

VARIATIONAL BAYESIAN MONTE CARLO

Luigi Acerbi

Department of Basic Neuroscience
University of Geneva

Nov 26, 2018

- 1 Introduction and motivation
- 2 Background Tools
- 3 Variational Bayesian Monte Carlo
- 4 Experiments

- 1 Introduction and motivation
- 2 Background Tools
- 3 Variational Bayesian Monte Carlo
- 4 Experiments

Goal

Bayesian inference with expensive black-box statistical models

Goal

Bayesian inference with expensive black-box **statistical models**

- Likelihood: $p(\mathcal{D}|\mathbf{x})$ (data \mathcal{D} , parameters $\mathbf{x} \in \mathcal{X} \subseteq \mathbb{R}^D$)

Goal

Bayesian inference with expensive **black-box** statistical models

- Likelihood: $p(\mathcal{D}|\mathbf{x})$ (data \mathcal{D} , parameters $\mathbf{x} \in \mathcal{X} \subseteq \mathbb{R}^D$)
- No detailed information (e.g., no gradient)

Goal

Bayesian inference with **expensive** black-box statistical models

- Likelihood: $p(\mathcal{D}|\mathbf{x})$ (data \mathcal{D} , parameters $\mathbf{x} \in \mathcal{X} \subseteq \mathbb{R}^D$)
- No detailed information (e.g., no gradient)
- ~ 500 – 1000 likelihood evaluations

Goal

Bayesian inference with expensive black-box statistical models

- Likelihood: $p(\mathcal{D}|\mathbf{x})$ (data \mathcal{D} , parameters $\mathbf{x} \in \mathcal{X} \subseteq \mathbb{R}^D$)
- No detailed information (e.g., no gradient)
- ~ 500 – 1000 likelihood evaluations

Posterior: $p(\mathbf{x}|\mathcal{D}) = \frac{p(\mathcal{D}|\mathbf{x})p(\mathbf{x})}{p(\mathcal{D})}$ (in usable form)

Marginal likelihood: $p(\mathcal{D}) = \int p(\mathcal{D}|\mathbf{x})p(\mathbf{x})d\mathbf{x}$

Goal

Bayesian inference with expensive black-box statistical models

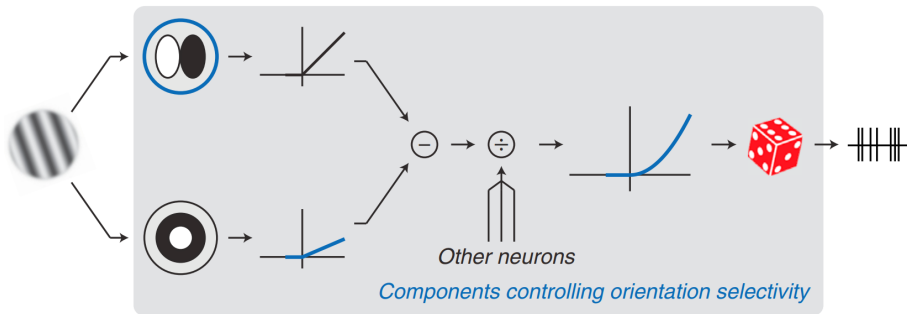
- Likelihood: $p(\mathcal{D}|\mathbf{x})$ (data \mathcal{D} , parameters $\mathbf{x} \in \mathcal{X} \subseteq \mathbb{R}^D$)
- No detailed information (e.g., no gradient)
- ~ 500 – 1000 likelihood evaluations

Posterior: $p(\mathbf{x}|\mathcal{D}) = \frac{p(\mathcal{D}|\mathbf{x})p(\mathbf{x})}{p(\mathcal{D})}$ (in usable form)

Marginal likelihood: $p(\mathcal{D}) = \int p(\mathcal{D}|\mathbf{x})p(\mathbf{x})d\mathbf{x}$

(Why Bayesian inference?)

Example: LN-LN neuronal model



from Goris et al., *Neuron* (2015)

Problem

Bayesian inference with expensive black-box statistical models?

Problem

Bayesian inference with expensive black-box statistical models?

Standard approximate Bayesian inference methods

- Markov Chain Monte Carlo (MCMC)
- Variational inference (VI)

Problem

Bayesian inference with **expensive** black-box statistical models?

Standard approximate Bayesian inference methods

- Markov Chain Monte Carlo (MCMC)
- Variational inference (VI)

require

- many likelihood evaluations

Problem

Bayesian inference with expensive **black-box** statistical models?

Standard approximate Bayesian inference methods

- Markov Chain Monte Carlo (MCMC)
- Variational inference (VI)

require

- many likelihood evaluations
- knowledge of the model (e.g., gradients, detailed structure)

Sketch solution

Bayesian inference with expensive black-box statistical models?

Sketch solution

Bayesian inference with expensive black-box statistical models?

- Fit *surrogate model* to likelihood evaluations

Sketch solution

Bayesian inference with expensive black-box statistical models?

- Fit *surrogate model* to likelihood evaluations
- Perform *approximate inference* with surrogate model

Sketch solution

Bayesian inference with expensive black-box statistical models?

- Fit *surrogate model* to likelihood evaluations
- Perform *approximate inference* with surrogate model
- Use *active sampling* to smartly evaluate likelihood landscape

What do we need?

- An *approximate inference* framework
- A *surrogate model*
- A method to combine the two

What do we need?

- An *approximate inference* framework: **variational inference**
- A *surrogate model*: **Gaussian processes**
- A method to combine the two: **Bayesian quadrature**

- 1 Introduction and motivation
- 2 Background Tools**
- 3 Variational Bayesian Monte Carlo
- 4 Experiments

Variational inference

- Approximate $p(\mathbf{x}|\mathcal{D})$ with $q_{\phi}(\mathbf{x})$

Variational inference

- Approximate $p(\mathbf{x}|\mathcal{D})$ with $q_\phi(\mathbf{x})$
- Minimize $\text{KL}[q_\phi(\mathbf{x})||p(\mathbf{x}|\mathcal{D})] = \mathbb{E}_{q_\phi} \left[\log \frac{q_\phi(\mathbf{x})}{p(\mathbf{x}|\mathcal{D})} \right]$

Variational inference

- Approximate $p(\mathbf{x}|\mathcal{D})$ with $q_\phi(\mathbf{x})$
- Minimize $\text{KL}[q_\phi(\mathbf{x})||p(\mathbf{x}|\mathcal{D})] = \mathbb{E}_{q_\phi} \left[\log \frac{q_\phi(\mathbf{x})}{p(\mathbf{x}|\mathcal{D})} \right]$

$$\Rightarrow \text{Maximize ELBO}(\phi) = \underbrace{\mathbb{E}_{q_\phi} [\log p(\mathcal{D}|\mathbf{x})p(\mathbf{x})]}_{\text{expected log joint}} + \underbrace{\mathcal{H}[q_\phi(\mathbf{x})]}_{\text{entropy}}$$

Variational inference

- Approximate $p(\mathbf{x}|\mathcal{D})$ with $q_\phi(\mathbf{x})$
- Minimize $\text{KL}[q_\phi(\mathbf{x})||p(\mathbf{x}|\mathcal{D})] = \mathbb{E}_{q_\phi} \left[\log \frac{q_\phi(\mathbf{x})}{p(\mathbf{x}|\mathcal{D})} \right]$

$$\implies \text{Maximize ELBO}(\phi) = \underbrace{\mathbb{E}_{q_\phi} [\log p(\mathcal{D}|\mathbf{x})p(\mathbf{x})]}_{\text{expected log joint}} + \underbrace{\mathcal{H}[q_\phi(\mathbf{x})]}_{\text{entropy}} \leq \log p(\mathcal{D})$$

Variational inference

- Approximate $p(\mathbf{x}|\mathcal{D})$ with $q_\phi(\mathbf{x})$
- Minimize $\text{KL}[q_\phi(\mathbf{x})||p(\mathbf{x}|\mathcal{D})] = \mathbb{E}_{q_\phi} \left[\log \frac{q_\phi(\mathbf{x})}{p(\mathbf{x}|\mathcal{D})} \right]$

$$\implies \text{Maximize ELBO}(\phi) = \underbrace{\mathbb{E}_{q_\phi} [\log p(\mathcal{D}|\mathbf{x})p(\mathbf{x})]}_{\text{expected log joint}} + \underbrace{\mathcal{H}[q_\phi(\mathbf{x})]}_{\text{entropy}} \leq \log p(\mathcal{D})$$

Obtains

- An approximate posterior $q_\phi(\mathbf{x})$
- A lower bound to the log marginal likelihood, $\text{ELBO}(\phi)$

Variational inference

- Approximate $p(\mathbf{x}|\mathcal{D})$ with $q_\phi(\mathbf{x})$
- Minimize $\text{KL}[q_\phi(\mathbf{x})||p(\mathbf{x}|\mathcal{D})] = \mathbb{E}_{q_\phi} \left[\log \frac{q_\phi(\mathbf{x})}{p(\mathbf{x}|\mathcal{D})} \right]$

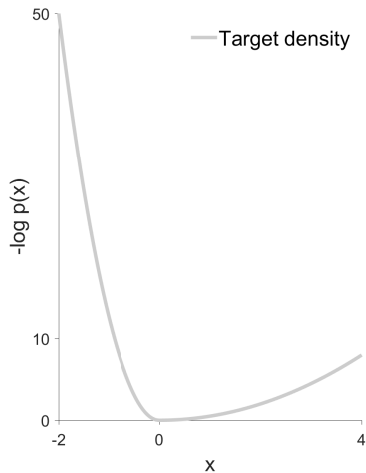
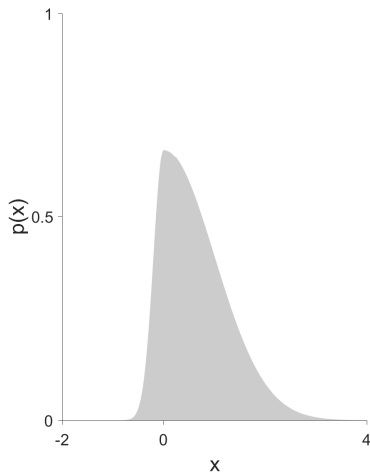
$$\implies \text{Maximize ELBO}(\phi) = \underbrace{\mathbb{E}_{q_\phi} [\log p(\mathcal{D}|\mathbf{x})p(\mathbf{x})]}_{\text{expected log joint}} + \underbrace{\mathcal{H}[q_\phi(\mathbf{x})]}_{\text{entropy}} \leq \log p(\mathcal{D})$$

