

A1 - Vector Space p103-107

4.1 Vector Spaces

Def A vector space over a field, T , of elements $\{\alpha, \beta, \gamma, \dots\}$ called scalars, is a set of elements $\{u, v, w\}$, called vectors, s.t. the following are satisfied:

A1 Closure: $u+v \in V$

A2 Associative: $(u+v)+w = u+(v+w)$

A3 Zero: $u+0=u \mid 0 \in V$

A4 Negative: $u+(-u)=0 \mid -u \in V$

M1 Closure: $\alpha u \in V$

M2 Ass: $\alpha(\beta u) = (\alpha\beta)u$

M3 Distri: a) $(\alpha+\beta)u = \alpha u + \beta u$
b) $\alpha(u+v) = \alpha u + \alpha v$

M4 Unitary: $|u=u \mid t \in T$

Def Fields are sets of real (\mathbb{R}) or complex (\mathbb{C}) numbers

A2-Vector Space Properties p 109-112

4.3 More on vectors

Proposition 1

Hilary

B1 - Subspaces p 122 - 125

5.1 Subspaces

Subspace test:

- 1) Elements of W under Add & Mult closure
are in $\mathcal{E} W$
- 2) Has 0-vector
- 3) Additive inverse is in W

B2 - Linear Combinations p126-127

5.3 Spanning Sets

Def A vector $v \in V$ is a linear combination of $\{v_1, v_2, \dots, v_n\} \subset V$ iff it can be written as:

$$v = \sum_{j=1}^n \lambda_j v_j = \lambda_1 v_1 + \dots + \lambda_n v_n$$

for some $\lambda_j \in \mathbb{R}$.

Ex $[5 \ 1] \in \mathbb{R}^2$ is combo of $\{[1 \ 1], [1 \ -1]\} \subset \mathbb{R}^2$
because $[5 \ 1] = 3[1 \ 1] + 2[1 \ -1]$

Ex $2+3x-2x^2+4x^3 \in P_3$ is combo of $\{1-x^2, x, x+x^3\}$
because $2+3x-2x^2+4x^3 = 4(x+x^3) + 2(1-x^2) - 1(x)$

Def The span of $\{v_1, v_2, \dots, v_n\} \subset V$, denoted $\text{span}\{v_1, v_2, \dots, v_n\}$ is:

$$\text{span}\{v_1, v_2, \dots, v_n\} = \left\{ v \mid v = \sum_{j=1}^n \lambda_j v_j, \forall \lambda_j \in \mathbb{R} \right\}$$

- span $\{v_1, v_2, \dots, v_n\}$ is the set of all possible linear combinations of $\{v_1, v_2, \dots, v_n\}$. This is the spanning set,
- ↪ The spanning set is a subset of V
 - ↪ Can be a subspace of V if passing test

Proposition 1

The span of $\{v_1, v_2, \dots, v_n\} \subseteq V$ is a subspace of the vector space V .

↳ Apply subspace test 0, addition, and multiplication

Proposition 2

Let $U = \text{span } \{v_1, v_2, \dots, v_n\} \subseteq V$. If W is a subspace of V containing the vectors $\{v_1, v_2, \dots, v_n\}$, then $U \subseteq W$.

B3 - Linear Independence p132-135

6.1 Linear Independence

Def A set of vectors $\{v_1, v_2, \dots, v_n\} \subset V$ is linearly independent iff:

$$\sum_{j=1}^n \lambda_j v_j = \lambda_1 v_1 + \dots + \lambda_n v_n = 0$$

implies that all $\lambda_j = 0$.

- All coeffs. $\lambda = 0$ then linearly independent, i.e. λ is the 0-vector

But if linearly independent, then:

Proposition 1

If $\{v_1, v_2, \dots, v_n\} \subset V$ is linearly independent and for all $v \in V$, then λ_j are uniquely determined.

Minimal Spanning sets:

Theorem 1

Let $\{v_1, v_2, \dots, v_n\} \subset V$, a vector space. For every v_k ($k = 1, \dots, n$), $\text{span}\{v_1, \dots, v_{k-1}, v_{k+1}, \dots, v_n\} \neq \text{span}\{v_1, \dots, v_n\}$ iff $\{v_1, \dots, v_n\}$ is linearly independent.

