

Dive into XGBoost

张海鹏

JiangNan University

2017-10-20

目录

 数学理论

 系统设计

 模型应用

 参考文献

数学理论

$$f(x_{k+1}) = f(x_k + x_{k+1} - x_k) \approx f(x_k) + \nabla f(x_k)(x_{k+1} - x_k)$$

$$f(x_{k+1}) < f(x_k) \Rightarrow \nabla f(x_k)(x_{k+1} - x_k) < 0$$

$$x_{k+1} = x_k - \gamma \nabla f(x_k)$$

$$\nabla f(x_k) = 0, x_{k+1} = x_k$$

数学理论

$$f(x) = l(h(x, D), Y) \quad h(x, d) = \frac{1}{1 + e^{-xd}}$$

$$l(h(x, D), Y) = \prod_{d \in D, y \in Y} (h(x, d)^y (1 - h(x, d)^{1-y}))$$

$$l(H(x_{k+1})) = l(H(x_t) + h(x_{t+1})) \quad H(x_t) = \sum_{i=1}^t h(x_i) \\ \approx l(H(x_t)) + \nabla l(H(x_t)) h(x_{t+1})$$

数学理论

$$H(x_{t+1}) = H(x_t) - \gamma \nabla l(H(x_t)) \quad H(x_t) = \sum_{i=1}^t h(x_i)$$

$$h(x_{t+1}) = -\gamma \nabla l(H(x_t))$$



$$h : D \xrightarrow{x} \nabla l(H(x_t, D))$$

数学理论

Model Formalization:

$$\hat{y}_i = \phi(x_i) = \sum_{k=1}^K f_k(x_i), f_k \in F$$

Training Objective:

$$L(\phi) = \sum_i l(y_i, \hat{y}_i) + \sum_k \Omega(f_k)$$

数学理论

$$\begin{aligned} L^{(t)} &= \sum_{i=1}^n l(y_i, \hat{y}_i^{(t)}) + \sum_{i=1}^t \Omega(f_i) \\ &= \sum_{i=1}^n l(y_i, \hat{y}_i^{(t-1)} + \boxed{f_t(x_i)}) + \sum_{i=1}^t \Omega(f_i) \end{aligned}$$


数学理论

$$L^{(t)} \simeq \sum_{i=1}^n [l(y_i, \hat{y}^{(t-1)}) + g_i f_t(x_i) + \frac{1}{2} h_i f_t^2(x_i)] + \sum_{i=1}^t \Omega(f_i)$$

$$g_i = \partial_{\hat{y}^{(t-1)}} l(y_i, \hat{y}^{(t-1)})$$

$$h_i = \partial_{\hat{y}^{(t-1)}}^2 l(y_i, \hat{y}^{(t-1)})$$

remove constant terms!


$$\tilde{L}^{(t)} = \sum_{i=1}^n [g_i f_t(x_i) + \frac{1}{2} h_i f_t^2(x_i)] + \Omega(f_t)$$

数学理论

$$q : \mathbb{R}^d \rightarrow \{1, 2, \dots, T\}$$

$$f_t(x) = w_{q(x)} \quad \longrightarrow \quad \Omega(f_t) = \gamma T + \frac{1}{2} \lambda \sum_{j=1}^T w_j^2$$

$$\tilde{L}^{(t)} = \sum_{i=1}^n [g_i f_t(x_i) + \frac{1}{2} h_i f_t^2(x_i)] + \gamma T + \frac{1}{2} \lambda \sum_{j=1}^T w_j^2$$

$$= \sum_{j=1}^T [(\sum_{i \in I_j} g_i) w_j + \frac{1}{2} (\sum_{i \in I_j} h_i + \lambda) w_j^2] + \gamma T$$

