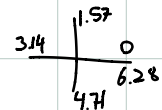


desired $\text{atan}\left(\frac{y}{x}\right)$

$y \backslash x$	-	0	+
-	$\begin{matrix} < 3.14 \\ > 4.71 \end{matrix}$	$\begin{matrix} < 4.71 \\ > 6.28 \end{matrix}$	
0	3.14	/	0
+	$\begin{matrix} < 1.57 \\ > 3.14 \end{matrix}$	$\begin{matrix} < 0 \\ > 1.57 \end{matrix}$	



$y \backslash x$	-	0	+
-	+	+	+
0	+	+	+
+	+	+	+

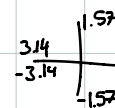
actual $\text{atan}\left(\frac{y}{x}\right)$

$y \backslash x$	-	0	+
-	$\begin{matrix} < \\ > \end{matrix}$		
0	/	/	/
+	$\begin{matrix} < \\ > \end{matrix}$		



$y \backslash x$	-	0	+
-	+	+	+
0	+	+	+
+	+	+	+

actual atan2



$y \backslash x$	-	0	+
-	+	+	+
0	+	+	+
+	+	+	+

Conclusions:

- add 2π , not π
- use atan2
- change condition:
if (input $X < \text{current } X$)
to
if (goal Angle < 0)