

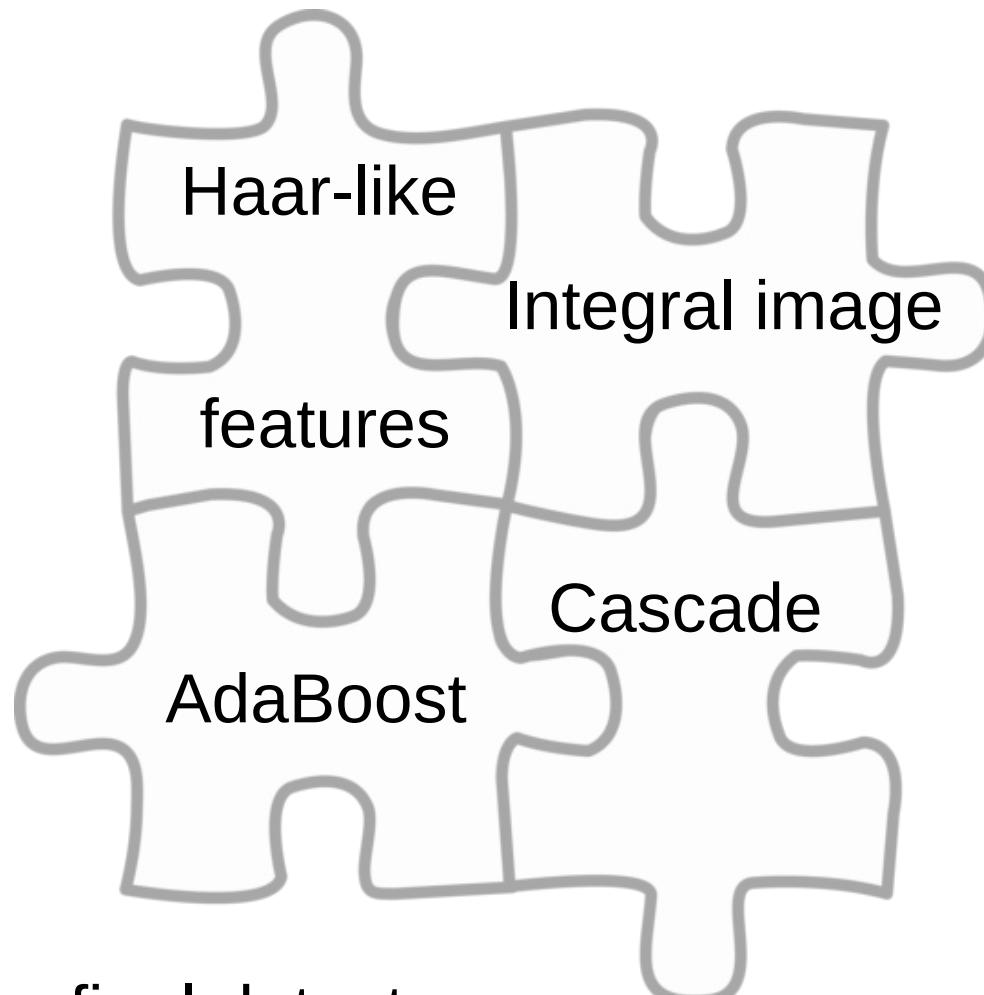
Real-time face detection with Haar cascades

Nora Kassner

Outline

- The Algorithm:

2001 by Paul Viola & Michael Jones

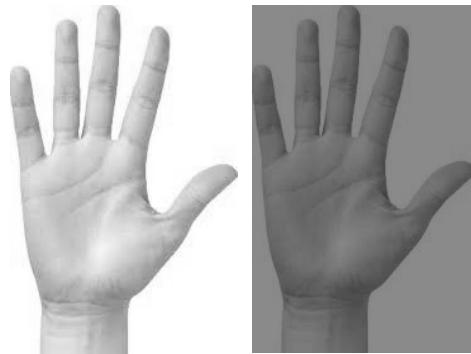


- Training & the final detector
- OpenCV

Choice of features

- How many features should be used?
- What makes a good feature?