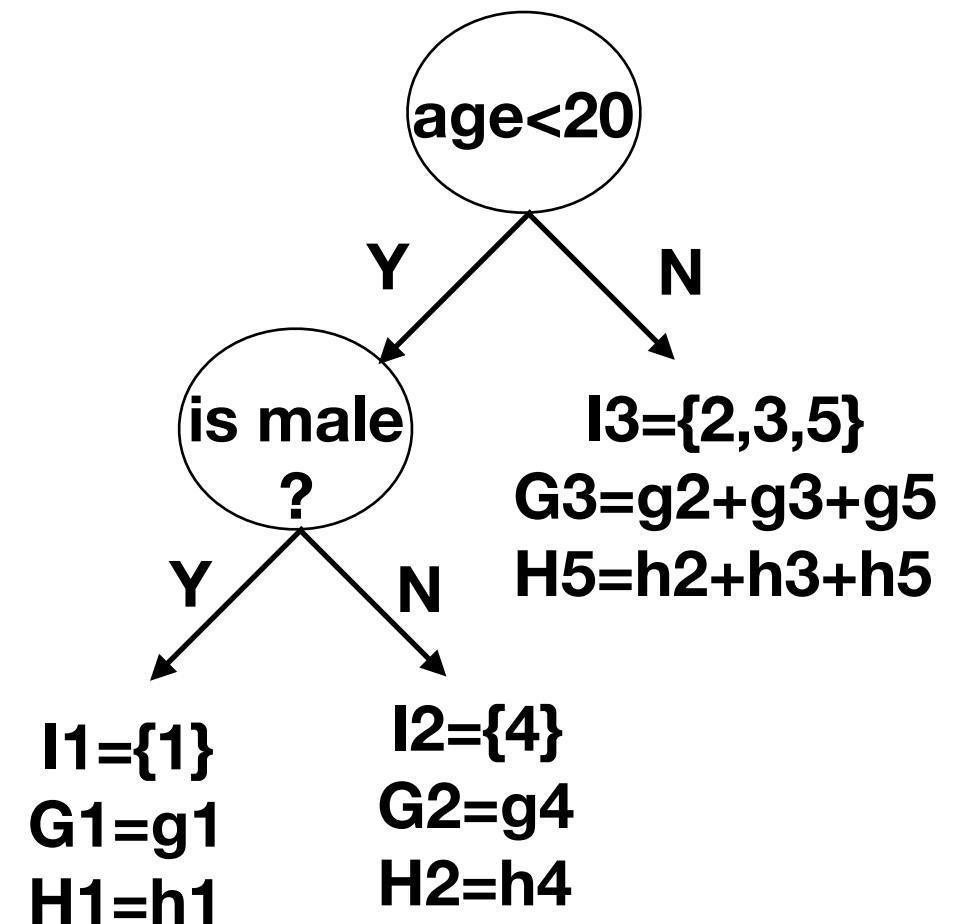
数学理论

$$w_j^* = - \frac{\sum_{i \in I_j} g_i}{\sum_{i \in I_j} h_i + \lambda}$$

$$\tilde{L}^{(t)}(q) = -\frac{1}{2} \sum_{j=1}^T \frac{(\sum_{i \in I_j} g_i)^2}{\sum_{i \in I_j} h_i + \lambda} + \gamma T$$

