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In [ ]: from PIL import Image, ImageDraw
import numpy as np
import random
import os.path
import pickle

#####
#                                     Functions for you to complete
#####

def ComputeSSD(TODOPatch, TODOMask, textureIm, patchL):
    patch_rows, patch_cols, patch_bands = np.shape(TODOPatch)
    tex_rows, tex_cols, tex_bands = np.shape(textureIm)
    ssd_rows = tex_rows - 2 * patchL
    ssd_cols = tex_cols - 2 * patchL
    SSD = np.zeros((ssd_rows,ssd_cols))
    for r in range(ssd_rows):
        for c in range(ssd_cols):
            # Compute sum square difference between textureIm
            # for all pixels where TODOMask = 0, and store th
            #
            # ADD YOUR CODE HERE
            #
            textureIm.astype(np.float64)
            TODOPatch.astype(np.float64)
            red = np.sum(np.square(np.bitwise_and(textureIm[r
            green = np.sum(np.square(np.bitwise_and(textureIm[r
            blue = np.sum(np.square(np.bitwise_and(textureIm[r
            SSD[r,c] = red + green + blue
            pass
        pass
    return SSD

def CopyPatch(imHole,TODOMask,textureIm,iPatchCenter,jPatchCenter,iMatchC
    patchSize = 2 * patchL + 1
    for i in range(patchSize):
        for j in range(patchSize):
            # Copy the selected patch selectPatch into the im
            # the hole imHole for each pixel where TODOMask =
            # The patch is centred on iPatchCenter, jPatchCen
            #
            # ADD YOUR CODE HERE
            #
            imHole[iPatchCenter-patchL+i,jPatchCenter-patchL+
            pass
        pass
    return imHole

#####
#                                     Some helper functions
#####

def DrawBox(im,x1,y1,x2,y2):
    draw = ImageDraw.Draw(im)
    draw.line((x1,y1,x1,y2),fill="white",width=1)
    draw.line((x1,y1,x2,y1),fill="white",width=1)
    draw.line((x2,y2,x1,y2),fill="white",width=1)
    draw.line((x2,y2,x2,y1),fill="white",width=1)
    del draw
    return im

def Find_Edge(hole_mask):

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[cols, rows] = np.shape(hole_mask)
edge_mask = np.zeros(np.shape(hole_mask))
for y in range(rows):
    for x in range(cols):
        if (hole_mask[x,y] == 1):
            if (hole_mask[x-1,y] == 0 or
                hole_mask[x+1,y] == 0 or
                hole_mask[x,y-1] == 0 or
                hole_mask[x,y+1] == 0):
                edge_mask[x,y] = 1

return edge_mask

#####
#                               Main script starts here
#####
def main_script(fileName, patchL=10, randomPatchSD=1):
    #
    # Constants
    #

    # Change patchL to change the patch size used (patch size is 2 *p
    # patchL = 10
    patchSize = 2*patchL+1

    # Standard deviation for random patch selection
    # randomPatchSD = 1

    # Display results interactively
    showResults = False

    #
    # Read input image
    #

    im = Image.open(fileName).convert('RGB')
    im_array = np.asarray(im, dtype=np.uint8)
    imRows, imCols, imBands = np.shape(im_array)

    #
    # Define hole and texture regions. This will use files fill_regi
    # texture_region.pkl, if both exist, otherwise user has to sele
    if os.path.isfile('fill_region.pkl') and os.path.isfile('texture_
        fill_region_file = open('fill_region.pkl', 'rb')
        fillRegion = pickle.load( fill_region_file )
        fill_region_file.close()

        texture_region_file = open('texture_region.pkl', 'rb')
        textureRegion = pickle.load( texture_region_file )
        texture_region_file.close()

    else:
        # ask the user to define the regions
        print("Specify the fill and texture regions using polysel
        exit()

    #
    # Get coordinates for hole and texture regions
    #

    fill_indices = fillRegion.nonzero()
    nFill = len(fill_indices[0]) # number of pixels to
    iFillMax = max(fill_indices[0])
    iFillMin = min(fill_indices[0])
    jFillMax = max(fill_indices[1])
    jFillMin = min(fill_indices[1])

