

# Template

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# 1 DP

## 1.1 斜率优化

```
const int N=400005;
const int mod=1e9+7;

ll a[N],f[N],s[N];
int n,t,l,r,pos;

struct node{
    ll x,y;
    node(ll x=0,ll y=0):x(x),y(y){}
} h[N];

ll cal(int x) {
    return f[x]-s[x]+a[x+1]*x;
}

bool check(const node &a,const node &b,const node &c) {
    return (c.y-b.y)*(b.x-a.x)>(b.y-a.y)*(c.x-b.x);
}
// 判断斜率递增

bool check2(const node &a,const node &b,int w) {
    return (b.y-a.y<(b.x-a.x)*w);
}
// 判断后比前优

int main(){
    ios::sync_with_stdio(false);
    while (cin>>n>>t) {
        rep(i,1,n+1) cin>>a[i];
        sort(a+1,a+n+1);
        rep(i,1,n+1) s[i]=s[i-1]+a[i];
        l=1,r=0;
        rep(i,t,n+1) {
            if (i-t<t) f[i]=s[i]-a[1]*i;else {
                while (l<r && check2(h[l],h[l+1],i)) l++;
                f[i]=h[l].y+s[i]-h[l].x*i;
            }
            pos=i+1-t;if (pos<t) continue;
            node tmp(a[pos+1],cal(pos));
            while (l<r && !check(h[r-1],h[r],tmp)) r--;
            h[++r]=tmp;
        }
        cout<<f[n]<<endl;
    }
    return 0;
}
```

# 2 DataStructure

## 2.1 2DST

```
namespace ST_2D{
    const int N = 1030;
    int LOG[N], P[20], dep1, dep2;
    short st[11][11][N][N];
    void build(int n, int m, short a[][N]){
        rep(i, 0, 11) P[i] = 1<<i;
        rep(i, 2, 1025) LOG[i] = LOG[i>>1]+1;
        for(dep1 = 0; (1<=dep1) < n; dep1++);
        for(dep2 = 0; (1<=dep2) < m; dep2++);
        rep(i, 1, n+1)
            rep(j, 1, m+1)
                st[0][0][i][j] = a[i][j]; //modi
        rep(i, 1, n+1)
            rep(j, 1, dep2+1)
                rep(k, P[j], m+1)
                    st[0][j][i][k] = max(st[0][j-1][i][k], st[0][j-1][i][k-P[j-1]]);
        rep(i, 1, dep1+1)
            rep(j, P[i], n+1)
                rep(k, 0, dep2+1) //attention to range of k
                    rep(l, P[k], m+1)
                        st[i][k][j][l]=max(st[i-1][k][j-P[i-1]][l], st[i-1][k][j][l]);
    }
    int qry(int x1, int y1, int x2, int y2){
        int l1 = LOG[x2-x1+1], l2 = LOG[y2-y1+1];
        int res1 = max(st[l1][l2][x1+P[l1]-1][y1+P[l2]-1], st[l1][l2][x2][y2]);
        int res2 = max(st[l1][l2][x1+P[l1]-1][y2], st[l1][l2][x2][y1+P[l2]-1]);
        return max(res1, res2);
    }
}
```

## 2.2 CDQ

```
const int N = 200005;
const int mod = 1e9+7;

int p1, p2, pos, n, k, nn, ans[N];

struct node{
    int x, y, z, num, ans;
    bool operator == (const node & b) const{
        return x == b.x && y == b.y && z == b.z;
    }
} a[N], tmp[N];

template<class T>
struct Fenwick{
    static const int N =2e5+7;
    int n;T a1[N],a2[N];
    void ini(int _n){
        fill_n(a1+1,n,_n,0);fill_n(a2+1,n=_n,0);
    }
    void add(T *a,int p,T d) { for(; p<=n; p+=p & -p) a[p]+=d; }
    void add(int l,int r,T d) {
        add(a1, l, d), add(a1, r + 1, -d);
    }
}
```

```

sort(a+1, a+n+1, cmp);
nn = 0;
rep(1, 1, n+1) {
    if (i > 1 && a[i] == a[i-1]) {
        a[nn].num++;
    } else {
        a[++nn] = a[i];
        a[nn].num = 1;
    }
}
fen.ini(N);
CDQ(1, nn);
rep(1, 1, nn+1) ans[a[i].ans] += a[i].num;
rep(1, 0, n) cout << ans[i] << endl;
return 0;
}

```

## 2.3 KDTree

```

const ll INF = pw(62);
const int N = 100005;

int T, n, Q, D;
ll now;

struct node {
    int d[2], l, r, mi[2], ma[2]; // sum, val, minp, p, id;
    bool operator < (const node &b) const {
        return d[Q] < b.d[Q];
    }
};

node a[N], ans, v, b[N];

struct KDTree {
    static const int N = 1e5 + 7;
    int root;
    node tr[N];

    inline void up(node &a, const node &b) {
        rep(i, 0, D) {
            a.mi[i] = min(a.mi[i], b.mi[i]);
            a.ma[i] = max(a.ma[i], b.ma[i]);
        }
    }

    inline void insert(int now) {
        int k = 0, p = root;
        if (!p) {root = now; return;}
        while (1) {
            up(tr[p], tr[now]);
            if (tr[now].d[k] >= tr[p].d[k]) {
                if (!tr[p].r) {tr[p].r = now; return;}
            } else {
                if (!tr[p].l) {tr[p].l = now; return;}
            }
        }
    }
}

```

```

add(a2, l, d * (l - 1)), add(a2, r + 1, -d * r);
}
T sum(T *a, int p) { T r=0; for(;; p>=1; p-=p & -p) r+=a[p]; return r; }
T pre(int p) { return !p ? 0 : sum(a1, p) * p - sum(a2, p); }
T qry(int l, int r) { return pre(r) - pre(l-1); }
};

Fenwick<int> fen;

bool cmp(node a, node b) {
    if (a.x != b.x) return a.x < b.x;
    if (a.y != b.y) return a.y < b.y;
    return a.z < b.z;
}

bool cmp2(node a, node b) {
    //if (a.y != b.y) return a.y < b.y;
    //return a.z < b.z;
    return a.y < b.y;
}

void CDQ(int l, int r) {
    if (l == r) {
        a[l].ans = a[l].num - 1;
        return;
    }
    int mid = l + r >> 1;
    CDQ(l, mid);
    CDQ(mid+1, r);
    pos = l;
    rep(i, mid+1, r+1) {
        while (pos <= mid && a[pos].y <= a[i].y) {
            fen.add(fen.a1, a[pos].z, a[pos].num);
            pos++;
        }
        a[i].ans += fen.sum(fen.a1, a[i].z);
    }
    rep(i, l, pos) fen.add(fen.a1, a[i].z, -a[i].num);
    p1 = l; p2 = mid+1;
    rep(i, l, r+1) {
        if (p1 > mid) {tmp[i] = a[p2]; p2++;}
        else if (p2 > r) {tmp[i] = a[p1]; p1++;}
        else if (a[p1].y <= a[p2].y) {tmp[i] = a[p1]; p1++;}
        else {tmp[i] = a[p2]; p2++;}
    }
    rep(i, l, r+1) a[i] = tmp[i];
}

int main() {
    freopen("a.in", "r", stdin);
    ios::sync_with_stdio(0);
    cin.tie(0);
    //cout << setiosflags(ios::fixed);
    //cout << setprecision(2);
    cin >> n >> k;
    rep(i, 1, n+1) cin >> a[i].x >> a[i].y >> a[i].z;
}