↳ If the spanning set of a vector space is linearly dependent, then we cannot remove a vector from the set without compromising the vector space.

Corollary (Negation)

Let $\{v_1, v_2, \dots, v_n\} \subset V$, a vector space. For at least one v_k ($1 \leq k \leq n$), $\text{span}\{v_1, \dots, v_{k-1}, v_{k+1}, \dots, v_n\} = \text{span}\{v_1, \dots, v_n\}$ iff $\{v_1, \dots, v_n\}$ is linearly dependent.

B4 - Fundamental theorem p135-136

Fundamental Theorem:

Theorem 2:

Let V be a vector space spanned by n vectors. If a set of m vectors from V is linearly independent, then $m \leq n$.

- ↳ If a set of vectors is linearly independent, then there are no more than n vectors
- ↳ If more than n then linearly dependent

B5 - Bases

p 137-138

Def A set of vectors $\{e_1, e_2, \dots, e_n\} \in V$ is a basis for the vector space V iff:

1. $\{e_1, \dots, e_n\}$ is lin. independent
2. $\{e_1, \dots, e_n\}$ spans V

↳ If one basis has n vectors, so does all its bases

Theorem 3:

Every basis for a given vector space contains the same number of vectors,

Def The dimensions of a vector space V , denoted by $\dim V$, is the number of vectors in any of its bases,

- $V = \{0\}$ has no basis, $\therefore \dim \{0\} = 0$

Proposition 2:

Let V be a finite-dimensional vector space with $\dim V = n$. Then,

1. A linearly independent set of vectors in V can at most contain n vectors
2. A spanning set for V must at least contain n vectors

- Basis can be called a minimal spanning set or a maximal independent set.

C1 - Row & Column Spaces pg 154 - 156

$$A = \begin{bmatrix} r_1 \\ r_2 \\ \vdots \\ r_m \end{bmatrix} = [c_1, c_2, \dots, c_n]$$

Def The row space of $A \in \mathbb{M}|\mathbb{R}^n$, denoted $\text{row } A$, is
 $\text{row } A \triangleq \text{span}\{r_1, \dots, r_m\}$

where $r_i \in \mathbb{R}^n$ are the rows of A . The column space denoted $\text{col } A$ is

$$\text{col } A \triangleq \text{span}\{c_1, \dots, c_n\}$$

where $c_i \in \mathbb{M}|\mathbb{R}$ are the columns of A ,

$\hookrightarrow \text{row } A \subseteq \mathbb{R}^n$ is a subspace of $\mathbb{R}^n \Rightarrow \text{row } A \leq n$

$\hookrightarrow \text{col } A \subseteq \mathbb{M}|\mathbb{R}$ is a subspace of $\mathbb{M}|\mathbb{R} \Rightarrow \text{col } A \leq m$

$\hookrightarrow (\dim \text{row } A \& \dim \text{col } A) \leq \min\{m, n\}$

\hookrightarrow Column space of A is the image space or range of A

$$\hookrightarrow \text{col } A = \{y | y = Ax, x \in \mathbb{M}|\mathbb{R}\}$$

$\hookrightarrow \dim \text{row } A = \dim \text{col } A$

Dimensions of Row & Column spaces.

Proposition 1 Let $A \in \mathbb{M}|\mathbb{R}^n$, $U \in \mathbb{M}|\mathbb{R}^m$, and $V \in \mathbb{M}|\mathbb{R}^n$. Then $\text{row } UA \subseteq \text{row } A$ with equality holding if U is invertible. Furthermore, $\text{col } AV \subseteq \text{col } A$ with equality holding if V is invertible.

Proposition 2 Let $\{x_1, \dots, x_r\} \subset \mathbb{M}|\mathbb{R}^n$ and let $U \in \mathbb{M}|\mathbb{R}^m$ be invertible. Then $\{Ux_1, \dots, Ux_r\}$ is lin. ind. iff $\{Ux_1, \dots, Ux_r\}$ is lin. ind.