Obtains

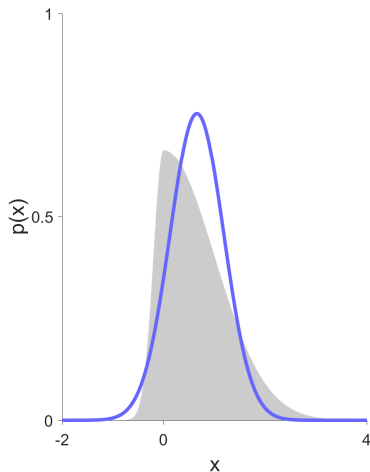
- An approximate posterior $q_\phi(\mathbf{x})$
- A lower bound to the log marginal likelihood, $\text{ELBO}(\phi)$

VI casts Bayesian inference into optimization + integration

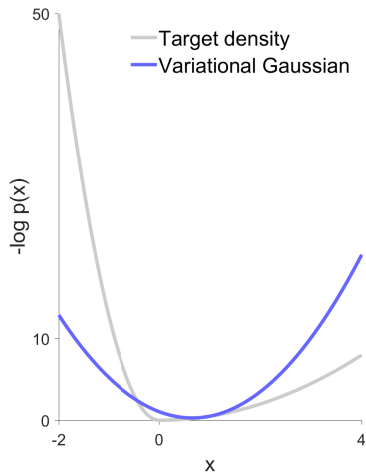
Variational inference: example



Variational inference: example

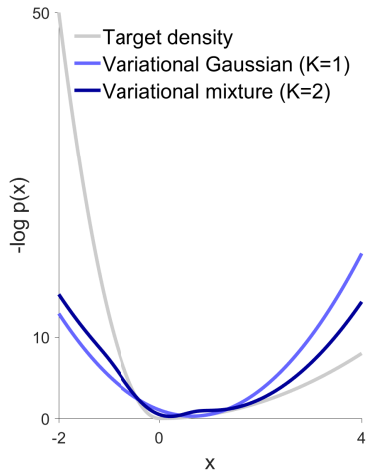
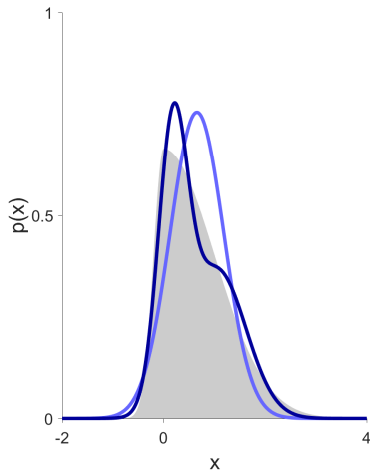


$$q_{\phi}(x) = \mathcal{N}(x, \mu, \sigma^2)$$



$$\phi = (\mu, \sigma^2)$$

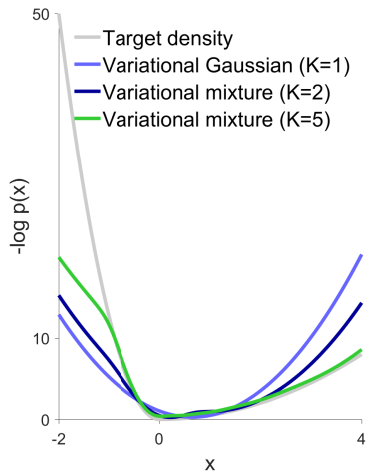
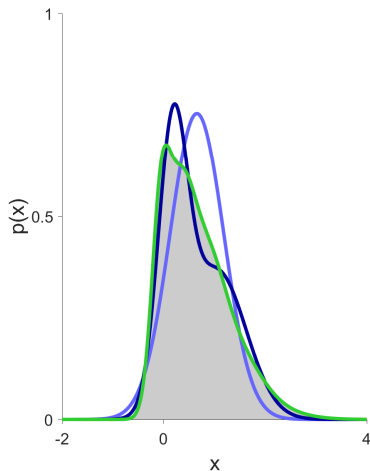
Variational inference: example



$$q_{\phi}(x) = \sum_{k=1}^K w_k \mathcal{N}(x, \mu_k, \sigma_k^2)$$

$$\phi = (w_k, \mu_k, \sigma_k^2)_{k=1}^K$$

Variational inference: example



$$q_{\phi}(x) = \sum_{k=1}^K w_k \mathcal{N}(x, \mu_k, \sigma_k^2)$$

$$\phi = (w_k, \mu_k, \sigma_k^2)_{k=1}^K$$

Gaussian Processes (GPs)

GPs used as *priors* over $f : \mathcal{X} \subseteq \mathbb{R}^D \rightarrow \mathbb{R}$

Gaussian Processes (GPs)

GPs used as *priors* over $f : \mathcal{X} \subseteq \mathbb{R}^D \rightarrow \mathbb{R}$

- mean function $m : \mathcal{X} \rightarrow \mathbb{R}$
 - ▶ zero, constant, polynomial...

Gaussian Processes (GPs)

GPs used as *priors* over $f : \mathcal{X} \subseteq \mathbb{R}^D \rightarrow \mathbb{R}$

- mean function $m : \mathcal{X} \rightarrow \mathbb{R}$
 - ▶ zero, constant, polynomial. . .
- covariance function $\kappa : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$
 - ▶ exponentiated quadratic $\kappa_{EQ}(\mathbf{x}, \mathbf{x}') = \sigma_f^2 \exp \left[-\frac{1}{2} \sum_i \frac{(x_i - x'_i)^2}{\ell_i^2} \right]$

Gaussian Processes (GPs)

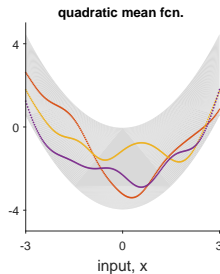
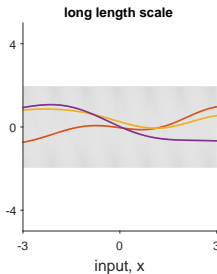
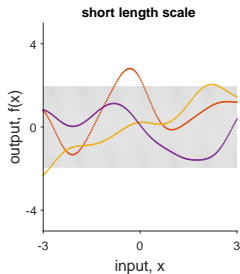
GPs used as *priors* over $f : \mathcal{X} \subseteq \mathbb{R}^D \rightarrow \mathbb{R}$

- mean function $m : \mathcal{X} \rightarrow \mathbb{R}$
 - ▶ zero, constant, polynomial. . .
- covariance function $\kappa : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$
 - ▶ exponentiated quadratic $\kappa_{EQ}(\mathbf{x}, \mathbf{x}') = \sigma_f^2 \exp \left[-\frac{1}{2} \sum_i \frac{(x_i - x'_i)^2}{\ell_i^2} \right]$
- observation function
 - ▶ Gaussian (\sim small numerical noise σ_{obs}^2)

Gaussian Processes (GPs)

GPs used as *priors* over $f : \mathcal{X} \subseteq \mathbb{R}^D \rightarrow \mathbb{R}$

- mean function $m : \mathcal{X} \rightarrow \mathbb{R}$
 - ▶ zero, constant, polynomial...
- covariance function $\kappa : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$
 - ▶ exponentiated quadratic $\kappa_{EQ}(\mathbf{x}, \mathbf{x}') = \sigma_f^2 \exp \left[-\frac{1}{2} \sum_i \frac{(x_i - x'_i)^2}{\ell_i^2} \right]$
- observation function
 - ▶ Gaussian (\sim small numerical noise σ_{obs}^2)



Posterior GPs

Training inputs $\mathbf{X} = (\mathbf{x}_1, \dots, \mathbf{x}_n)$

Observed values $\mathbf{y} = (y_1 = f(\mathbf{x}_1), \dots, y_n = f(\mathbf{x}_n))$

GP hyperparameters $\psi = (\sigma_f, \ell, \sigma_{\text{obs}}, m_0, \dots)$

Posterior GPs

Training inputs $\mathbf{X} = (\mathbf{x}_1, \dots, \mathbf{x}_n)$

Observed values $\mathbf{y} = (y_1 = f(\mathbf{x}_1), \dots, y_n = f(\mathbf{x}_n))$

GP hyperparameters $\boldsymbol{\psi} = (\sigma_f, \ell, \sigma_{\text{obs}}, m_0, \dots)$

Posterior mean $\bar{f}(\mathbf{X}^*; \mathbf{X}, \mathbf{y}, \boldsymbol{\psi}) = \kappa(\mathbf{X}, \mathbf{X}^*) [\kappa(\mathbf{X}, \mathbf{X}) + \sigma_{\text{obs}}^2 \mathbf{I}_n]^{-1} \mathbf{y}$

Posterior covariance $C(\mathbf{X}^*; \mathbf{X}, \mathbf{y}, \boldsymbol{\psi}) = \text{analytical expression}$