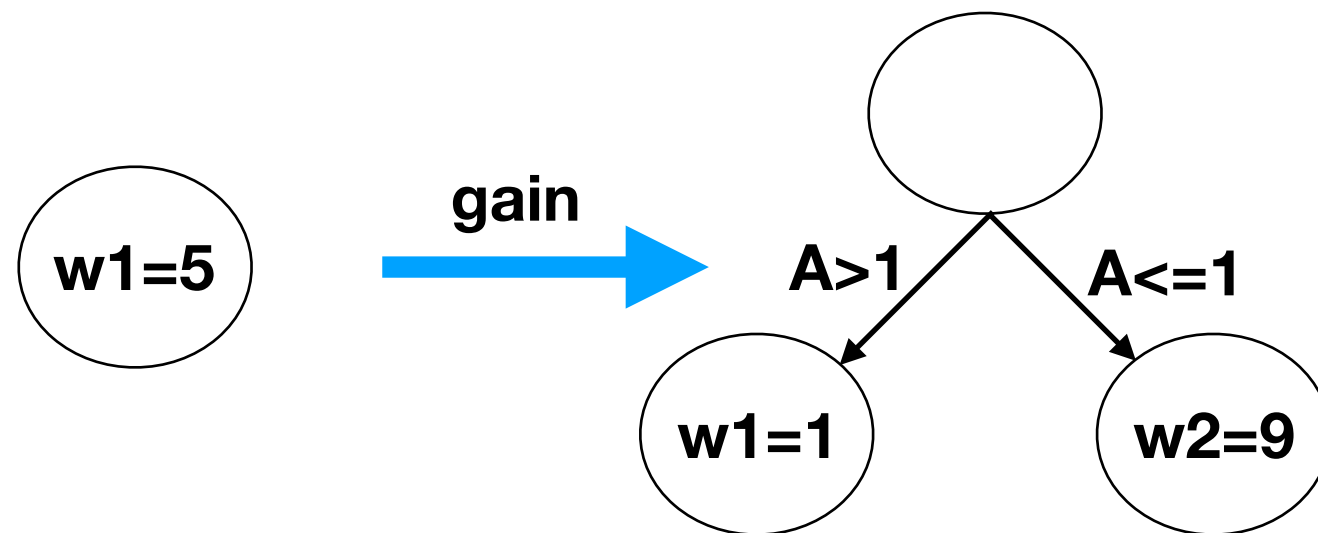
Example

Index	G	H
1	g1	h1
2	g2	h2
3	g3	h3
4	g4	h4
5	g5	h5



$$Obj = - \sum_j \frac{G_j^2}{H_j + \lambda} + 3\gamma$$

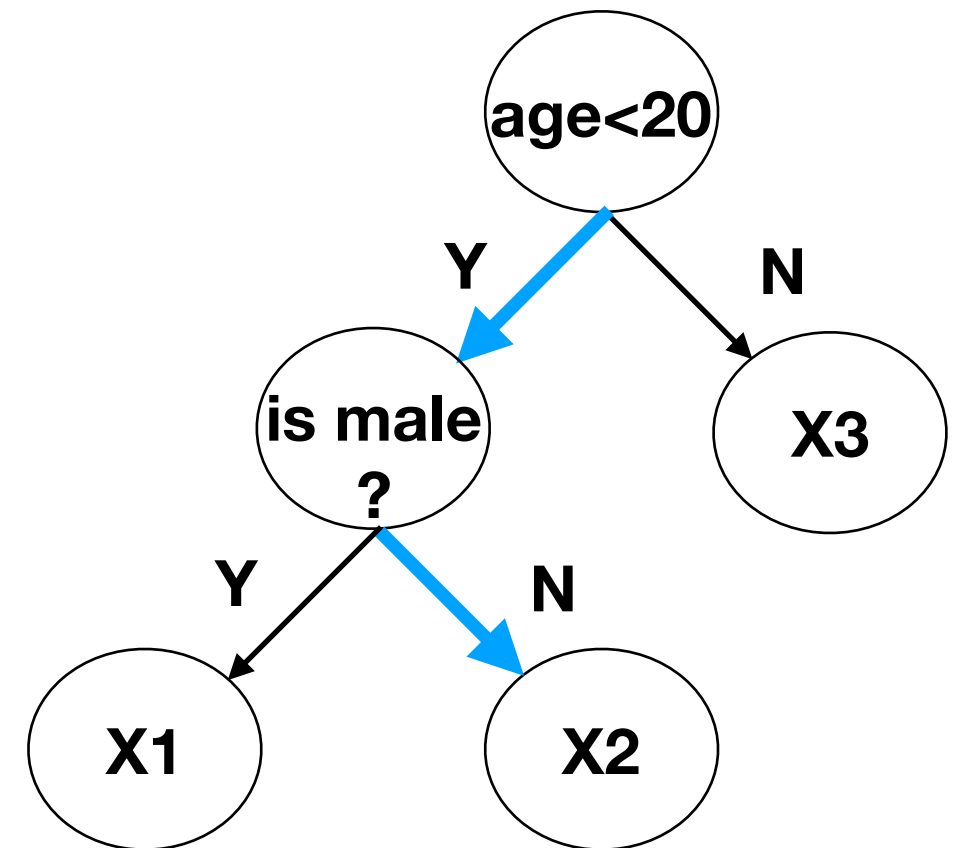
Tree Growing Algorithm



$$gain = \frac{1}{2} \left[\frac{(\sum_{i \in I_L} g_i)^2}{\sum_{i \in I_L} h_i + \lambda} + \frac{(\sum_{i \in I_R} g_i)^2}{\sum_{i \in I_R} h_i + \lambda} - \frac{(\sum_{i \in I} g_i)^2}{\sum_{i \in I} h_i + \lambda} \right] - \gamma$$

Missing Values Handling

example	Age	Gender
X1	?	male
X2	15	?
X3	25	female



Time Complexity:

$$O(ndK \log n) \xrightarrow{\text{pre-sorted features}} O(ndK)$$

Alg-1

Algorithm 1: Exact Greedy Algorithm for Split Finding

Input: I , instance set of current node

Input: d , feature dimension

$gain \leftarrow 0$

$G \leftarrow \sum_{i \in I} g_i, H \leftarrow \sum_{i \in I} h_i$

for $k = 1$ **to** m **do**

$G_L \leftarrow 0, H_L \leftarrow 0$

for j *in* $\text{sorted}(I, \text{by } \mathbf{x}_{jk})$ **do**

$G_L \leftarrow G_L + g_j, H_L \leftarrow H_L + h_j$