```

```
// index : [0, n)
// limit: 2^M >= N
// !!! : bud()

namespace ST {
    const int N = ::N, M = 22;
    int lg2[N];
    int st[N][M];
    void bud(int n, int a[]) {
        assert((1 <= M) > n);
        lg2[0] = -1; rep(i, 1, n + 1) lg2[i] = lg2[i >> 1] + 1;
        rep(i, 0, n) st[i][0] = a[i];
        rep(j, 1, M) rep(i, 0, n) {
            if (1 + (1 <= j) > n) break;
            st[i][j] = max(st[i][j - 1], st[i + (1 <= (j - 1))][j - 1]);
        }
    }
    int qry(int l, int r) {
        if (1 > r) swap(l, r);
        int lv = lg2[r - l + 1];
        return max(st[l][lv], st[r - (1 <= lv) + 1][lv]);
    }
}
```

## 2.5 cartesian\_tree

```
// desc : bud a cartesian tree from a[0] .. a[n - 1]
// time : O(N)
// !!! : return rt, a[n] will be rewrite
int ls[N], rs[N];
int cartesian_tree(int a[], int n) {
    a[n] = INT_MAX;
    vi v(1, n);
    fill_n(ls, n, -1), fill_n(rs, n, -1);
    rep(i, 0, n) {
        while (a[v.back()] < a[i])
            ls[i] = v.back(), v.pop_back();
        v.pb(rs[v.back()] = i);
    }
    return v[1];
}
```

## 2.6 fenwick\_tree

```
// index : [1, n]
// time : nlogn
// support : segment add, sum
// !!! : use before init()!
template<class T>
struct Fenwick {
    static const int N = 2e5 + 7;
    int n; T a1[N], a2[N];
    void ini(int _n) {
        fill_n(a1 + 1, n = _n, 0); fill_n(a2 + 1, n = _n, 0);
    }
}
```

```
    }
    else p = tr[p].l;
    k = (k + 1) % D;
}

int build(int l, int r, int k) {
    if (1 > r) return 0;
    int mid = l + r >> 1; Q = k;
    nth_element(a + l, a + mid, a + r + 1);
    tr[mid] = a[mid];
    rep(i, 0, D) tr[mid].ma[i] = tr[mid].mi[i] = tr[mid].d[i];
    tr[mid].l = build(l, mid - 1, (k + 1) % D);
    tr[mid].r = build(mid + 1, r, (k + 1) % D);
    if (tr[mid].l) up(tr[mid], tr[tr[mid].l]);
    if (tr[mid].r) up(tr[mid], tr[tr[mid].r]);
    return mid;
}

inline ll sqr(ll x) {return x * x;}

inline ll get(const node &v, int x) { // dis function need update
    if (!x) return INF + 1;
    ll res = 0;
    rep(i, 0, D) {
        if (v.d[i] < tr[x].mi[i]) res += sqr(tr[x].mi[i] - v.d[i]);
        if (v.d[i] > tr[x].ma[i]) res += sqr(v.d[i] - tr[x].ma[i]);
    }
    return res;
}

inline void check(const node &v, const node &p) {
    ll dis = 0;
    rep(i, 0, D) dis += sqr(p.d[i] - v.d[i]);
    if (dis) now = min(now, dis);
    return;
}

void ask(const node &v, int x) {
    if (!x) return;
    check(v, tr[x]);
    ll lm = get(v, tr[x].l), rm = get(v, tr[x].r);
    if (lm < rm) {
        if (lm <= now) ask(v, tr[x].l);
        if (rm <= now) ask(v, tr[x].r);
    } else {
        if (rm <= now) ask(v, tr[x].r);
        if (lm <= now) ask(v, tr[x].l);
    }
} kdt;
```

## 2.4 ST

```

void add(T *a,int p,T d) { for( ; p<=n; p+=p & -p) a[p]+=d; }
void add(int l,int r,T d) {
    add(a1, l, d), add(a1, r + 1, -d);
    add(a2, l, d * (1 - 1)), add(a2, r + 1, -d * r);
}
T sum(T *a,int p) { T r=0; for( ; p>=1; p-=p & -p) r+=a[p]; return r; }
T pre(int p) { return lp ? 0 : sum(a1, p) * p - sum(a2, p); }
T qry(int l,int r) {return pre(r)-pre(l-1); }
};

```

### 3 Graph

#### 3.1 DMST

```

// id starts from 0
// can handle multi edge, self ring
struct edge {int u, v, d, u, v;bitset<1005> b;};
struct DMST{
    static const int N = ::N, M = N * N, inf = 2e9;
    edge e[M];int n, m, vis[N], pre[N], id[N], index[N], Pre[N];
    bitset<1005> fang;
    int in[N];
    void ini(int n) {this->n = n, m = 0;}
    void addedge(int u, int v, int d) {e[m] = edge({u,v,d,u,v}); e[m].reset();e[m].b[m] = 1;m++;}
    int run(int root){
        int ans = 0;
        while(1){
            rep(i, 0, n) in[i] = inf;
            rep(i, 0, m){
                int u = e[i].u, v = e[i].v;
                if(e[i].d < in[v] && u != v){
                    in[v] = e[i].d, pre[v] = u; index[v] = i;
                }
            }
            rep(i, 0, n) {
                if(i == root) continue;
                if(in[i] == inf) return -1;
                fang ^= e[index[i]].b;
            }
            int cnt = 0;in[root] = 0;
            memset(id, -1, sizeof(*id)*n);
            memset(vis, -1, sizeof(*vis)*n);
            rep(i, 0, n){
                ans += in[i]; int v = i;
                int t = index[i];
                while(vis[v] != i && id[v] == -1 && v!=root){
                    vis[v] = i;v = pre[v];
                }
                if(v != root && id[v] == -1) {
                    for(int u=pre[v];u != v;u = pre[u]) id[u] = cnt;
                    id[v] = cnt++;
                }
            }
        }
    }
}

