

CREPE: A Convolutional Representation of Pitch Estimation

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- Discussion and Conclusion

Auditory Attribute of Musical Tones

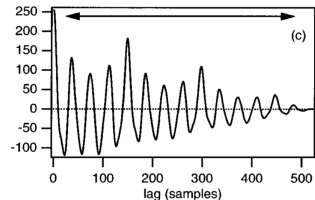
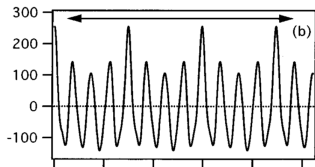
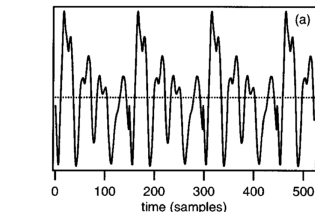
- Pitch (\approx fundamental frequency/ F_0 , for voiced speech)
- Timbre (spectrum, envelope, instruments)
- Duration (timing, pauses, rate)
- Loudness (amplitude/energy)

Pitch Estimation

Three mostly used methods for pitch estimation:

- Autocorrelation of Speech - used by baseline: pYIN
- Cepstrum Pitch Determination
- Single Inverse Filter Tracking(SIFT) Algorithm

Pitch Estimation by Autocorrelation Method



Autocorrelation Function

$$r_t(\tau) = \sum_{j=t+1}^{t+W} x_j x_{j+\tau} \quad (1)$$

$$r'_t(\tau) = \sum_{j=t+1}^{t+W-\tau} x_j x_{j+\tau} \quad (2)$$

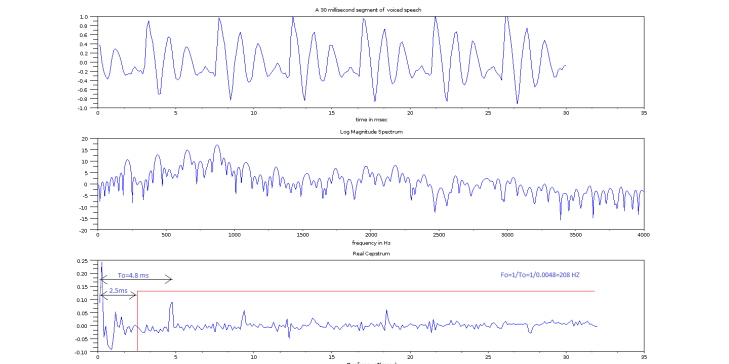
The second largest peak location in samples gives T_0 and thus pitch is computed as:

$$F_0 = F_s / T_0 \quad (3)$$

F_s : sampling frequency

T_0 : pitch period in samples

Cepstrum Pitch Determination



The largest peak location gives T_0 and thus pitch is computed as:

$$F_0 = 1/T_0 \quad (4)$$

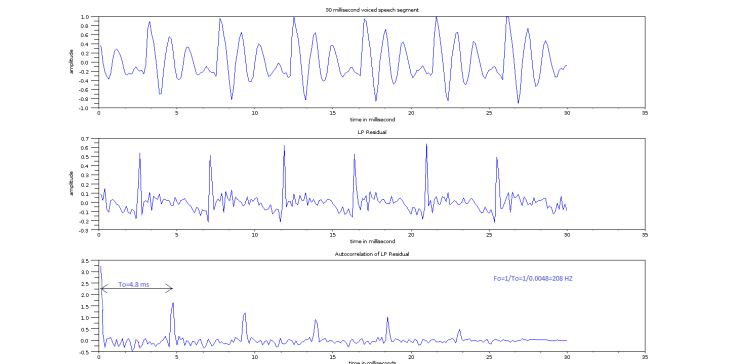
F_s : sampling frequency

T_0 : pitch period in time

Linear prediction (LP)

- A speech sample can be approximated as a linear combination of past samples.
- Obtain a unique set of predictor coefficients by minimizing the sum of the squared differences between the actual speech samples and the linearly predicted ones over a finite interval.
- Decomposes the speech into two highly independent components:
 1. Vocal tract parameters (LP coefficients)
 2. Glottal excitation (LP residual).
- The autocorrelation of LP residual will therefore have unambiguous peaks representing the pitch period 'T0' information.

Pitch estimation by SIFT method



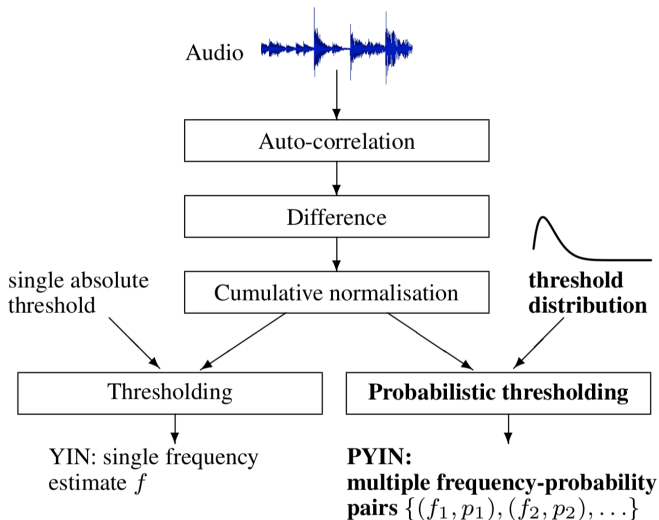
A single peak picking can be employed for the estimation of pitch period T_0 as illustrated in the figure. Pitch is computed as:

$$F_0 = 1/T_0 \quad (5)$$

F_s : sampling frequency

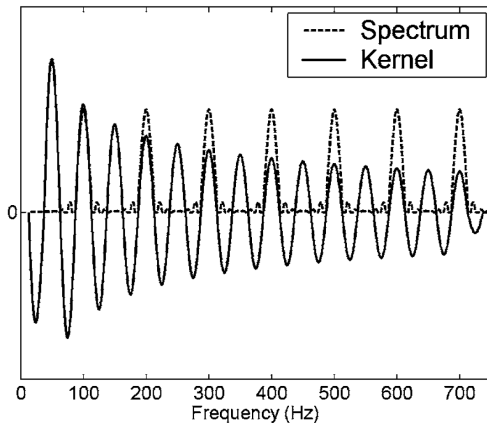
T_0 : pitch period in time

Baseline: YIN and pYIN



Baseline: SWIPE Pitch Estimation

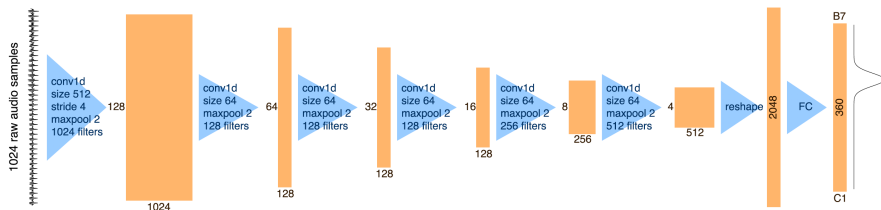
Sawtooth Waveform Inspired Pitch Estimator(SWIPE)



Shortcomings of existing methods and Motivation

- The development of well-performed systems solely depends on devising a robust **candidate-generating function**(i.e. heuristics) and/or **sophisticated post-processing steps**.
- **None** of the model **directly learn from data**, except for manual hyper-parameter tuning.
- In **other problems** in music information retrieval, e.g. chord ID, beat detection, **data-driven methods have been shown consistently out-perform heuristic approaches**.
- Current methods still produce noisy results for uncommon instruments and highly fluctuated pitch curves.

CREPE - Architecture



- Input: 1024 samples excerpt from time-domain audio signal, 16kHz sampling rate.
- 6 convolutional layers, resulting in 2048 latent representation
- Sigmoid activation, deterministic
- 360-dim output vector where each frequency bin covers 20 **cents**.

CREPE - Output Interpretation

Cent: A unit representing musical intervals relative to a reference pitch f_{ref} in *Hz*, defined as a function of frequency f in *Hz*:

$$c(f) = 1200 \times \log_2 \frac{f}{f_{ref}} \quad (6)$$

Where $f_{ref} = 10\text{Hz}$ is used throughout the experiment. The 360 pitch values are denoted c_1, c_2, \dots, c_{360} , covers **6 octaves** from **C1** to **B7**. Resulting pitch estimate \hat{c} is the weighted average of the associated c_i .

$$\hat{c}(f) = \frac{\sum_{i=1}^{360} \hat{y}_i c_i}{\sum_{i=1}^{360} \hat{y}_i} \quad (7)$$

and obtain the estimated frequency:

$$\hat{f} = f_{ref} \times 2^{\hat{c}/1200} \quad (8)$$

RWC-synth

- **6.16 hours** of audio synthesized from the RWC Music Database.
- Have perfect control over the F_0 of the resulting signal.
- Synthesized using a fixed sum of a small number of sinusoidal, highly homogeneous in timbre and represents an **over-simplified scenario**.

MDB-stem-synth

- 230 tracks with 25 instruments, totaling 15.56 hours of audio.
- Monophonic stems taken from MedleyDB and re-synthesized, with a **perfect f0 annotation** that **maintains the timbre and dynamics** of the original track.
- Representing a **real-world scenario**.

Target Output

360-dimensional vector(same as model's output). Frequency bin with the ground truth frequency is given a magnitude of 1 and then Gaussian blurred.

$$y_i = \exp\left(-\frac{(c_i - c_{true})^2}{2 \times 25^2}\right) \quad (9)$$

Cross entropy loss between predicted vector \hat{y} and target vector y

$$L(y, \hat{y}) = \sum_{i=1}^{360} (-y_i \log \hat{y}_i - (1 - y_i) \log(1 - \hat{y}_i)) \quad (10)$$

- Optimized by ADAM optimizer with learning rate 0.0002.
- Trained for 32 epochs with 500 batches and batch size 32.
- Each convolutional layer is followed with a drop out layer with drop-out rate 0.25.