$G_R \leftarrow G - G_L, H_R \leftarrow H - H_L$

$score \leftarrow \max(score, \frac{G_L^2}{H_L + \lambda} + \frac{G_R^2}{H_R + \lambda} - \frac{G^2}{H + \lambda})$

end

end

Output: Split with max score

Alg-2

Algorithm 2: Approximate Algorithm for Split Finding

for $k = 1$ **to** m **do**

 | Propose $S_k = \{s_{k1}, s_{k2}, \dots, s_{kl}\}$ by percentiles on feature k .
 | Proposal can be done per tree (global), or per split(local).

end

for $k = 1$ **to** m **do**

 | $G_{kv} \leftarrow \sum_{j \in \{j | s_{k,v} \geq \mathbf{x}_{jk} > s_{k,v-1}\}} g_j$
 | $H_{kv} \leftarrow \sum_{j \in \{j | s_{k,v} \geq \mathbf{x}_{jk} > s_{k,v-1}\}} h_j$

end

Follow same step as in previous section to find max score only among proposed splits.

Alg-3

Algorithm 3: Sparsity-aware Split Finding

Input: I , instance set of current node

Input: $I_k = \{i \in I | x_{ik} \neq \text{missing}\}$

Input: d , feature dimension

Also applies to the approximate setting, only collect statistics of non-missing entries into buckets