Posterior GPs

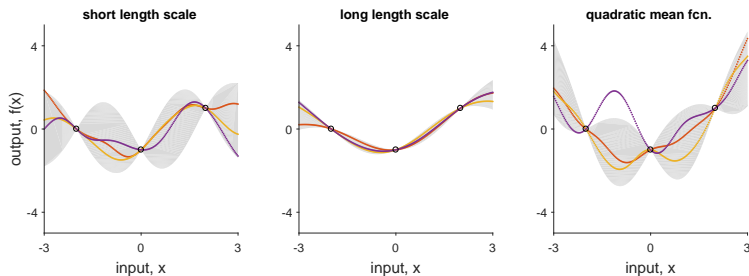
Training inputs $\mathbf{X} = (\mathbf{x}_1, \dots, \mathbf{x}_n)$

Observed values $\mathbf{y} = (y_1 = f(\mathbf{x}_1), \dots, y_n = f(\mathbf{x}_n))$

GP hyperparameters $\boldsymbol{\psi} = (\sigma_f, \ell, \sigma_{\text{obs}}, m_0, \dots)$

Posterior mean $\bar{f}(\mathbf{X}^*; \mathbf{X}, \mathbf{y}, \boldsymbol{\psi}) = \kappa(\mathbf{X}, \mathbf{X}^*) [\kappa(\mathbf{X}, \mathbf{X}) + \sigma_{\text{obs}}^2 \mathbf{I}_n]^{-1} \mathbf{y}$

Posterior covariance $C(\mathbf{X}^*; \mathbf{X}, \mathbf{y}, \boldsymbol{\psi}) = \text{analytical expression}$



Posterior GPs

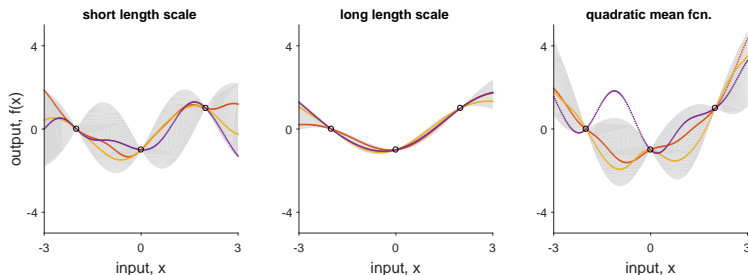
Training inputs $\mathbf{X} = (\mathbf{x}_1, \dots, \mathbf{x}_n)$

Observed values $\mathbf{y} = (y_1 = f(\mathbf{x}_1), \dots, y_n = f(\mathbf{x}_n))$

GP hyperparameters $\boldsymbol{\psi} = (\sigma_f, \ell, \sigma_{\text{obs}}, m_0, \dots)$

Posterior mean $\bar{f}(\mathbf{X}^*; \mathbf{X}, \mathbf{y}, \boldsymbol{\psi}) = \kappa(\mathbf{X}, \mathbf{X}^*) [\kappa(\mathbf{X}, \mathbf{X}) + \sigma_{\text{obs}}^2 \mathbf{I}_n]^{-1} \mathbf{y}$

Posterior covariance $C(\mathbf{X}^*; \mathbf{X}, \mathbf{y}, \boldsymbol{\psi}) = \text{analytical expression}$



GP marginal likelihood $p(\mathbf{y}|\mathbf{X}, \boldsymbol{\psi})$

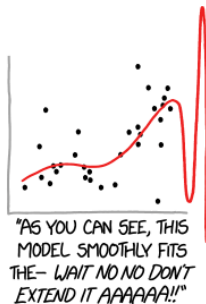
Why don't we use GPs *all the time*

Why don't we use GPs *all the time*

- Computation of $[\kappa(\mathbf{X}, \mathbf{X}) + \sigma_{\text{obs}}^2 \mathbf{I}_n]^{-1}$ is $O(n^3)$

Why don't we use GPs *all the time*

- Computation of $[\kappa(\mathbf{X}, \mathbf{X}) + \sigma_{\text{obs}}^2 \mathbf{I}_n]^{-1}$ is $O(n^3)$
- Model mismatch



from xkcd.com/2048

Bayesian Quadrature (BQ)

Evaluate integral of (expensive) black-box functions

Bayesian Quadrature (BQ)

Evaluate integral of (expensive) black-box functions

$$Z = \int p(\mathbf{x})f(\mathbf{x})d\mathbf{x}$$

Bayesian Quadrature (BQ)

Evaluate integral of (expensive) black-box functions

$$Z = \int p(\mathbf{x})f(\mathbf{x})d\mathbf{x}$$

- $p(\mathbf{x})$ is Gaussian
- $f(\mathbf{x})$ approximated via a GP with EQ covariance

Bayesian Quadrature (BQ)

Evaluate integral of (expensive) black-box functions

$$Z = \int p(\mathbf{x})f(\mathbf{x})d\mathbf{x}$$

- $p(\mathbf{x})$ is Gaussian
 - $f(\mathbf{x})$ approximated via a GP with EQ covariance
- \implies posterior Z can be computed analytically

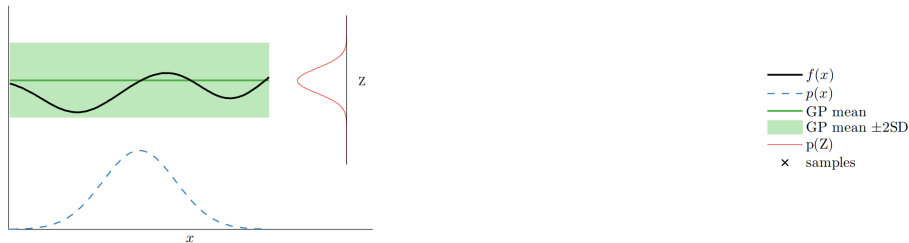
Bayesian Quadrature (BQ)

Evaluate integral of (expensive) black-box functions

$$Z = \int p(x) f(x) dx$$

- $p(x)$ is Gaussian
- $f(x)$ approximated via a GP with EQ covariance

\Rightarrow posterior Z can be computed analytically



from Duvenaud, *NIPS workshop on Probabilistic Numerics* (2012)

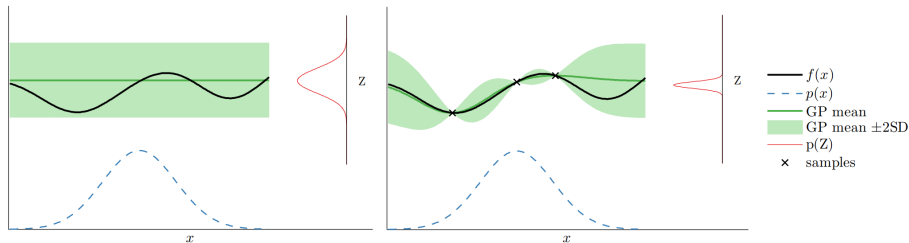
Bayesian Quadrature (BQ)

Evaluate integral of (expensive) black-box functions

$$Z = \int p(x) f(x) dx$$

- $p(x)$ is Gaussian
- $f(x)$ approximated via a GP with EQ covariance

\Rightarrow posterior Z can be computed analytically



from Duvenaud, *NIPS workshop on Probabilistic Numerics* (2012)

BQ for Bayesian inference (previous work)

Evaluate marginal likelihood of (expensive) black-box functions

BQ for Bayesian inference (previous work)

Evaluate marginal likelihood of (expensive) black-box functions

- Bayesian Monte Carlo (BMC), Rasmussen and Ghahramani, *NIPS* (2003)
- Doubly-Bayesian quadrature (BBQ), Osborne et al., *NIPS* (2012)
- Warped seq. active Bayesian integration (WSABI), Gunter et al., *NIPS* (2014)

BQ for Bayesian inference (previous work)

Evaluate marginal likelihood of (expensive) black-box functions

- Bayesian Monte Carlo (BMC), Rasmussen and Ghahramani, *NIPS* (2003)
- Doubly-Bayesian quadrature (BBQ), Osborne et al., *NIPS* (2012)
- Warped seq. active Bayesian integration (WSABI), Gunter et al., *NIPS* (2014)

Active sampling

BQ for Bayesian inference (previous work)

Evaluate marginal likelihood of (expensive) black-box functions

- Bayesian Monte Carlo (BMC), Rasmussen and Ghahramani, *NIPS* (2003)
- Doubly-Bayesian quadrature (BBQ), Osborne et al., *NIPS* (2012)
- Warped seq. active Bayesian integration (WSABI), Gunter et al., *NIPS* (2014)

Active sampling

- Minimize expected variance of integral Z

BQ for Bayesian inference (previous work)

Evaluate marginal likelihood of (expensive) black-box functions

- Bayesian Monte Carlo (BMC), Rasmussen and Ghahramani, *NIPS* (2003)
- Doubly-Bayesian quadrature (BBQ), Osborne et al., *NIPS* (2012)
- Warped seq. active Bayesian integration (WSABI), Gunter et al., *NIPS* (2014)

Active sampling

- Minimize expected variance of integral Z
- *Uncertainty sampling*: Maximize variance of integrand $p(\mathbf{x})f(\mathbf{x})$

Putting things together

Putting things together

- Variational inference:

$$\begin{aligned} q_{\phi}(\mathbf{x}) &= \operatorname{argmax}_{\phi} \operatorname{ELBO}(\phi) \\ &= \operatorname{argmax}_{\phi} \left\{ \int q_{\phi}(\mathbf{x}) \log [p(\mathcal{D}|\mathbf{x})p(\mathbf{x})] d\mathbf{x} + \mathcal{H}[q_{\phi}(\mathbf{x})] \right\} \end{aligned}$$

Putting things together

- Variational inference:

$$\begin{aligned} q_\phi(\mathbf{x}) &= \operatorname{argmax}_\phi \operatorname{ELBO}(\phi) \\ &= \operatorname{argmax}_\phi \left\{ \int q_\phi(\mathbf{x}) \log [p(\mathcal{D}|\mathbf{x})p(\mathbf{x})] d\mathbf{x} + \mathcal{H}[q_\phi(\mathbf{x})] \right\} \end{aligned}$$

