CS3081 Computational Mathematics

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0.1 Question 2.31

Question: Write a user-defined MATLAB function that calculates the determinant of a square ($n \times n$) matrix, where n can be 2, 3, or 4. For function name and arguments, use D = Determinant (A). The input argument A is the matrix whose determinant is calculated. The function Determinant should first check if the matrix is square. If it is not, the output D should be the message "The matrix must be square." Use Determinant to calculate the determinant of the following two matrices:

$$\begin{bmatrix}
1 & 5 & 4 \\
2 & 3 & 6 \\
1 & 1 & 1
\end{bmatrix}
\begin{bmatrix}
1 & 2 & 3 & 4 \\
5 & 6 & 7 & 8 \\
9 & 10 & 11 & 12 \\
13 & 14 & 15 & 16
\end{bmatrix}$$

Part (a):

- (i) 4
- (ii) 13
- (iii) 26
- (iv) 18

Your Answer:

The answer I got for part (a) was (ii)..13.

Part (b):

- (i) 0
- (ii) 12
- (iii) 7
- (iv) 4

Your Answer:

The answer I got for part (b) was (i)..0.

My MATLAB code for calculating these answers can be seen below.

```
% Creating function Determinant()...
function D = Determinant(A)
% Getting dimensions of matrix...
[m, n] = size(A);
\% If matrix is not square, output error message and return..
if (m = n)
    disp("The_matrix_must_be_square");
    return;
end
\% If 2x2 matrix, get determinant
if (m == 2)
    \% For a matrix [a \ b; \ c \ d] the determinant is ad - cb.
    part1 = A(1,1) * A(2,2);
    part2 = A(1,2) * A(2,1);
   D = part1 - part2;
\% If 3x3 matrix, get determinant (We can use recursion here)
elseif (m == 3)
    \% Part 1, 2 and 3 consists of make 2x2 matrices for recursion.
    part1 = [A(2,2) \ A(2,3);
             A(3,2) A(3,3);
    part2 = [A(2,1) \ A(2,3);
             A(3,1) A(3,3);
    part3 = [A(2,1) \ A(2,2);
             A(3,1) A(3,2);
    \% Caclulating determinant...
    part4 = A(1,1) * Determinant(part1);
    part5 = A(1,2) * Determinant(part2);
    part6 = A(1,3) * Determinant(part3);
   D = part4 - part5 + part6;
% If 4x4 matrix, get determinant.. same principle as step above.
elseif (m == 4)
    % Creating 3x3 matrices for recursion..
    part1 = [A(2,2) \ A(2,3) \ A(2,4);
             A(3,2) A(3,3) A(3,4);
```

```
A(4,2) A(4,3) A(4,4);
    part2 = [A(2,1) \ A(2,3) \ A(2,4);
             A(3,1) A(3,3) A(3,4);
             A(4,1) A(4,3) A(4,4);
    part3 = [A(2,1) \ A(2,2) \ A(2,4);
             A(3,1) A(3,2) A(3,4);
             A(4,1) A(4,2) A(4,4);
    part4 = [A(2,1) \ A(2,2) \ A(2,3);
             A(3,1) A(3,2) A(3,3);
             A(4,1) A(4,2) A(4,3);
    % Calculating determinant.
    part5 = A(1,1) * Determinant(part1);
    part6 = A(1,2) * Determinant(part2);
    part7 = A(1,3) * Determinant(part3);
    part8 = A(1,4) * Determinant(part4);
   D = part5 - part6 + part7 - part8;
end
\% Part(a) = 13
% Part(b) = 0
```

0.2 Question 3.2

Question: Determine the root of $f(x) = x - 2e^{-x}$ by:

- (a) Using the bisection method. Start with a=0 and b=1, and carry out the first three iterations.
- (b) Using the secant method. Start with the two points, x1 = 0 and x2 = 1, and carry out the first three iterations.
- (c) Using Newton's method. Start at x1 = 1 and carry out the first three iterations.

Part (a):

- (i) 0.1241
- (ii) 0.08125
- (iii) 0.074995
- (iv) 0.003462

Your Answer:

Bisection Method: is a bracketing method for finding a numerical solution of an equation of the form f(x) = 0 when it is known that withing a given interval [a, b], f(x) is continuous and the equation has a solution.