$\text{gain} \leftarrow 0$

$G \leftarrow \sum_{i \in I} g_i, H \leftarrow \sum_{i \in I} h_i$

for $k = 1$ **to** m **do**

// enumerate missing value goto right

$G_L \leftarrow 0, H_L \leftarrow 0$

for j in sorted(I_k , ascent order by \mathbf{x}_{jk}) **do**

$G_L \leftarrow G_L + g_j, H_L \leftarrow H_L + h_j$

$G_R \leftarrow G - G_L, H_R \leftarrow H - H_L$

$\text{score} \leftarrow \max(\text{score}, \frac{G_L^2}{H_L + \lambda} + \frac{G_R^2}{H_R + \lambda} - \frac{G^2}{H + \lambda})$

end

// enumerate missing value goto left

$G_R \leftarrow 0, H_R \leftarrow 0$

for j in sorted(I_k , descent order by \mathbf{x}_{jk}) **do**

$G_R \leftarrow G_R + g_j, H_R \leftarrow H_R + h_j$

$G_L \leftarrow G - G_R, H_L \leftarrow H - H_R$

$\text{score} \leftarrow \max(\text{score}, \frac{G_L^2}{H_L + \lambda} + \frac{G_R^2}{H_R + \lambda} - \frac{G^2}{H + \lambda})$

end

end

Output: Split and default directions with max gain

训练过程

初始化模型参数；

设置training sample默认预测值为相同类别，计算grad和hess；

从第一棵树直到设定的树的数目：

$\text{grad}', \text{hess}' = (\text{grad}, \text{hess}) * \text{sample_weight}$ ；

原始数据集行列采样得到采样后数据集D；

对D进行划分， $X=(\text{属性集合})$ ， $Y=(\text{真实值}, \text{预测值}, \text{grad}', \text{hess}')$ ；