- Bayesian quadrature:

$$Z = \int q(\mathbf{x}) f(\mathbf{x}) d\mathbf{x}$$

Putting things together

- Variational inference:

$$\begin{aligned} q_{\phi}(\mathbf{x}) &= \operatorname{argmax}_{\phi} \operatorname{ELBO}(\phi) \\ &= \operatorname{argmax}_{\phi} \left\{ \int q_{\phi}(\mathbf{x}) \log [p(\mathcal{D}|\mathbf{x})p(\mathbf{x})] d\mathbf{x} + \mathcal{H}[q_{\phi}(\mathbf{x})] \right\} \end{aligned}$$

- Bayesian quadrature:

$$Z = \int q(\mathbf{x}) f(\mathbf{x}) d\mathbf{x}$$

Putting things together

- Variational inference:

$$\begin{aligned} q_{\phi}(\mathbf{x}) &= \operatorname{argmax}_{\phi} \operatorname{ELBO}(\phi) \\ &= \operatorname{argmax}_{\phi} \left\{ \int q_{\phi}(\mathbf{x}) \log [p(\mathcal{D}|\mathbf{x})p(\mathbf{x})] d\mathbf{x} + \mathcal{H}[q_{\phi}(\mathbf{x})] \right\} \end{aligned}$$

- Bayesian quadrature:

$$Z = \int q(\mathbf{x}) f(\mathbf{x}) d\mathbf{x}$$

$$\text{VI} + \text{BQ} \Rightarrow \text{VBMC}$$

- 1 Introduction and motivation
- 2 Background Tools
- 3 Variational Bayesian Monte Carlo**
- 4 Experiments

VBMC in a nutshell

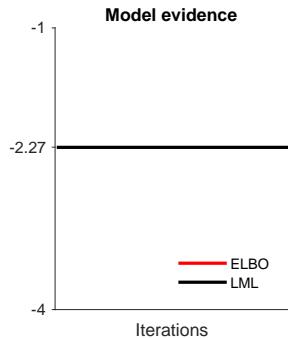
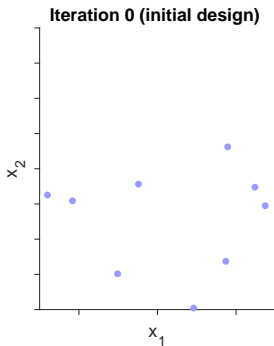
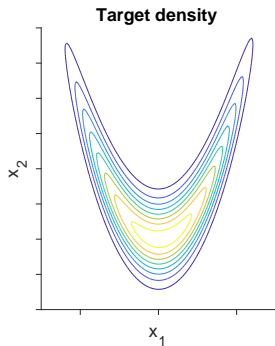
In each iteration t :

- 1 (Actively) sample new points, evaluate $f = \log p(\mathcal{D}|\mathbf{x}_{\text{new}})p(\mathbf{x}_{\text{new}})$
- 2 train GP model of the log joint f
- 3 update variational posterior q_{ϕ_t} by optimizing the ELBO

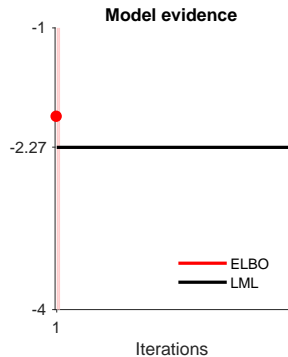
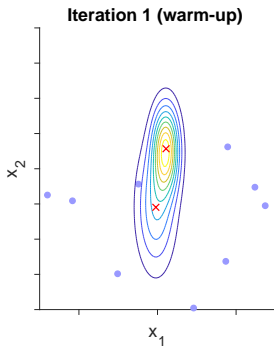
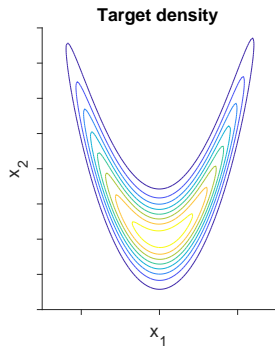
Loop until reaching termination criterion

Acerbi, *NeurIPS* (2018)

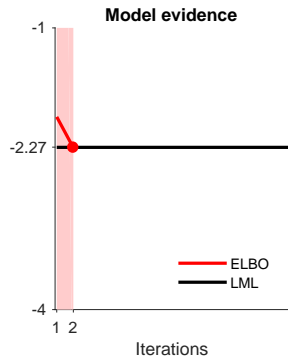
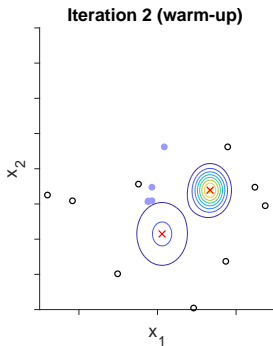
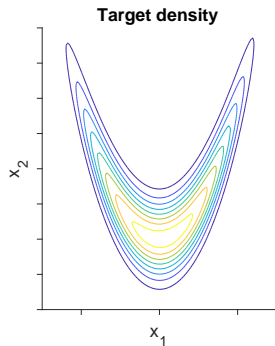
VBMC demo



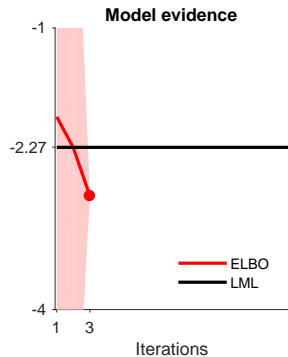
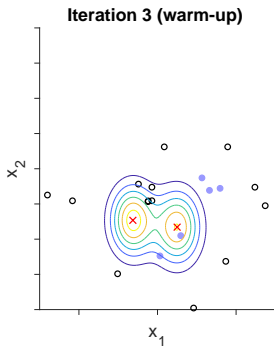
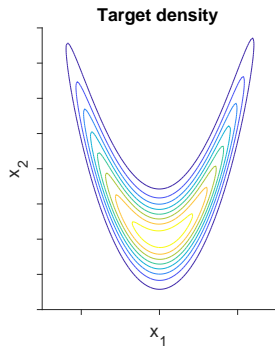
VBMC demo



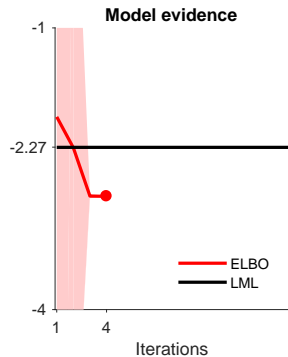
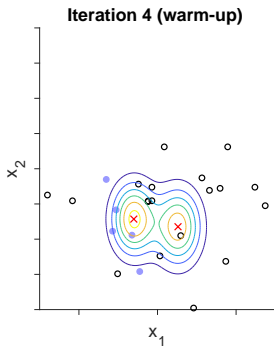
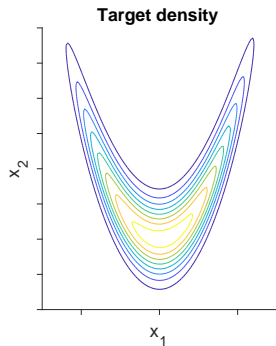
VBMC demo



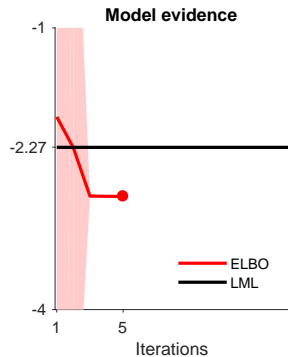
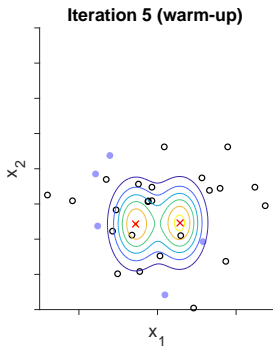
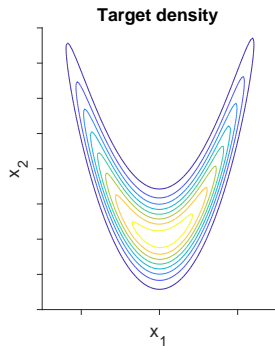
VBMC demo



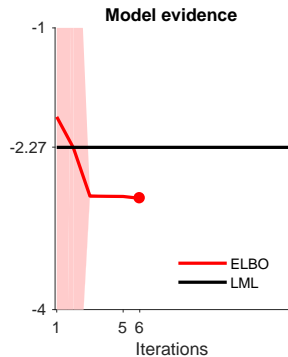
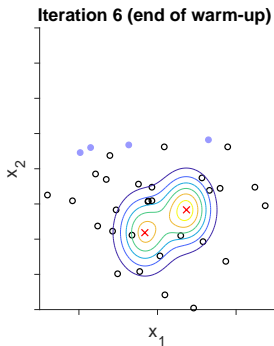
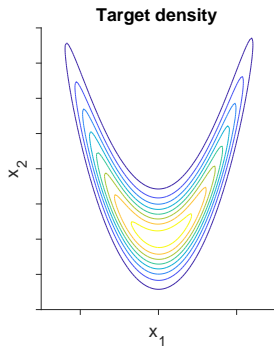
VBMC demo



