

Modelling & Simulation

Microscopic Simulation and Digital Twin of Traffic Flow on Porto's VCI Inner-Ring

A data-driven approach to urban motorway modelling using SUMO and real sensor data

Group 13

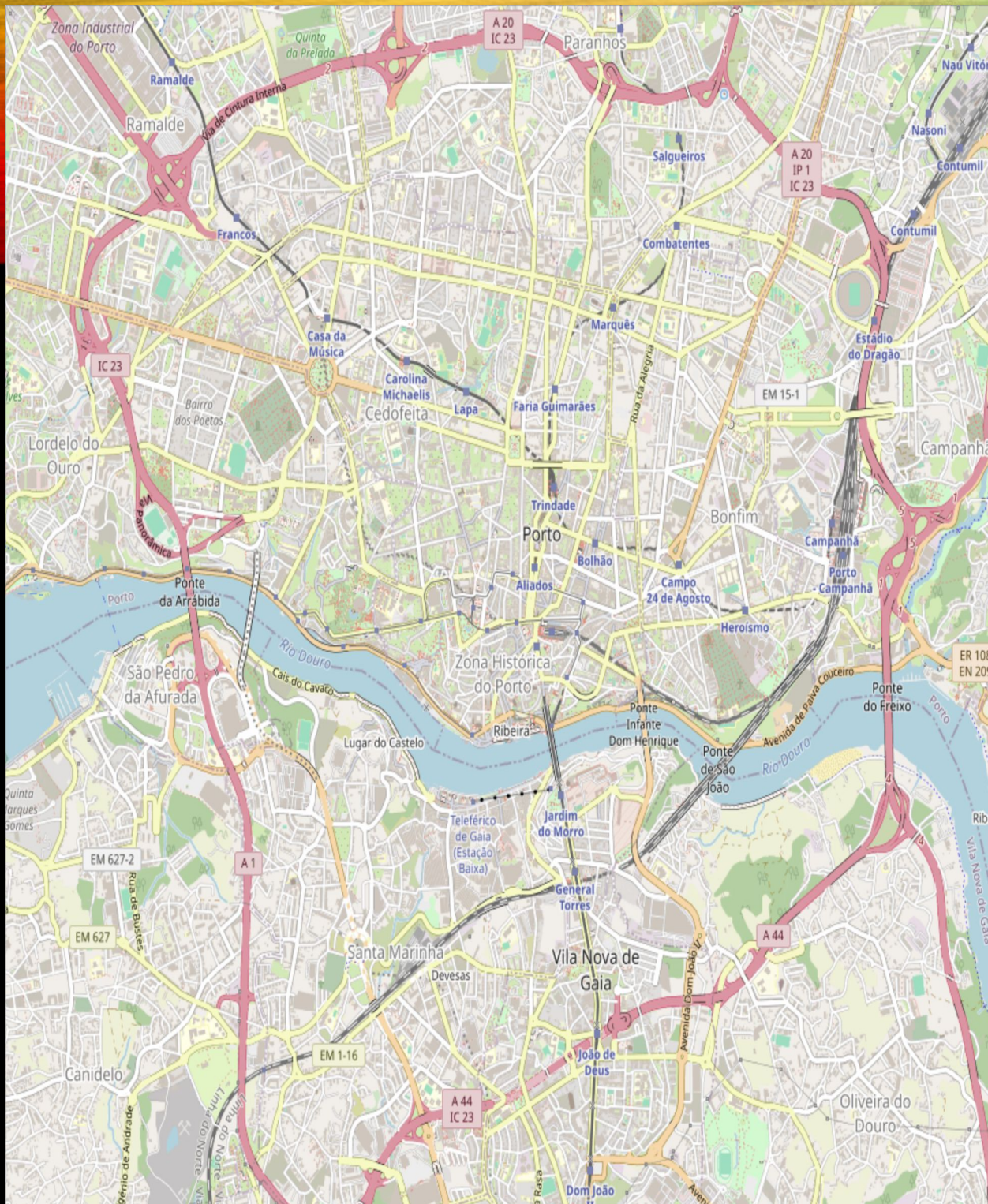
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Problem Description

The VCI (Via de Cintura Interna) is Porto's most critical urban ring motorway, facing significant operational challenges.

Current Challenges

- Frequent congestion and unstable traffic flow patterns
- High temporal variability in demand throughout the day
- Vast inductive-loop sensor data remains underutilised
- Traffic management is predominantly reactive

The Gap

Despite abundant sensor infrastructure, Porto lacks **predictive and descriptive digital twin models** capable of understanding and forecasting traffic behaviour on the VCI corridor.

Project Objectives

01

Build Digital Twin

Develop a microscopic simulation-based digital twin of the VCI inner-ring

02

Integrate Real Data

Utilise inductive-loop sensor data from 2013–2015 archives

03

Learn Behaviour

Implement data-driven vehicle behaviour learning in SUMO using a Multi-Armed Bandit Approach

04

Validate Accuracy

Assess simulation fidelity using quantitative KPIs

05

Enable Scalability

Deliver a descriptive simulation supporting understanding and visualization

System Model & Data Architecture /

Modelled Entities

Infrastructure: Road segments, ramps, lanes

Vehicle classes: Cars

System variables: Flow, speed, density, occupancy

Data Source

AEDL inductive-loop sensors capturing 5-minute interval measurements:
volume, speed, occupancy, and vehicle class ratios.

