



# Review of Machine Learning

#### **Materials from**

- Intel Deep Learning <a href="https://www.intel.com/content/www/us/en/developer/learn/course-deep-learning.html">https://www.intel.com/content/www/us/en/developer/learn/course-deep-learning.html</a>
- Introduction to Neural Networks <a href="https://www.deeplearning.ai/">https://www.deeplearning.ai/</a>

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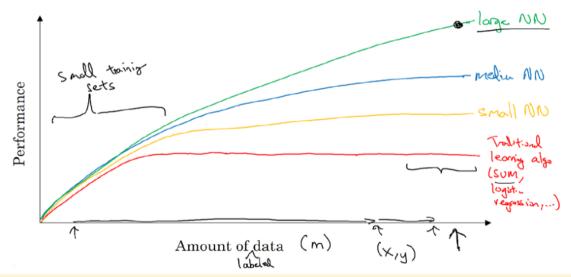
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## Why is Deep Learning Taking Off?

Deep learning is taking off due to a large amount of data available through the digitization of the society, faster computation and innovation in the development of neural network algorithm.

#### Scale drives deep learning progress

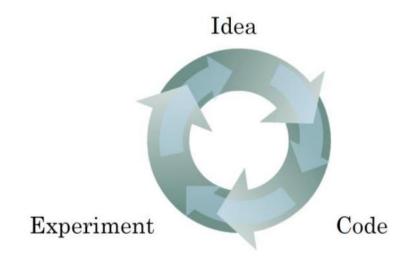


Two things have to be considered to get to the high level of performance:

- 1. Being able to train a big enough neural network
- 2. Huge amount of labeled data

#### Process of Training a Neural Network

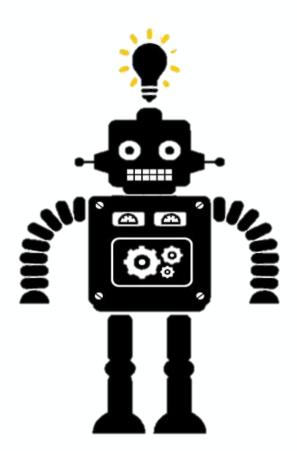
The process of training a neural network is iterative.



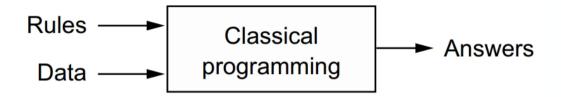
It could take a good amount of time to train a neural network, which affects your productivity. Faster computation helps to iterate and improve new algorithm.

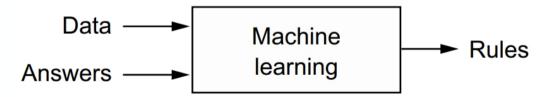
#### What is Machine Learning?

Machine learning allows computers to learn and infer from data.



#### Classical Programming and Machine Learning

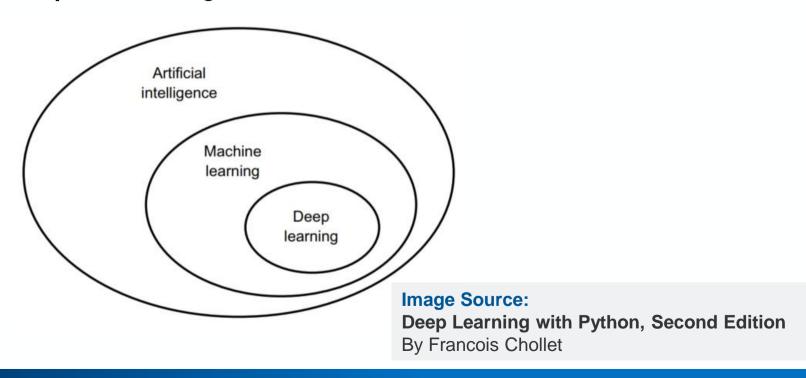




#### **Image Source:**

**Deep Learning with Python, Second Edition**By Francois Chollet

# Artificial Intelligence, Machine Learning, and Deep Learning



#### Types of Machine Learning

Supervised

data points have known outcome

Unsupervised

data points have unknown outcome

#### Types of Supervised Learning

Regression

outcome is continuous (numerical)