The algorithm for the bisection method is as follows:

- 1. Choose first interval by finding points a and b such that a solution exists between them (a and b should have different signs). For us, a and b have been given to us as 0 and 1 respectively.
- 2. Calculate the first estimate of the numerical solution x_{NS1} by:

$$x_{NS1} = \frac{(a+b)}{2}$$

- 3. Determine if the solution is between a and x_{NS1} or b and x_{NS1} . This is done by checking the sign of the product $f(a) * f(x_{NS1})$. If the result of this is less than 0, the solution is between a and x_{NS1} , else if the solution is greater than 0, the solution is between x_{NS1} and b.
- 4. Select the subinterval that contains the true solution and go back to step 2. Step 2 through 4 are repeated until error bound is attained.

Since we have step 1 already done for us we will begin with step 2.

- Iteration 0: $x_{NS1} = \frac{(0+1)}{2} = 0.5$. This is our first estimate of our numerical solution. $f(0) * f(0.5) = ((0) 2e^{-(0)}) * ((0.5) 2e^{-(0.5)}) = -2 * -0.7130 = 1.426$. Since this is greater than 0, we know our solution is in between x_{NS1} and b.
- Iteration 1: $x_{NS1} = \frac{(0.5+1)}{2} = 0.75$. This is our second estimate of our numerical solution. $f(0.5) * f(0.75) = ((0.5) 2e^{-(0.5)}) * ((0.75) 2e^{-(0.75)}) = -0.7130 * -0.1947 = 0.1388$. Since this is greater than 0, we know our solution is in between x_{NS1} and b.

- Iteration 2: $x_{NS1} = \frac{(0.75+1)}{2} = 0.875$. This is our third estimate of our numerical solution. $f(0.75)*f(0.875) = ((0.75)-2e^{-(0.75)})*((0.875)-2e^{-(0.875)}) = -0.1947*0.04127 = -0.0080$. Since this is less than 0, we know our solution is in between a and x_{NS1} .
- Iteration 3: $x_{NS1} = \frac{(0.75 + 0.875)}{2} = 0.8125$. This is our final estimate of our numerical solution. $f(0.75) * f(0.8125) = ((0.75) 2e^{-(0.75)}) * ((0.8125) 2e^{-(0.8125)}) = -0.1947 * -0.07499 = -0.0146$. Since this is less than 0, we know our solution is in between x_{NS1} and a.

The answer we end up with is 0.8125.. or (ii)

Part (b):

- (i) 0.72481
- (ii) 0.86261
- (iii) 0.62849
- (iv) 0.17238

Your Answer:

Secant Method: is a scheme for finding a numerical solution of an equation of the form f(x) = 0. The method uses two points in the neighborhood of the solution to determine a new estimate for the solution. Two points are used to define a straight line, and the point where the line intersects the x-axis is the new estimate for the solution.

The equation can be generalized to an iteration formula in which a new estimate of the solution x_{i+1} is determined from the previous two solutions x_i and x_{i-1}

$$x_{i+1} = x_i - \frac{f(x_i)(x_{i-1} - x_i)}{f(x_{i-1}) - f(x_i)}$$

- Iteration 1: Let $x_i = b..(1)$ and $x_{i-1} = a..(0)$. We first find our next estimate of the solution by subbing into our formula.. $x_{i+1} = 1 \frac{f(1)(0-1)}{f(0)-f(1)}$, giving us $x_{i+1} = 0.88339$. f(0.88339) = 0.05663.
- Iteration 2: We now repeat the process for our new estimate of the solution. $x_{i+1} = 0.88339 \frac{f(0.88339)(1-0.88339)}{f(1)-f(0.88339)}$, giving us $x_{i+1} = 0.85154$. f(0.85154) = -0.00197.

Iteration 3: And again. $x_{i+1} = 0.85154 - \frac{f(0.85154)(0.88339 - 0.85154)}{f(0.88339) - f(0.85154)}$, giving us $x_{i+1} = 0.85261$. f(0.85261) = 0.00000833298.

So our answer is 0.85261 or (ii).. probably some inaccuracies due to rounding.

Part (c):

- (i) 0.65782
- (ii) 0.59371
- (iii) 0.45802
- (iv) 0.85261

Your Answer:

Newton's method is a scheme for finding a numerical solution of an equation of the form f(x) = 0 where f(x) if continuous and differentiable and the equation is known to have a solution near a given point. The equation can be generalized for determining the "next" solution x_{i+1} from the present solution x_i :

$$x_{i+1} = x_i - \frac{f(x_i)}{f'(x_i)}$$

Iteration 1: First easiest to find out what f'(x) is.. $f'(x) = 2e^{-x} + 1$. We know that $x_i = 1$, so we just need to plug it into our formula to get the next solution. $x_{i+1} = 1 - \frac{f(1)}{f'(1)} = 0.848$.