建树，返回树模型curTree；

更新预测值(学习率*新的预测值)，grad, hess；

子树添加到根树；打印训练信息；

建树过程

初始化参数，获取训练数据X,Y；

判断当前训练样本是否构成叶子节点，如果是，计算叶子节点score并返回当前TreeNode，内含信息：叶子标志，叶子得分；否则，执行下一步；

对X列采样，得到X_selected；

找到X_selected的最佳属性，最佳属性分割阈值，最佳gain，空值默认分割方向；

如果最佳gain为负，构成叶子节点，返回当前TreeNode；

分割X；分别对X的左右子树建树；

属性重要性计数；

返回TreeNode，内含信息：左右子树，分割属性，分割阈值，分割方向；

预测过程

初始化预测值pred为0；

对根树中的每一棵子树： //RandomForest的区别

 //并行加速

 pred += 学习率*每棵树的预测结果；

返回预测结果pred；

系统设计

☐ Column Block for Parallel Learning

☒ exact greedy, approximate

☐ Cache-aware Access

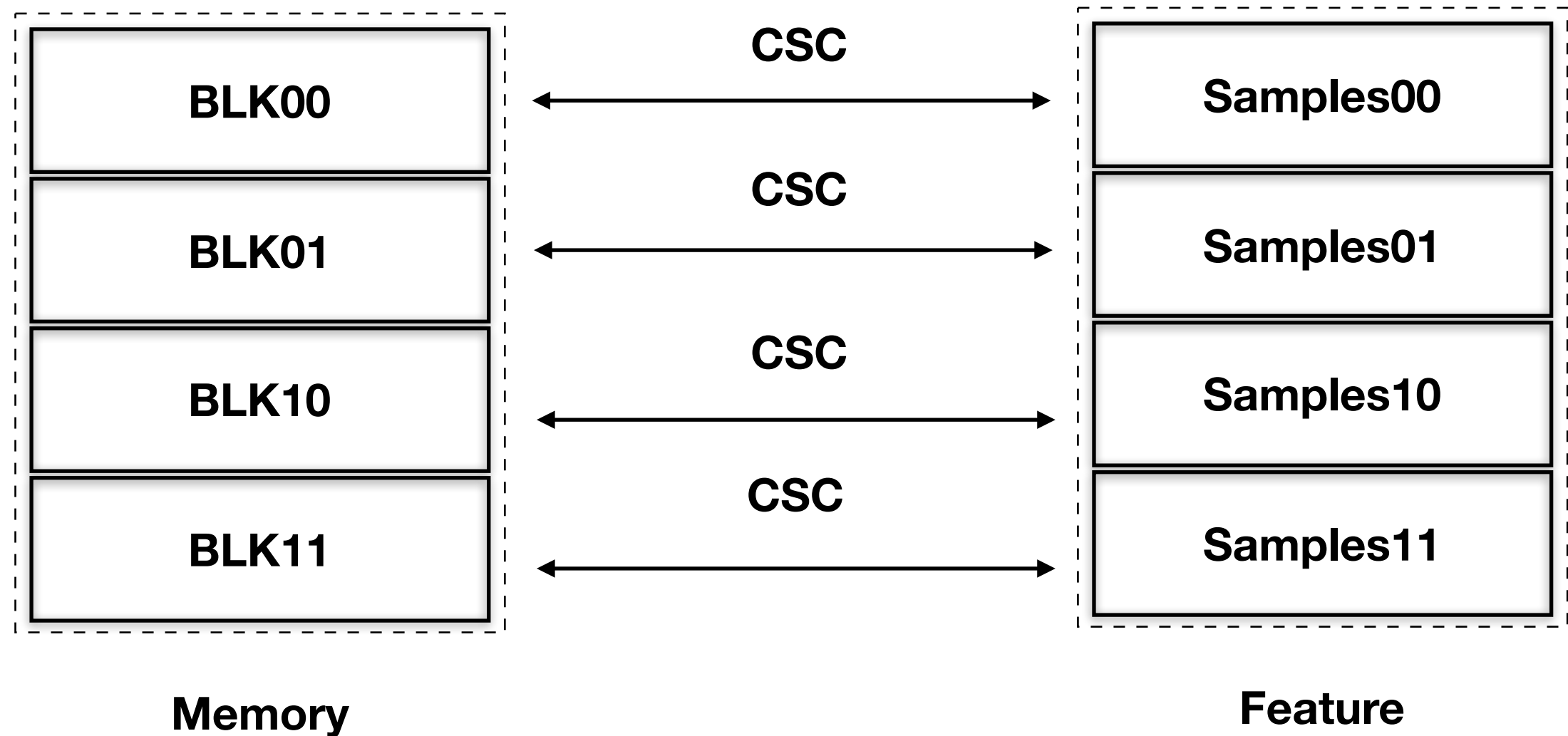
☒ exact greedy: cache-aware prefetching

☒ approximate: choose better block size to balance cache property and parallelization