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assert((iFillMin >= patchL) and
        (iFillMax < imRows - patchL) and
        (jFillMin >= patchL) and
        (jFillMax < imCols - patchL)) , "Hole is too close to edge"

texture_indices = textureRegion.nonzero()
iTextureMax = max(texture_indices[0])
iTextureMin = min(texture_indices[0])
jTextureMax = max(texture_indices[1])
jTextureMin = min(texture_indices[1])
textureIm = im_array[iTextureMin:iTextureMax+1, jTextureMin:jTextureMax+1]
texImRows, texImCols, texImBands = np.shape(textureIm)
assert((texImRows > patchSize) and
        (texImCols > patchSize)) , "Texture image is small"

#
# Initialize imHole for texture synthesis (i.e., set fill pixels
#

imHole = im_array.copy()
imHole[fill_indices] = 0

#
# Is the user happy with fillRegion and textureIm?
#
if showResults == True:
    # original
    im.show()
    # convert to a PIL image, show fillRegion and draw a box
    im1 = Image.fromarray(imHole).convert('RGB')
    im1 = DrawBox(im1, jTextureMin, iTextureMin, jTextureMax, iTextureMax)
    im1.show()
    print("Are you happy with this choice of fillRegion and textureIm?")
    Yes_or_No = False
    while not Yes_or_No:
        answer = input("Yes or No: ")
        if answer == "Yes" or answer == "No":
            Yes_or_No = True
    assert answer == "Yes", "You must be happy. Please try again"

#
# Perform the hole filling
#

while (nFill > 0):
    print("Number of pixels remaining = " , nFill)

    # Set TODORegion to pixels on the boundary of the current fillRegion
    TODORegion = Find_Edge(fillRegion)
    edge_pixels = TODORegion.nonzero()
    nTODO = len(edge_pixels[0])

    while(nTODO > 0):

        # Pick a random pixel from the TODORegion
        index = np.random.randint(0, nTODO)
        iPatchCenter = edge_pixels[0][index]
        jPatchCenter = edge_pixels[1][index]

        # Define the coordinates for the TODOPatch
        TODOPatch = imHole[iPatchCenter-patchL:iPatchCenter+patchL+1,
                           jPatchCenter-patchL:jPatchCenter+patchL+1]
        TODOMask = fillRegion[iPatchCenter-patchL:iPatchCenter+patchL+1,
                              jPatchCenter-patchL:jPatchCenter+patchL+1]

        #

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# Compute masked SSD of TODOPatch and textureIm
#
ssdIm = ComputeSSD(TODOPatch, TODOMask, textureIm

# Randomized selection of one of the best texture
ssdIm1 = np.sort(np.copy(ssdIm), axis=None)
ssdValue = ssdIm1[min(round(abs(random.gauss(0, ra
ssdIndex = np.nonzero(ssdIm==ssdValue)]
iSelectCenter = ssdIndex[0][0]
jSelectCenter = ssdIndex[1][0]

# adjust i, j coordinates relative to textureIm
iSelectCenter = iSelectCenter + patchL
jSelectCenter = jSelectCenter + patchL
selectPatch = textureIm[iSelectCenter-patchL:iSel

#
# Copy patch into hole
#
imHole = CopyPatch(imHole, TODOMask, textureIm, iPat

# Update TODORegion and fillRegion by removing loc
TODORegion[iPatchCenter-patchL:iPatchCenter+patch
fillRegion[iPatchCenter-patchL:iPatchCenter+patch

edge_pixels = TODORegion.nonzero()
nTODO = len(edge_pixels[0])

fill_indices = fillRegion.nonzero()
nFill = len(fill_indices[0])

#
# Output results
#
if showResults == True:
    Image.fromarray(imHole).convert('RGB').show()
    Image.fromarray(imHole).convert('RGB').save(fileName.replace('.jpg',

```

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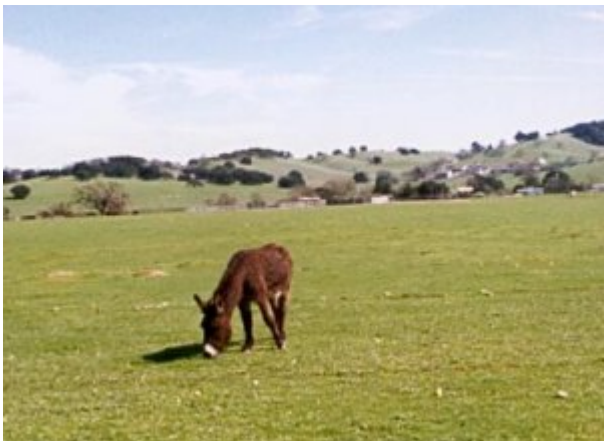
In [ ]: main_script("donkey.jpg")
display(Image.open("donkey.jpg"))
display(Image.open("donkey-results.jpg"))

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Number of pixels remaining = 3473
Number of pixels remaining = 1043
Number of pixels remaining = 53

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In [ ]: main_script("dog.jpg")
display(Image.open("dog.jpg"))
display(Image.open("dog-results.jpg"))
# The grass in the background is quite difficult for the algorithm. There
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Number of pixels remaining = 4172
Number of pixels remaining = 1844
Number of pixels remaining = 322
```