```

```

if(cnt == 0) break;
rep(i, 0, n) if(id[i] == -1) id[i] = cnt++;
rep(i, 0, m) {
    int v=e[i].v;
    e[i].u = id[e[i].u]; e[i].v = id[e[i].v];
    if(e[i].u != e[i].v) {e[i].d -= in[v];e[i].b ^= e[index[v]].b;}
}
n = cnt; root = id[root];
return ans;
}
} dmst;

```

#### 3.2 StoerWagner\_O(n3)

```

struct StoerWagner{
    static const int N = 305;
    static const int INF = 0x3f3f3f3f;;
    int n;
    int g[N][N], val[N];
    bool vis[N], use[N];
    void init(int _n) {
        n = _n;
        fill_n(use + 1, n, 0);
        rep(i, 1, n+1) fill_n(g[i] + 1, n, 0);
    }
    void add_edge(int u, int v, int w) {
        g[u][v] += w;
        g[v][u] += w;
    }
    void merge(int u, int v) {
        rep(i, 1, n+1) {
            g[v][i] += g[u][i];
            g[i][v] += g[i][u];
        }
        use[u] = 1;
    }
    int MinimumCutPhase(int cnt, int &s, int &t) {
        fill_n(val + 1, n, 0);
        fill_n(vis + 1, n, 0);
        t = 1;
        while (--cnt) {
            vis[s = t] = 1;
            rep(i, 1, n+1) if (!vis[i] && !use[i]) val[i] += g[t][i];
            int ma = 0;
            rep(i, 1, n+1) if (!vis[i] && !use[i] && val[i] >= ma) {
                ma = val[i]; t = i;
            }
            if (!ma) return 0;
        }
        return val[t];
    }
    int solve() {
        int res = INF;
        for (int i = n, s, t; i > 1; --i) {

```

```

res = min(res, MinimumCutPhase(i, s, t));
if (res == 0) break;
merge(s, t);
}
return res;
} Sw;

```

### 3.3 StoerWagner\_O(nmlog(m))

```

struct StoerWagner{
    static const int N = 3005, M = 100005 * 2, INF = 0x3f3f3f3f;
    int head[N], val[N], e, n;
    int to[M], ne[M], data[M];
    bool vis[N];
    int fa[N], link[N];
    void init(int _n) {
        n = _n;
        fill_n(head + 1, n, -1);
        fill_n(link + 1, n, -1);
        rep(i, 1, n+1) fa[i] = 1;
        e = 0;
    }
    void add_edge(int u, int v, int w) {
        to[e] = v; data[e] = w; ne[e] = head[u]; head[u] = e++;
        to[e] = u; data[e] = w; ne[e] = head[v]; head[v] = e++;
    }
    int findset(int u) {
        return u == fa[u] ? u : fa[u] = findset(fa[u]);
    }
    void merge(int u, int v) {
        int p = u;
        while (~link[p]) p = link[p];
        link[p] = v;
        fa[v] = u;
    }
    int MinimumCutPhase(int cnt, int &s, int &t) {
        fill_n(val + 1, n, 0);
        fill_n(vis + 1, n, 0);
        priority_queue<pii> q;
        t = 1;
        while (--cnt) {
            vis[s = t] = 1;
            for (int u = s; ~u; u = link[u]) {
                for (int p = head[u]; ~p; p = ne[p]) {
                    int v = findset(to[p]);
                    if (!vis[v]) q.push(mp(val[v] += data[p], v));
                }
            }
            while (!q.empty() && (vis[q.top().se] || val[q.top().se] != q.top().fi)) {
                q.pop();
            }
            if (q.empty()) return 0;
            t = q.top().se; q.pop();
        }
    }
}

```

```

return val[t];
}
int solve() {
    int res = INF;
    for (int i = n, s, t; i > 1; --i) {
        res = min(res, MinimumCutPhase(i, s, t));
        if (res == 0) break;
        merge(s, t);
    }
    return res;
} Sw;

```

### 3.4 max\_clique\_BK

```

//g[i][i] should be 0
//g[i] is i's edge
//index [0..N)
//O(n ^ 3)
typedef unsigned long long T;
struct BK {
    static const int N = 100; T g[N];
    inline int ctz(T s){ return s ? __builtin_ctzll(s) : 64;}
    int n, ans;
    void ini(int _n) {
        //per(i, 0, n = _n) g[i] = (1ull << n) - 1 - (1ull << i); }
        n = _n; rep(i, 0, n) g[i] = 0;
        rep(i, 0, n) rep(j, 0, n) if (a[i][j]) g[i] |= 1ull << j;
    }
    void gao(T cur, T can, T ban) {
        if (!can && !ban) { ans = max(ans, __builtin_popcountll(cur)); return; }
        if (!can) return;
        int piv = ctz(can | ban), ret = 0;
        T z = can & ~g[piv];
        for (int u = ctz(z); u < n; u += ctz(z >> (u + 1)) + 1) {
            gao(cur | (1ull << u), can & g[u], ban & g[u]);
            can ^= 1ull << u, ban |= 1ull << u;
        }
    }
    int run() { gao(ans = 0, (1ull << n) - 1, 0); return ans; }
} bk;

```

### 3.5 max\_clique\_fastest

```

const int N = 130;
typedef bool BB[N];
struct MaxClique {
    const BB *e; int pk, lv; db Tlimit;
    struct ve {int i, d; ve(int i): i(i), d(0) {}}; //ve : Vertex
    struct sc {int a, b; sc( ) : a(0), b(0) {}}; //sc : StepCount
    typedef vector<ve> ves; ves v; //ves: Vertices
    typedef vector<int> cc; cc Q, QMAX; //cc : ColorClass
    vector<cc> C;
    vector<sc> S;
}