☐ Blocks for Out-of-core Computation

☒ block compression, block sharding

Column-Block



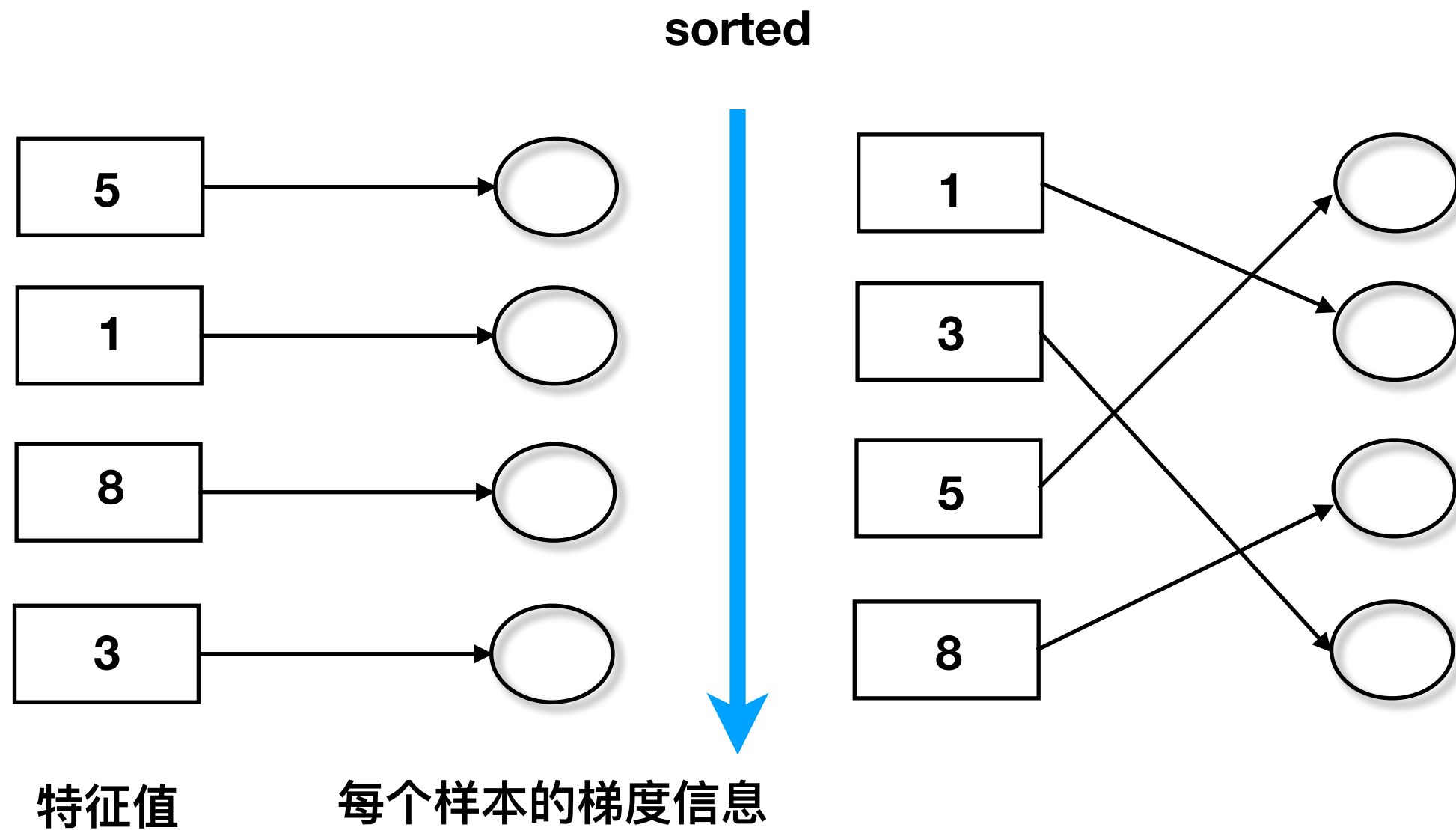
Compressed Row Storage

$$A = \begin{pmatrix} 10 & 0 & 0 & 0 & -2 & 0 \\ 3 & 0 & 0 & 0 & 0 & 3 \\ 0 & 7 & 8 & 7 & 0 & 0 \\ 3 & 0 & 8 & 7 & 5 & 0 \\ 0 & 8 & 0 & 9 & 9 & 13 \\ 0 & 4 & 0 & 0 & 2 & -1 \end{pmatrix}$$

