

# Design Assignment 5

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Primary Github address: <https://github.com/WorkuT1226/CPE301.git>

Directory:

Submit the following for all Labs:

- In the document, for each task submit the modified or included code (only) with highlights and justifications of the modifications. Also, include the comments.
- Use the previously create a Github repository with a random name (no CPE/301, Lastname, Firstname). Place all labs under the root folder ESD301/DA, sub-folder named LABXX, with one document and one video link file for each lab, place modified asm/c files named as LabXX-TYY.asm/c.
- If multiple asm/c files or other libraries are used, create a folder LabXX-TYY and place these files inside the folder.
- The folder should have a) Word document (see template), b) source code file(s) and other include files, c) text file with youtube video links (see template).
- **COMPONENTS LIST AND CONNECTION BLOCK DIAGRAM w/ PINS**  
Atmega328p  
NRF24L01  
LM35
- **INITIAL/MODIFIED/DEVELOPED CODE OF TASK 1/A**

```
#define BAUD 9600
#define F_CPU 16000000UL
#include <avr/io.h>
#include <util/delay.h>
#include <avr/interrupt.h>
#include <stdbool.h>
#include <stdio.h>
#include <string.h>
unsigned int ADC_TEMP;
// #include "nrf24l01.h"
// #include "nrf24l01-mnemonics.h"
// #include "spi.h"
void print_config(void);
void ADC_INIT(void);
void READ_ADC(void);
volatile bool message_received = false;
volatile bool status = false;
int main(void){
    char tx_message[32];
```

```

char *tx_ptr = tx_message;
ADC_INIT();
printf("begin");
printf("end");
ADC_TEMP = 0;
while (1){
    tx_ptr = tx_message;
    if (message_received){
        printf("hello");
        message_received = false;
        _delay_ms(500);
        if (status == true)
            printf("sent");
    }
}
}
ISR(INT0_vect){
    message_received = true;
}
void ADC_INIT(void){
    ADMUX = (0<<REFS1)|
    (1<<REFS0)|
    (0<<ADLAR)|
    (1<<MUX2)|
    (0<<MUX1)|
    (0<<MUX0);
    ADCSRA = (1<<ADEN)|
    (0<<ADSC)|
    (0<<ADIF)|
    (0<<ADIE)|
    (1<<ADPS2)|
    (0<<ADPS1)| (1<<ADPS0);
    TIMSK1 |= (1<<TOIE1);
    TCCR1B |= (1<<CS12)|(1<<CS10);
    TCNT1 = 49911;

void READ_ADC(void) {
    unsigned char i=3;
    ADC_TEMP = 0;
    while (i--){
        ADCSRA |= (1<<ADSC);
        while(ADCSRA & (1<<ADSC));
        ADC_TEMP+= ADC;
        _delay_ms(150);
    }
    ADC_TEMP = ADC_TEMP/4;
}
void print_config(void){
    uint8_t D;
    printf("done\n\n nRF24L01+ : \n");
    nrf24_read(&D,1);
    printf("0x%02X\n",D);
    nrf24_read(&D,1);
    printf("0x%02X\n",D);
    nrf24_read(&D,1);
    printf(" 0x%02X\n",D);
    nrf24_read(&D,1);
    printf("%02X\n",D);
    nrf24_read(&D,1);
    printf("0x%02X\n",D);
    nrf24_read(&D,1);
    printf("0x%02X\n",D);
    nrf24_read(&D,1);
}

```

```

        printf("0x%02X\n",D);
        nrf24_read(&D,1);
        printf("0x%02X\n",D);
    }
}

