A I ADAJL	CODING	IABL	_				EZHU	<u>U/Huar</u>
Path	Waypoint	Fly	Magnetic	Turn	Altitude	IAS	VPA/TCH	Navigatio
Terminator	ID	over	Course(°)	Direction	(m)	(kt)	VI A/ ICII	Specificati
		RW	Y01L/01R Ho	olding(Outbour	nd Time:1min)		
НМ	AGUXI	Υ	195	L	2700	MAX205		RNAV1
НМ	XSH	Υ	207	L	2400	MAX205		RNAV1
НМ	EC417	Y	237	R	2400	MAX205		RNAV1
	·	RWY01L	/01R/19L/19	R Holding(Out	tbound Time:	1min)		
НМ	EC514	Y	343	R	3600	MAX230		RNAV1
		RW	Y19L/19R Ho	olding(Outbour	nd Time:1min)		
НМ	EC522	Y	263	L	1500	MAX205		RNAV1
НМ	XSH	Y	343	R	1500	MAX205		RNAV1
			RWY01L Appr	oach Transit	ion EC403			
IF	EC403				700	MAX205		RNAV1
TF	EC402				700			RNAV1
	·		RWY01L Appı	roach Transit	ion EC414			
IF	EC414				900	MAX205		RNAV1
TF	EC402				700			RNAV1
	•	RWY	'01L Missed	Approach RN.	AV ILS/DME	Z		
CA			015		250			RNAV1
DF	AGUXI			L	900	MAX205		RNAV1
	•	RWY01L N	Missed Appro	ach Holding((Outbound Tim	ie:1min)		
НМ	AGUXI	Υ	195	L	900	MAX205		RNAV1
,	<u>'</u>	1	RWY01R Appr	roach Transit	ion EC403		1	'
IF	EC403				900	MAX205		RNAV1
TF	EC413				900			RNAV1
,			RWY01R App	roach Transi	tion EC414		1	-
IF	EC414				900	MAX205		RNAV1
TF	EC413				900			RNAV1
	-	RWY	01R Missed	Approach RN	AV ILS/DME	Z		
CA			015		250			RNAV1
DF	XSH			R	1200	MAX205		RNAV1
	•	RWY01R N	Missed Appro	ach Holding((Outbound Tim	ne:1min)		
НМ	XSH	Υ	207	L	1200	MAX205		RNAV1
	'		RWY19L App	oroach Trans	ition XGD			
IF	XGD				1200	MAX205		RNAV1
TF	EC512				900			RNAV1
	1		RWY19L App	roach Transit	ion EC513	•	•	•
IF	EC513				900	MAX205		RNAV1
TF	EC512				900			RNAV1
	1	RWY	19L Missed	Approach RN.	AV ILS/DME	Z	•	•
CA			195		300			RNAV1
Changes: New Ch	art.							