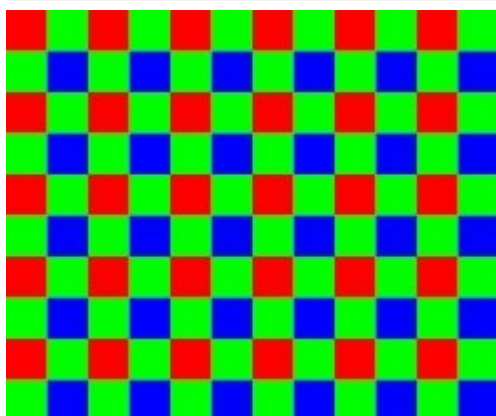


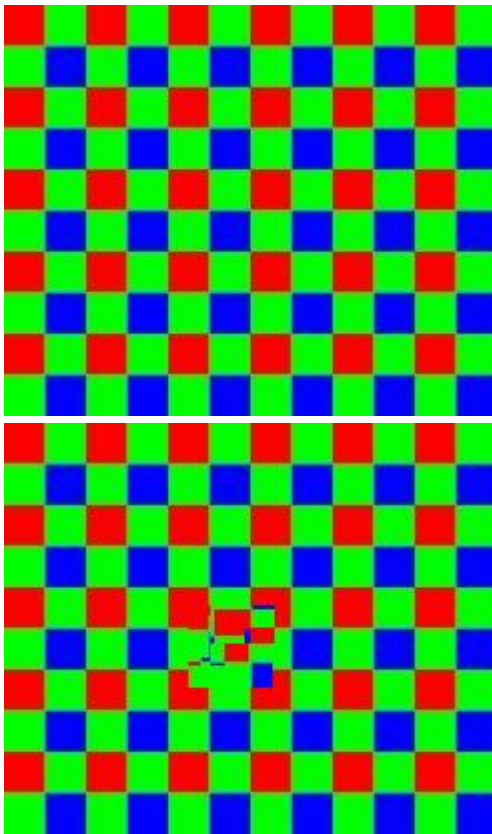
```
In [ ]: main_script("ducks.jpg")
display(Image.open("ducks.jpg"))
display(Image.open("ducks-results.jpg"))
# In this case, the algorithm performs pretty well at replacing the duck.
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```
Number of pixels remaining = 3072
Number of pixels remaining = 931
```



```
In [ ]: # RandomPatchSD for greater randomization in the selection of the best te
# If this value is too small, for larger fills, there will be a lot of re
# If this value is too large, the texture patch will be very different fr
display(Image.open("bayer.jpg"))
main_script("bayer.jpg", randomPatchSD=0.1)
display(Image.open("bayer-results.jpg"))
main_script("bayer.jpg", randomPatchSD=10)
display(Image.open("bayer-results.jpg"))
# In this example, I run the algorithm on a blue square. With a low rand
# With a high randomPatchSD, the pool of possible texture patches is much
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In [ ]: # patchL is proportional to the size of the texture patch that the SSD an
# If this value is too small, the texture patch will be too small to capt
# If this value is too large, given that we do not have a Gaussian weight
display(Image.open("ducks.jpg"))
main_script("ducks.jpg", patchL=6)
display(Image.open("ducks-results.jpg"))
main_script("ducks.jpg", patchL=20)
display(Image.open("ducks-results.jpg"))
# In the first duck texture synthesis, you can see that the 'horizontal'
# In the second duck texture synthesis, while longer waves are captured,
# Therefore the more optimal value of 10 gets less noticeable artifacts.
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