Experiment and Evaluation Criteria

Methodology

5-fold cross-validation, 60/20/20 train, validation and test split.

Evaluation

Raw Pitch Accuracy(RPA) and Raw Chorma Accuracy(RCA) within 50 cent(a quarter-tone) threshold of the ground truth.

Added Noise - Audio Degradation Toolbox(ADT)

4 Noise sources: pub, while, pink, brown

Use different Signal-to-Noise Ratios(SNR): , 40, 30, 20, 10, 5, 0dB

Results - Pitch Accuracy with 50 cents(standard) threshold

Table 1. Average raw pitch/chroma accuracies and their standard deviations, tested with the 50 cents threshold

Dataset	Metric	CREPE	pYIN	SWIPE
RWC-synth	RPA	0.999 ± 0.002	0.990 ± 0.006	0.963 ± 0.023
	RCA	0.999 ± 0.002	0.990 ± 0.006	0.966 ± 0.020
MDB-stem-synth	RPA	0.967 ± 0.091	0.919 ± 0.129	0.925 ± 0.116
	RCA	0.970 ± 0.084	0.936 ± 0.092	0.936 ± 0.100

Results - Pitch Accuracy with different evaluation thresholds

Table 2: Average raw pitch accuracies and their standard deviations, with different evaluation thresholds.

Dataset	Threshold	CREPE	pYIN	SWIPE
RWC-synth	50 cents	0.999 ± 0.002	0.990 ± 0.006	0.963 ± 0.023
	25 cents	0.999 ± 0.003	0.972 ± 0.012	0.949 ± 0.026
	10 cents	0.995 ± 0.004	0.908 ± 0.032	0.833 ± 0.055
MDB-stem-synth	50 cents	0.967 ± 0.091	0.919 ± 0.129	0.925 ± 0.116
	25 cents	0.953 ± 0.103	0.890 ± 0.134	0.897 ± 0.127
	10 cents	0.909 ± 0.126	0.826 ± 0.150	0.816 ± 0.165

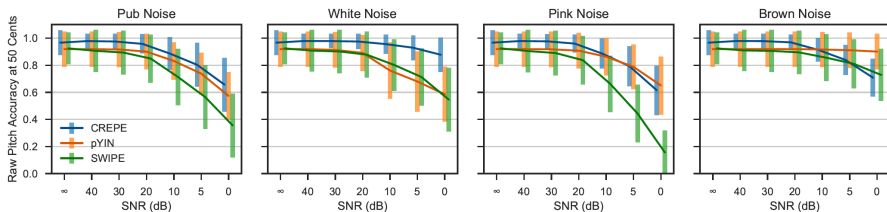
This suggests that CREPE is especially preferable when even minor deviations from the true pitch should be avoided as best as possible.

Results - Niose Robustness

Pitch tracking performance when additive noise signals.

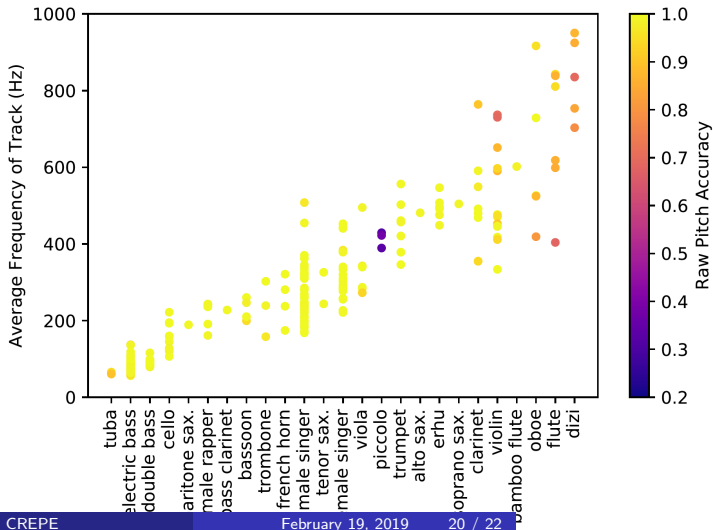
The error bars are centered at the average raw pitch accuracies and span the first standard deviations.

With brown noise being a notable exception, CREPE shows the highest noise robustness in general.



Results - Performance by Instrument

RPA of CREPEs predictions on each of the 230 tracks in MDB-stem-synth with respect to the instrument, sorted by the average frequency.



Contribution of this model

- ① State-of-the-art performance on both datasets with homogeneous and heterogeneous timbre.
- ② Highly accurate even at strict evaluation threshold.
- ③ More robust to added noise.
- ④ Innovative data-driven pitch tracking algorithm.

Future Work

- ① Model should be invariant to all transformations that do not effect pitch. Use data augmentation to generate transformed and degraded signal and make the model to learn the invariance.
- ② Robustness can be improve by applying pitch-shift to cover a wider pitch range.
- ③ Enforcing temporal smoothness to improve the performance, by using CRNN.

Q & A