Research Log - Week 02

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July 28, 2016

May 22, 2016 Added more to thesis document.

Worked on singular-value of previous blending equation. where:

$$\begin{bmatrix} x_{uv} & 0 \\ 0 & y_{uv} \end{bmatrix} = \begin{bmatrix} \mathbf{u} & \mathbf{0} \\ \mathbf{0} & \mathbf{u} \end{bmatrix}^T \begin{bmatrix} \mathbf{M} & \mathbf{0} \\ \mathbf{0} & \mathbf{M} \end{bmatrix}^T \begin{bmatrix} \mathbf{X} & \mathbf{0} \\ \mathbf{0} & \mathbf{Y} \end{bmatrix} \begin{bmatrix} \mathbf{M} & \mathbf{0} \\ \mathbf{0} & \mathbf{M} \end{bmatrix} \begin{bmatrix} \mathbf{v} & \mathbf{0} \\ \mathbf{0} & \mathbf{v} \end{bmatrix}$$

where

$$\mathbf{u} = \begin{bmatrix} u \\ 1 \end{bmatrix}, \ \mathbf{v} = \begin{bmatrix} v \\ 1 \end{bmatrix}, \ \mathbf{X} = \begin{bmatrix} x_{00} & x_{01} \\ x_{10} & x_{11} \end{bmatrix}, \ \mathbf{Y} = \begin{bmatrix} y_{00} & y_{01} \\ y_{10} & y_{11} \end{bmatrix}, \ \text{and} \ \mathbf{M} = \begin{bmatrix} -1 & 1 \\ 1 & 0 \end{bmatrix}$$

May 23, 2016 Read [Chen1993] [1] section 2.4 on Block Compression.

SUMMARY: Blocks are established established by *threshold* where each block contains pixels that are *offset by no more than the threshold*, allowing all pixels to be offset at once.

Question for Kamangar: Doesn't this assume that all pixels in the block have a uniform offset?

Working on MatLab program to perform pixel offsets of corresponding points (i.e. assign corresponding points to pixels in MatLab by non automatic methods)

May 24, 2016 Read following sections from [Chen1993] [1]:

- Implementations (3)
 - Preprocessing (3.1)
 - Interactive Interpolation (3.2)
 - Examples (3.3)
- Applications (4)
 - Virtual Reality (4.1)
 - Motion Blur (4.2)

Question for Kamangar: With regards to Section 3.1 and Section 1, why is a graph structure needed? Why is it a lattice?

Question for Kamangar: With regards to Section 4.1, I don't understand the concepts of temporal anti-aliasing and super-sampling?

Made additional changes / added material to thesis document.

May 25, 2016 Was using figures from http://www.robots.ox.ac.uk/~vgg/hzbook/hzbook2/HZfigures.html as test images, which may not be best source as there white borders, appear to be up-sampled, and do not contain (extrinsic) calibration info. Consider using images located at http://vision.middlebury.edu/stereo/data/scenes2014/ that contain meta-info including (intrinsic) calibration info.

References

[1] Shenchang Eric Chen and Lance Williams. View interpolation for image synthesis. In *Proceedings of the 20th Annual Conference on Computer Graphics and Interactive Techniques*, SIGGRAPH '93, pages 279–288, New York, NY, USA, 1993. ACM.