```

```

Maxcliq(BB *conn, int sz, const db tt = 0.025): pk(0), lv(1), Tlimit(tt) {
    rep(i, 0, sz) v.pb(ve(i)); e = conn;
    C.resize(sz + 1);
    S.resize(sz + 1);
}

static bool desc_deg(const ve &a, const ve &b) { return a.d > b.d; }

void ini_col(ves &v) { per(i, 0, sz(v)) v[i].d = min(i, v[0].d) + 1; }
void set_deg(ves &v) { rep(i, 0, sz(v)){v[i].d = 0; rep(j, 0, sz(v)) v[i].d += e[v[j].i].i; } }
void deg_sort(ves &R) { set_deg(R); sort(all(R), desc_deg); }
bool cut1(int pi, cc &va) { rep(i, 0, sz(va)) if (e[pi][va[i]]) return true;
return false; }
void cut2(ves &va, ves &vb) { rep(i, 0, sz(va) - 1) if (e[va.back().i][va[i].i]) vb.pb(va[i].i); }
void co_sort(ves &R) {
    int j = 0, maxno = 1, min_k = max(sz(QMAX) - sz(Q) + 1, 1);
    rep(i, 1, 3) C[i].clear();
    rep(i, 0, sz(R)) {
        int pi = R[i].i, k = 1;
        while (cut1(pi, C[k])) k++;
        if (k > maxno) C[(maxno = k) + 1].clear(); C[k].pb(pi);
        if (k < min_k) R[j++].i = pi;
    }
    if (j > 0) R[j - 1].d = 0;
    rep(k, min_k, maxno + 1)
        rep(i, 0, sz(C[k]))
            R[j].i = C[k][i], R[j++].d = k;
}

void exp_dyn(ves &R) { // expand_dyn
    S[lv].a += S[lv - 1].a - S[lv].b;
    S[lv].b = S[lv - 1].a;
    for (; sz(R); Q.pop_back(), R.pop_back()) {
        if (sz(Q) + R.back().d <= sz(QMAX)) return;
        Q.pb(R.back().i);
        ves Rp; cut2(R, Rp);
        if (sz(Rp)) {
            if ((db) S[lv].a / ++pk < Tlimit) deg_sort(Rp);
            co_sort(Rp); S[lv++].a++;
            exp_dyn(Rp); --lv;
        } else if (sz(Q) > sz(QMAX)) QMAX = Q;
    }
}

void mcqdyn(int *mxc, int &sz) { // mcqdyn(int maxcliq, int &sz)
    set_deg(V); sort(all(V), desc_deg);
    ini_col(V); rep(i, 0, sz(V) + 1) S[i].a = S[i].b = 0;
    exp_dyn(V); per(i, 0, sz(QMAX)) mxc[i] = QMAX[i];
    sz = sz(QMAX);
}
};

```

```

const int N=1e5+7;
int n;
ll a[N], mod[N], M , R;

void exgcd(ll a,ll b,ll &x,ll &y){
    if(b == 0){
        x = 1; y = 0;
        return;
    }
    exgcd(b, a % b, y, x);
    y -= a / b * x;
}

ll Inv(ll a, ll mod){
    ll x = 0, y = 0;
    exgcd(a, mod, x, y);
    x %= mod;
    if (x < 0) x += mod;
    return x;
}

ll CRT(int n, ll *a, ll *mod){
    M = mod[1], R = a[1];
    rep(i, 2, n+1) {
        ll g=__gcd(M, mod[i]);
        ll inv = Inv(M / g, mod[i] / g);
        if ((a[i] - R) % g) return -1; // 无解
        R += inv * ((a[i] - R) / g) % (mod[i] / g) * M;
        M = M / g * mod[i];
        R = (R % M + M) % M; // 可能为 0 看是否需要是正整数
    }
    return R;
}

```

## 4.2 Euler\_power

```

int phi(int n) {
    if (M.count(n)==1) return M[n];
    int r=n, nn=n;
    for(int i=2; i*i<=n; i++) if (n%i==0) {
        r=r/i*(i-1);
        while (n%i==0) n/=i;
    }
    if (n>1) r=r/n*(n-1);
    M[nn]=r;
    return r;
}

ll Euler_qpow(ll a, ll b, ll mod) {
    ll res=1; bool ok=(b>0 && a>=mod);
    while (b>0) {
        if (b&1) {
            res=res*a;
            ok|=(res>=mod);
        }
    }
}

```

## 4 Math

## 4.1 CRT

```

for (N = 1; N < na || N < nb; N <= 1); N <= 1;
work(), fft(a, 0), fft(b, 0);
rep(i, 0, N) a[i] = a[i]*b[i];
fft(a, 1);
//rep(i, 0, N) a[i].print();
}
} fft;

```

#### 4.4 FFTMOD

```

const int MOD = 1e9+7;
const int MAXN=1<<17;
const double PI = acos(-1);

int N, L, MASK, na, nb;
int a[MAXN], b[MAXN];

struct vir
{
    double re, im;
    vir(double r=0.0, double i=0.0) {re=r, im=i;}
    void print() {printf("%lf %lf\n", re, im);}
};

vir operator +(const vir&A, const vir&B) {return vir(A.re+B.re, A.im+B.im);}
vir operator -(const vir&A, const vir&B) {return vir(A.re-B.re, A.im-B.im);}
vir operator *(const vir&A, const vir&B) {return vir(A.re*B.re-A.im*B.im, A.re*B.im+A.im*B.re);}

vir conj(vir a) {return vir(a.re, -a.im);}

vir w[MAXN];
void FFTInit() {
    for (int i = 0; i < N; ++i) {
        w[i] = vir(cos(2 * i * PI / N), sin(2 * i * PI / N));
    }
}

void FFT(vir p[], int n) {
    for (int i = 1, j = 0; i < n - 1; ++i) {
        for (int s = n; j ^ s >= 1, ~j & s; j = w[j]) {
            swap(p[i], p[j]);
        }
    }
    for (int d = 0; (1 <= d) < n; ++d) {
        int m = 1 <= d, m2 = m * 2, rm = n >= (d + 1);
        for (int i = 0; i < n; i += m2) {
            for (int j = 0; j < m; ++j) {
                vir &p1 = p[i + j + m], &p2 = p[i + j];
                vir t = w[rm * j] * p1;
                p1 = p2 - t;
                p2 = p2 + t;
            }
        }
    }
}

```

```

res%=mod;
}
a=a*a;
ok!=(b>1 && a>=mod);
a%=mod;
b>>=1;
}
return res+mod*ok;
}

ll work(int l, int r, int mod) {
    if (mod==1) return 1;
    if (l==r) return a[l];
    return Euler_qpow(a[l], work(l+1, r, phi(mod)), mod);
}