C2 - Row & Column space dimension pg 158-161

Lemma 1 Let $A \in \mathbb{M}(\mathbb{R}^n)$. Then $\text{row } \tilde{A} = \text{row } A$, where \tilde{A} is the RREF of A , hence $\dim \text{row } \tilde{A} = \dim \text{row } A$. The nonzero rows of \tilde{A} constitute a basis for $\text{row } A$,
 $\hookrightarrow \dim \text{row } A = r = \dim \text{row } \tilde{A}$

Lemma 2 Let $A \in \mathbb{M}(\mathbb{R}^n)$. Then,

- 1) The set of columns of leading ones of \tilde{A} , constitutes a basis for $\text{col } \tilde{A}$
- 2) The set of corresponding columns $\{c_1, \dots, c_r\}$ of A constitutes a basis for $\text{col } A$.
 $\therefore \dim \text{col } \tilde{A} = \dim \text{col } A$

Theorem Let $A \in \mathbb{M}(\mathbb{R}^n)$. $\dim \text{row } A = \dim \text{col } A \rightarrow \dim \text{row } A = \dim \text{row } \tilde{A}$

Proof

$$\begin{aligned} \text{row } A &= \text{row } \tilde{A} \\ \dim \text{row } A &= \dim \text{row } \tilde{A} \\ \dim \text{col } A &= \dim \text{col } \tilde{A} \end{aligned} \quad \begin{aligned} &= r && [\text{L1}] \\ &= \dim \text{col } \tilde{A} \\ &= \dim \text{col } A && [\text{L2}] \end{aligned}$$

$$\begin{bmatrix} 1 & 2 & 3 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 \end{bmatrix}$$

C3-Finding the basis pg 161-163

Basis found by:

1) Find spanning set

2) Do RREF

3) Basis is the non-zero rows = also equals dim of spanning set, s

C4 - Rank and Dimension formula pg 164-165

Rank is the common dimensions of the row A and col A.

Properties:

$$1. \text{rank } A = \text{rank } \tilde{A}$$

$$\hookrightarrow \text{row } A = \text{row } \tilde{A}$$

$$2. \text{rank } A = \text{rank } A^T$$

$$\hookrightarrow \dim \text{col } A = \dim \text{row } A^T$$

Rank nullity theorem:

$$\dim \text{null } A = n - \text{rank } A , \quad n: \text{no. of columns of } A$$

D1 - Linear Transformations pg 180-182

Def The mapping $\ell: V \rightarrow W$ is a linear transformation (operator) iff:

L1 Distribution: $\ell(u+v) = \ell(u) + \ell(v)$ for all $u, v \in V$

L2 Homogeneity: $\ell(\lambda v) = \lambda \ell(v)$ for all $\lambda \in \mathbb{R}, v \in V$

Axiom L1 & L2 are preserved by ℓ . Can be combined.
addition multiplication

$$\ell(\lambda u + \mu v) = \lambda \ell(u) + \mu \ell(v)$$

Note V is the domain of ℓ
and W is the codomain/target space of ℓ

Consider v lives in V but $\ell(v)$ lives in W , $u+v$ uses vector addition of V but $\ell(u) + \ell(v)$ uses vector addition of W .

Operators

Trace Sum of the diagonal entries in a square matrix
 $\text{tr } A$

Differential Differential operation $\rightarrow T: P_n \rightarrow P_n \rightarrow T(p+q)' = T(p)' + T(q)'$
 $T(p) = p' \quad T(cp)' = cT(p)'$

Identity Leaves vector unchanged ie $i(v) = v$ for any $v \in V$
 $i: V \rightarrow V$

Zero Returns zero, $z(0) = 0$

02 - Image & Kernels pg 184-186

Def The image of a linear transformation, $\ell: V \rightarrow W$, is denoted as:

$$\text{im } \ell = \{w \mid w = \ell(v), \forall v \in V\}$$

- Image can also be called the range
- Image is not the codomain
 $\hookrightarrow \text{im } \ell = \ell(V) \subseteq W$

If $\text{im } \ell = W$, ℓ maps V "onto" W instead of "into". ie the transformation is surjective.

If ℓ produces for each $v \in V$ a different $w \in W$, ie $\ell(u) = \ell(v)$

$u = v$, ℓ is one-to-one or injective.