- Pixels

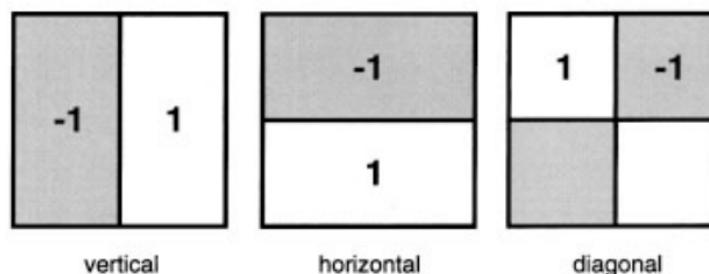


- Histograms



- Haar-like features: local, oriented intensity differences

wavelets in 2D



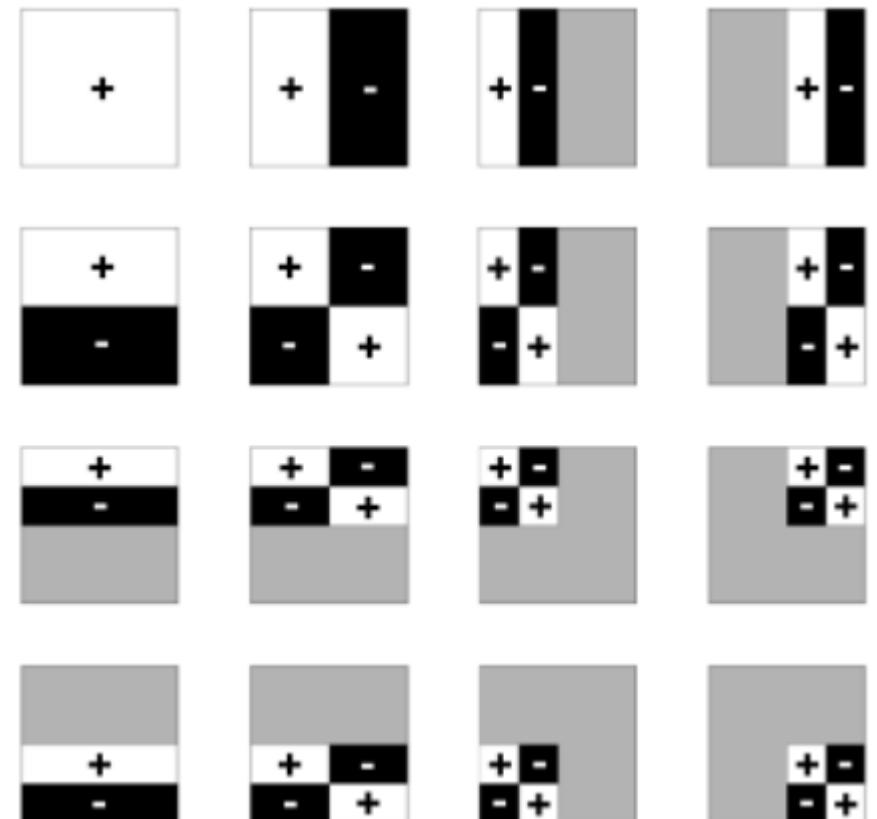
Haar wavelets

Original-Matrix

10	14	7	5
16	12	13	19
14	12	1	5
8	2	3	3

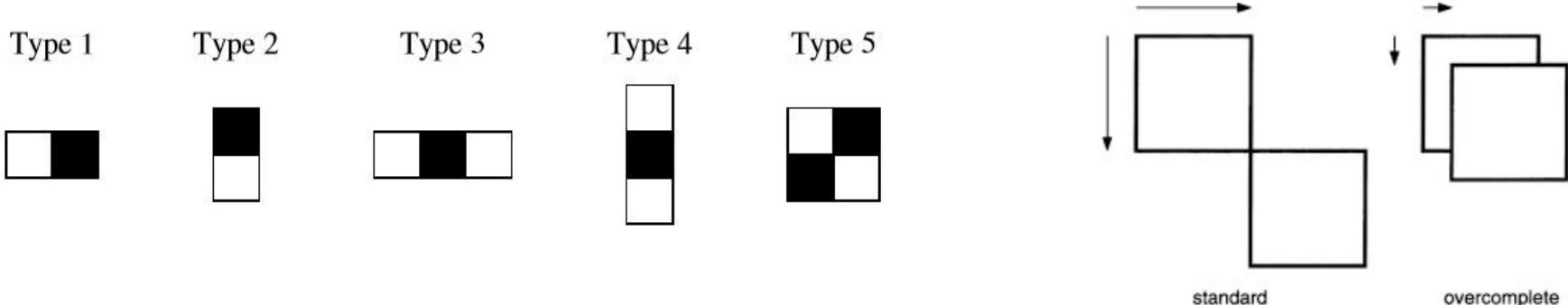


9	2	1	-1
3	-1	-1	0
-3	2	-2	2
2	2	-1	-1



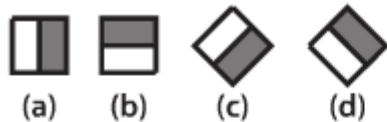
Zweidimensionale Basisfunktionen für ein 4×4 -Bild