```

#### 4.3 FFT

```

const int M = 1<<16;
const db pi = acos(-1);

struct vir{
    db re, im;
    vir(db r = 0.0, db i = 0.0) {re = r, im = i;}
    void print() {printf("%lf %lf\n", re, im);}
} a[M*2], b[M*2], w[2][M*2];

vir operator +(const vir&A, const vir&B) {return vir(A.re+B.re, A.im+B.im);}
vir operator -(const vir&A, const vir&B) {return vir(A.re-B.re, A.im-B.im);}
vir operator *(const vir&A, const vir&B) {return vir(A.re*B.re-A.im*B.im, A.re*B.im+A.im*B.re);}

struct FFT{
    int N, na, nb, rev[M*2];
    void fft(vir *a, int f){
        vir x, y;
        rep(i, 0, N) if (i < rev[i]) swap(a[i], a[rev[i]]);
        for (int i = 1; i < N; i <= 1)
            for (int j = 0, t = N/(i<<1); j < N; j += i<<1)
                for (int k = 0, l = 0; k < i; k++, l += t)
                    x = w[f][l] * a[j+k+i], y = a[j+k], a[j+k+i] = y+x, a[j+k] = y-x;
        if (f) rep(i, 0, N) a[i].re /= N;
    }
}

void work(){
    rep(i, 0, N){
        int x = i, y = 0;
        for (int k = 1; k < N; k >= 1, k <= 1) (y<=1)?x=x&1;
        rev[i] = y;
    }
    rep(i, 0, N) {
        w[0][i] = vir(cos(2*pi*i/N), sin(2*pi*i/N));
        w[1][i] = vir(cos(2*pi*i/N), -sin(2*pi*i/N));
    }
}

void doit(vir *a, vir *b, int na, int nb){
}

```



```

} x[N|1], y[N|1], z[N|1], w[N|1];

int K;

void fft(vir x[], int k, int v){
    for(int i=0; j=0; i<k; i++){
        if(i>j)swap(x[i], x[j]);
        for(int l=k>>1; (j^=1)<l; l>=1);
    }
    w[0] = vir(1, 0);
    for(int i=2; i<=k; i<=1){
        vir g = vir(cos(2*pi/i), (v ? -1 : 1) * sin(2*pi/i));
        for(int j=(i>>1); j>=0; j--=2) w[j] = w[j>>1];
        for(int j=1; j<i>>1; j+=2) w[j] = w[j-1] * g;
        for(int j=0; j<k; j+=1){
            vir *a = x+j, *b = a+(i>>1);
            for(int l=0; l<i>>1; l++){
                vir o = b[l] * w[l];
                b[l] = a[l] - o;
                a[l] = a[l] + o;
            }
        }
    }
    if (v) for(int i=0; i<k; i++) x[i] = vir(x[i].a/k, x[i].b/k);
}

void doit(int *a, int *b, int na, int nb) {
    for(K = 1; K <= na+nb>>1; K <= 1);
    rep(1, 0, K) x[1] = y[1] = vir(0, 0);
    for(int i=0; i<=na; i++) (i&1 ? x[i>>1].b : x[i>>1].a) = a[i];
    for(int i=0; i<=nb; i++) (i&1 ? y[i>>1].b : y[i>>1].a) = b[i];
    fft(x, K, 0);
    fft(y, K, 0);
    rep(1, 0, K){
        int j = K-1 & K-i;
        vir tmp = (i&K>>1) ? vir(1, 0) - w[i&K>>1] : w[1] + vir(1, 0);
        z[i] = (x[i]*y[i]*4 - (x[i] - i*x[j])*(y[i] - i*y[j]))*tmp)*0.25;
    }
    fft(z, K, 1);
    rep(i, 0, na+nb+1) a[i] = i&1 ? z[i>>1].b + 0.1 : z[i>>1].a + 0.1;
}

```

#### 4.6 NTT

```

const int MAXN=1<<17;
const int G=3;
const int P=1004535809; //P=C*2^k+1
int N, na, nb, a[MAXN*2], b[MAXN*2], w[2][MAXN*2], rev[MAXN*2];

ll Pow(ll a, int b)
{
    ll c=1;
    for (;b; b>>=1, a=a*a%p) if (b&1) c=c*a%p;
    return c;
}

```

```

}
vir A[MAXN], B[MAXN], C[MAXN], D[MAXN];

void init(){
    L=0;
    scanf("%d", &na); rep(i, 0, na) scanf("%d", &a[i]);
    scanf("%d", &nb); rep(i, 0, nb) scanf("%d", &b[i]);
    for (N=1; N<na || N<nb; N<=1) L++; N<=1;
    MASK=(1<<L)-1;
    FFTInit();
    for (int i = 0; i < N; ++i) {
        A[i] = vir(a[i] >> L, a[i] & MASK);
        B[i] = vir(b[i] >> L, b[i] & MASK);
    }
}

void mul() {
    FFT(A, N), FFT(B, N);
    for (int i = 0; i < N; ++i) {
        int j = (N - i) % N;
        vir da = (A[i] - conj(A[j])) * vir(0, -0.5),
                db = (A[i] + conj(A[j])) * vir(0.5, 0),
                dc = (B[i] - conj(B[j])) * vir(0, -0.5),
                dd = (B[i] + conj(B[j])) * vir(0.5, 0);
        C[j] = da * dd + da * dc * vir(0, 1);
        D[j] = db * dd + db * dc * vir(0, 1);
    }
    FFT(C, N), FFT(D, N);
    for (int i = 0; i < N; ++i) {
        ll da = (ll)(C[i].im / N + 0.5) % MOD,
            db = (ll)(C[i].re / N + 0.5) % MOD,
            dc = (ll)(D[i].im / N + 0.5) % MOD,
            dd = (ll)(D[i].re / N + 0.5) % MOD;
        a[i] = ((dd << (L * 2)) + ((db + dc) << L) + da) % MOD;
    }
}

int main(){
    init();
    mul();
    rep(1, 0, N) printf("%d\n", a[i]);
}

```

#### 4.5 FFT\_fast

```

const int N = 1 << 21;
const double pi=acos(-1.0);
struct vir{
    double a, b;
    vir(double r=0.0, double i=0.0) {a=r, b=i;}
    vir operator +(const vir &o) const{return vir(a+o.a, b+o.b);}
    vir operator -(const vir &o) const{return vir(a-o.a, b-o.b);}
    vir operator *(const vir &o) const{return vir(a*o.a-b*o.b, b*o.a+a*o.b);}
    vir operator /(const double &o) const{return vir(a/o, b/o);}
}