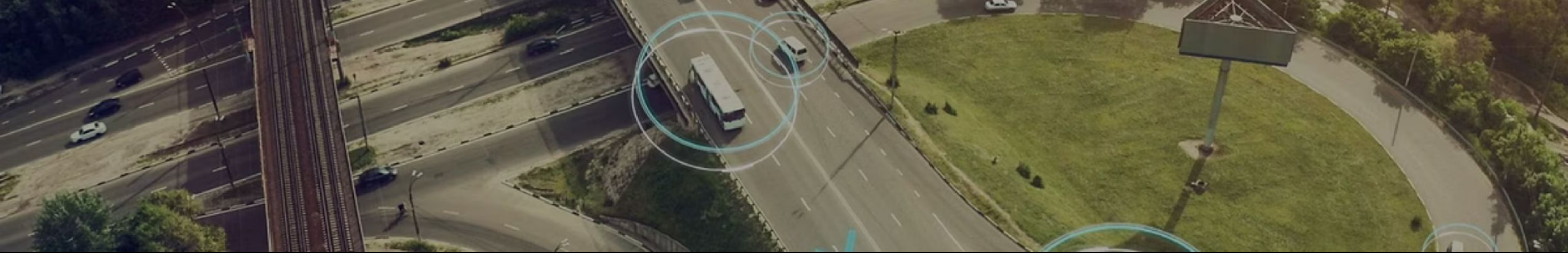


Inductive Loop

Raw Data

Preprocessing

Simulation



Methodology & Simulation Approach



Data Preprocessing

Python-based cleaning and transformation of sensor data



MAB Policy

Multi-Armed Bandit decision policy shared across entrances



SUMO Simulation

Microscopic traffic simulation with calibrated parameters



Evaluation

Continuous calibration to minimise real-simulated divergence

Experimental Setup

Temporal Scope

Data obtained from 2013 to 2015.

Traffic Scenarios

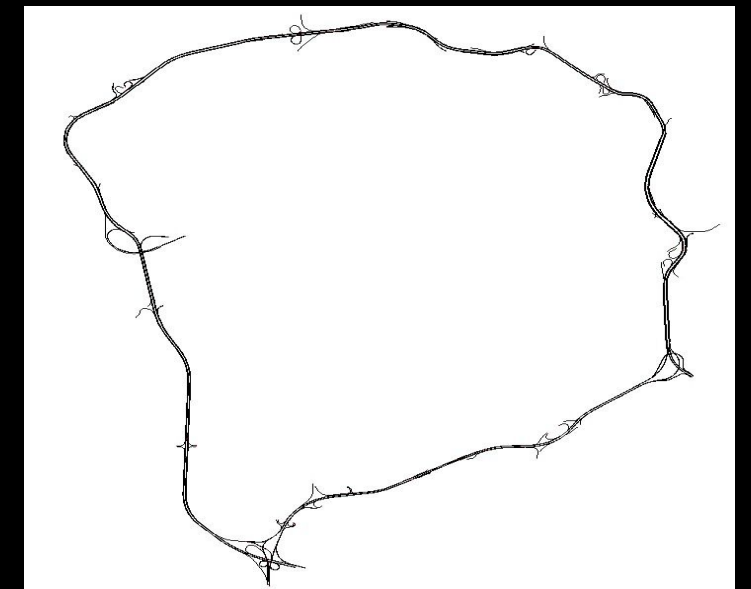
- **Baseline:** Average daily traffic conditions
- **Rush-hour:** Peak morning and evening periods

Key Points

- Missing data addressed via temporal interpolation
- Vehicle trajectories reconstructed from sensor observations
- Distinct training and validation periods defined
- MAB Approach with 1 arm per entrance.



Original Netedit



Final Netedit

Key Performance Indicators



Traffic Metrics

- Volume (veh/h)
- Traffic density
- Daily relative error



Statistical Accuracy

- SMAPE
- NRMSE, RMSE
- MAE



Validation

- Real vs simulated comparison
- Temporal consistency

Results

Data only Results:

MAE: 6.46

RMSE: 8.26

MAPE: 3.85%

The digital twin model only trained on data, successfully reproduced observed traffic patterns with strong correlation to real-world sensor measurements, while the digital twin model trained with SUMO shows a good learning behaviour

MAE	Daily Relative Error	RMSE	SMAPE	NRMSE
Baseline: 115,37				
Trained Model: 331,09	1.59	407.92	109%	2.21
Consistent with theoretical bandit convergence rates ($O(1/\sqrt{n})$)	Seasonal shifts not yet learned	Large errors dominate occasionally (daily traffic fluctuations)	Predictions off by the same order of magnitude	Confirms data variability dominates

Discussion

Strengths

- Data-driven approach improves realism over hand-crafted models
- Scalable framework for large networks
- Effective integration of MAB learning
- Possible strong validation against real measurements

Limitations

- Sensor sparsity constraints spatial resolution
- Trajectory reconstruction introduces uncertainty
- Simplified driver decision-making assumptions
- Historical data may not reflect current conditions
- SUMO simulation training is very computationally expensive.



Conclusions & Future Work

Key Achievements

- Successfully demonstrated microscopic digital twin for VCI
- Validated realism using real-world sensor data
- Supports traffic understanding and visualisation
- Established foundation for predictive systems

Future Directions

- Real-time data streaming integration
- Predictive congestion modelling
- Prescriptive traffic control strategies
- Advanced reinforcement learning approaches