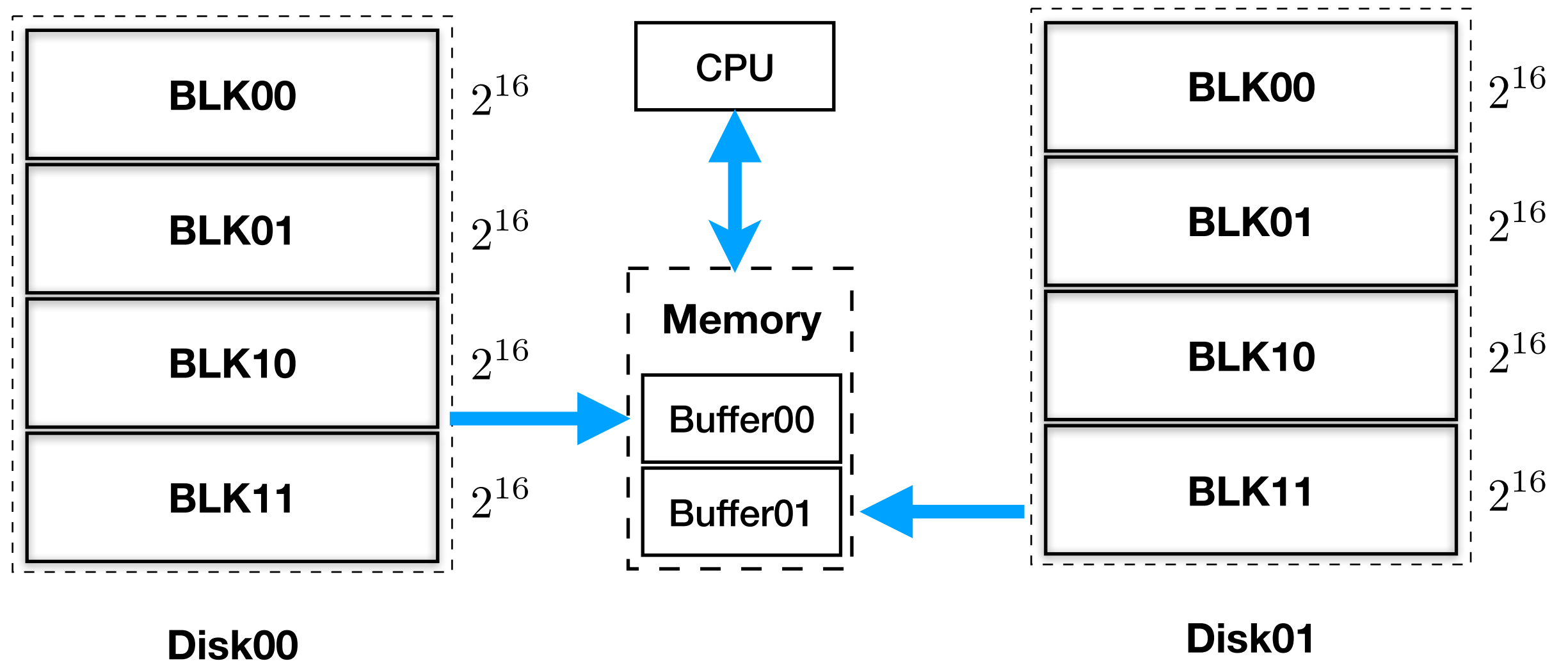
row_ptr	1	3	6	9	13	17	20
---------	---	---	---	---	----	----	----

val	10	-2	3	0	3	7	8	7	3 ... 0	13	4	2	-1
col_ind	1	5	1	2	6	2	3	4	1 ... 5	6	2	5	6

Cache-Aware



Out-of-core Computation



模型应用

- ☑ Feature Importance
- ☑ Customized Metric/Loss Function
- ☑ Combination Features(stacking)

参考文献

- 1.XGBoost的Github地址: <https://github.com/dmlc/xgboost>
 - 2.XGBoost的tiny实现: <https://github.com/zhpmatrix/groot>
 - 3.GBDT的实现: <https://github.com/liuzhiqiangruc/dml/tree/master/gbdt>
 4. 《Higgs Boson Discovery with Boosted Trees》, JMLR Workshop, Tianqi Chen, Tong He, 2015
 5. 《XGBoost: A Scalable Tree Boosting System》, KDD, Tianqi Chen, Carlos Guestrin, 2016
 6. 《Practical Lessons from Predicting Clicks on Ads at Facebook》, Xinran He
 - 7.XGBoost源码阅读: <https://zhpmatrix.github.io/2017/03/15/xgboost-src-reading-2>
-

TKS

有啥问题需要探讨的吗？