```

```

}
T x = a.fi * b.se - a.se * b.fi;
return (x > 0) - (x < 0);
}
inline bool in(const V &a, const V &b, const V &c) {
    return 0 <= cmp(c, a) && cmp(c, b) < 0;
}
pii operator+(const pii &a, const pii &b) {
    return mp(a.fi + b.fi, a.se + b.se);
}
pii operator*(const pii &a, U x) {
    return mp(a.fi * x, a.se * x);
}
bool search(V v, U MAXB, pii &lo, pii &hi, int f) {
    V x;
    U l = 0, r = f > 0 ? (hi.se ? (MAXB - lo.se) / hi.se : INF) :
        (lo.se ? (MAXB - hi.se) / lo.se : INF);
    while (l + 1 < r) {
        U z = (l + r) >> 1;
        x = f > 0 ? lo + hi * z : lo * z + hi;
        f * cmp(x, v) <= 0 ? l = z : r = z;
    }
    x = f > 0 ? lo + hi * r : lo * r + hi;
    r = f * cmp(x, v) <= 0 ? r - 1;
    f > 0 ? lo = lo + hi * r : hi = lo * r + hi;
    return r > 0;
}
pii solve(V v, U MAXB) { // find ROUND_HALF_UP(a / b) = v, b <= MAXB
    V L = mp(v.fi * 10 - 5, v.se * 10);
    V R = mp(v.fi * 10 + 5, v.se * 10);
    pii lo(0, 1), hi(1, 0);
    while (true) {
        bool ok = 0;
        //V m = mp(lo.fi + hi.fi, lo.se + hi.se);
        //if (in(L, R, m)) return mp(m.fi, m.se);
        ok |= search(v, MAXB, lo, hi, 1);
        ok |= search(v, MAXB, lo, hi, -1);
        if (!ok) break;
    }
    db t1 = (db) lo.fi / lo.se;
    db t2 = (db) hi.fi / hi.se;
    db t3 = (db) v.fi / v.se;
    if (t2 - t3 <= t3 - t1) return hi; else return lo;
    //if (in(L, R, lo)) return lo;
    //if (in(L, R, hi)) return hi;
    return mp(-1, -1);
}
};

```

#### 4.8 bell

```

// desc : 0^k + 1^k + 2^k + .. + (n-1)^k
// time-init : O(n^2)
// time-cal : k + log
namespace Bell {
    const int N = 1000;
}

```

```

}
void FFT(int*a, int f)
{
    rep(i, 0, N) if (i < rev[i]) swap(a[i], a[rev[i]]);
    for (int i=1; i<N; i<=1)
        for (int j=0; j<N; j+=i<=1)
            for (int k=0; k<N; k+=i)
                x = (1LL)w[f][1]*a[j+k+i]%P, y = a[j+k]; a[j+k+i] = (y-x+p)%P;
    if (f) for (int i=0; i<N; i++) a[i] = (1LL)a[i]*x%p;
}

void work()
{
    rep(i, 0, N)
    {
        int x=i, y=0;
        for (int k=1; k<N; k>=1, k<=1) (y<=1) |= x&1;
        rev[i]=y;
    }
    w[0][0]=w[1][0]=1;
    for (int i=1; i<N; i++)
        w[0][i] = (1LL)x*w[0][i-1]%P, w[1][i] = (1LL)y*w[1][i-1]%P;
}

void init()
{
    scanf("%d", &na); for (int i=0; i<na; i++) scanf("%d", &a[i]);
    scanf("%d", &nb); for (int i=0; i<nb; i++) scanf("%d", &b[i]);
    for (N=1; N<na|N<nb; N<=1); N<=1;
}

void doit()
{
    work(), FFT(a, 0), FFT(b, 0);
    rep(i, 0, N) a[i] = (1LL)a[i]*b[i]%P;
    FFT(a, 1);
    rep(i, 0, N) printf("%d\n", a[i]);
}

int main() {
    init();
    doit();
}

```

#### 4.7 SternBrocotTree

```

namespace SBT {
    typedef long double db;
    typedef int U;
    typedef pair<U, U> pii;
    const U INF = 1e9 + 7;
    typedef __int128 T;
    typedef pair<T, T> V; // V = [double|long double|fraction]
    inline int cmp(const V &a, const V &b) {

```

```
int C[N][N], B[N];
void ini() {
    rep(i, 0, N) C[i][0] = 1;
    rep(i, 0, N) rep(j, 1, i + 1) C[i][j] = add(C[i - 1][j - 1], C[i - 1][j]);
    B[0] = 1;
    rep(i, 1, N) {
        B[i] = 0;
        rep(j, 0, i) B[i] = add(B[i], MOD - mul(C[i + 1][j], B[j]));
        B[i] = mul(B[i], qpow(C[i + 1][i], MOD - 2)) % MOD;
    }
}
int cal(int n, int k) {
    int sum = 0;
    rep(i, 0, k + 1) sum = add(sum, mul(C[k + 1][i], mul(B[i], qpow(n, k + 1 - i))));
    return mul(sum, qpow(k + 1, MOD - 2));
}
};
```

4.9 lindstrom\_gessel\_viennot\_lemma

```
/*
 * 对于一张无边权的 DAG 图，给定 n 个起点和对应的 n 个终点，这 n 条不相交路径的方案数为矩阵
 * e(a1,b1),e(a1,b2)...e(a1,bn)
 * e(a2,b1),e(a2,b2)...e(a2,bn)
 * .....
 * .....
 * e(an,b1),e(an,b2)...e(an,bn)
 * 的行列式。
 * 即 M[i][j]=e(ai,bj)
 * e(a,b) 为 a 到 b 的路径方案数
 */
```

4.10 math\_function

```
const int N = 1e6 + 7;
int n, m, f[N], g[N], phi[N], h[N], u[N], p[N]; //f[n] 为 n 的最小质因子, g[n]=f[n]^k ,
phi[n] 为欧拉函数, u[n] 为莫比乌斯函数, h[n] 为一般积性函数

void prime(int n) {
    u[1]=phi[1]=1,h[1]=0; //1 的时候特判
    rep(i, 2, n+1) {
        if (!f[i]) {
            p[++m]=i;
            f[i] = g[i] = i;
            phi[i] = i - 1;
            u[i] = -1;
            h[i] = 0;
        } //质数的时候特判
        for (int j = 1, k; j <= m && p[j] <= f[i] && i * p[j] <= n; j++) {
            f[k = i * p[j]] = p[j];
            if (p[j] < f[i]) {
                g[k] = p[j];
                phi[k] = phi[i] * phi[p[j]];
            }
        }
    }
}
```

```
u[k] = u[i] * u[p[j]];
h[k] = h[i] * h[p[j]];
}
else {
    g[k] = g[i] * p[j];
    phi[k] = phi[i] * p[j];
    u[k] = 0;
    h[k] = h[i] / g[i]] * (0);
} //质数次幂特判 */
//phi[i*p[j]]=phi[i]*phi[j] (gcd(i,j)=1);
//u[i*p[j]]=u[i]*u[j] (gcd(i,j)=1);
}
/*phi[i*j]=phi[i]*phi[j] (gcd(i,j)=1)
   phi[i]*j (j|i)
   u[i*j]=u[i]*u[j] (gcd(i,j)=1)
   0 (j|i)
*/
}
}
```

