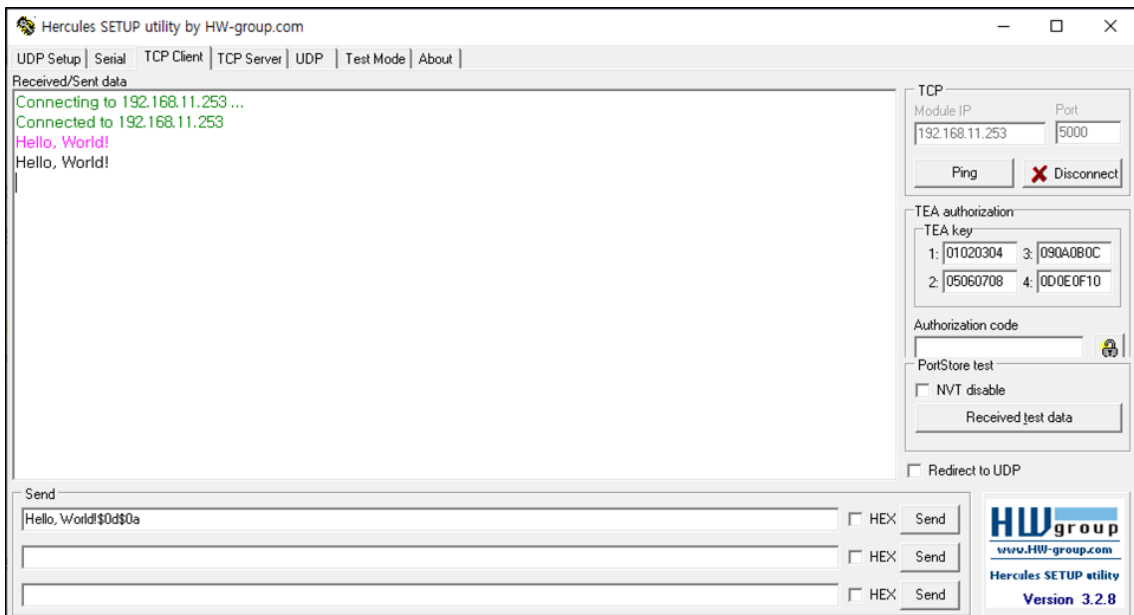

Figure 6. Receive back sent message

Revision history

Version	Date	Descriptions
Ver. 1.0.0	Nov, 2024	Initial release.

Table 1. Revision history

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