```

- **SCREENSHOTS OF EACH TASK OUTPUT (ATMEL STUDIO OUTPUT)**

```

unsigned char i=3;
ADC_TEMP = 0;
while (i--){
    ADCSRA |= (1<<ADSC);
    while(ADCSRA & (1<<ADSC));
    ADC_TEMP+= ADC;
    _delay_ms(150);
}
ADC_TEMP = ADC_TEMP/4;
}

void print_config(void){
    uint8_t D;
    printf("done\n\n nRF24L01+ :\n");
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    printf("0x%02X\n",D);
    nrf24_read(&D,1);
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    printf("0x%02X\n",D);
    nrf24_read(&D,1);
    printf("0x%02X\n",D);
    nrf24_read(&D,1);
    printf("0x%02X\n",D);
}
}

message_received = true;
}

void ADC_INIT(void){
    ADMUX = (0<<REFS1)|
    (1<<REFS0)|
    (0<<ADLAR)|
    (1<<MUX2)|
    (0<<MUX1)|
    (0<<MUX0);
    ADCSRA = (1<<ADEN) |
    (0<<ADSC)|
    (0<<ADATE)|
    (0<<ADIF)|
    (0<<ADIE)|
    (1<<ADPS2)|
    (0<<ADPS1) | (1<<ADPS0);
    TIMSK1 |= (1<<TOIE1);
    TCCR1B |= (1<<CS12)|(1<<CS10);
    TCNT1 = 49911;
}

void READ_ADC(void) {
    unsigned char i=3;
    ADC_TEMP = 0;
    while (i--){
        ADCSRA |= (1<<ADSC);
        while(ADCSRA & (1<<ADSC));
        ADC_TEMP+= ADC;
        _delay_ms(150);
    }
    ADC_TEMP = ADC_TEMP/4;
}

void print_config(void){
    uint8_t D;
    printf("done\n\n nRF24L01+ :\n");
    nrf24_read(&D,1);
    printf("0x%02X\n",D);
}

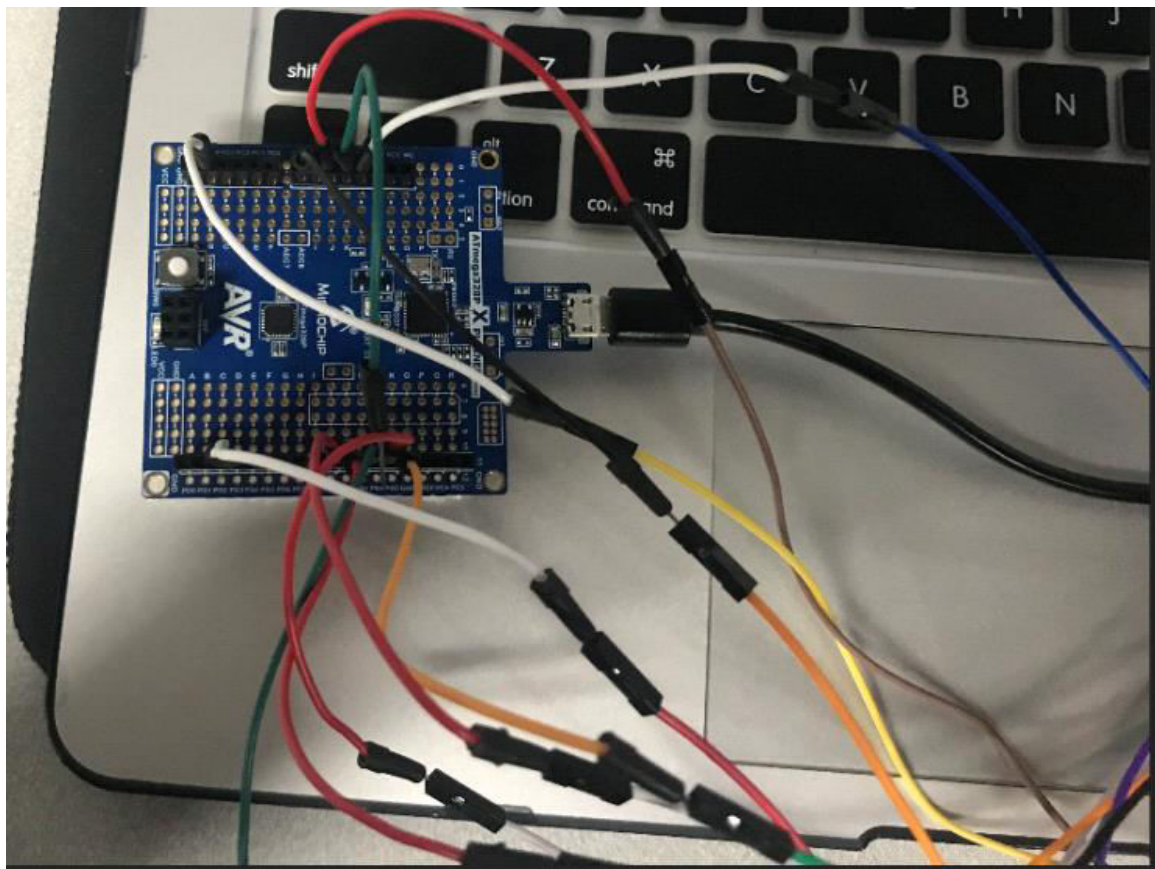
```