If a transformation is both surjective & injective, the transformation is bijective.

Whereas $Ax=0$ forms a nullspace, for transformations it is called a kernel.

Def The kernel of a linear transformation, $\ell: V \rightarrow W$, is denoted as:

$$\ker \ell = \{v \in V \mid \ell(v) = 0\}$$

Note null space \rightarrow null A
kernel \rightarrow ker A

Formula Dimension:

$$\dim \ker \ell + \dim \text{im } \ell = \dim V$$

Note image is the span of vectors of the linear transformation

Hilary

E1 - Determinants pg 209-210

Some determinants:

$$\text{Ex } \det A = \begin{bmatrix} 1 & 8 & 0 \\ -1 & -2 & 1 \\ 2 & 4 & 3 \end{bmatrix} = 0$$

\times_2

$$\text{Ex } \det A = \begin{bmatrix} -1 & 2 & 4 \\ 4 & -8 & -16 \\ 3 & 0 & 5 \end{bmatrix} = 0$$

\times_2

$$\text{Ex } \det A = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 1 \\ 3 & 0 & 0 \end{bmatrix} = 0$$

$$\text{Ex } \det A = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 2 & 3 \\ 3 & 2 & 1 \end{bmatrix} = 0$$

$$\text{Ex } \det A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} = ad - bc$$

↙ Equal

$$\text{Ex } \det A = \begin{bmatrix} a+c & b+d \\ c & d \end{bmatrix} = (a+c)d - (b+d)c$$

$$\text{Ex } \det A = \begin{bmatrix} c & d \\ a & b \end{bmatrix} = cb - da \rightarrow -1$$

$$\text{Ex } \det I = 1 \rightarrow \text{Identity matrix}$$

E4 - Adjoints pg 231-233

$$\text{For a } 2 \times 2, A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}, A^{-1} = \frac{1}{\det A} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

Def The (i, j) -cofactor of matrix $A \in \mathbb{R}^n$ is:

$$C_{ij}(A) = (-1)^{i+j} \det M_{ij}(A)$$

Def Laplace expansion for the determinant:

$$\det A = \sum_{j=1}^n a_{kj} C_{kj}$$

↳ Assumes expansion across a row

Def The adjoint of matrix $A \in \mathbb{R}^n$ is:

$$\text{adj } A = C^T \in \mathbb{R}^n$$

where $C = [C_{ij}] \in \mathbb{R}^n$ and $c_{ij}(A)$ is the (i, j) -cofactor of A .

Theorem Let $A \in \mathbb{R}^n$. Then:

$$A \text{adj } A = (\text{adj } A)A = (\det A)I$$

Furthermore:

$$A^{-1} = \frac{1}{\det A} \text{adj } A$$

F1 - Eigen problem

pg 238-242

Def Eigen problem:

$$Ap = \lambda p \quad \text{or} \quad (\lambda I - A)p = 0, \quad p \neq 0$$

For nontrivial sol: $\det(\lambda I - A) = 0$

For characteristic polynomial/eigenpolynomial of A :

$$c_A(\lambda) = \det(\lambda I - A)$$

The eigenspace of λ :

$$E_\lambda = \text{null}(\lambda I - A) = \{p \in \mathbb{R}^n \mid Ap = \lambda p\}$$

F4 - Diagonalization Test pg 254-256

Ex Can you diagonalize $A = \begin{bmatrix} 0 & -4 & 0 \\ 1 & 4 & 0 \\ 0 & 0 & 2 \end{bmatrix}$

(characteristic eq'n):

$$C_A(\lambda) = \det(\lambda I - A) = \det \begin{bmatrix} \lambda & 4 & 0 \\ -1 & -\lambda - 4 & 0 \\ 0 & 0 & \lambda - 2 \end{bmatrix}$$

Laplace expansion:

$$\begin{aligned} C_A(\lambda) &= (\lambda - 2)[\lambda(\lambda - 4) + 4] = (\lambda - 2)(\lambda^2 - 4\lambda + 4) \\ &= (\lambda - 2)^3 \\ &= 0 \end{aligned}$$