Classification

outcome is a category

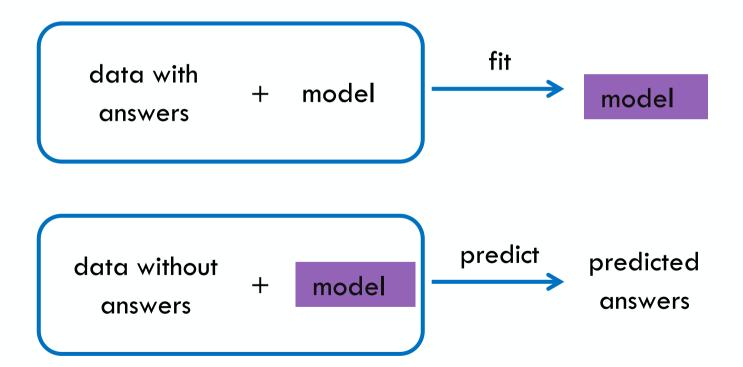
#### Machine Learning Vocabulary

- Target: predicted category or value of the data (column to predict)
- Features: properties of the data used for prediction (non-target columns)
- Example: a single data point within the data (one row)
- Label: the target value for a single data point

#### Machine Learning Vocabulary (Synonyms)

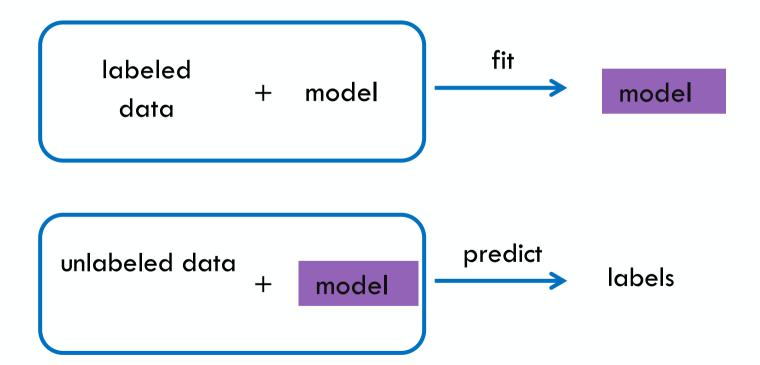
- Target: Response, Output, Dependent Variable, Labels
- Features: Predictors, Input, Independent Variables, Attributes
- **Example:** Observation, Record, Instance, Datapoint, Row
- Label: Answer, y-value, Category

#### Supervised Learning Overview

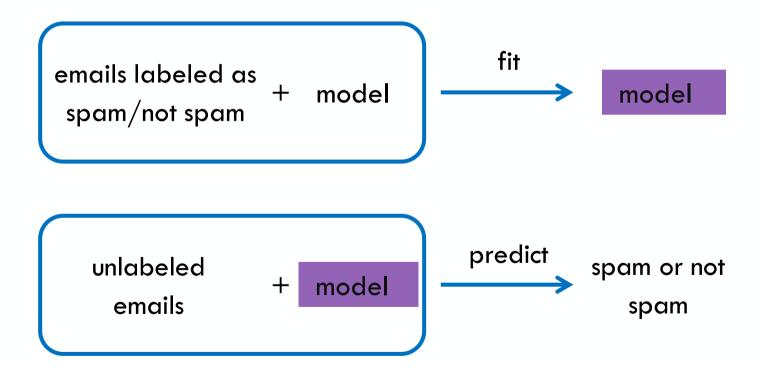


#### Regression: Numeric Answers

#### Classification: Categorical Answers



#### Classification: Categorical Answers



#### Three Types of Classification Predictions

- **Hard Prediction:** Predict a single category for each instance.
- Ranking Prediction: Rank the instances from most likely to least likely. (binary classification)
- Probability Prediction: Assign a probability
   distribution across the classes to each instance.