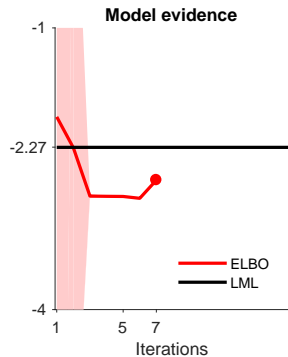
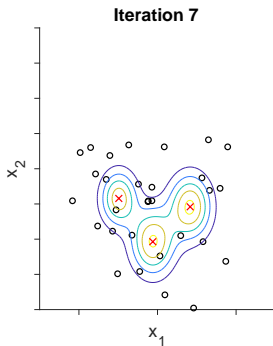
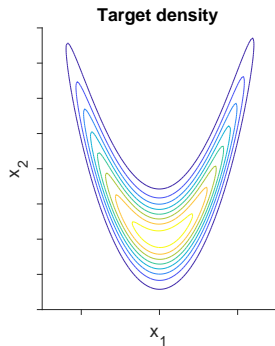
VBMC demo



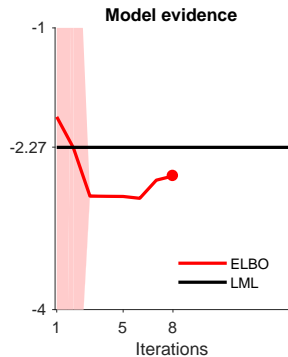
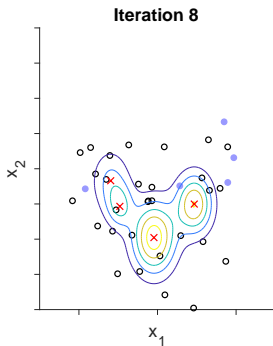
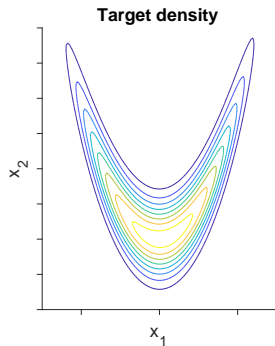
VBMC demo



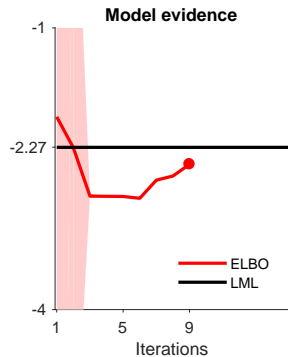
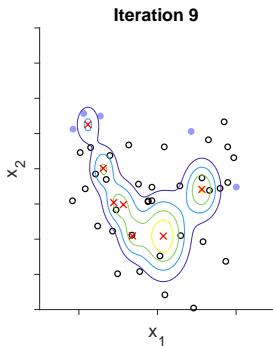
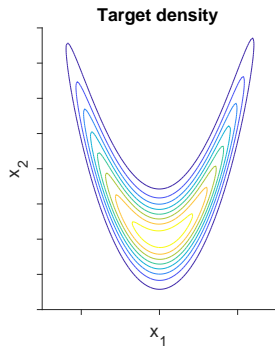
VBMC demo



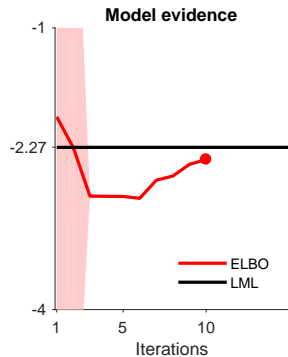
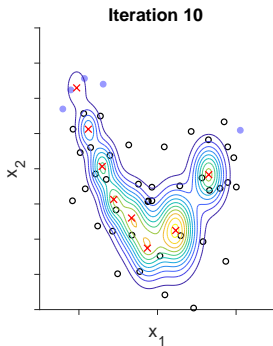
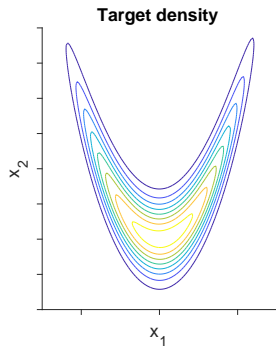
VBMC demo



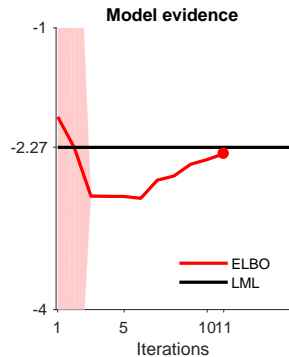
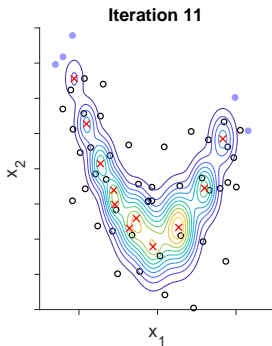
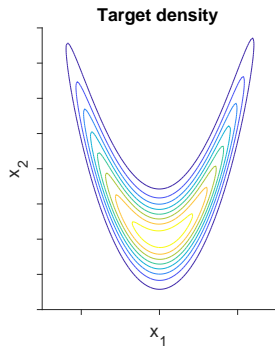
VBMC demo



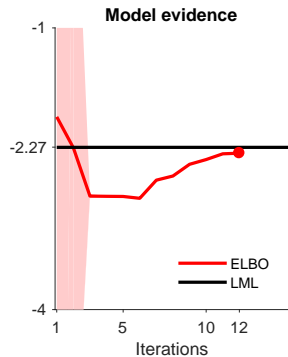
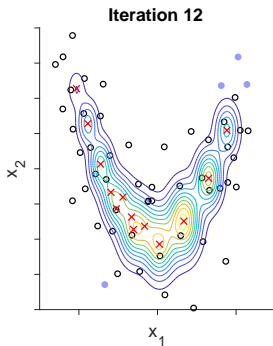
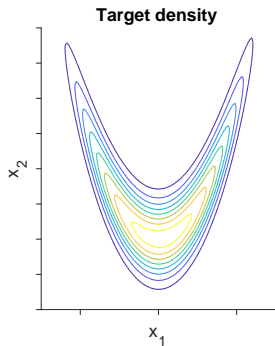
VBMC demo



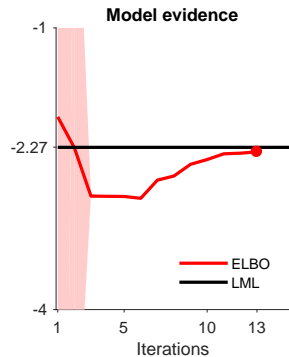
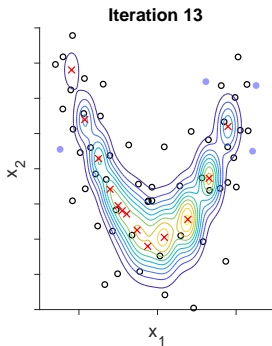
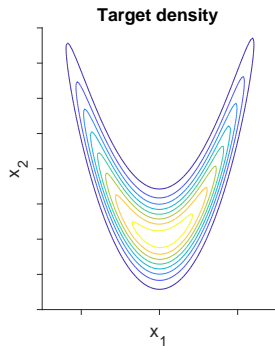
VBMC demo



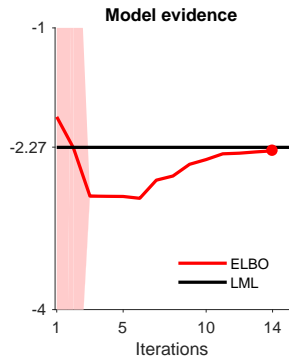
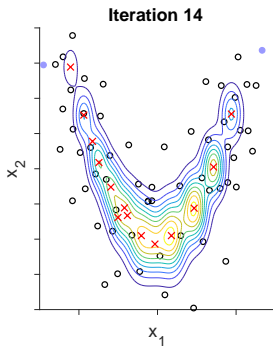
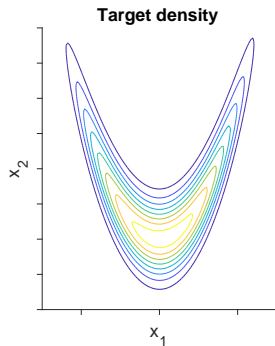
VBMC demo



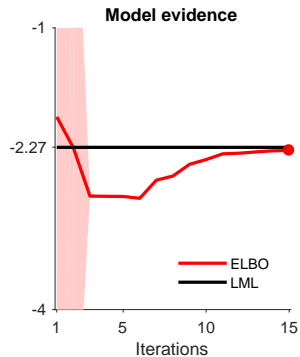
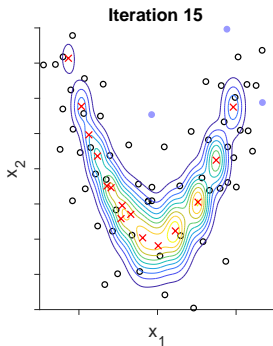
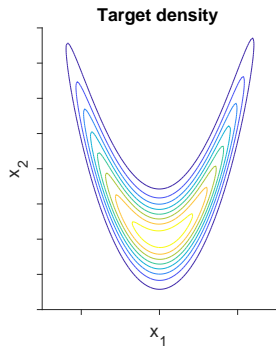
VBMC demo



VBMC demo



VBMC demo



Variational posterior

$$q_{\phi}(\mathbf{x}) = \sum_{k=1}^K w_k \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_k, \sigma_k^2 \boldsymbol{\Sigma}), \quad \boldsymbol{\Sigma} \equiv \text{diag}[\lambda^{(1)2}, \dots, \lambda^{(D)2}]$$

Variational posterior

$$q_{\phi}(\mathbf{x}) = \sum_{k=1}^K w_k \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_k, \sigma_k^2 \boldsymbol{\Sigma}), \quad \boldsymbol{\Sigma} \equiv \text{diag}[\lambda^{(1)2}, \dots, \lambda^{(D)2}]$$

- $\mathbf{x} \in \mathbb{R}^D$
- $\phi \equiv (w_1, \dots, w_K, \boldsymbol{\mu}_1, \dots, \boldsymbol{\mu}_K, \sigma_1, \dots, \sigma_K, \boldsymbol{\lambda})$
- $K(D+2) + D$ parameters
- K is changed adaptively each iteration

