

# \*\* 的基本认知

学生: \*\*

\*\* 学院

October 18, 2023



● \*\*\*\*

## 2 参考文献

The current font is  
. 当前中文字体类型是:

- 1.
- 2.
- 3.
- 4.

1 \*\*\*

● \*\*\*\*

## 2 参考文献

1 \*\*\*

\*\*\*\*

## 2 参考文献

## References I

- [1] V. Kramar, O. Kramar, and A. Kabanov, "An artificial neural network approach for solving inverse kinematics problem for an anthropomorphic manipulator of robot sar-401," *Machines*, vol. 10, no. 4, p. 241, 2022.