# **Brandon Woodward**

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### **EDUCATION**

## **Carnegie Mellon University**

Pittsburgh, PA

Master's Mechanical Engineering and Artificial Intelligence

**Graduation Date December 2024** 

Coursework: Robot Dynamics and Analysis, Modern Control Theory, Machine Learning for Engineers

# **Georgia Institute of Technology**

Atlanta, GA

**Bachelor's Mechanical Engineerings** 

Graduation Date December 2022

Minor in Robotics with coursework in machine learning, robotics, and controls

#### **SKILLS**

Manufacturing: Band Saw, Miter Saw, Dremel, CNC Router, Laser Cutter, 3D Printer, Plasma Cutter, Manual Mill and Lathe

Hardware: RasPi, Arduino, Up2 Computer, T-motors, Futek load cells, CAN and Serial Communication

Programming Languages: Java, Python, C++, C, C#, MATLAB, SQL

Software: GIT, Gradle, Solidworks, Inkscape, Cura, Unity, OnShape, ROS, Byte decoding, Bitwise operations, Wireshark,

Multithreading, DynamoDB, Postgres, TesorFlow **BILINGUAL:** Native Spanish and English speaker

#### INTERNSHIP EXPERIENCE

Area I / Anduril

Kennesaw, GA

Software Engineering Intern

May 2022 - August 2022

- Tested data transmission between proprietary hardware and software via byte decoding, ensuring data integrity
- Developed automated testing systems to verify hardware in C++, improving efficiency and accuracy
- Created a GUI to control and test payloads using PyQT, streamlining payload testing processes

Ihmc Robotics

Pensacola, FL

Software Integration Intern

May 2021 - August 2021

- Developed controls infrastructure in Java for a load bearing lower body exoskeleton, allowing for basic locomotion
- Calibrated Futek load cells, T-motors, and more, ensuring consistency in force and torque readings
- Generated biological knee and ankle joint torque trajectories via Java FX and lab recorded data
- Created 3D models of robots in RViz using ROS and urdf files, allowing for accurate simulations

## RESEARCH EXPERIENCE

# Georgia Tech EPIC Lab

Atlanta, GA

Undergraduate Researcher

August 2021 - May 2022

- Tuned LABView controls algorithm for a lower back exoskeleton to be applied in live tests
- Design and assembly of exoskeleton hardware to reduce mass by along with running testing procedures

### **Georgia Tech LIDAR Lab**

Atlanta, GA

**Undergraduate Researcher** 

August 2020 - May 2021

- Designed tarsal segments in SOLIDWorks to attach to a foot on Cassie, a bipedal robot, improving stability
- Redesigned and manufacturing new prototypes based on test results over several iterations

#### **LEADERSHIP**

Master's Representative, MechE Graduate Student Organization - Pittsburgh, PA

August 2023 - Present

Voicing concerns of master's students to the organization, ensuring representation

Executive Officer, Yellow Jacket Archery Club - Atlanta, GA

President: Lead fellow officers to maintain stability and improve conditions

May 2022 - December 2022

January 2021 - December 2022

• Equipment Manager: Restructured and designed new storage facility

May 2021 - May 2022

Historian: Documented club activities and photographed practices

January 2021 - May 2021

Coached as a level 2 instructor and level 1 judge under USA Archery