Deep Neural Network for Image Classification: Application

By the time you complete this notebook, you will have finished the last programming assignment of Week 4, and also the last programming assignment of Course 1! Go you!

To build your cat/not-a-cat classifier, you'll use the functions from the previous assignment to build a deep network. Hopefully, you'll see an improvement in accuracy over your previous logistic regression implementation.

After this assignment you will be able to:

· Build and train a deep L-layer neural network, and apply it to supervised learning

Let's get started!

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1 - Packages

Begin by importing all the packages you'll need during this assignment.

- numpy (https://www.numpy.org/) is the fundamental package for scientific computing with Python.
- matplotlib (http://matplotlib.org) is a library to plot graphs in Python.
- h5py (http://www.h5py.org) is a common package to interact with a dataset that is stored on an H5 file.
- <u>PIL (http://www.pythonware.com/products/pil/)</u> and <u>scipy (https://www.scipy.org/)</u> are used here to test your model with your own picture at the end.
- dnn_app_utils provides the functions implemented in the "Building your Deep Neural Network: Step by Step" assignment to this notebook.
- np.random.seed(1) is used to keep all the random function calls consistent. It helps grade your work so please don't change it!

```
In [1]:
        import time
        import numpy as np
        import h5py
        import matplotlib.pyplot as plt
        import scipy
        from PIL import Image
        from scipy import ndimage
        from dnn app utils v3 import *
        from public_tests import *
        %matplotlib inline
        plt.rcParams['figure.figsize'] = (5.0, 4.0) # set default size of plots
        plt.rcParams['image.interpolation'] = 'nearest'
        plt.rcParams['image.cmap'] = 'gray'
        %load ext autoreload
        %autoreload 2
        np.random.seed(1)
```

2 - Load and Process the Dataset

You'll be using the same "Cat vs non-Cat" dataset as in "Logistic Regression as a Neural Network" (Assignment 2). The model you built back then had 70% test accuracy on classifying cat vs non-cat images. Hopefully, your new model will perform even better!

Problem Statement: You are given a dataset ("data.h5") containing:

```
- a training set of `m_train` images labelled as cat (1) or non-cat (0)
- a test set of `m_test` images labelled as cat and non-cat
- each image is of shape (num_px, num_px, 3) where 3 is for the 3 channels (RGB).
```

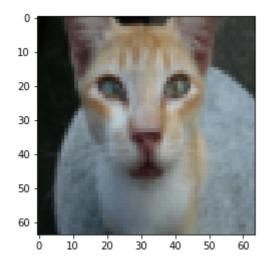
Let's get more familiar with the dataset. Load the data by running the cell below.

```
In [2]: train_x_orig, train_y, test_x_orig, test_y, classes = load_data()
```

The following code will show you an image in the dataset. Feel free to change the index and re-run the cell multiple times to check out other images.

```
In [4]: # Example of a picture
index = 11
plt.imshow(train_x_orig[index])
print ("y = " + str(train_y[0,index]) + ". It's a " + classes[train_y[0,index]].decod
e("utf-8") + " picture.")
```

y = 1. It's a cat picture.



In [5]: # Explore your dataset m_train = train_x_orig.shape[0] num_px = train_x_orig.shape[1] m_test = test_x_orig.shape[0] print ("Number of training examples: " + str(m_train)) print ("Number of testing examples: " + str(m_test)) print ("Each image is of size: (" + str(num_px) + ", " + str(num_px) + ", 3)") print ("train_x_orig shape: " + str(train_x_orig.shape)) print ("train_y shape: " + str(train_y.shape)) print ("test_x_orig shape: " + str(test_x_orig.shape)) print ("test_y shape: " + str(test_y.shape))

```
Number of training examples: 209
Number of testing examples: 50
Each image is of size: (64, 64, 3)
train_x_orig shape: (209, 64, 64, 3)
train_y shape: (1, 209)
test_x_orig shape: (50, 64, 64, 3)
test_y shape: (1, 50)
```

As usual, you reshape and standardize the images before feeding them to the network. The code is given in the cell below.

reshaped image vector

pixel image Blue Green 255 134 93 255 134 202 22 194 202

Figure 1: Image to vector conversion.

```
In [6]: # Reshape the training and test examples
    train_x_flatten = train_x_orig.reshape(train_x_orig.shape[0], -1).T # The "-1" make
    s reshape flatten the remaining dimensions
    test_x_flatten = test_x_orig.reshape(test_x_orig.shape[0], -1).T

# Standardize data to have feature values between 0 and 1.
    train_x = train_x_flatten/255.
    test_x = test_x_flatten/255.

print ("train_x's shape: " + str(train_x.shape))
    print ("test_x's shape: " + str(test_x.shape))

train_x's shape: (12288, 209)
    test_x's shape: (12288, 50)
```

Note: 12,288 equals $64 \times 64 \times 3$, which is the size of one reshaped image vector.

