Fitting algebraic curves to data

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Affine variety

consider system of p, q-variate polynomials

$$r_i(w_1,\ldots,w_q)=0, \quad i=1,\ldots,p \qquad \iff \qquad R(w)=0$$

the set of their real valued solutions

$$\mathscr{B} = \{ w \in \mathbb{R}^q \mid R(w) = 0 \}$$

is affine variety

of primary interest for data modeling is the set \mathcal{B} (the model)

R(w) = 0 is demoted to (kernel) representation of \mathscr{B}

Dimension of affine variety

image representation:

$$\mathscr{B} = \{ w \mid w = P(u), \text{ for all } u \in \mathbb{R}^g \}$$

 $\dim(\mathcal{B}) =: \min g$ in image representation of \mathcal{B}

affine variety of dimension one is called algebraic curve

Algebraic curves in 2D

in the special case q = 2, we use

$$x := w_1$$
 and $y := w_2$

the set

$$\mathscr{B} = \{ (x,y) \in \mathbb{R}^2 \mid r(x,y) = 0 \}$$

may be

- empty, e.g., $r(x, y) = x^2 + y^2 + 1$
- finite (isolated points), e.g., $r(x,y) = x^2 + y^2$, or
- infinite (curve), e.g., $r(x, y) = x^2 + y^2 1$

Examples

- subspace
- •
- conic section
- cissoid
- folium of Descartes
- four-leaved rose

linear \mathcal{B} ($q \ge 2$, zeroth degree repr.)

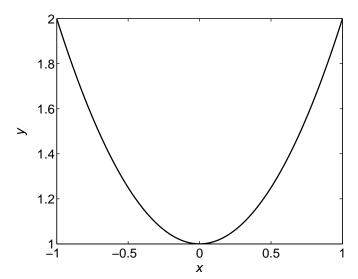
second order algebraic curve in \mathbb{R}^2

$$\mathscr{B} = \{(x,y) \mid y^2(1+x) = (1-x)^3\}$$

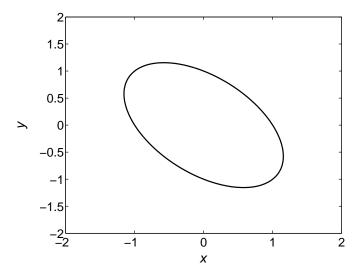
$$\mathscr{B} = \{ (x,y) \mid x^3 + y^3 - 3xy = 0 \}$$

$$\mathscr{B} = \{(x,y) \mid (x^2 + y^2)^3 - 4x^2y^2 = 0\}$$

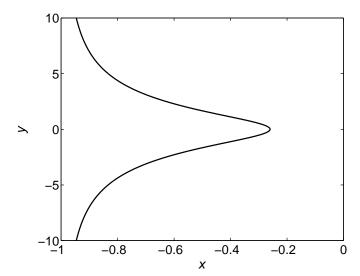
Parabola $y = x^2 + 1$



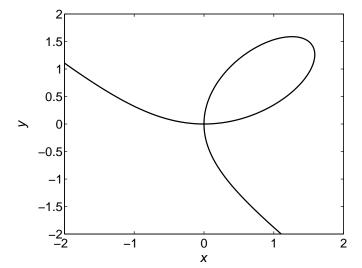
Ellipse
$$y^2 + xy + x^2 - 1 = 0$$



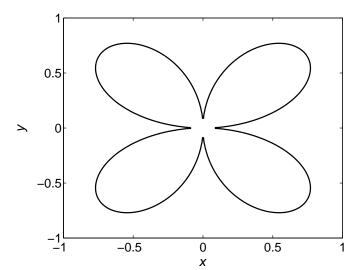
Cissoid
$$y^2(1+x) = (1-x)^3$$



Folium of Descartes $x^3 + y^3 - 3xy = 0$



Rose
$$(x^2+y^2)^3-4x^2y^2=0$$



Explicit vs implicit representations

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• function y = f(x) vs relation (r(x,y) = 0) (mathematics)
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• input/output vs kernel representation (system theory)

regression vs EIV regression (statistics)

• functional vs structural models (statistics)