Haar-like features

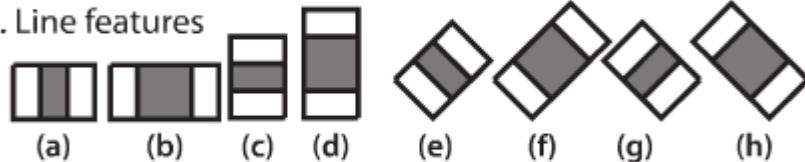


→ 160.000 features per 24x24 px window

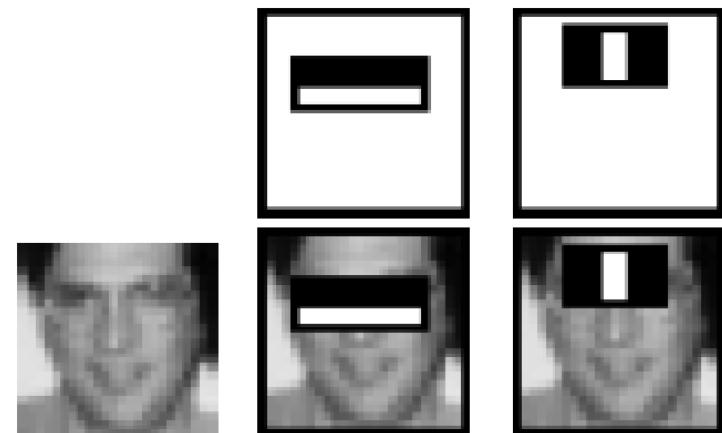
1. Edge features



2. Line features



3. Center-surround features



→ Features encode knowledge

→ Sensitive to edges, bars, simple structure

Integral Image

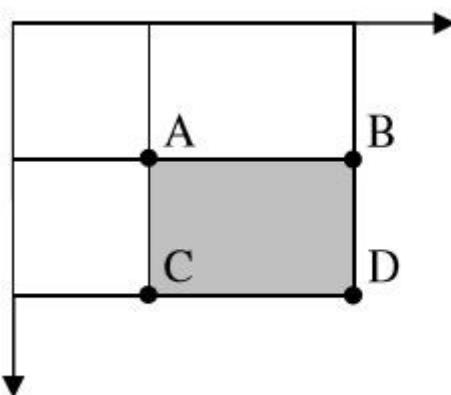
→ Very fast

1	1	1
1	1	1
1	1	1

Input image

1	2	3
2	4	6
3	6	9

Integral image



Sum of grey rectangle = $D - (B + C) + A$

Type 1



Type 2



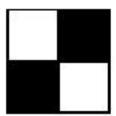
Type 3



Type 4



Type 5



Number of array references: 6

8

9

AdaBoost

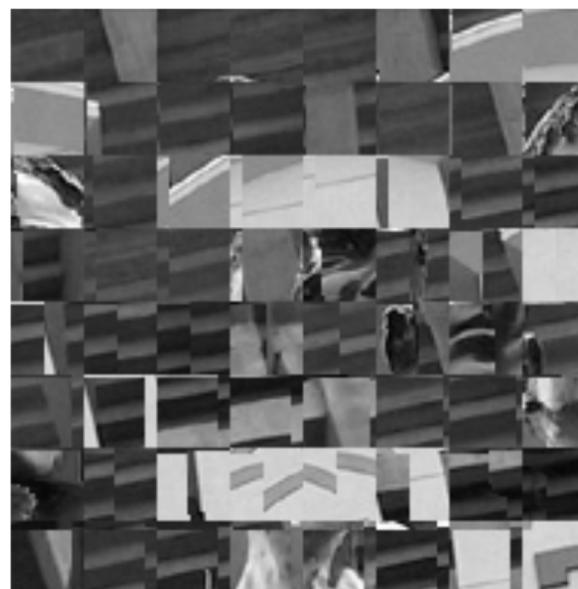
→ narrowing down number of features to only a few useful ones

- Weak classifier: perform at least better than random:

$$h(x, f, p, \theta) = \begin{cases} 1 & \text{if } pf(x) > p\theta \\ 0 & \text{otherwise} \end{cases}$$

- Combining weak classifiers in a weighted sum to form a strong classifier:

$$C(x) = \begin{cases} 1 & \text{if } \sum_{t=1}^T \alpha_t h_t(x) \geq \frac{1}{2} \sum_{t=1}^T \alpha_t \\ 0 & \text{otherwise} \end{cases}$$



AdaBoost

- Given examples images $(x_1, y_1), \dots, (x_n, y_n)$ where $y_i=0,1$ for negative and positive examples.
- Initialize weights $w_{1,i} = \frac{1}{2m}, \frac{1}{2l}$ for $y_i=0,1$, where m and l are the numbers of positive and negative examples.
- For $t=1, \dots, T$:

1) Normalize the weights, $w_{t,i} \leftarrow \frac{w_{t,i}}{\sum_{j=1}^n w_{t,j}}$

2) Select the best weak classifier with respect to the weighted error:

$$\varepsilon_t = \min_{f,p,\theta} \sum_i w_i |h(x_i, f, p, \theta) - y_i|$$

3) Define $h_t(x) = h(x, f_t, p_t, \theta_t)$ where f_t , p_t and θ_t are the minimizers of ε_t .

4) Update the weights:

$$w_{t+1,i} = w_{t,i} \beta^{1-e_i}$$

where $e_i = 0$ if example x_i is classified correctly and $e_i = 1$ otherwise, and $\beta_t = \frac{\varepsilon_t}{1-\varepsilon_t}$

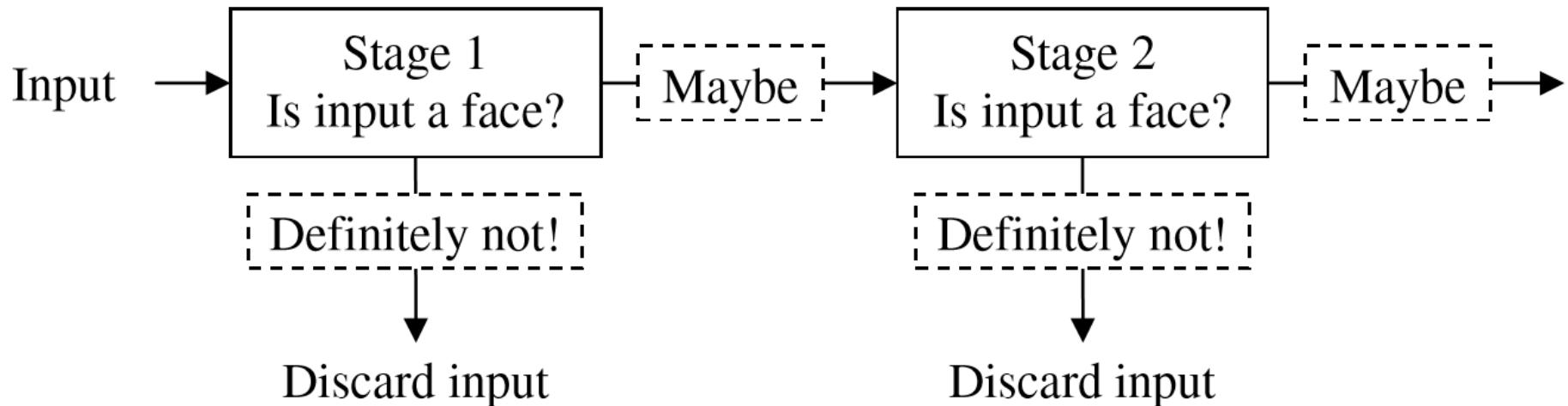
- The final strong classifier is:

$$C(x) = \begin{cases} 1 & \text{if } \sum_{t=1}^T \alpha_t h_t(x) \geq \frac{1}{2} \sum_{t=1}^T \alpha_t \\ 0 & \text{otherwise} \end{cases}$$

where $\alpha_t = \log \frac{1}{\beta_t}$

The cascade

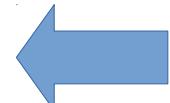
→ Focus of attention



Training the cascade

- AdaBoost
 - minimize false negative
- Parameters:
 - # stages
 - # features per stage
 - Threshold of each stage

- Select:
- Max. false positive / stage
 - Min. true positive / stage
 - Target overall false positive



See how the cascade looks like:

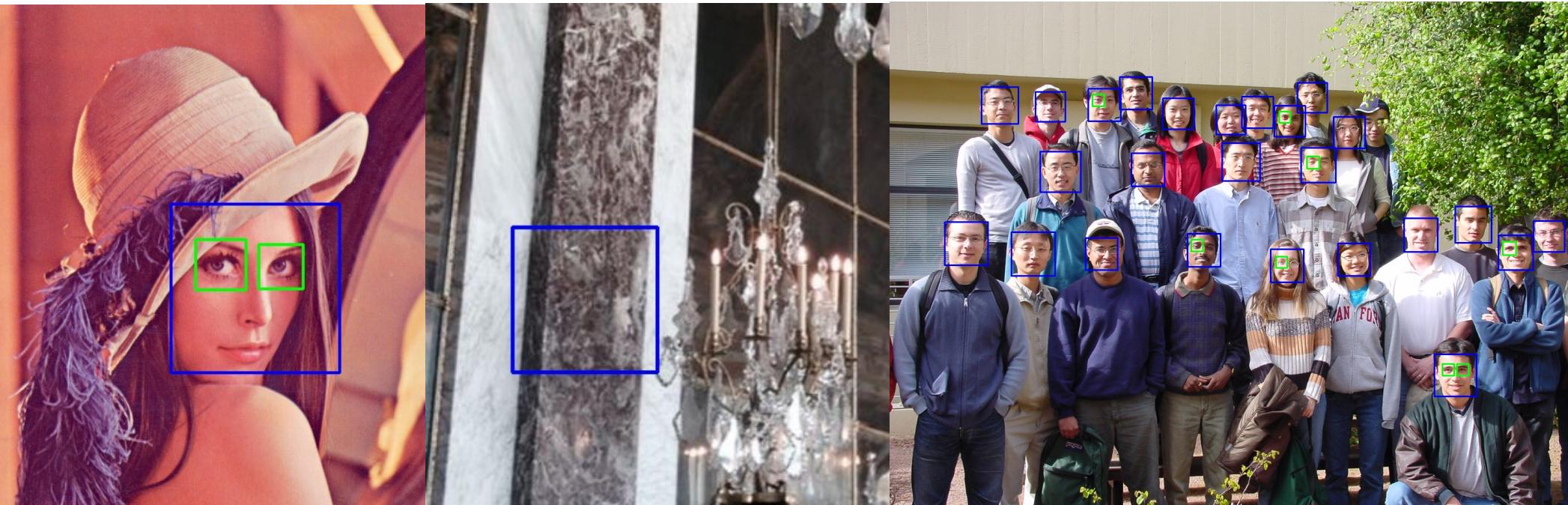
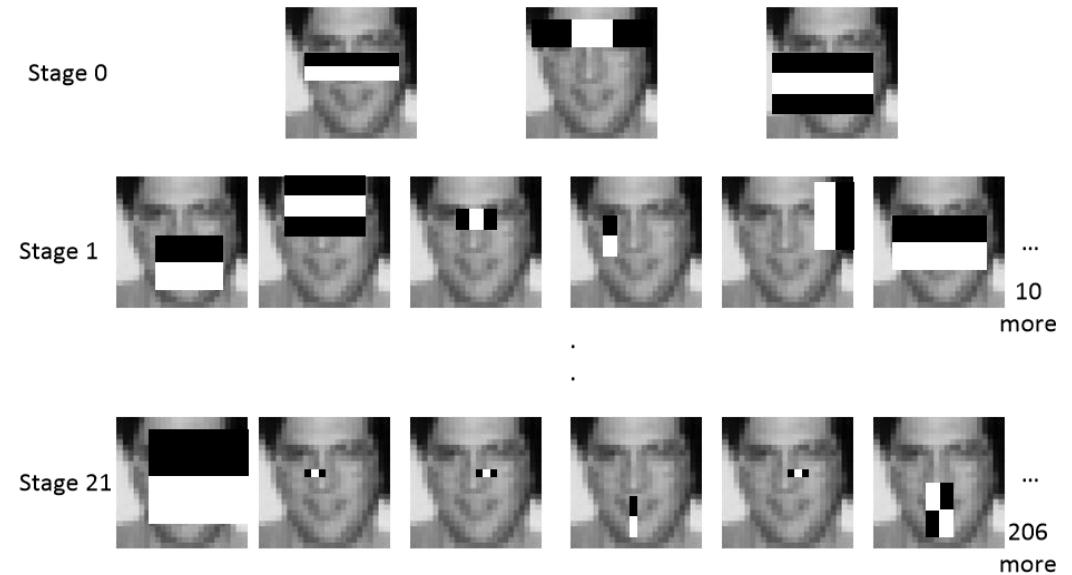
<http://www.makematics.com/research/viola-jones/>