Gaussian process representation

$$f(\mathbf{x}) = \log p(\mathcal{D}|\mathbf{x})p(\mathbf{x})$$

Gaussian process representation

$$f(\mathbf{x}) = \log p(\mathcal{D}|\mathbf{x})p(\mathbf{x})$$

- Exponentiated quadratic covariance
- Gaussian observation noise
- *Negative quadratic* mean

Gaussian process representation

$$f(\mathbf{x}) = \log p(\mathcal{D}|\mathbf{x})p(\mathbf{x})$$

- Exponentiated quadratic covariance
- Gaussian observation noise
- *Negative quadratic* mean

$$m_{\text{NQ}}(\mathbf{x}) = m_0 - \frac{1}{2} \sum_{i=1}^D \frac{\left(x^{(i)} - x_m^{(i)}\right)^2}{\omega^{(i)2}},$$

Gaussian process representation

$$f(\mathbf{x}) = \log p(\mathcal{D}|\mathbf{x})p(\mathbf{x})$$

- Exponentiated quadratic covariance
- Gaussian observation noise
- *Negative quadratic mean*

$$m_{\text{NQ}}(\mathbf{x}) = m_0 - \frac{1}{2} \sum_{i=1}^D \frac{\left(x^{(i)} - x_m^{(i)}\right)^2}{\omega^{(i)2}},$$

Sample over GP hyperparameters (later optimize)

Variational optimization

$$\text{ELBO}(\phi, f) = \int q_{\phi}(\mathbf{x}) f(\mathbf{x}) d\mathbf{x} + \mathcal{H}[q_{\phi}(\mathbf{x})]$$

Variational optimization

$$\text{ELBO}(\phi, f) = \int q_{\phi}(\mathbf{x}) f(\mathbf{x}) d\mathbf{x} + \mathcal{H}[q_{\phi}(\mathbf{x})]$$

- Expected log joint and gradient are analytical

Variational optimization

$$\text{ELBO}(\phi, f) = \int q_{\phi}(\mathbf{x})f(\mathbf{x})d\mathbf{x} + \mathcal{H}[q_{\phi}(\mathbf{x})]$$

- Expected log joint and gradient are analytical
- Entropy via simple Monte Carlo
- Entropy gradient via reparametrization trick (Kingma & Welling, 2013; Miller et al., 2017)

Variational optimization

$$\text{ELBO}(\phi, f) = \int q_{\phi}(\mathbf{x})f(\mathbf{x})d\mathbf{x} + \mathcal{H}[q_{\phi}(\mathbf{x})]$$

- Expected log joint and gradient are analytical
- Entropy via simple Monte Carlo
- Entropy gradient via reparametrization trick (Kingma & Welling, 2013; Miller et al., 2017)

Optimize with SGD (Adam; Kingma & Ba, 2014)

Active sampling

Optimize *acquisition function*: $\mathbf{x}_{\text{next}} = \arg \max_{\mathbf{x}} a(\mathbf{x})$

Active sampling

Optimize *acquisition function*: $\mathbf{x}_{\text{next}} = \arg \max_{\mathbf{x}} a(\mathbf{x})$

Goal: Evaluate $\mathbb{E}_{\phi} [f] = \int q_{\phi}(\mathbf{x}) f(\mathbf{x}) d\mathbf{x}$

Active sampling

Optimize *acquisition function*: $\mathbf{x}_{\text{next}} = \arg \max_{\mathbf{x}} a(\mathbf{x})$

Goal: Evaluate $\mathbb{E}_{\phi}[f] = \int q_{\phi}(\mathbf{x})f(\mathbf{x})d\mathbf{x}$

\Rightarrow 'Vanilla' uncertainty sampling: $a_{\text{us}}(\mathbf{x}) = V(\mathbf{x})q_{\phi}(\mathbf{x})^2$

Active sampling

Optimize *acquisition function*: $\mathbf{x}_{\text{next}} = \arg \max_{\mathbf{x}} a(\mathbf{x})$

Goal: Evaluate $\mathbb{E}_{\phi} [f] = \int q_{\phi}(\mathbf{x}) f(\mathbf{x}) d\mathbf{x}$

\implies 'Vanilla' uncertainty sampling: $a_{\text{us}}(\mathbf{x}) = V(\mathbf{x}) q_{\phi}(\mathbf{x})^2$

Goal: Evaluate $\mathbb{E}_{\phi_1} [f], \mathbb{E}_{\phi_2} [f], \dots, \mathbb{E}_{\phi_T} [f]$

Active sampling

Optimize *acquisition function*: $\mathbf{x}_{\text{next}} = \arg \max_{\mathbf{x}} a(\mathbf{x})$

Goal: Evaluate $\mathbb{E}_{\phi} [f] = \int q_{\phi}(\mathbf{x}) f(\mathbf{x}) d\mathbf{x}$

\implies 'Vanilla' uncertainty sampling: $a_{\text{us}}(\mathbf{x}) = V(\mathbf{x}) q_{\phi}(\mathbf{x})^2$

Goal: Evaluate $\mathbb{E}_{\phi_1} [f], \mathbb{E}_{\phi_2} [f], \dots, \mathbb{E}_{\phi_T} [f]$

\implies Prospective uncertainty sampling: $a_{\text{pro}}(\mathbf{x}) = V(\mathbf{x}) q_{\phi}(\mathbf{x}) \exp(\bar{f}(\mathbf{x}))$

Algorithmic details

Algorithmic details

Evidence Lower Confidence Bound (ELCBO)

$$\text{ELCBO}(\phi, f) = \text{ELBO}(\phi, f) - \beta_{LCB} \cdot \text{SD} [\mathbb{E}_{\phi} [f]]$$

Algorithmic details

Evidence Lower Confidence Bound (ELCBO)

$$\text{ELCBO}(\phi, f) = \text{ELBO}(\phi, f) - \beta_{\text{LCB}} \cdot \text{SD} [\mathbb{E}_{\phi} [f]]$$

- Adaptive number of components
 - ▶ Try adding new components at each iteration
 - ▶ Prune small components with little effect on ELCBO

Algorithmic details

Evidence Lower Confidence Bound (ELCBO)

$$\text{ELCBO}(\phi, f) = \text{ELBO}(\phi, f) - \beta_{\text{LCB}} \cdot \text{SD} [\mathbb{E}_{\phi} [f]]$$

- Adaptive number of components
 - ▶ Try adding new components at each iteration
 - ▶ Prune small components with little effect on ELCBO
- Warm-up
 - ▶ Clamp $K = 2$, $w_1 = w_2 = \frac{1}{2}$
 - ▶ Warm-up ends when ELCBO improvement slows down

Algorithmic details

Evidence Lower Confidence Bound (ELCBO)

$$\text{ELCBO}(\phi, f) = \text{ELBO}(\phi, f) - \beta_{\text{LCB}} \cdot \text{SD} [\mathbb{E}_{\phi} [f]]$$

- Adaptive number of components
 - ▶ Try adding new components at each iteration
 - ▶ Prune small components with little effect on ELCBO
- Warm-up
 - ▶ Clamp $K = 2$, $w_1 = w_2 = \frac{1}{2}$
 - ▶ Warm-up ends when ELCBO improvement slows down
- Termination criteria
 - ▶ Reliability index $\rho(t)$
 - ▶ Long-term stability: $\rho(t) \leq 1$ for n_{stable} iterations

- 1 Introduction and motivation
- 2 Background Tools
- 3 Variational Bayesian Monte Carlo
- 4 Experiments**

Experiment setup

Benchmark sets:

- Three families of synthetic functions ($D \in \{2, 4, 6, 8, 10\}$)
- Neuronal model with real data ($D = 7$)

Experiment setup

Benchmark sets:

- Three families of synthetic functions ($D \in \{2, 4, 6, 8, 10\}$)
- Neuronal model with real data ($D = 7$)

Procedure:

- Budget of $50 \times (D + 2)$ likelihood evaluations
- Metrics
 - ▶ Error wrt true log marginal likelihood (LML)
 - ▶ 'Gaussianized' symmetrized KL divergence between ground truth and posterior approximation (gsKL)

Algorithms

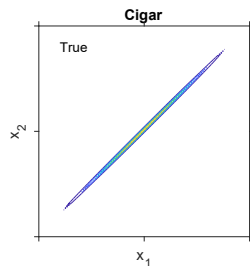
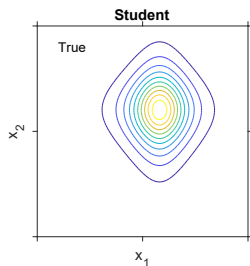
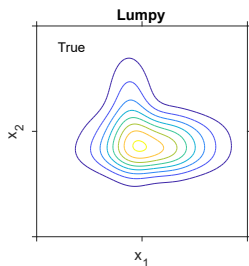
- VBMC-U (a_{us}) and VBMC-P (a_{pro})
- Simple Monte Carlo (SMC), annealed importance sampling (AIS)
- Bayesian Monte Carlo (BMC)
- Doubly-Bayesian quadrature (BBQ, BBQ*)
- WSABI, linearized (WSABI-L) and moment-matching (WSABI-M)
- Posterior estimation via GPs (AGP, BAPE)

Algorithms

- VBMC-U (a_{us}) and VBMC-P (a_{pro})
- Simple Monte Carlo (**SMC**), annealed importance sampling (**AIS**)
- Bayesian Monte Carlo (**BMC**)
- Doubly-Bayesian quadrature (**BBQ**, **BBQ***)
- WSABI, linearized (**WSABI-L**) and moment-matching (**WSABI-M**)
- Posterior estimation via GPs (AGP, BAPE)