Iteration 2: $x_{i+1} = 0.848 - \frac{f(0.848)}{f'(0.848)} = 0.8433.$

Iteration 3: $x_{i+1} = 0.8433 - \frac{f(0.833)}{f'(0.833)} = 0.852$. f(0.852) = -0.0011.

So our answer is 0.852 or (iv).

0.3 Question 4.24

Question: Write a user-defined MATLAB function that determines the inverse of a matrix using the Gauss-Jordan method. For the function name and arguments use Ainv =Inverse (A), where A is the matrix to be inverted, and Ainv is the inverse of the matrix. Use the Inverse function to calculate the inverse of:

The Matrix A
$$\begin{bmatrix}
-1 & 2 & 1 \\
2 & 2 & -4 \\
0.2 & 1 & 0.5
\end{bmatrix}$$
The Matrix B
$$\begin{bmatrix}
-1 & -2 & 1 & 2 \\
1 & 1 & -4 & -2 \\
1 & -2 & -4 & -2 \\
2 & -4 & 1 & -2
\end{bmatrix}$$

(i)

$$\begin{bmatrix} \text{Inverse(a)} & \text{Inverse(b)} \\ -0.7143 & 0.0 & 1.4286 \\ 0.2571 & 0.1000 & 0.2857 \\ -0.2286 & -0.2000 & 0.8571 \end{bmatrix} \begin{bmatrix} 1.6667 & 2.8889 & -2.2222 & 1.0000 \\ 0.0 & 0.3333 & -0.3333 & 0.0 \\ -0.3333 & -0.4444 & 0.1111 & 0.0 \\ 1.5000 & 2.0000 & -1.5000 & 0.5000 \end{bmatrix}$$

(ii)

(iii)

(iv)

$$\begin{bmatrix} 0.8343 & 1.01 & 1.3336 \\ 2.2572 & 0.1003 & 0.3857 \\ -0.2486 & -0.2110 & 0.9671 \end{bmatrix} \begin{bmatrix} 1.6777 & 4.9889 & 3.2232 & 1.11700 \\ 0.3443 & -0.3443 & 0.3233 & 0.07371 \\ -0.3443 & -0.2979 & 0.3211 & 0.07800 \\ 1.2480 & 2.1220 & -1.5883 & 0.5621 \end{bmatrix}$$

Your Answer:

The answer I got was (a)

$$\begin{bmatrix} -0.7143 & 0.0 & 1.4286 \\ 0.2571 & 0.1000 & 0.2857 \\ -0.2286 & -0.2000 & 0.8571 \end{bmatrix} \begin{bmatrix} 1.6667 & 2.8889 & -2.2222 & 1.0000 \\ 0.0 & 0.3333 & -0.3333 & 0.0 \\ -0.3333 & -0.4444 & 0.1111 & 0.0 \\ 1.5000 & 2.0000 & -1.5000 & 0.5000 \end{bmatrix}$$

My MATLAB code for calculating this can be seen below.

```
% Creating function Inverse()
function Ainv = Inverse(A)
% Getting dimensions of matrix
[m, n] = size(A);
% Making sure matrix is square...
if (m = n)
    disp("Square_matrices_only");
end
% Creating empty matrix of same size..
Inv = zeros(m);
% Formatting empty matrix to identity matrix..
for i = 1:m
   Inv(i,i) = 1
end
% Just need 1 for loop for the diagonal..
for i = 1:m
```

```
% If the diagonal isn't 1
     if A(i,i) = 1
          % Divide that row so it is...
          temp = A(i, i);
           for k = 1:m
                A(i,k) = A(i,k) / temp;
                Inv(i,k) = Inv(i,k) / temp;
          end
     end
     \% For the all column cells of the diagonal..
     for j = 1:n
         % Make them 0...
         \mathbf{i} \mathbf{f} \quad \mathbf{i} \quad = \mathbf{j} \quad \&\& \quad \mathbf{A}(\mathbf{j}, \mathbf{i}) \quad = 0
              temp = A(j,i);
               for k = 1:m
                   A(j,k) = A(j,k) - (temp*A(i,k));
                   Inv(j,k) = Inv(j,k) - (temp*Inv(i,k));
              end
         end
     \quad \text{end} \quad
end
% Rinse and repeat
\mathbf{disp}(A);
disp(Inv);
```