Training the Cascade

- User selects values for f , the maximum acceptable false positive rate per layer and d , the minimum acceptable detection rate per layer.
- User selects target overall false positive rate, F_{target} .
- P = set of positive examples
- N = set of negative examples
- $F_0 = 1.0; D_0 = 1.0$
- $i = 0$
- while $F_i > F_{target}$
 - $i \leftarrow i + 1$
 - $n_i = 0; F_i = F_{i-1}$
 - while $F_i > f \times F_{i-1}$
 - * $n_i \leftarrow n_i + 1$
 - * Use P and N to train a classifier with n_i features using AdaBoost
 - * Evaluate current cascaded classifier on validation set to determine F_i and D_i .
 - * Decrease threshold for the i th classifier until the current cascaded classifier has a detection rate of at least $d \times D_{i-1}$ (this also affects F_i)
 - $N \leftarrow \emptyset$
 - If $F_i > F_{target}$ then evaluate the current cascaded detector on the set of non-face images and put any false detections into the set N

The final detector

- 6000 features
- 38 stages
- Input parameters:
 - Cascade containing features
 - Starting scale
 - Starting delta
 - Scale increment
- 15 frames/s



OpenCV

- Free for academic & commercial use
- Link installation instruction: http://docs.opencv.org/master/d9/df8/tutorial_root.html
- C++, C, Python and Java interfaces
- Supports Windows, Linux, Mac OS, iOS and Android

Stuff you can do with it:

<https://www.youtube.com/watch?v=oJAI9Yd3kNo>

<https://www.youtube.com/watch?v=8h9vU1pnNZA>



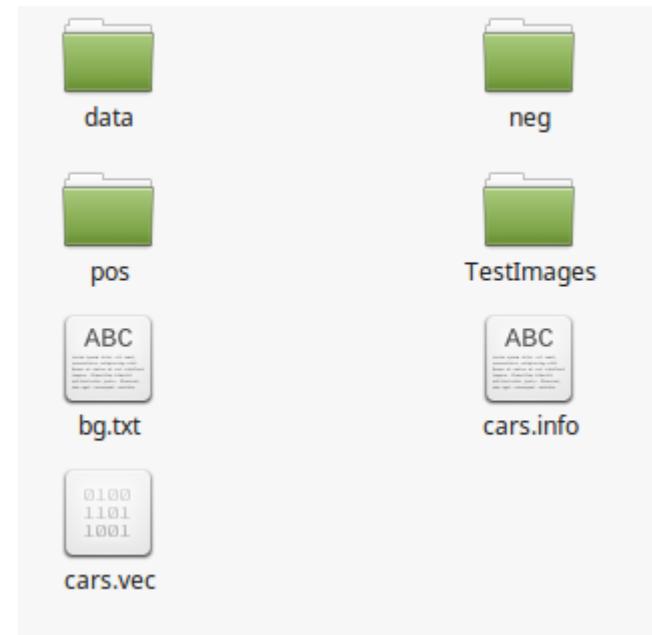
Do it yourself!

```
nora@NorasT520 ~/OpenCV/TrainCars $ ls  
bg.txt cars.info neg pos  
nora@NorasT520 ~/OpenCV/TrainCars $ opencv_createsamples -info cars.info -num 500 -w 48 -h 24 -vec cars.vec
```

```
nora@NorasT520 ~/OpenCV/TrainCars $ opencv_traincascade -data data -vec cars.vec -bg bg.txt -numPos 500 -numNeg 500  
-numStages 10 -w 48 -h 24
```

```
bg.txt  
/home/nora/OpenCV/Training/background/image_0001.jpg  
/home/nora/OpenCV/Training/background/image_0002.jpg  
/home/nora/OpenCV/Training/background/image_0003.jpg  
/home/nora/OpenCV/Training/background/image_0004.jpg
```

