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Employment History

- 2015 – 2018 📌 **Lecturer.** Department of Electrical and Computer Engineering, School of Engineering, Adama Science and Technology University, Adama, Ethiopia.
- 2010 – 2011 📌 **Graduate Assistant.** Department of Electrical and Computer Engineering, School of Engineering, Adama Science and Technology University, Adama, Ethiopia.

Education

- 2018 – 2024 📌 **Ph.D. in Aerospace Engineering**, Pusan National University, Busan, South Korea.
Research area: Sensor fusion, UAV navigation and guidance, and Embedded systems.
- 2012 – 2015 📌 **M.Sc. in Control Engineering**, Addis Ababa Institute of Technology, Addis Ababa, Ethiopia.
Thesis title: *Intelligent Controller for Autonomous Mobile Robot Outdoor Navigation: Fuzzy Logic Approach*
- 2006 – 2010 📌 **B.Sc. in Electrical Engineering**, Arba Minch University, Arba Minch, Ethiopia.
Thesis title: *Computer Based Remote Controlled Mobile Robot Design and Implementation.*

Projects

- 2023 📌 **Ship Tracking and Docking Support using AI-Powered Drone**
- Dataset preparation and training with Yolov5 and Yolov8
 - Software development in C++ for ship detection and information (ship relative location from drone, orientation, and dimension) extraction based on the live onboard camera view.
 - Deploying the software in Modalai VOXL 2 autopilot
 - Grabbing live video frames from a camera stream
 - Streaming the detection result overlayed onto the input video to the ground station
- 2021 – 2022 📌 **Inertial Navigation Sensor (INS) Design and Development**
- IMU, magnetometer and barometer sensors driver code writing for TI microcontroller
 - Extended Kalman Filter (EKF) based sensor fusion algorithm for attitude and altitude estimation
 - Mavlink protocol support feature integration

Projects (continued)

2020

UAV Flight Controller (Autopilot software) Design and Programming

- EEPROM to TI microcontroller interfacing driver code writing
- SD card to TI microcontroller Interfacing driver code writing and logging protocol setup

2019

Vision Based UAV Localization and Navigation

- Object detection and recognition using Yolo3
- ZED stereo camera integration to Yolo3
- Jetson Xavier to pixhawk interfacing
- Localization and navigation algorithm development

2018

LiDAR Sensor Based Obstacle Avoidance Feature Integration to PX4 Firmware

- PX4 code navigation module modification
- Simulation test on Gazebo
- Field flight test

Research Publications




Journal Articles

- 1 Debele, Y., Shi, H.-Y., **Wondosen, A.**, Ku, T.-W., & Kang, B.-S. (2023). Deep learning-based robust actuator fault detection and isolation scheme for highly redundant multirotor uavs. *Drones*, 7(7). [doi:10.3390/drones7070437](https://doi.org/10.3390/drones7070437)
- 2 **Wondosen, A.**, Debele, Y., Kim, S.-K., Shi, H.-Y., Endale, B., & Kang, B.-S. (2023). Bayesian optimization for fine-tuning ekf parameters in uav attitude and heading reference system estimation. *Aerospace*, 10(12). [doi:10.3390/aerospace10121023](https://doi.org/10.3390/aerospace10121023)
- 3 Debele, Y., Shi, H.-Y., **Wondosen, A.**, Kim, J.-H., & Kang, B.-S. (2022). Multirotor unmanned aerial vehicle configuration optimization approach for development of actuator fault-tolerant structure. *Applied Sciences*, 12(13). [doi:10.3390/app12136781](https://doi.org/10.3390/app12136781)
- 4 **Wondosen, A.**, Jin-Seok, J., Seung-Ki, K., Yisak, D., & Beom-Soo, K. (2021). Improved attitude and heading accuracy with double quaternion parameters estimation and magnetic disturbance rejection. *Sensors*, 21, 5475. [doi:10.3390/s21165475](https://doi.org/10.3390/s21165475)
- 5 Abera, T., Endale, B., **Wondosen, A.**, & Ho-Yon, H. (2021). Machine learning approach to real-time 3d path planning for autonomous navigation of unmanned aerial vehicle. *Applied Science*, 11, 4706. [doi:10.3390/app11104706](https://doi.org/10.3390/app11104706)

Conference Proceedings









- 1 **Wondosen, A.**, Yisak, D., Seung-Ki, K., Jin-Seok, J., & Beom-Soo, K. (2014). Real-time uav attitude and position estimation error identification using fuzzy. In *KSAS 2020 fall conference* (pp. 895–896). Jeju, South Korea. Retrieved from https://www.dbpia.co.kr/pdf/pdfView.do?nodeId=NODE10526349&mark=0&useDate=&ipRange=N&accessgl=Y&language=ko_KR&hasTopBanner=true

Skills

- Languages  Strong reading, writing and speaking competencies for Amharic and English. Reading and writing for Korean.
- Coding  C/C++, MATLAB, Python, Java, C#, \LaTeX , ...
- Misc.  Academic research, teaching, training, consultation, \LaTeX typesetting and publishing.

Miscellaneous Experience

Certification

- 2021  **Certified Complete Blender Creator: Learn 3D Modeling for Beginners online course.** Awarded by Udemy.
-  **Certified Learn to Speak Korean 1: an online non-credit course.** Awarded by Yonsei University and offered through Coursera .
- 2019  **Certified Machine Learning with MATLAB MathWorks Training.** Awarded by MathWorks.
- 2017  **Certified E-learning Materials Content Development as subject matter expert.** Awarded by KOICA.
- 2014  **Certified Microcontroller Programming and Embedded System Design.** Awarded by Adama Science and Technology University.
- 2013  **Certified Electric Power Distribution System Design.** Awarded by Ethiopian Electric Power Corporation .
- 2011  **Certified Photovoltaic Stand Alone Systems Design and Installation.** Awarded by Adama Science and Technology University.
-  **Certified Micro PLC LOGO! Programming.** Awarded by Adama Science and Technology University.

References

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