The fitting problem

Given:

- data points $w_d = \{ w_d(1), ..., w_d(N) \}$
- set of candidate curves (model class) M
- data-model distance measure dist(w_d, B)

find model $\widehat{\mathscr{B}} \in \mathscr{M}$ that is as close as possible to the data:

minimize over $\mathscr{B} \in \mathscr{M}$ dist (w_d, \mathscr{B})

Algebraic vs geometric distance measures

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geometric distance: \operatorname{dist}(w_{\mathsf{d}},\mathscr{B}) := \min_{\widehat{w} \subset \mathscr{B}} \|w_{\mathsf{d}} - \widehat{w}\|
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algebraic "distance": $\|R(w_d)\|$ where R defines kernel repr. of \mathscr{B}

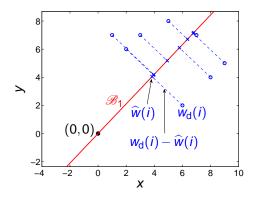
other interpretations:

misfit vs latency

P. Lemmerling and B. De Moor, Misfit versus latency, Automatica, 37:2057–2067, 2001

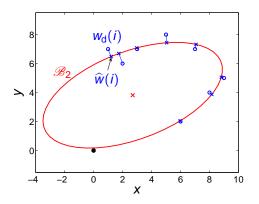
- algebraic \leftrightarrow LS \leftrightarrow ARMAX

Example: geometric distance to a linear model



$$dist(w_{d}, \mathcal{B}_{1}) = \min_{\widehat{w}(1), \dots, \widehat{w}(8) \in \mathcal{B}_{1}} \sqrt{\sum_{t=1}^{8} \|w_{d}(t) - \widehat{w}(t)\|_{2}^{2}} = 7.8865$$

Example: geometric distance to a quadratic model



$$dist(w_{d}, \mathcal{B}_{2}) = \min_{\widehat{w}(1), \dots, \widehat{w}(8) \in \mathcal{B}_{2}} \sqrt{\sum_{t=1}^{8} \|w_{d}(t) - \widehat{w}(t)\|^{2}} = 1.1719$$

Kernel representation in 2D

$$r(w) = \sum_{k=1}^{n_{\theta}} \theta_k \phi_k(w) = \phi(w)\theta$$
 linear in θ nonlinear in w

- θ vector of parameters
- $\phi(w)$ vector of monomials, e.g.,

$$q = 2$$
, $d := \deg(r) = 2$ \Rightarrow $\phi(w) = \begin{bmatrix} x^2 & xy & x & y^2 & y & 1 \end{bmatrix}$
 $d = 3 \Rightarrow \phi(w) = \begin{bmatrix} x^3 & x^2y^1 & x^2 & xy^2 & xy & x & y^3 & y^2 & y & 1 \end{bmatrix}$

- $n_{\theta} = \binom{q+d}{d}$ measure of complexity of \mathcal{M}_d the degree d is the only design parameter in the curve fitting prob.
- θ is nonunique, θ and $\alpha\theta$, for all $\alpha \neq 0$, define the same \mathscr{B}

Algebraic curve fitting in \mathbb{R}^2

minimize over
$$\|\theta\|_2 = 1$$
 $\sum_{i=1}^{N} \|r_{\theta}(w_{d}(i))\|_2^2$

$$\sum_{i=1}^{N} \|r_{\theta}(w_{d}(i))\|_{2}^{2} = \left\| \begin{bmatrix} \phi(w_{d}(1)) \\ \vdots \\ \phi(w_{d}(N)) \end{bmatrix} \theta \right\|_{2}^{2} = \theta^{\top} \Phi^{\top}(w_{d}) \Phi(w_{d}) \theta = \theta^{\top} \Psi(w_{d}) \theta$$

algebraic curve fitting is eigenvalue problem

minimize over
$$\|\theta\|_2 = 1$$
 $\theta^{\top} \Psi(w_d) \theta$

or, equivalently, (unstructured) low-rank approximation problem

minimize over
$$\widehat{\Phi}$$
 and $\theta \| \Phi(w_d) - \widehat{\Phi} \|_F$ subject to rank $(\widehat{\Phi}) \le n_\theta - 1$