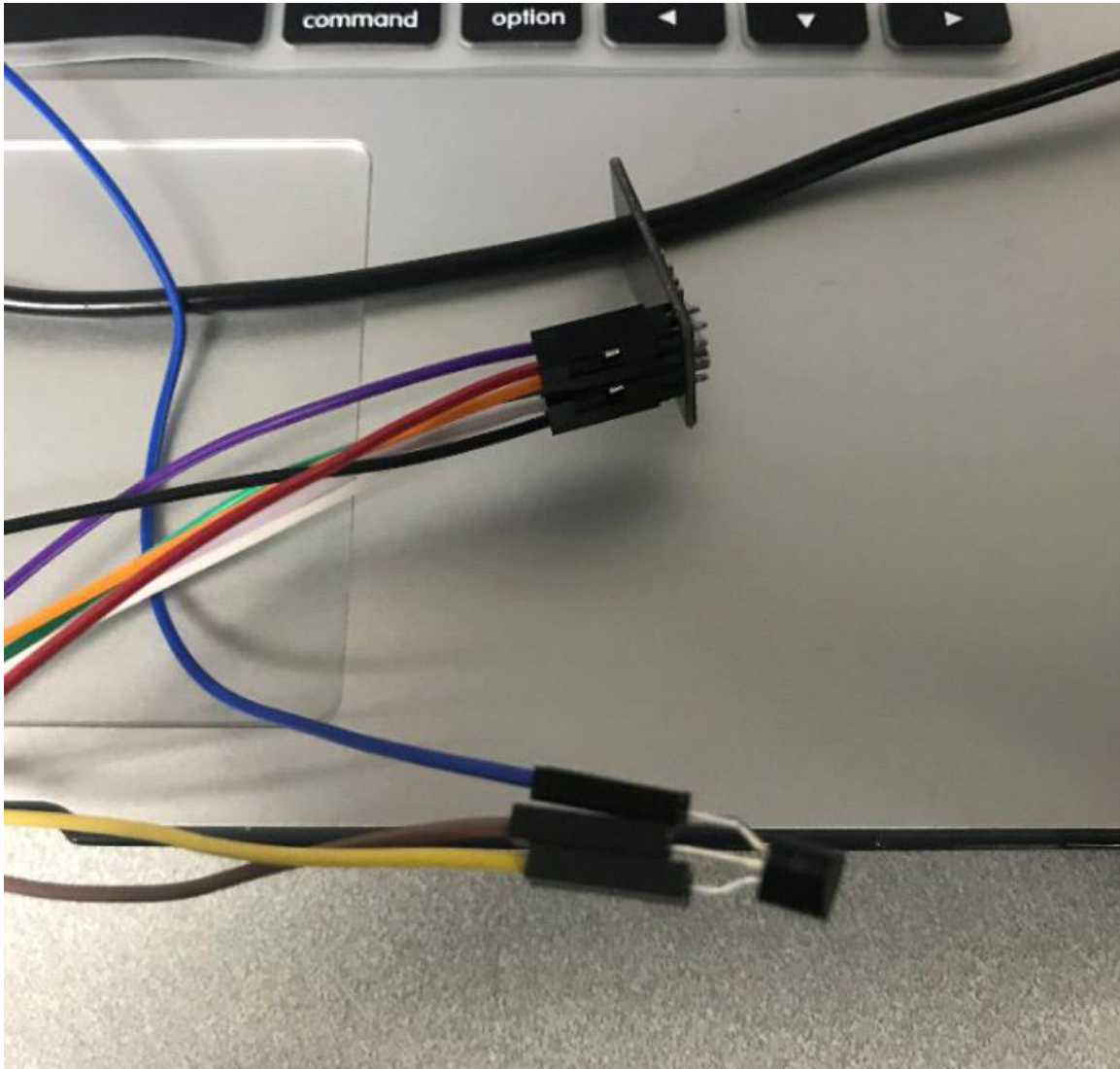
```

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void print_config(void);
void ADC_INIT(void);
void READ_ADC(void);
volatile bool message_received = false;
volatile bool status = false;
int main(void){
    char tx_message[32];
    char *tx_ptr = tx_message;
    ADC_INIT();
    printf("begin");
    printf("end");
    ADC_TEMP = 0;
    while (1){
        tx_ptr = tx_message;
        if (message_received){
            printf("hello");
            message_received = false;
            _delay_ms(500);
            if (status == true)
                printf("sent");
        }
    }
}

```

- SCREENSHOT OF EACH DEMO (BOARD SETUP)





- VIDEO LINKS OF EACH DEMO
- GITHUB LINK OF THIS DA

Student Academic Misconduct Policy

<http://studentconduct.unlv.edu/misconduct/policy.html>

*"This assignment submission is my own, original work".*  
Worku Tafara