4.11 min\_25

```
struct Min_25 {
    // F(i) 要拆成多个完全积性函数的和
    static const int N = 1e6 + 7;
    int Sqr, m, p[N], id1[N], id2[N], tot, cntp;
    ll g[N], sp[N], h[N], n, w[N];
    bool isp[N];
    // f(p) = p ^ k
    ll f(int p) { return 1; }
    // 要求的积性函数 F(p ^ e)
    ll F(int p, int e) { return e == 1 ? -1 : 0; }
    // 假设都是质数的完全积性函数前缀和去掉 f(1)
    ll calc(ll n) { return n - 1; }

    void prime(int n) {
        cntp = 0; isp[1] = 1;
        rep(i, 2, n+1) {
            if (!isp[i]) p[++cntp] = i;
            for (int j = 1; j <= cntp && i * p[j] <= n; j++) {
                isp[i * p[j]] = 1;
                if (i % p[j] == 0) break;
            }
        }
        rep(i, 1, cntp+1) sp[i] = sp[i - 1] + f(p[i]);
        p[++cntp] = INT_MAX;
    }

    ll S(ll x, int y) {
        if (x <= 1 || p[y] > x) return 0;
        int k = (x <= Sqr ? id1[x] : id2[n/x]);
        ll ret = -(g[k] - sp[y-1]); // 质数的答案
        for (int i = y; i <= tot && 1ll * p[i] * p[i] <= x; i++) {
            // 质数的时候特判
            if (i % p[i] == 0) break;
            for (int j = 1, k; j <= m && p[j] <= f[i] && i * p[j] <= x; j++) {
                f[k = i * p[j]] = p[j];
                phi[k] = phi[i] * phi[p[j]];
            }
        }
    }
}
```

```

}
}
T get(int n, int k, T *x, T *y) { // f(k)
    T res = 0;
    rep(i, 0, n+1) {
        T s1 = y[i], s2 = 1;
        rep(j, 0, n+1) if (j != i) s1 = mul(s1, k - x[j]);
        rep(j, 0, n+1) if (j != i) s2 = mul(s2, x[i] - x[j]);
        res = add(res, mul(s1, kpow(s2, P - 2)));
    }
    return res;
}

T get(int n, int k, T *y) { // x is [1..n]
    fac[0] = 1; rep(i, 1, n+1) fac[i] = mul(fac[i-1], i);
    ifac[n] = kpow(fac[n], P - 2);
    per(i, 0, n) ifac[i] = mul(ifac[i+1], i+1);
    pre[0] = suf[n+1] = 1;
    rep(i, 1, n+1) pre[i] = mul(pre[i-1], k - i);
    per(i, 1, n+1) suf[i] = mul(suf[i+1], k - i);
    T ans = 0;
    rep(i, 1, n+1) {
        T s1 = mul(pre[i-1], suf[i+1]);
        T s2 = mul(ifac[i-1], ifac[n-i]);
        T fg = (n-i)&1 ? -1 : 1;
        ans = add(ans, mul(fg*s1, mul(s2, y[i])));
    }
    return ans;
}
};

```

#### 4.13 polysum

```

struct polysum {
    static const int D = 101000;
    static const int P = 998244353;
    ll a[D], fac[D], ifac[D], p1[D], p2[D], h[D][2], c[D];
    ll add(ll a, ll b) {a = (a + b) % P; return a < 0 ? a + P : a;}
    ll mul(ll a, ll b) {a = 1ll * a * b % P; return a < 0 ? a + P : a;}
    ll kpow(ll a, ll b) {ll r=1; for(;b;b>>=1, a=mul(a,a)) {if(b&1)r=mul(r,a);} return r;}
    void init(int M) {
        fac[0] = 1; rep(i, 1, M+5) fac[i] = mul(fac[i-1], i);
        ifac[M+4] = kpow(fac[M+4], P - 2);
        per(i, 0, M+4) ifac[i] = mul(ifac[i+1], i+1);
    }
    ll calcn(int d, ll *a, ll n) { // a[0]..a[d] a[n]
        if (n <= d) return a[n];
        p1[0] = p2[0] = 1;
        rep(i, 0, d+1) p1[i+1] = mul(p1[i], (n - i) % P);
        rep(i, 0, d+1) p2[i+1] = mul(p2[i], (n - d + i) % P);
        ll ans = 0;
        rep(i, 0, d+1) {
            ll s1 = mul(p1[i], p2[d - i]);
            ll s2 = mul(ifac[i], ifac[d - i]);
            ll t = mul(mul(s1, s2), a[i]);
            ans = (d-i)&1 ? add(ans, -t) : add(ans, t);
        }
    }
};

```

```

ll t1 = p[i], t2 = 1ll * p[i] * p[i];
for(int e = 1; t2 <= x; e++, t1 = t2, t2 *= p[i]) {
    if (F(p[i], e)) ret += S(x / t1, i + 1) * F(p[i], e);
    ret += F(p[i], e + 1); // 合数的答案
}
return ret;
}

ll solve(ll _n) {
    n = _n; if (n == 0) return 0;
    m = 0; Sqr = sqrt(n);
    tot = upper_bound(p + 1, p + cntp + 1, Sqr) - (p + 1);
    for(ll i = 1, j; i <= n; i = j + 1) {
        j = n / (n / i);
        w[+m] = n / i;
        g[m] = calc(w[m]);
        w[m] <= Sqr ? id1[w[m]] = m : id2[j] = m;
    }
    rep(j, 1, tot + 1)
        for(int i = 1; i <= m && 1ll * p[j] * p[j] <= w[i]; i++) {
            ll t = w[i] / p[j];
            int k = t <= Sqr ? id1[t] : id2[n / t];
            g[i] -= f(p[j]) * (g[k] - sp[j - 1]);
        }
    return S(n, 1) + 1;
}
}
} _u;