#### Metrics for Classification

- Hard Prediction: Accuracy, Precision, Recall (Sensitivity), Specificity, F1 Score
- Ranking Prediction: AUC (ROC), Precision-Recall
   Curves
- Probability Prediction: Log-loss (aka Cross-Entropy),
   Brier Score

#### Metrics for Regression

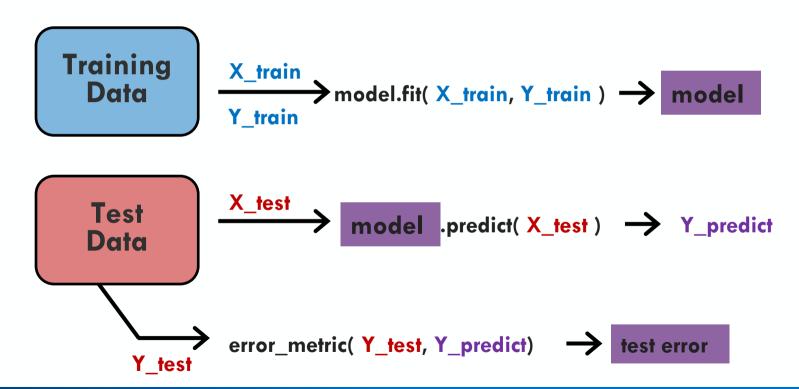
Root Mean Square Error (RMSE)

$$RMSE = \sqrt{\frac{1}{n} \sum_{i=1}^{n} (y_i - \hat{y}_i)^2}$$

Mean Absolute Error (MAE)