3 - Model Architecture

3.1 - 2-layer Neural Network

Now that you're familiar with the dataset, it's time to build a deep neural network to distinguish cat images from non-cat images!

You're going to build two different models:

- · A 2-layer neural network
- An L-layer deep neural network

Then, you'll compare the performance of these models, and try out some different values for L.

Let's look at the two architectures:

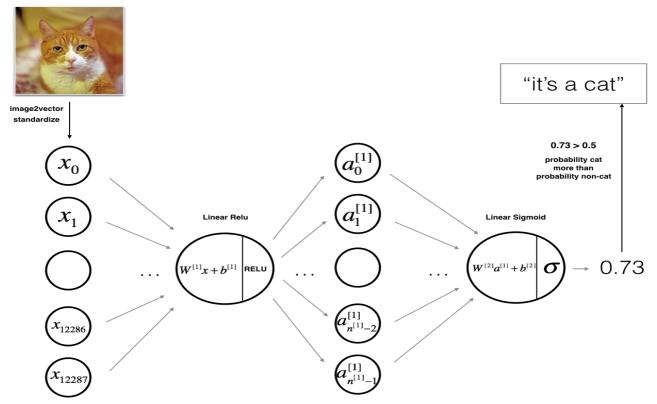


Figure 2: 2-layer neural network.

The model can be summarized as: INPUT -> LINEAR -> RELU -> LINEAR -> SIGMOID -> OUTPUT.

Detailed Architecture of Figure 2:

- The input is a (64,64,3) image which is flattened to a vector of size (12288,1).
- The corresponding vector: $[x_0,x_1,\ldots,x_{12287}]^T$ is then multiplied by the weight matrix $W^{[1]}$ of size $(n^{[1]},12288)$.
- Then, add a bias term and take its relu to get the following vector: $[a_0^{[1]}, a_1^{[1]}, \dots, a_{n^{[1]}-1}^{[1]}]^T$.
- · Repeat the same process.
- Multiply the resulting vector by $W^{[2]}$ and add the intercept (bias).
- Finally, take the sigmoid of the result. If it's greater than 0.5, classify it as a cat.

3.2 - L-layer Deep Neural Network

It's pretty difficult to represent an L-layer deep neural network using the above representation. However, here is a simplified network representation:

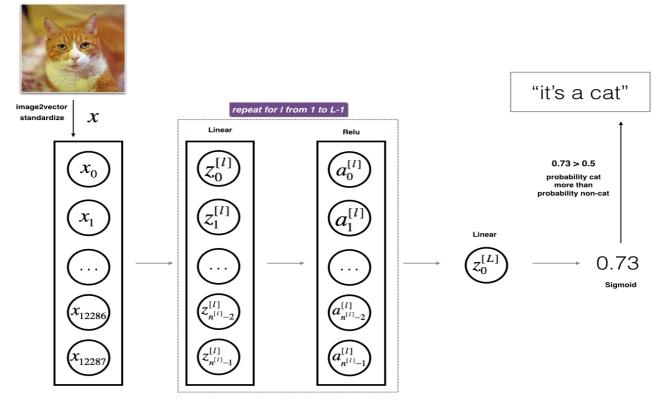


Figure 3: L-layer neural network.

The model can be summarized as: [LINEAR -> RELU] \times (L-1) -> LINEAR -> SIGMOID

Detailed Architecture of Figure 3:

- The input is a (64,64,3) image which is flattened to a vector of size (12288,1).
- The corresponding vector: $[x_0,x_1,\ldots,x_{12287}]^T$ is then multiplied by the weight matrix $W^{[1]}$ and then you add the intercept $b^{[1]}$. The result is called the linear unit.
- Next, take the relu of the linear unit. This process could be repeated several times for each $(W^{[l]},b^{[l]})$ depending on the model architecture.
- Finally, take the sigmoid of the final linear unit. If it is greater than 0.5, classify it as a cat.