Geometric distance

minimize over
$$\widehat{w} \subset \mathscr{B} \quad ||w_d - \widehat{w}||$$

let
$$\mathscr{B} = \{ w \mid \phi(w)\theta = 0 \}$$

$$\widehat{w} \subset \mathscr{B} \iff \widehat{w}(i) \in \mathscr{B}, \text{ for } i = 1, ..., N$$

$$\iff \phi(\widehat{w}(i))\theta = 0, \text{ for } i = 1, ..., N$$

$$\iff \Phi(\widehat{w})\theta = 0$$

the problem of computing the geometric distance is:

minimize over
$$\widehat{w} \quad \|w_d - \widehat{w}\|$$
 subject to $\Phi(\widehat{w})\theta = 0$

Geometric curve fitting

minimize over $\mathscr{B} \in \mathscr{M}_d$ dist (w_d, \mathscr{B})

assuming that $N \ge n_{\theta}$, we have

$$\Phi(\widehat{w})\theta = 0, \ \theta \neq 0 \quad \iff \quad \operatorname{rank}\left(\Phi(\widehat{w})\right) \leq n_{\theta} - 1, \quad n_{\theta} := {2+d \choose d}$$

geometric curve fitting is nonlinearly structured low-rank approx.:

minimize over
$$\widehat{w}$$
 and $\theta \| w_d - \widehat{w} \|$
subject to rank $(\Phi(\widehat{w})) \le n_\theta - 1$

note: algebraic fitting is a relaxation of geometric fitting, obtained by removing the structure constraint

Comparison of algebraic and geometric fits

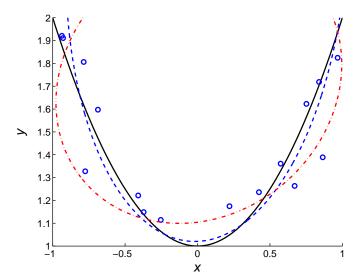
Simulation setup:

• true model $\bar{\mathscr{B}} = \{ w \mid \phi(w)\bar{\theta} = 0 \}, (q = 2, p = 1)$

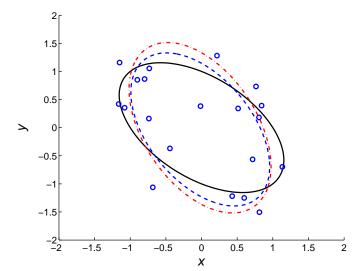
• data points
$$w_d = \bar{w} + \widetilde{w}, \; \bar{w} \subset \bar{\mathscr{B}}, \; \widetilde{w} \sim \mathsf{N}(0, \sigma^2 I)$$

- algebraic fit dashed dotted line
- geometric fit dashed line

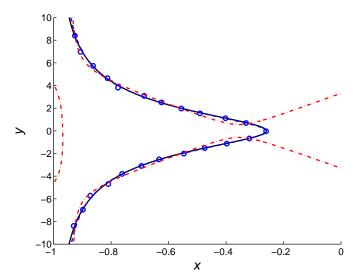
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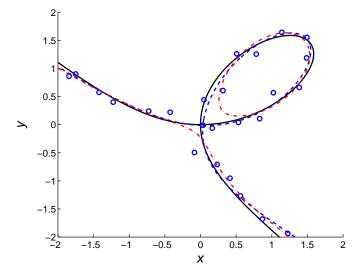
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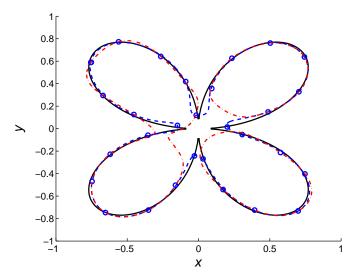
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new application of structured low-rank approximation the first I know of with nonlinear structure

To-do list:

- Robust and efficient optimization methods
- Noniterative (subspace-type) methods
- Generalize to nD (vector polynomials)
- Link to linear system identification
- Link to related curve fitting methods, e.g., principal curves
- Statistical properties
- Impact on applications

Questions?