```

#### 4.12 polynomial

```

template<class T>
struct polynomial {
    static const int N = 101010;
    static const int P = 998244353;
    T a1[N], b1[N], c[N], a[N], pre[N], suf[N], ifac[N], fac[N];
    T add(T a, T b) {a = (a + b) % P; return a < 0 ? a + P : a;}
    T mul(T a, T b) {a = 1ll * a * b % P; return a < 0 ? a + P : a;}
    T kpow(T a, T b) {T r=1; for(;b;b>>=1, a=mul(a,a)) {if(b&1)r=mul(r,a);} return r;}
    void calc(int n, T *a, T *b) {
        fill_n(c, n+4, 0);
        rep(i, 0, n+1) rep(j, 0, 2) c[i+j] = add(c[i+j], mul(a[i], b[j]));
        memcpy(a, c, sizeof(a[0]) * (n+1));
    }
    void solve(int n, T *x, T *y) { // a[0]*x^0 ... a[n]*x^n
        fill_n(a, n+1, 0);
        rep(i, 0, n+1) {
            fill_n(a1, n+4, 0); a1[0] = 1;
            rep(j, 0, n+1) if (j != i) a1[0] = mul(a1[0], x[i] - x[j]);
            a1[0] = mul(y[i], kpow(a1[0], P - 2));
            rep(j, 0, n+1) if (j != i) {
                b1[0] = -x[j]; b1[1] = 1;
                calc(n, a1, b1);
            }
            rep(j, 0, n+1) a1[j] = add(a1[j], a1[j]);
        }
    }
};

```

```

    }
    return ans;
}
ll Polysum(ll n, ll *a, ll m) { // a[0].. a[m] \sum_{i=0}^{n-1} a[i]
    a[m+1] = calcn(m, a, m+1);
    rep(i, 1, m+2) a[i] = add(a[i-1], a[i]);
    return calcn(m+1, a, n-1);
}
ll qpolysum(ll R, ll n, ll *a, ll m) { // a[0].. a[m] \sum_{i=0}^{n-1} a[i]*R^i
    if (R == 1) return Polysum(n, a, m);
    a[m+1] = calcn(m, a, m+1);
    ll r = kpow(R, P - 2), p3 = 0, p4 = 0, c, ans;
    h[0][0] = 0; h[0][1] = 1;
    rep(i, 1, m+2) {
        h[i][0] = mul(h[i-1][0] + a[i-1], r);
        h[i][1] = mul(h[i-1][1], r);
    }
    rep(i, 0, m+2) {
        ll t = mul(ifac[i], ifac[m+1-i]);
        p3 = i & 1 ? add(p3, -mul(h[i][0], t)) : add(p3, mul(h[i][0], t));
        p4 = i & 1 ? add(p4, -mul(h[i][1], t)) : add(p4, mul(h[i][1], t));
    }
    c = mul(kpow(p4, P - 2), -p3);
    rep(i, 0, m+2) h[i][0] = add(h[i][0], h[i][1] * c);
    rep(i, 0, m+2) c[i] = h[i][0];
    ans = add(mul(calcn(m, C, n), kpow(R, n)), -c);
    return ans;
}
};

```

#### 4.14 prime

```

// time : O(n)
// low[] : optional
const int N = 1e6 + 6;
int low[N], cntp, p[N];
bool isp[N];

void getprime() {
    fill_n(isp + 2, N - 2, 1);
    rep(i, 2, N) {
        if (isp[i]) p[cntp++] = i;
        for (int j = 0; j < cntp & p[j] * i < N; j++) {
            // low[p[j] * i] = p[j];
            isp[p[j] * i] = 0;
            if (i % p[j] == 0) break;
        }
    }
}

// 优化版埃拉筛法 bitset 需要 O2
const int N = 3e7 + 6;
const int M = 2e6 + 6;
// int low[N],
bitset<N> isp;

```

```

int cntp, p[M];

void getprime() {
    cntp = 2; p[0] = 2; p[1] = 3;
    for (int i = 5, k = 1; i <= N; (k & 1) == 1 ? i += 2 : i += 4, k++) {
        if (!isp[k]) p[cntp++] = i;
        for (int j = 2; j < cntp && p[j] * i < N; j++) {
            // low[p[j] * i] = p[j];
            isp[p[j] * i / 3] = 1;
            if (i % p[j] == 0) break;
        }
    }

    // 优化埃氏筛法空间最小可以不存质数
    const int N = 3e8 + 6;
    const int M = 2e7 + 6;
    int cntp, p[M];
    bitset<N / 3 + 1> bit;

    void getprime(int n) {
        int i, j;
        cntp = 2; p[0] = 2; p[1] = 3;
        for (i = 5, j = 1; i * i <= n; (j & 1) == 1 ? i += 2 : i += 4, j++) {
            if (bit[j] == 0) {
                p[cntp++] = i;
                for (int j = i * i; j <= n; j += i)
                    if (j % 2 != 0 && j % 3 != 0) bit[j / 3] = 1;
            }
        }
        for (; i <= n; (j & 1) == 1 ? i += 2 : i += 4, j++) if (bit[j] == 0) p[cntp++] = i;
    }
}

```

## 5 Others

### 5.1 roman\_numerals

```

const int rom[30] = {
    3000, 2000, 1000, 900, 800, 700, 600, 500, 400, 300, 200, 100,
    90, 80, 70, 60, 50, 40, 30, 20, 10,
    9, 8, 7, 6, 5, 4, 3, 2, 1
};

string smb[30] = {
    "MMM", "MM", "M",
    "CM", "DCCC", "DCC", "DC", "D", "CD", "CCC", "CC", "C",
    "XC", "LXXX", "LXX", "LX", "L", "XL", "XXX", "XX", "X",
    "IX", "VIII", "VII", "VI", "V", "IV", "III", "II", "I"
};

string toRoman(ll d) {
    string r;
    rep(i, 0, 30) if (d >= rom[i]) d -= rom[i], r += smb[i];
    return r;
}

```

# abel变换

---

$$\sum_{i=1}^n ai * bi = \sum_{i=1}^{n-1} Ai * (bi - bi+1) + An * bn$$
$$Ai = \sum_{j=1}^i aj$$

# Mobius反演

---

$$F(n) = \sum_{n|d} f(d) => f(n) = \sum_{n|d} \mu(\frac{d}{n}) F(d)$$
$$\sum_{d=1}^n f(d) * h(d) => \sum_{d=1}^n F(d) * (h \circ \mu)(d)$$