3.3 - General Methodology

As usual, you'll follow the Deep Learning methodology to build the model:

- 1. Initialize parameters / Define hyperparameters
- 2. Loop for num_iterations: a. Forward propagation b. Compute cost function c. Backward propagation d. Update parameters (using parameters, and grads from backprop)
- 3. Use trained parameters to predict labels

Now go ahead and implement those two models!

4 - Two-layer Neural Network

Exercise 1 - two_layer_model

Use the helper functions you have implemented in the previous assignment to build a 2-layer neural network with the following structure: LINEAR -> RELU -> LINEAR -> SIGMOID. The functions and their inputs are:

```
In [8]: # GRADED FUNCTION: two_layer_model
        def two_layer_model(X, Y, layers_dims, learning_rate = 0.0075, num_iterations = 3000,
        print_cost=False):
            Implements a two-layer neural network: LINEAR->RELU->LINEAR->SIGMOID.
            Arguments:
            X -- input data, of shape (n_x, number of examples)
            Y -- true "label" vector (containing 1 if cat, 0 if non-cat), of shape (1, number
        of examples)
            layers_dims -- dimensions of the layers (n_x, n_h, n_y)
            num_iterations -- number of iterations of the optimization Loop
            learning rate -- learning rate of the gradient descent update rule
            print_cost -- If set to True, this will print the cost every 100 iterations
            Returns:
            parameters -- a dictionary containing W1, W2, b1, and b2
            np.random.seed(1)
            grads = \{\}
            costs = []
                                                     # to keep track of the cost
            m = X.shape[1]
                                                      # number of examples
            (n_x, n_h, n_y) = layers_dims
            # Initialize parameters dictionary, by calling one of the functions you'd previou
        sly implemented
            #(≈ 1 line of code)
            # parameters = ...
            # YOUR CODE STARTS HERE
            parameters = initialize parameters(n x, n h, n y)
            # YOUR CODE ENDS HERE
            # Get W1, b1, W2 and b2 from the dictionary parameters.
            W1 = parameters["W1"]
            b1 = parameters["b1"]
            W2 = parameters["W2"]
            b2 = parameters["b2"]
            # Loop (gradient descent)
            for i in range(0, num iterations):
                 # Forward propagation: LINEAR -> RELU -> LINEAR -> SIGMOID. Inputs: "X, W1, b
        1, W2, b2". Output: "A1, cache1, A2, cache2".
                \#(\approx 2 \text{ lines of code})
                # A1, cache1 = ...
                \# A2, cache2 = ...
                # YOUR CODE STARTS HERE
                A1, cache1 = linear_activation_forward(X, parameters["W1"], parameters["b1"],
        "relu")
                A2, cache2 = linear_activation_forward(A1, parameters["W2"], parameters["b2"
        ], "sigmoid")
                # YOUR CODE ENDS HERE
                # Compute cost
                #(≈ 1 line of code)
                # cost = ...
                # YOUR CODE STARTS HERE
                cost = compute_cost(A2, Y)
                # YOUR CODE ENDS HERE
```

```
# Initializing backward propagation
                dA2 = - (np.divide(Y, A2) - np.divide(1 - Y, 1 - A2))
                # Backward propagation. Inputs: "dA2, cache2, cache1". Outputs: "dA1, dW2, db
        2; also dA0 (not used), dW1, db1".
                #(≈ 2 lines of code)
                # dA1, dW2, db2 = ...
                # dA0, dW1, db1 = ...
                # YOUR CODE STARTS HERE
                dA1, dW2, db2 = linear_activation_backward(dA2, cache2, activation="sigmoid")
                dA0, dW1, db1 = linear_activation_backward(dA1, cache1, activation="relu")
                # YOUR CODE ENDS HERE
                # Set grads['dWL'] to dW1, grads['db1'] to db1, grads['dW2'] to dW2, grads['d
        b2'1 to db2
                grads['dW1'] = dW1
                grads['db1'] = db1
                grads['dW2'] = dW2
                grads['db2'] = db2
                # Update parameters.
                #(approx. 1 line of code)
                # parameters = ...
                # YOUR CODE STARTS HERE
                parameters = update parameters(parameters, grads, learning rate)
                # YOUR CODE ENDS HERE
                # Retrieve W1, b1, W2, b2 from parameters
                W1 = parameters["W1"]
                b1 = parameters["b1"]
                W2 = parameters["W2"]
                b2 = parameters["b2"]
                # Print the cost every 100 iterations
                if print_cost and i % 100 == 0 or i == num_iterations - 1:
                    print("Cost after iteration {}: {}".format(i, np.squeeze(cost)))
                if i % 100 == 0 or i == num iterations:
                    costs.append(cost)
            return parameters, costs
        def plot costs(costs, learning rate=0.0075):
            plt.plot(np.squeeze(costs))
            plt.ylabel('cost')
            plt.xlabel('iterations (per hundreds)')
            plt.title("Learning rate =" + str(learning_rate))
            plt.show()
In [9]: parameters, costs = two_layer_model(train_x, train_y, layers_dims = (n_x, n_h, n_y),
        num_iterations = 2, print_cost=False)
        print("Cost after first iteration: " + str(costs[0]))
        two layer model test(two layer model)
        Cost after iteration 1: 0.6926114346158595
        Cost after first iteration: 0.693049735659989
        Cost after iteration 1: 0.6915746967050506
        Cost after iteration 1: 0.6915746967050506
        Cost after iteration 1: 0.6915746967050506
```

