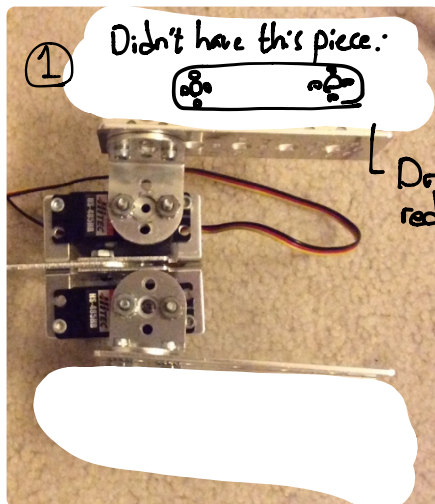


## Two potential arm designs:

Embodiment

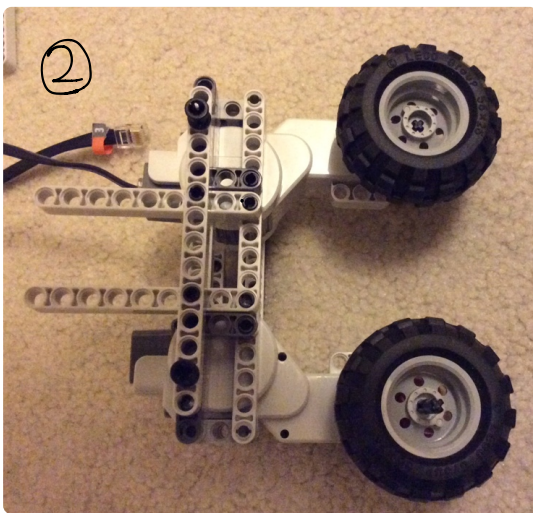


### Sustains:

Compact  
Light weight

### Refines:

Improve grip coefficient  
Limit range of motion



### Sustains:

Grippiness  
Ease of block grabbing

### Refines:

Bulky  
Heavy

## Conclusion:

Combine the two!

Widen ①'s grip width

Put ②'s grippy wheels on ①'s servos

## New potential

Could feed directly into  
a hopper

Allows for proper sensor placement