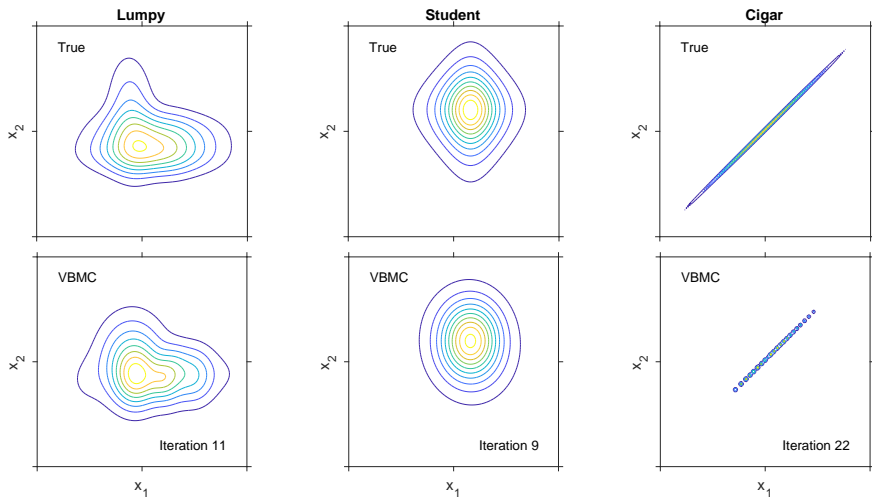
Synthetic target densities

Three families: *Lumpy*, *Student*, *Cigar* $D \in \{2, 4, 6, 8, 10\}$

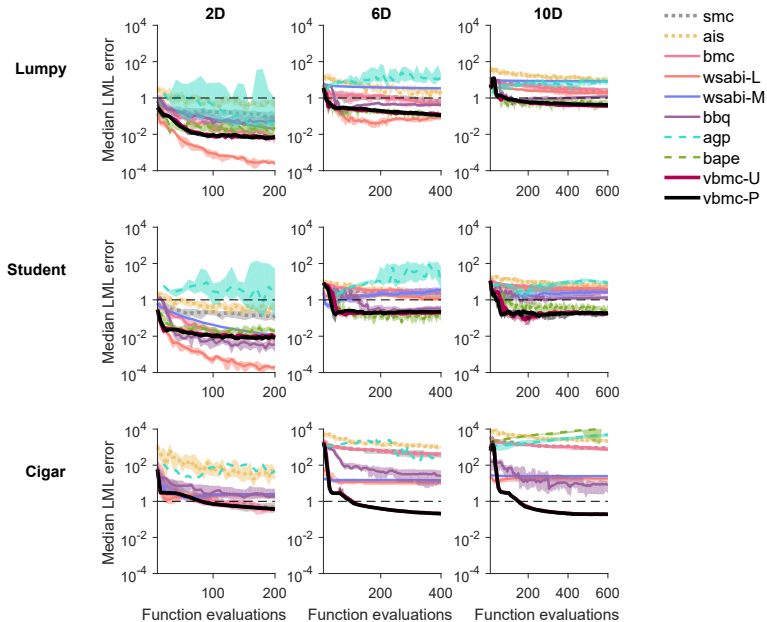


Synthetic target densities

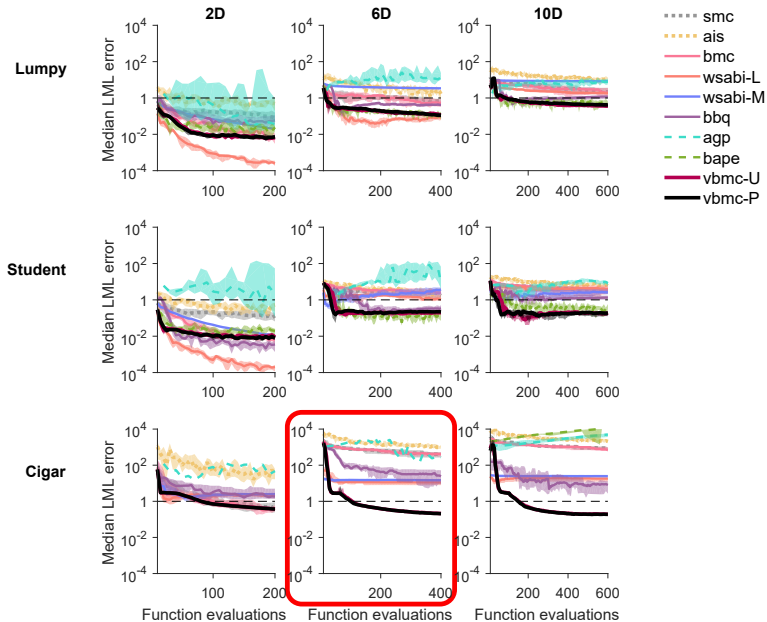
Three families: *Lumpy*, *Student*, *Cigar* $D \in \{2, 4, 6, 8, 10\}$