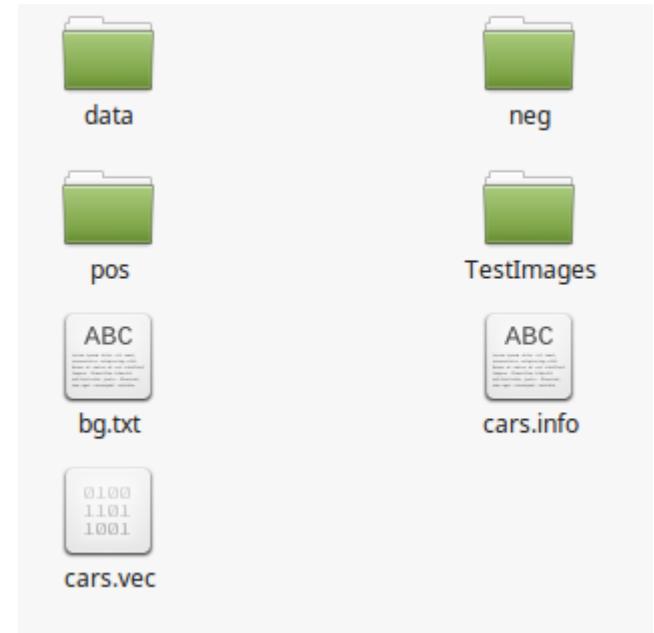
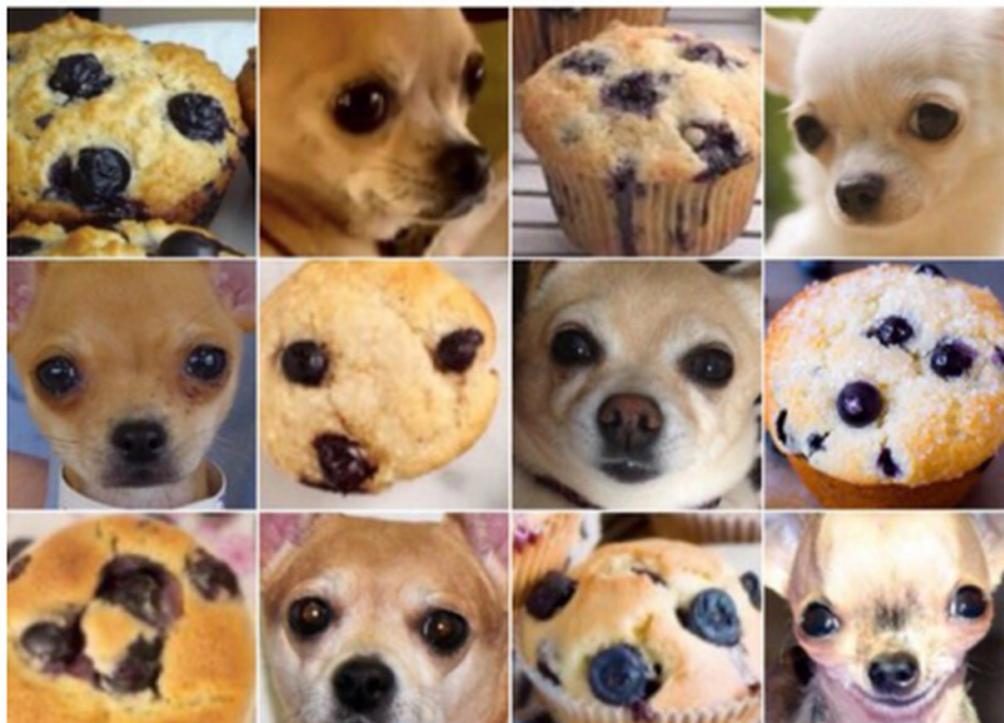
```
cars.info  
x  
pos/pos-532.pgm 1 0 0 100 40  
pos/pos-166.pgm 1 0 0 100 40  
pos/pos-76.pgm 1 0 0 100 40  
pos/pos-193.pgm 1 0 0 100 40  
pos/pos-0.pgm 1 0 0 100 40
```



Do it yourself!

```
nora@NorasT520 ~/OpenCV/TrainCars $ ls  
bg.txt cars.info neg pos  
nora@NorasT520 ~/OpenCV/TrainCars $ opencv_createsamples -info cars.info -num 500 -w 48 -h 24 -vec cars.vec
```

```
nora@NorasT520 ~/OpenCV/TrainCars $ opencv_traincascade -data data -vec cars.vec -bg bg.txt -numPos 500 -numNeg 500  
-numStages 10 -w 48 -h 24
```



Sources

- P. Viola, M. Jones: Rapid Object Detection using a Boosted Cascade of Simple Features, Conference Paper in Computer Vision and Pattern Recognition, 2001, Vol.2.
- R. Lienhart, J. Maydt: An Extended Set of Haar-like Features for Rapid Object Detection, Conference Paper in Proceedings / ICIP ... International Conference on Image Processing 1, 2002, Vol. 1.
- O. Jensen: Implementing the Viola-Jones Face Detection Algorithm, Master thesis 2008, Technical University of Denmark, Informatics and Mathematical Modelling.
- A. Barczak, F. Dadgostar: Real-time hand tracking using a set of cooperative classifiers based on Haar-like features, Res. Lett. Inf. Math. Sci., 2005, Vol. 7.
- C. Papageorgiou, T. Poggio: Trainable System for Object Detection, International Journal of Computer Vision, 2000, Vol. 38.1.
- <http://docs.opencv.org/master/index.html>
- https://www.cs.auckland.ac.nz/~rklette/CCV-CIMAT/pdfs/B27-Haar_VJ_AB.pdf
- https://en.wikipedia.org/wiki/Haar_wavelet
- <http://www.makematics.com/research/viola-jones/>
- <http://www.tilman.de/uni/ws05/scivis/wavelet-transformation.html>