$$MAE = \frac{1}{n} \sum_{i=1}^{n} |y_i - \hat{y}_i|$$

#### Fitting Training and Test Data

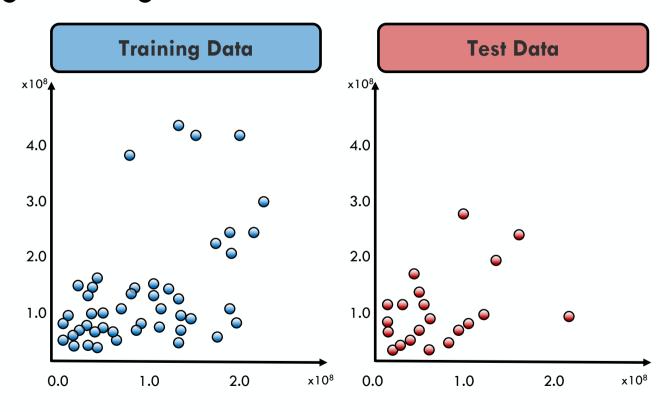


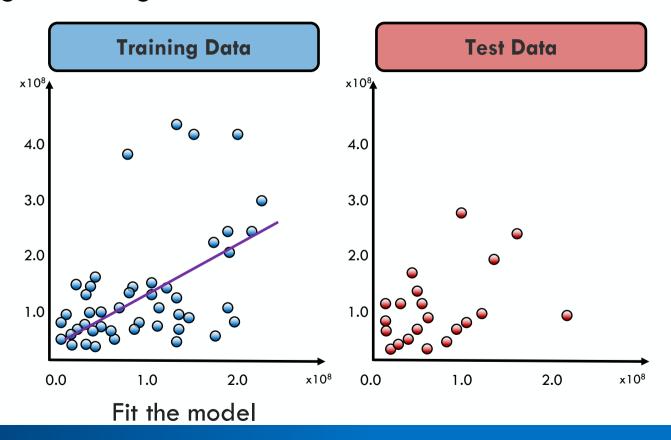
Training Data fit the model

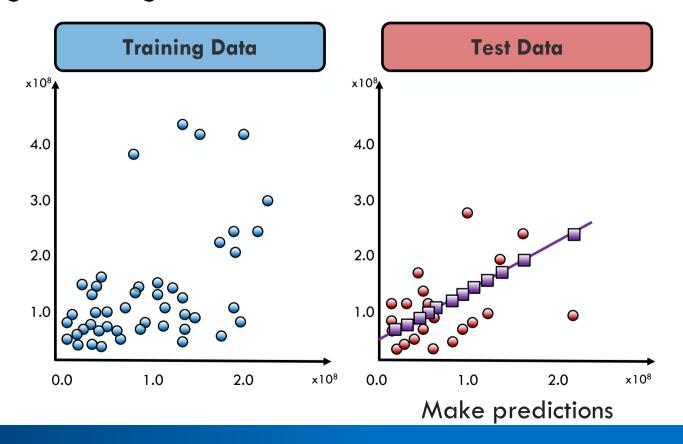
Test Data

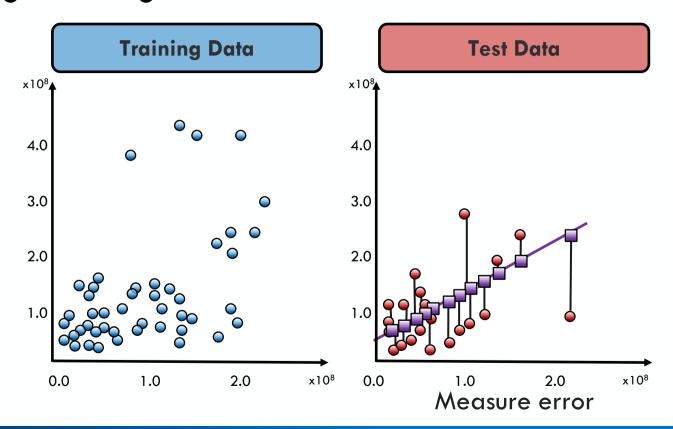
#### measure performance

- predict label with model
- compare with actual value
- measure error

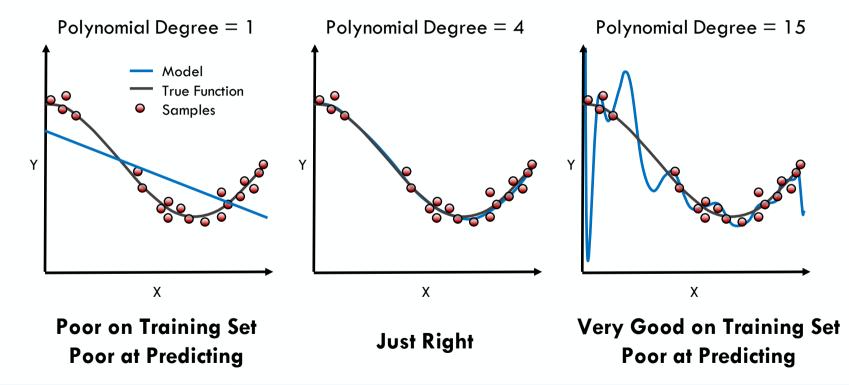




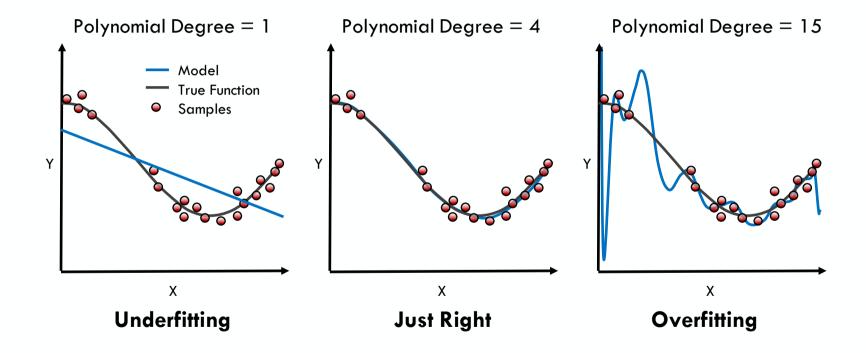




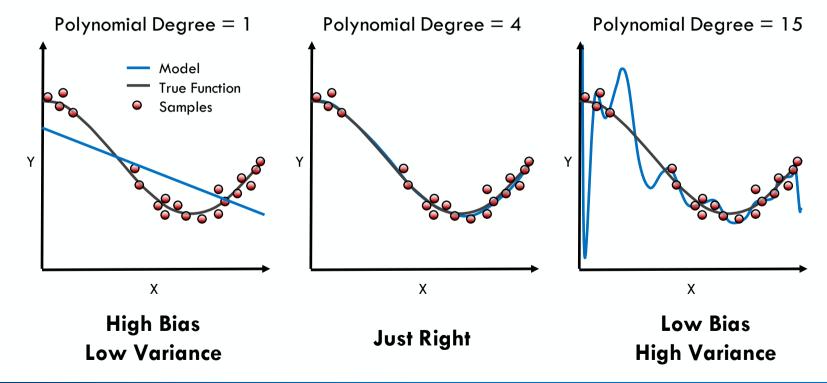
#### How Well Does the Model Generalize?



# Underfitting vs Overfitting

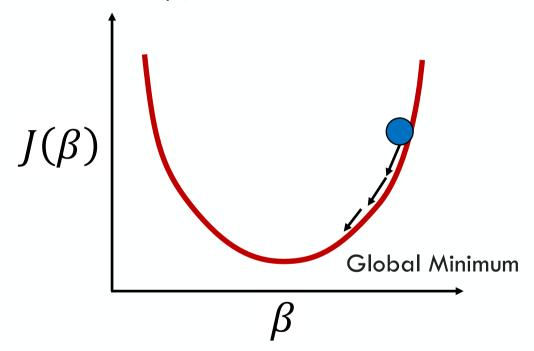


#### Bias - Variance Tradeoff



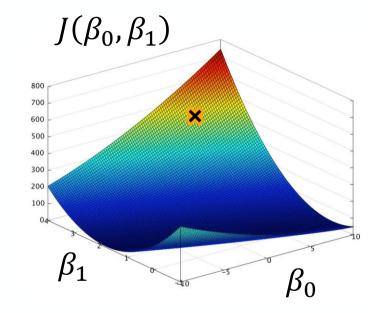
#### **Gradient Descent**

Start with a cost function  $J(\beta)$ :