All tests passed.

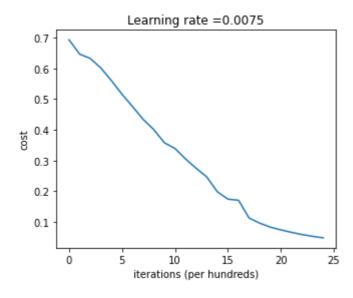
cost after iteration 1 must be around 0.69

4.1 - Train the model

If your code passed the previous cell, run the cell below to train your parameters.

- The cost should decrease on every iteration.
- It may take up to 5 minutes to run 2500 iterations.

Cost after iteration 0: 0.693049735659989 Cost after iteration 100: 0.6464320953428849 Cost after iteration 200: 0.6325140647912677 Cost after iteration 300: 0.6015024920354665 Cost after iteration 400: 0.5601966311605747 Cost after iteration 500: 0.5158304772764729 Cost after iteration 600: 0.4754901313943325 Cost after iteration 700: 0.43391631512257495 Cost after iteration 800: 0.4007977536203886 Cost after iteration 900: 0.3580705011323798 Cost after iteration 1000: 0.3394281538366413 Cost after iteration 1100: 0.30527536361962654 Cost after iteration 1200: 0.2749137728213015 Cost after iteration 1300: 0.2468176821061484 Cost after iteration 1400: 0.19850735037466102 Cost after iteration 1500: 0.17448318112556638 Cost after iteration 1600: 0.1708076297809692 Cost after iteration 1700: 0.11306524562164715 Cost after iteration 1800: 0.09629426845937156 Cost after iteration 1900: 0.0834261795972687 Cost after iteration 2000: 0.07439078704319085 Cost after iteration 2100: 0.06630748132267933 Cost after iteration 2200: 0.05919329501038172 Cost after iteration 2300: 0.053361403485605606 Cost after iteration 2400: 0.04855478562877019 Cost after iteration 2499: 0.04421498215868956



Expected Output:

Cost after iteration 0 0.6930497356599888

Cost after iteration 100 0.6464320953428849

Cost after iteration 2499 0.04421498215868956

Nice! You successfully trained the model. Good thing you built a vectorized implementation! Otherwise it might have taken 10 times longer to train this.

Now, you can use the trained parameters to classify images from the dataset. To see your predictions on the training and test sets, run the cell below.

Expected Output:

Accuracy 0.9999999999998

Expected Output:

Accuracy 0.72

Congratulations! It seems that your 2-layer neural network has better performance (72%) than the logistic regression implementation (70%, assignment week 2). Let's see if you can do even better with an L-layer model.

Note: You may notice that running the model on fewer iterations (say 1500) gives better accuracy on the test set. This is called "early stopping" and you'll hear more about it in the next course. Early stopping is a way to prevent overfitting.