\hookrightarrow Eigenvalue $\lambda = 2$

\hookrightarrow Eigenspace $E_{\lambda=2} = \text{null}(2I - A)$

$$\hookrightarrow 2I - A = \begin{bmatrix} 2 & 4 & 0 \\ -1 & -2 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Rank = 1

$$(\text{rank}(2I - A) = 1)$$

$$\text{Note } \text{rank}(2I - A) = 1 \rightarrow \therefore \dim E_{\lambda=2} = 3 - \text{rank}(2I - A) \\ = 3 - \text{rank} \underbrace{(2I - A)}_{=} \\ = 2$$

$2 \neq 3 \therefore$ Not diagonalizable

Theorem Let $A \in \mathbb{R}^n$ with distinct $\lambda_1, \dots, \lambda_r$, $r \leq n$.
 If $x_\alpha \in E_{\lambda_\alpha} \setminus \{0\}$, $\alpha = 1, \dots, r$, then $\{x_1, \dots, x_r\}$ is lin. ind.

Corollary If $A \in \mathbb{R}^n$ has n distinct λ , A is diagonalizable

Lemma Let $A \in \mathbb{R}^n$ with distinct $\lambda_1, \dots, \lambda_r$, $r \leq n$.
If $x_\alpha \in E_{\lambda_\alpha}$ and $x_1 + \dots + x_r = 0$, then
 $x_\alpha = 0$, $\alpha = 1, \dots, r$.

Theorem Let $A \in \mathbb{R}^n$ with distinct $\lambda_1, \dots, \lambda_r$, $r \leq n$.
If H_{λ_α} is a linearly ind. set in E_{λ_α} , then
 $H = H_{\lambda_1} \cup H_{\lambda_2} \cup \dots \cup H_{\lambda_r} \equiv \bigcup_{\alpha=1}^r H_{\lambda_\alpha}$
is lin. ind. and
 $m_1 + \dots + m_r \leq n$
where $m_\alpha = \dim E_{\lambda_\alpha}$

F5 - Geometric & Algebraic Multiplicities pg 257-260

Def Let $A \in \mathbb{R}^n$ with eigenvalues λ_α . The highest power n_α of $\lambda - \lambda_\alpha$ that divides the characteristic polynomial $c_A(\lambda)$ s.t $c_A(\lambda) = (\lambda - \lambda_\alpha)^{n_\alpha} g(\lambda)$ is the algebraic multiplicity of λ_α .

The dimension m_α of E_{λ_α} is the geometric multiplicity of λ_α .

Note If $n_\alpha > 1$ then repeated / multiple eigenvalue.

Proposition Let $A = \begin{bmatrix} I & B \\ 0 & C \end{bmatrix} \in \mathbb{R}^n$ where $B \in \mathbb{R}^{n-r}$, $C \in \mathbb{R}^{(n-r) \times (n-r)}$, $I \in \mathbb{R}^r$

the $r \times r$ identity matrix. Then $\det A = \det C$.

Theorem Multiplicity theorem:

Let λ_α be an eigenvalue of $A \in \mathbb{R}^n$. Then $1 \leq m_\alpha \leq n_\alpha$, where m_α and n_α are the geometric and algebraic multiplicities of λ_α . Note if $n_\alpha = 1$ then $m_\alpha = n_\alpha = 1$

Theorem Diagonalization Test:

Let $A \in \mathbb{R}^n$ with distinct eigenvalues λ_α , $\alpha = 1, \dots, r$. Then, A is diagonalizable iff $m_\alpha = n_\alpha$, $\alpha = 1, \dots, r$.

↪ If $m_\alpha = n_\alpha$

F6 - Differential Eqns pg 264-266

Let $\dot{x} = Ax$ where $x(t) \in \mathbb{R}^n$ and $A \in \mathbb{R}^{n \times n}$,
and $x_0 = x(0)$ are the initial cond. Assume
a is diagonalized by $P = [p_1 \dots p_n]$, therefore

$$P^{-1}AP = \Lambda = \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_r \end{bmatrix} \quad \text{and} \quad Ap_\alpha = \lambda_\alpha p_\alpha$$

where each λ_α , $\alpha = 1, \dots, r$ is repeated $m_\alpha = n_\alpha$ times