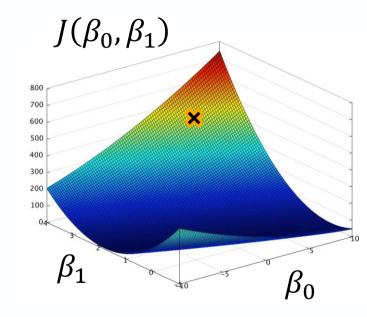
Then gradually move towards the minimum.

- Now imagine there are two parameters  $(\beta_0,\beta_1)$
- This is a more complicated surface on which the minimum must be found
- How can we do this without knowing what  $J(\beta_0,\beta_1)$  looks like?

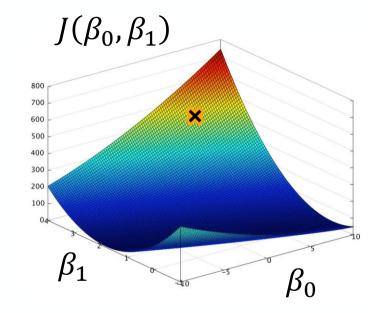


 The gradient is a vector whose coordinates consist of the partial derivatives of the parameters

$$\nabla J(\beta_0, \dots, \beta_n) = \langle \frac{\partial J}{\partial \beta_0}, \dots, \frac{\partial J}{\partial \beta_n} \rangle$$



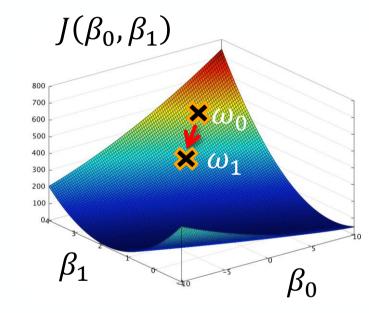
- Compute the gradient,  $\nabla J(\beta_0, \beta_1)$ , which points in the direction of the biggest increase!
- $-\nabla J(\beta_0, \beta_1)$  (negative gradient) points to the biggest decrease at that point!



• Then use the gradient  $(\nabla)$  and the cost function to calculate the next point  $(\omega_1)$  from the current one  $(\omega_0)$ :

$$\omega_1 = \omega_0 - \alpha \nabla \frac{1}{2} \sum_{i=1}^{m} \left( \left( \beta_0 + \beta_1 x_{obs}^{(i)} \right) - y_{obs}^{(i)} \right)^2$$

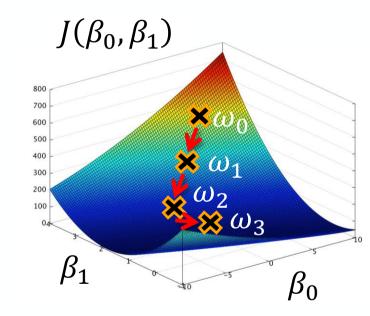
• The learning rate  $(\alpha)$  is a tunable parameter that determines step size



 Each point can be iteratively calculated from the previous one

$$\omega_{2} = \omega_{1} - \alpha \nabla \frac{1}{2} \sum_{i=1}^{m} \left( \left( \beta_{0} + \beta_{1} x_{obs}^{(i)} \right) - y_{obs}^{(i)} \right)^{2}$$

$$\omega_{3} = \omega_{2} - \alpha \nabla \frac{1}{2} \sum_{i=1}^{m} \left( \left( \beta_{0} + \beta_{1} x_{obs}^{(i)} \right) - y_{obs}^{(i)} \right)^{2}$$

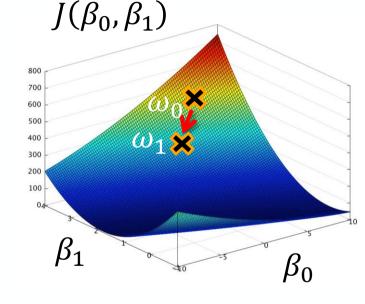


#### Stochastic Gradient Descent

 Use a single data point to determine the gradient and cost function instead of all the data

$$\omega_1 = \omega_0 - \alpha \nabla \frac{1}{2} \underbrace{\sum_{i=1}^{m} \left( \left( \beta_0 + \beta_1 x_{obs}^{(i)} \right) - y_{obs}^{(i)} \right)^2}_{i=1}$$

$$\omega_1 = \omega_0 - \alpha \nabla \frac{1}{2} \left( \left( \beta_0 + \beta_1 x_{obs}^{(0)} \right) - y_{obs}^{(0)} \right)^2$$



#### Stochastic Gradient Descent

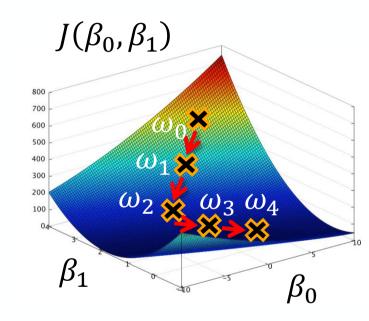
 Use a single data point to determine the gradient and cost function instead of all the data

$$\omega_1 = \omega_0 - \alpha \nabla \frac{1}{2} \left( \left( \beta_0 + \beta_1 x_{obs}^{(0)} \right) - y_{obs}^{(0)} \right)^2$$

• • •

$$\omega_4 = \omega_3 - \alpha \nabla \frac{1}{2} \left( \left( \beta_0 + \beta_1 x_{obs}^{(3)} \right) - y_{obs}^{(3)} \right)^2$$

 Path is less direct due to noise in single data point—"stochastic"



#### Mini Batch Gradient Descent

• Perform an update for every n training examples

$$\omega_1 = \omega_0 - \alpha \nabla \frac{1}{2} \sum_{i=1}^{n} \left( \left( \beta_0 + \beta_1 x_{obs}^{(i)} \right) - y_{obs}^{(i)} \right)^2$$

#### Best of both worlds:

- Reduced memory relative to "vanilla" gradient descent
- Less noisy than stochastic gradient descent