5 - L-layer Neural Network

Exercise 2 - L_layer_model

Use the helper functions you implemented previously to build an L-layer neural network with the following structure: $[LINEAR -> RELU] \times (L-1) -> LINEAR -> SIGMOID$. The functions and their inputs are:

```
In [13]: ### CONSTANTS ###
layers_dims = [12288, 20, 7, 5, 1] # 4-layer model
```

```
In [14]: # GRADED FUNCTION: L_layer_model
         def L_layer_model(X, Y, layers_dims, learning_rate = 0.0075, num_iterations = 3000, p
         rint_cost=False):
             Implements a L-layer neural network: [LINEAR->RELU]*(L-1)->LINEAR->SIGMOID.
             Arguments:
             X -- data, numpy array of shape (num_px * num_px * 3, number of examples)
              Y -- true "label" vector (containing 0 if cat, 1 if non-cat), of shape (1, number
         of examples)
              layers_dims -- list containing the input size and each layer size, of length (num
         ber of layers + 1).
             learning rate -- learning rate of the gradient descent update rule
             num_iterations -- number of iterations of the optimization loop
             print cost -- if True, it prints the cost every 100 steps
             Returns:
             parameters -- parameters learnt by the model. They can then be used to predict.
             np.random.seed(1)
                                                 # keep track of cost
             costs = []
             # Parameters initialization.
             #(≈ 1 line of code)
             # parameters = ...
             # YOUR CODE STARTS HERE
             parameters = initialize_parameters_deep(layers_dims)
             # YOUR CODE ENDS HERE
             # Loop (gradient descent)
             for i in range(0, num iterations):
                  # Forward propagation: [LINEAR -> RELU]*(L-1) -> LINEAR -> SIGMOID.
                  #(≈ 1 line of code)
                  # AL, caches = ...
                  # YOUR CODE STARTS HERE
                  AL, caches = L model forward(X, parameters)
                  # YOUR CODE ENDS HERE
                  # Compute cost.
                  #(≈ 1 line of code)
                  # cost = ...
                  # YOUR CODE STARTS HERE
                  cost = compute_cost(AL, Y)
                  # YOUR CODE ENDS HERE
                  # Backward propagation.
                  #(≈ 1 line of code)
                  \# grads = ...
                  # YOUR CODE STARTS HERE
                  grads = L model backward(AL, Y, caches)
                  # YOUR CODE ENDS HERE
                  # Update parameters.
                  \#(\approx 1 \text{ line of code})
                  # parameters = ...
                  # YOUR CODE STARTS HERE
                  parameters = update_parameters(parameters, grads, learning_rate)
```

```
# YOUR CODE ENDS HERE

# Print the cost every 100 iterations
if print_cost and i % 100 == 0 or i == num_iterations - 1:
    print("Cost after iteration {}: {}".format(i, np.squeeze(cost)))
if i % 100 == 0 or i == num_iterations:
    costs.append(cost)

return parameters, costs
```

5.1 - Train the model

If your code passed the previous cell, run the cell below to train your model as a 4-layer neural network.

- · The cost should decrease on every iteration.
- It may take up to 5 minutes to run 2500 iterations.

```
parameters, costs = L_layer_model(train_x, train_y, layers_dims, num_iterations = 250
In [16]:
         0, print cost = True)
         Cost after iteration 0: 0.7717493284237686
         Cost after iteration 100: 0.6720534400822914
         Cost after iteration 200: 0.6482632048575212
         Cost after iteration 300: 0.6115068816101356
         Cost after iteration 400: 0.5670473268366111
         Cost after iteration 500: 0.5401376634547801
         Cost after iteration 600: 0.5279299569455267
         Cost after iteration 700: 0.4654773771766851
         Cost after iteration 800: 0.369125852495928
         Cost after iteration 900: 0.39174697434805344
         Cost after iteration 1000: 0.31518698886006163
         Cost after iteration 1100: 0.2726998441789385
         Cost after iteration 1200: 0.23741853400268137
         Cost after iteration 1300: 0.19960120532208644
         Cost after iteration 1400: 0.18926300388463307
         Cost after iteration 1500: 0.16118854665827753
         Cost after iteration 1600: 0.14821389662363316
         Cost after iteration 1700: 0.13777487812972944
         Cost after iteration 1800: 0.1297401754919012
         Cost after iteration 1900: 0.12122535068005211
         Cost after iteration 2000: 0.11382060668633713
         Cost after iteration 2100: 0.10783928526254133
         Cost after iteration 2200: 0.10285466069352679
         Cost after iteration 2300: 0.10089745445261786
         Cost after iteration 2400: 0.09287821526472398
         Cost after iteration 2499: 0.08843994344170202
```

Expected Output:

Cost after iteration 0 0.771749

Cost after iteration 100 0.672053

... ...