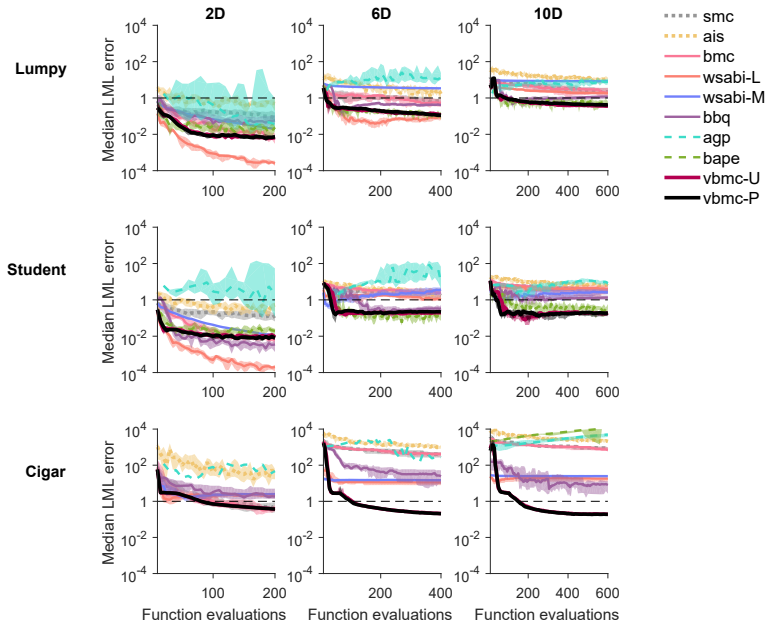
Synthetic target densities: Results



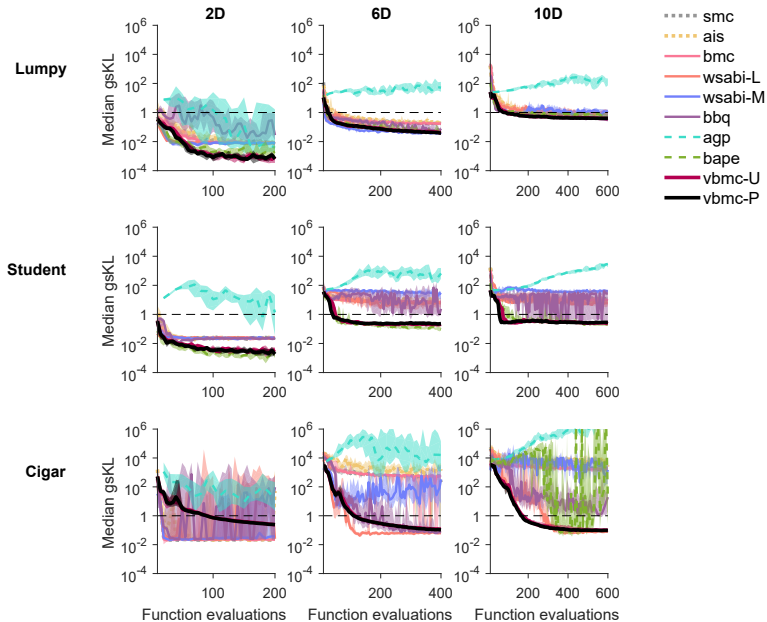
Synthetic target densities: Results



Synthetic target densities: Results



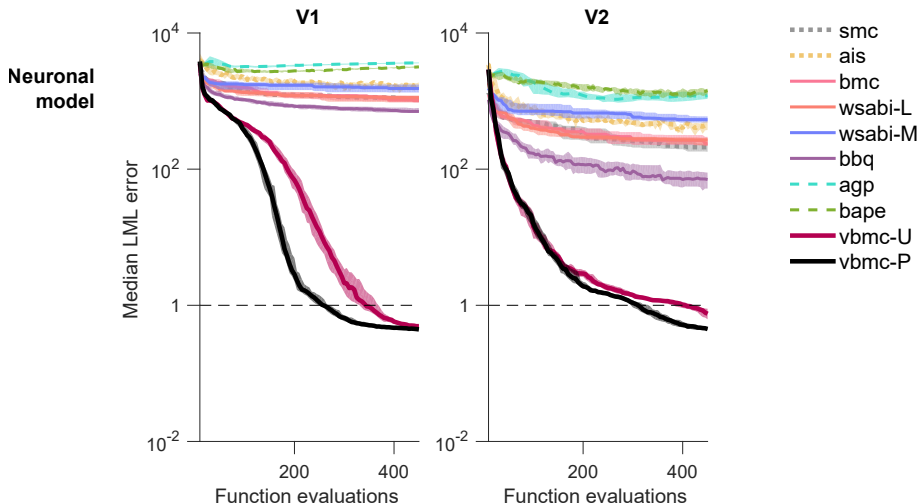
Synthetic target densities: Results



Neuronal model: Results

Two datasets: V1, V2

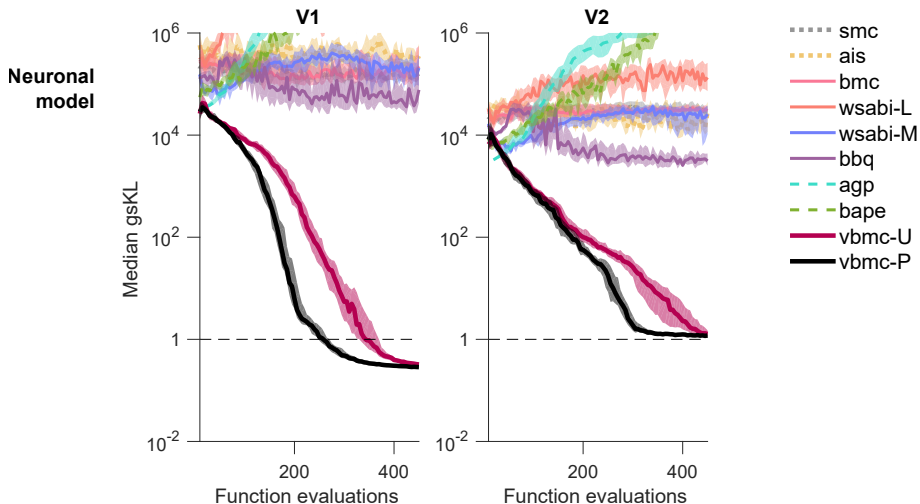
$D = 7$



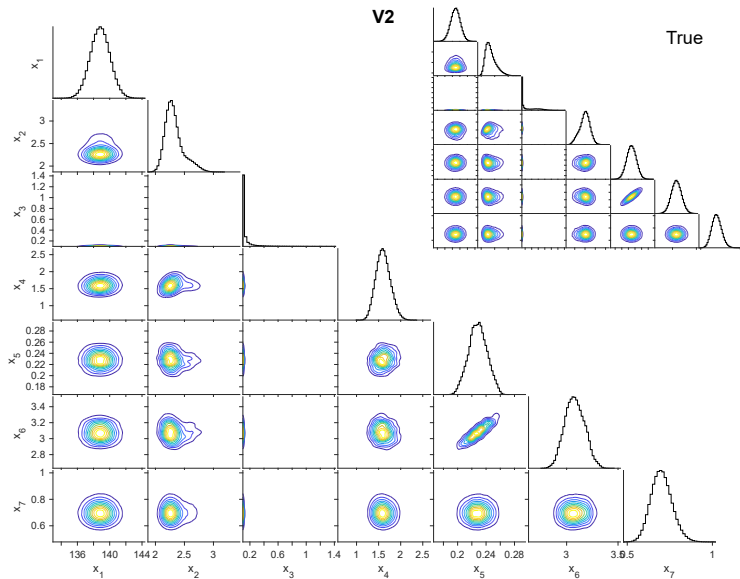
Neuronal model: Results

Two datasets: V1, V2

$D = 7$

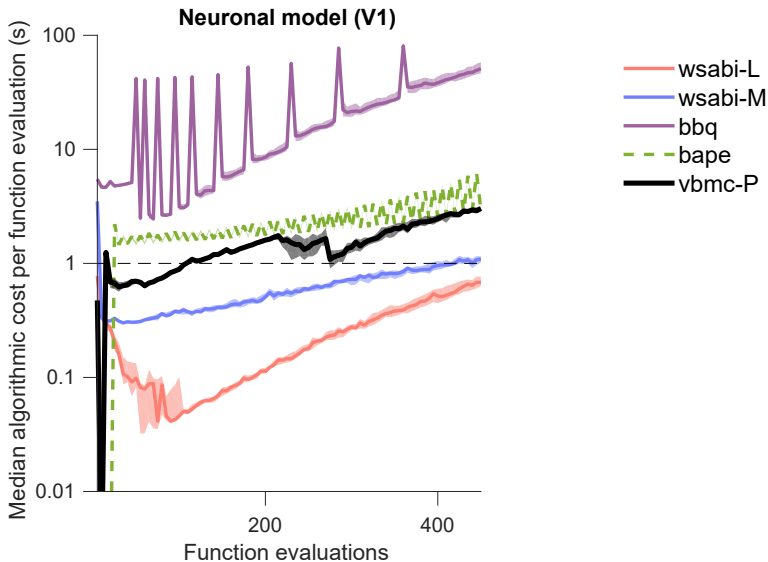


Neuronal model: VBMC



VBMC (iteration 52)

Computational cost



What's the secret sauce?

What's the secret sauce?

Other quadrature methods:

(BMC, BBQ, WSABI)

$$Z = \int p(\mathbf{x})p(\mathcal{D}|\mathbf{x})d\mathbf{x}$$

What's the secret sauce?

Other quadrature methods: (BMC, BBQ, WSABI)

$$Z = \int p(\mathbf{x})p(\mathcal{D}|\mathbf{x})d\mathbf{x}$$

VBMC:

$$\mathcal{I}_k = \int q_k(\mathbf{x}) \log [p(\mathbf{x})p(\mathcal{D}|\mathbf{x})] d\mathbf{x}$$

What's the secret sauce?

Other quadrature methods:

(BMC, BBQ, WSABI)

$$Z = \int p(\mathbf{x}) p(\mathcal{D}|\mathbf{x}) d\mathbf{x}$$

VBMC:

$$\mathcal{I}_k = \int q_k(\mathbf{x}) \log [p(\mathbf{x}) p(\mathcal{D}|\mathbf{x})] d\mathbf{x}$$

- GP representation

What's the secret sauce?

Other quadrature methods:

(BMC, BBQ, WSABI)

$$Z = \int p(\mathbf{x}) p(\mathcal{D}|\mathbf{x}) d\mathbf{x}$$

VBMC:

$$\mathcal{I}_k = \int q_k(\mathbf{x}) \log [p(\mathbf{x}) p(\mathcal{D}|\mathbf{x})] d\mathbf{x}$$

- GP representation
- Integration scope

Discussion and future directions

- Model mismatch and robustness (e.g., nonstationarity)

Discussion and future directions

- Model mismatch and robustness (e.g., nonstationarity)
- Alternative GP representations

Discussion and future directions

- Model mismatch and robustness (e.g., nonstationarity)
- Alternative GP representations
- More principled algorithmic solutions

Discussion and future directions

- Model mismatch and robustness (e.g., nonstationarity)
- Alternative GP representations
- More principled algorithmic solutions
- Killer application in machine learning

Toolboxes

lacerbi / vbmc

Unwatch 5

Star 34

Fork 3

Code

Issues 0

Pull requests 0

Projects 0

Wiki

Insights

Settings

Variational Bayesian Monte Carlo (VBMC) algorithm for posterior and model inference in MATLAB

Edit

bayesian-inference

variational-inference

gaussian-processes

data-analysis

machine-learning

matlab

Manage topics

344 commits

1 branch

0 releases

1 contributor

GPL-3.0

lacerbi / bads

Unwatch 9

Star 83

Fork 15

Code

Issues 3

Pull requests 0

Projects 0

Wiki

Insights

Settings

Bayesian Adaptive Direct Search (BADS) optimization algorithm for model fitting in MATLAB

Edit

optimization-algorithms

bayesian-optimization

log-likelihood

noiseless-functions

noisy-functions

matlab

Manage topics

156 commits

2 branches

6 releases

1 contributor

GPL-3.0

Acerbi & Ma, *NIPS* (2017)

Final slide

- VBMC paper: <https://arxiv.org/abs/1810.05558>
- VBMC toolbox at: github.com/lacerbi/vbmc
- BADS toolbox at: github.com/lacerbi/bads

Final slide

- VBMC paper: <https://arxiv.org/abs/1810.05558>
- VBMC toolbox at: github.com/lacerbi/vbmc
- BADS toolbox at: github.com/lacerbi/bads

Acknowledgments

- Alexandre Pouget and the Pouget lab
- Robbe Goris

Final slide

- VBMC paper: <https://arxiv.org/abs/1810.05558>
- VBMC toolbox at: github.com/lacerbi/vbmc
- BADS toolbox at: github.com/lacerbi/bads

Acknowledgments

- Alexandre Pouget and the Pouget lab
- Robbe Goris

Thanks!

References

- Acerbi, L. & Ma, W. J. (2017). Practical Bayesian optimization for model fitting with Bayesian Adaptive Direct Search. In *Advances in Neural Information Processing Systems* **30**, 1834-1844.
- Acerbi, L. (2018) Variational Bayesian Monte Carlo. To appear in *Advances in Neural Information Processing Systems* **31**.
- Ghahramani, Z. & Rasmussen, C. E. (2002) Bayesian Monte Carlo. In *Advances in Neural Information Processing Systems* **15**, 505-512.
- Goris, R. L., Simoncelli, E. P., & Movshon, J. A. (2015) Origin and function of tuning diversity in macaque visual cortex. *Neuron* **88**, 819-831.
- Gunter, T., Osborne, M. A., Garnett, R., Hennig, P., & Roberts, S. J. (2014) Sampling for inference in probabilistic models with fast Bayesian quadrature. In *Advances in Neural Information Processing Systems* **27**, 2789-2797.
- Kingma, D. P. & Welling, M. (2013) Auto-encoding variational Bayes. In *Proceedings of the 2nd International Conference on Learning Representations*.
- Kingma, D. P. & Ba, J. (2014) Adam: A method for stochastic optimization. In *Proceedings of the 3rd International Conference on Learning Representations*.
- Miller, A. C., Foti, N., & Adams, R. P. (2017) Variational boosting: Iteratively refining posterior approximations. In *Proceedings of the 34th International Conference on Machine Learning* **70**, 2420-2429.
- Osborne, M., Duvenaud, D. K., Garnett, R., Rasmussen, C. E., Roberts, S. J., & Ghahramani, Z. (2012) Active learning of model evidence using Bayesian quadrature. In *Advances in Neural Information Processing Systems* **25**, 4654.

Control experiment

LML computed with WSABI-L on VBMC samples

