Online Optimization with \mathbf{b}_k = sine-sine and time-varying Hessian **OGD** 10^{2} Control-based [1] SIMBO-B 10^{1} 10⁰ Tracking error 10^{-1} 10^{-2} 10⁻³ 10^{-4} 100 200 500 300 400

Time