Cost after iteration 2499 0.088439

```
In [17]: pred_train = predict(train_x, train_y, parameters)
```

Accuracy: 0.9856459330143539

Expected Output:

Train Accuracy 0.985645933014

Expected Output:

Test Accuracy 0.8

Congrats! It seems that your 4-layer neural network has better performance (80%) than your 2-layer neural network (72%) on the same test set.

This is pretty good performance for this task. Nice job!

In the next course on "Improving deep neural networks," you'll be able to obtain even higher accuracy by systematically searching for better hyperparameters: learning rate, layers dims, or num iterations, for example.

6 - Results Analysis

First, take a look at some images the L-layer model labeled incorrectly. This will show a few mislabeled images.



A few types of images the model tends to do poorly on include:

- · Cat body in an unusual position
- Cat appears against a background of a similar color
- · Unusual cat color and species
- · Camera Angle
- · Brightness of the picture
- Scale variation (cat is very large or small in image)

Congratulations on finishing this assignment!

You just built and trained a deep L-layer neural network, and applied it in order to distinguish cats from non-cats, a very serious and important task in deep learning.;)

By now, you've also completed all the assignments for Course 1 in the Deep Learning Specialization. Amazing work! If you'd like to test out how closely you resemble a cat yourself, there's an optional ungraded exercise below, where you can test your own image.

Great work and hope to see you in the next course!

7 - Test with your own image (optional/ungraded exercise)

From this point, if you so choose, you can use your own image to test the output of your model. To do that follow these steps:

- 1. Click on "File" in the upper bar of this notebook, then click "Open" to go on your Coursera Hub.
- 2. Add your image to this Jupyter Notebook's directory, in the "images" folder
- 3. Change your image's name in the following code
- 4. Run the code and check if the algorithm is right (1 = cat, 0 = non-cat)!

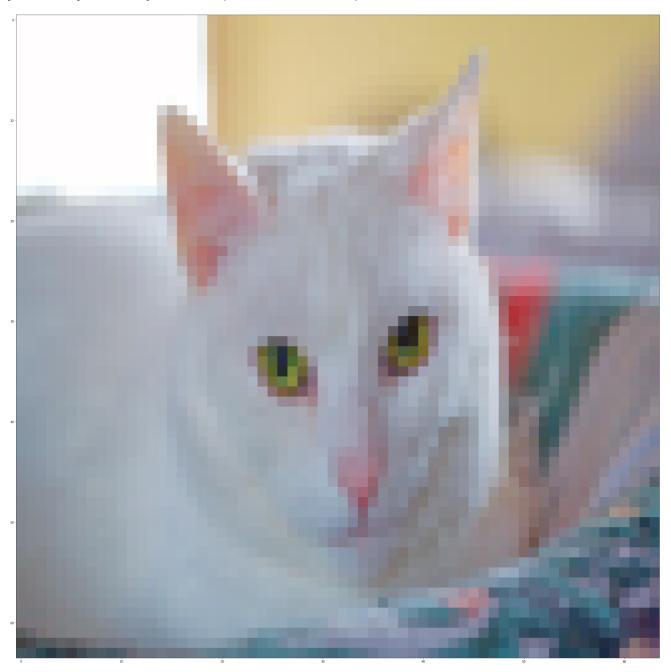
```
In [20]: ## START CODE HERE ##
my_image = "my_image.jpg" # change this to the name of your image file
my_label_y = [1] # the true class of your image (1 -> cat, 0 -> non-cat)
## END CODE HERE ##

fname = "images/" + my_image
image = np.array(Image.open(fname).resize((num_px, num_px)))
plt.imshow(image)
image = image / 255.
image = image.reshape((1, num_px * num_px * 3)).T

my_predicted_image = predict(image, my_label_y, parameters)

print ("y = " + str(np.squeeze(my_predicted_image)) + ", your L-layer model predicts
a \"" + classes[int(np.squeeze(my_predicted_image)),].decode("utf-8") + "\" pictur
e.")
```

Accuracy: 1.0 y = 1.0, your L-layer model predicts a "cat" picture.



References: • for auto-reloading external module: http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipython (http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipython)