

Structured Low-Rank Approximation in Signal Processing

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Introduction

We will consider the following signal processing problems:

- | | | |
|-----------------------|---|-----------------------------|
| 1. Linear prediction | ↔ | sum-of-damped-exp. modeling |
| 2. Harmonic retrieval | ↔ | sum-of-exp. modeling |
| 3. Deconvolution | ↔ | FIR modeling |
| 4. 2D deconvolution | ↔ | image deblurring |

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Outline

Signal processing

Low-rank approximation

Algorithms

Conclusions

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Linear prediction problem

Future values of w are estimated as linear comb. of past values

$$w(t) = r_1 w(t-1) + r_2 w(t-2) + \dots + r_n w(t-n) \quad (\text{LP})$$

r_i are the linear prediction coefficients

Given an observed signal w_d , how do we find the coefficients r_i ?

There are many methods for doing this:

- Pisarenko, Prony, Kumaresan–Tufts methods
- subspace methods
- frequency domain methods
- maximum likelihood method

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Sum-of-damped-exponentials model

Model the signal w as

$$w(t) = \sum_{i=1}^n a_i e^{d_i t} e^{i(\omega_i t + \phi_i)} \quad (\text{SDE})$$

where a_i , d_i , ϕ_i , and ω_i are parameters of the model

a_i — amplitudes d_i — dampings
 ω_i — frequencies ϕ_i — initial phases

For all $\{a_i, d_i, \omega_i, \phi_i\}$ there are r_i and $w(-n+1), \dots, w(0)$, s.t. the solution of (LP) coincides with (SDE) and vice verse.

the LP problem \iff modeling by (SDE)

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Deconvolution problem and FIR model

Given signals u and y , find a signals h , such that

$$y(t) = (h \star u)(t) := \sum_{\tau=T_{\text{ini}}}^{T_f} h(\tau) u(t - \tau)$$

Interpretation:

u — input y — output
 h — **impulse response** (of an FIR system)

model y as the output of an FIR system with input u

$T_{\text{ini}} \geq 0 \implies$ **causal** system

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Harmonic retrieval problem

Corresponds to modeling w as a **sum-of-exponentials**

$$w(t) = \sum_{i=1}^n a_i e^{i(\omega_i t + \phi_i)}$$

A special sum-of-damped-exp. model, with dampings $d_i = 0$.

\implies w satisfies the linear prediction (LP) equation

Moreover, a sum-of-exp. signal w satisfies the equation

$$w(t-n) = r_1 w(t-n+1) + r_2 w(t-n+2) + \dots + r_n w(t) \quad (\text{LP}')$$

where r_i are the linear prediction coefficients.

(LP) — **forward** prediction (LP') — **backward** prediction

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2D deconvolution and image deblurring

Deconvolution for signals with two independent variables

$$y(t_1, t_2) = (h \star u)(t_1, t_2) := \sum_{\tau_1=T_{\text{ini}1}}^{T_{f1}} \sum_{\tau_2=T_{\text{ini}2}}^{T_{f2}} h(\tau_1, \tau_2) u(t_1 - \tau_1, t_2 - \tau_2)$$

Interpretation:

u — true image y — blurred image
 h — **point spread function** (PSF of an blurring operator)

given a blurred image and PSF, find the true image

(The topic of the previous summer school organized in Monopoli.)

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Linear prediction problem

$w = (w(1), \dots, w(T))$ **sum-of-damped-exp.** $\implies w$ satisfies

$$r_0 w(t) + r_1 w(t+1) + \dots + r_n w(t+n) = 0, \quad \text{for } t = 1, \dots, T-n$$

Written in a matrix form these equations are

$$\begin{bmatrix} r_0 & r_1 & \dots & r_n \end{bmatrix} \underbrace{\begin{bmatrix} w(1) & w(2) & \dots & w(T-n) \\ w(2) & w(3) & \dots & w(T-n+1) \\ \vdots & \vdots & & \vdots \\ w(n+1) & w(n+2) & \dots & w(T) \end{bmatrix}}_{\mathcal{H}_{n+1}(w)} = 0$$

which shows that the Hankel matrix $\mathcal{H}_{n+1}(w)$ is rank deficient

$$\text{rank}(\mathcal{H}_{n+1}(w)) \leq n$$

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Harmonic retrieval problem

$w = (w(1), \dots, w(T))$ **sum-of-exp.** $\implies w$ satisfies

forward LP equation: $r \mathcal{H}_{n+1}(w) = 0$

and backward LP equation

$$\begin{bmatrix} r_0 & r_1 & \dots & r_n \end{bmatrix} \underbrace{\begin{bmatrix} w(n+1) & w(n+2) & \dots & w(T) \\ \vdots & \vdots & & \vdots \\ w(2) & w(3) & \dots & w(T-n+1) \\ w(1) & w(2) & \dots & w(T-n) \end{bmatrix}}_{\mathcal{T}_{n+1}(w)} = 0$$

$$\implies r(\mathcal{H}_{n+1}(w) + \mathcal{T}_{n+1}(w)) = 0, \text{ i.e.,}$$

$$\text{rank}(\mathcal{H}_{n+1}(w) + \mathcal{T}_{n+1}(w)) \leq n$$

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Deconvolution problem

1-dimensional case:

$$h \star u = y \iff h \mathcal{T}_n(u) = y \iff \text{rank} \left(\begin{bmatrix} \mathcal{T}_n \\ y \end{bmatrix} \right) \leq n$$

2-dimensional case:

$$h \star u = y \iff \text{rank} \left(\begin{bmatrix} \mathcal{S}_n \\ y \end{bmatrix} \right) \leq n$$

where \mathcal{S} is a **block-Toeplitz, Toeplitz-block** structured matrix

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Optimal modeling: structured low-rank approximation

Given $w_d = (w_d(1), \dots, w_d(T))$, find $\hat{w} = (\hat{w}(1), \dots, \hat{w}(T))$ that is

1. sum-of-damped-exp, or sum-of-exp, or FIR
 $\iff \text{rank}(\mathcal{S}(\hat{w})) \leq n$, for certain structures \mathcal{S}
2. as close as possible to w_d , i.e., $\|w_d - \hat{w}\|$ is minimized

$$\hat{w}^* := \arg \min_{\hat{w}} \|w_d - \hat{w}\| \quad \text{subject to} \quad \text{rank}(\mathcal{S}(\hat{w})) \leq n$$

In the first 3 appl., $\mathcal{S}(\cdot)$ is composed of blocks that are:

Hankel, Toeplitz, Hankel+Toeplitz, or unstructured.

\leadsto **efficient algorithms** (computational complexity $O(T)$)

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Multivariable and multidimensional systems

$$\begin{array}{c}
 y = \mathcal{T}(h)u = \mathcal{T}(u)h \\
 \text{Toeplitz matrix times vector} \\
 \updownarrow \\
 (u, y) \in \mathcal{B}(h) \iff y = h * u \iff y(z) = h(z)u(z) \\
 \text{FIR sys. traj.} \quad \text{convolution} \quad \text{polyn. multipl.}
 \end{array}$$

$$\begin{array}{c}
 \text{Multivariable case: block Toeplitz structure} \\
 \text{multivariable systems} \iff \text{matrix valued time series} \iff \text{matrix valued polynomials}
 \end{array}$$

$$\begin{array}{c}
 \text{2D case: block Toeplitz-Toeplitz block structure} \\
 \text{multidim. system} \iff \text{function of several indep. variables} \iff \text{polyn. of several var.}
 \end{array}$$

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Unstructured low-rank approximation

$$\hat{D}^* := \arg \min_{\hat{D}} \|D - \hat{D}\|_F \quad \text{subject to} \quad \text{rank}(\hat{D}) \leq n$$

Closed form solution: Let $D = U\Sigma V^T$ be the SVD of D .

$$U = \begin{bmatrix} U_1 & U_2 \end{bmatrix}, \quad \Sigma = \begin{bmatrix} \Sigma_1 & 0 \\ 0 & \Sigma_2 \end{bmatrix}, \quad \text{and} \quad V = \begin{bmatrix} V_1 & V_2 \end{bmatrix}$$

An optimal low-rank approximate solution is

$$\hat{D}^* = U_1 \Sigma_1 V_1^T$$

It is unique if and only if $\sigma_n \neq \sigma_{n+1}$.

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Structured low-rank approximation

No closed form solution is known for the general SLRA problem

$$\hat{w}^* := \arg \min_{\hat{w}} \|w_d - \hat{w}\| \quad \text{subject to} \quad \text{rank}(\mathcal{S}(\hat{w})) \leq n$$

NP-hard, consider solution methods based on local optimization

Representing the constraint in a kernel form, the problem is

$$\min_{r, r^T=1} \left(\min_{\hat{w}} \|w_d - \hat{w}\| \quad \text{subject to} \quad r \mathcal{S}(\hat{w}) = 0 \right)$$

Double minimization with bilinear equality constraint.

There is a matrix $G(r)$, such that $r \mathcal{S}(\hat{w}) = 0 \iff \hat{w} G(r) = 0$.

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Algorithmic details using the VARPRO approach

The structured low-rank approximation problem is equivalent to

$$\min_{r, r^T=1} r \mathcal{S}(w_d) (G^T(r) G(r))^{-1} \mathcal{S}^T(w_d) r^T$$

To evaluate the cost function we need to solve for z

$$(G^T(r) G(r)) z = (r \mathcal{S}(w_d))$$

What special structure does $G^T G$ have?

Banded Toeplitz for any $\mathcal{S} = [\mathcal{S}_1 \ \cdots \ \mathcal{S}_q]$, where \mathcal{S}_i is Toeplitz, Hankel, Toeplitz+Hankel, unstructured, or fixed.

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Variable projection vs. alternating projections

Two ways to approach the double minimization:

- Variable projections (VARPRO):
solve the inner minimization analytically

$$\min_{r, r^T=1} r \mathcal{S}(w_d) (G^T(r) G(r))^{-1} \mathcal{S}^T(w_d) r^T$$

\rightsquigarrow a nonlinear least squares problem for r only.

- Alternating projections (AP):
alternate between solving two least squares problems

VARPRO is globally convergent with a super linear conv. rate.

AP is globally convergent with a linear convergence rate.

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Special case: sum-of-damped-exp. modeling

In the sum-of-damped-exp. modeling, the structure is

$$\mathcal{S}(w) = \mathcal{H}_{n+1}(w)$$

What matrix G satisfies

$$r \mathcal{H}_{n+1}(w) = 0 \iff w G(r) = 0$$

for all r and w ? What is the structure of $G^T G$?

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Special case: sum-of-damped-exp. modeling

$$\begin{aligned}
 & \begin{bmatrix} r_0 & r_1 & \cdots & r_n \end{bmatrix} \underbrace{\begin{bmatrix} w(1) & w(2) & \cdots & w(T-n) \\ w(2) & w(3) & \cdots & w(T-n+1) \\ \vdots & \vdots & & \vdots \\ w(n+1) & w(n+2) & \cdots & w(T) \end{bmatrix}}_{\mathcal{H}_{n+1}(w)} \\
 &= \begin{bmatrix} w_1 & w_2 & \cdots & w_T \end{bmatrix} \underbrace{\begin{bmatrix} r_0 & & & & \\ r_1 & r_0 & & & \\ \vdots & r_1 & \ddots & & \\ r_n & \vdots & \ddots & r_0 & \\ & r_n & & r_1 & \\ & & \ddots & \vdots & \\ & & & r_n & \end{bmatrix}}_{G(r)}
 \end{aligned}$$

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Special case: sum-of-damped-exp. modeling

Therefore,

$$G^\top G = \begin{bmatrix} r_0 & r_1 & \cdots & r_n \\ & r_0 & r_1 & \cdots & r_n \\ & & \ddots & \ddots & \ddots \\ & & & r_0 & r_1 & \cdots & r_n \end{bmatrix} \begin{bmatrix} r_0 & & & & \\ r_1 & r_0 & & & \\ \vdots & r_1 & \ddots & & \\ r_n & \vdots & \ddots & r_0 & \\ & r_n & & r_1 & \\ & & \ddots & \vdots & \\ & & & r_n & \end{bmatrix}$$

(All missing elements are zeros.)

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Special case: sum-of-damped-exp. modeling

$$G^\top G = \begin{bmatrix} \sum_{i=0}^n r_i r_i & \sum_{i=1}^n r_i r_{i-1} & \cdots & r_n r_0 \\ \sum_{i=1}^n r_{i-1} r_i & \ddots & & \ddots \\ \vdots & & \ddots & \\ r_0 r_n & & & r_n r_0 \\ & \ddots & & \vdots & \\ & & \ddots & \sum_{i=1}^n r_i r_{i-1} \\ & & & \ddots & \sum_{i=0}^n r_i r_i \end{bmatrix}$$

banded Toeplitz, bandwidth $2n+1$

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Special case: sum-of-exp. modeling

In sum-of-exponentials modeling, the structure \mathcal{S} is

$$\mathcal{S}(w) = \mathcal{H}_{n+1}(w) + \mathcal{I}_{n+1}(w)$$

What matrix G satisfies

$$r(\mathcal{H}_{n+1}(w) + \mathcal{I}_{n+1}(w)) = 0 \iff wG(r) = 0$$

for all r and w ? What is the structure of $G^\top G$?

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Special case: sum-of-exp. modeling

$$\begin{aligned}
 & \begin{bmatrix} r_0 & r_1 & \cdots & r_n \end{bmatrix} (\mathcal{H}_{n+1}(w) + \mathcal{I}_{n+1}(w)) \\
 &= \begin{bmatrix} w_1 & w_2 & \cdots & w_T \end{bmatrix} \underbrace{\left(\begin{bmatrix} r_0 & & & & \\ r_1 & r_0 & & & \\ \vdots & r_1 & \ddots & & \\ r_n & \vdots & \ddots & r_0 & \\ & r_n & & r_1 & \\ & & \ddots & \vdots & r_n \end{bmatrix} + \begin{bmatrix} r_n & & & & \\ \vdots & r_n & & & \\ r_1 & \vdots & \ddots & & \\ r_0 & r_1 & & r_n & \\ & r_0 & \ddots & \vdots & \\ & & r_0 & \ddots & r_1 \\ & & & \ddots & r_0 \end{bmatrix} \right)}_{G(r)}
 \end{aligned}$$

Define

$$\tilde{r}_i := r_i + r_{n-i}, \quad \text{for } i = 0, 1, \dots, n$$

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Special case: sum-of-exp. modeling

$$G^\top G = \begin{bmatrix} \sum_{i=0}^n \tilde{r}_i \tilde{r}_i & \sum_{i=1}^n \tilde{r}_i \tilde{r}_{i-1} & \cdots & \tilde{r}_n \tilde{r}_0 \\ \sum_{i=1}^n \tilde{r}_{i-1} \tilde{r}_i & \ddots & & \vdots \\ \vdots & & \ddots & \tilde{r}_0 \tilde{r}_n \\ \tilde{r}_0 \tilde{r}_n & & & \tilde{r}_n \tilde{r}_0 \\ & \ddots & & \vdots \\ & & \ddots & \sum_{i=1}^n \tilde{r}_i \tilde{r}_{i-1} \\ & & & \sum_{i=0}^n \tilde{r}_i \tilde{r}_i \end{bmatrix}$$

banded Toeplitz, bandwidth $2n+1$

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Special case: sum-of-exp. modeling

Therefore,

$$G^\top G = \begin{bmatrix} \tilde{r}_0 & \tilde{r}_1 & \cdots & \tilde{r}_n & \\ & \tilde{r}_0 & \tilde{r}_1 & \cdots & \tilde{r}_n \\ & & \ddots & \ddots & \ddots \\ & & & \tilde{r}_0 & \tilde{r}_1 & \cdots & \tilde{r}_n \end{bmatrix} \begin{bmatrix} \tilde{r}_0 \\ \tilde{r}_1 & \tilde{r}_0 \\ \vdots & \tilde{r}_1 & \ddots \\ \tilde{r}_n & \vdots & \ddots & \tilde{r}_0 \\ & \tilde{r}_n & & \tilde{r}_1 \\ & & \ddots & \vdots \\ & & & \tilde{r}_n \end{bmatrix}$$

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Special case: FIR system modeling

In FIR system modeling, the structure \mathcal{S} is

$$\mathcal{S}(w) = \begin{bmatrix} \mathcal{H}_n(u) \\ y \end{bmatrix}$$

What matrix G satisfies

$$\begin{bmatrix} h & -1 \end{bmatrix} \begin{bmatrix} \mathcal{H}_n(u) \\ y \end{bmatrix} = 0 \iff wG(h) = 0$$

for all h and $w = (u, y)$. What is the structure of $G^\top G$?

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Special case: FIR system modeling

$$\begin{aligned}
 & [h_1 \ \cdots \ h_n \ -1] \underbrace{\begin{bmatrix} u(1) & u(2) & \cdots & u(T-n+1) \\ \vdots & \vdots & & \vdots \\ u(n) & u(n+1) & \cdots & u(T) \\ y(1) & u(2) & \cdots & y(T-n+1) \end{bmatrix}}_{\text{col}(\mathcal{H}_n(u), y)} \\
 & = [u_1 \ \cdots \ u_T \mid y_1 \ \cdots \ y_{T-n+1}] \underbrace{\begin{bmatrix} h_1 & & & & \\ & \ddots & & & \\ & & h_1 & & \\ & & \vdots & \ddots & \\ h_n & & & & \ddots & \\ & & & h_n & & h_1 \\ & & & & \ddots & \vdots \\ & & & & & \ddots & h_n \\ & & & & & & -I \end{bmatrix}}_{G(h)}
 \end{aligned}$$

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Special case: FIR system modeling

Therefore,

$$G^T G = \left[\begin{array}{cccc|c} h_1 & \cdots & h_n & & \\ & h_1 & \cdots & h_n & \\ & & \ddots & & \ddots \\ & & & h_1 & \cdots & h_n \\ \hline & & & & & -I \end{array} \right] \begin{bmatrix} h_1 \\ \vdots \\ h_1 \\ h_n \\ \vdots \\ h_n \\ & & h_1 \\ & & \vdots \\ & & h_n \\ \hline & & & & -I \end{bmatrix}$$

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Special case: FIR system modeling

$$G^T G = \begin{bmatrix} 1 + \sum_{i=1}^n h_i h_i & \sum_{i=2}^n h_i h_{i-1} & \cdots & h_n h_1 \\ \sum_{i=2}^n h_{i-1} h_i & \ddots & & \vdots \\ \vdots & & \ddots & h_n h_1 \\ h_1 h_n & & & \sum_{i=1}^n h_i h_i \\ & \ddots & & \vdots \\ & & \ddots & \sum_{i=1}^n h_i h_i \\ & & & 1 + \sum_{i=1}^n h_i h_i \end{bmatrix}$$

banded Toeplitz, bandwidth $2n - 1$

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Outline

Signal processing

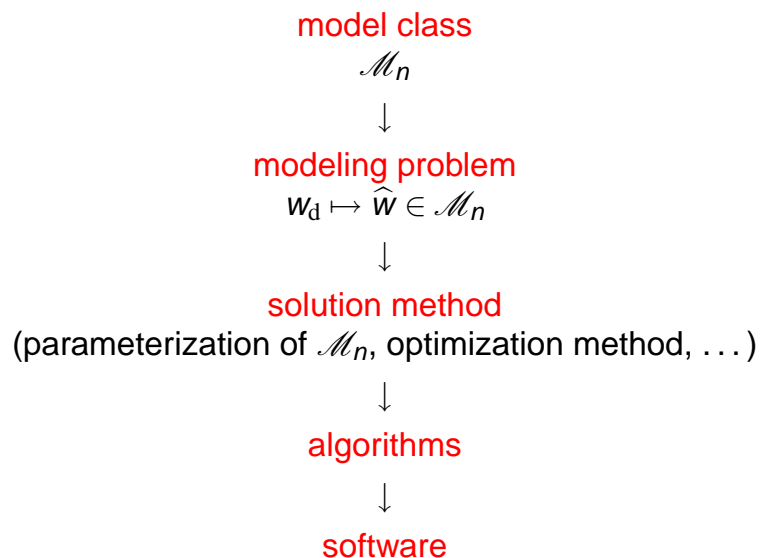
Low-rank approximation

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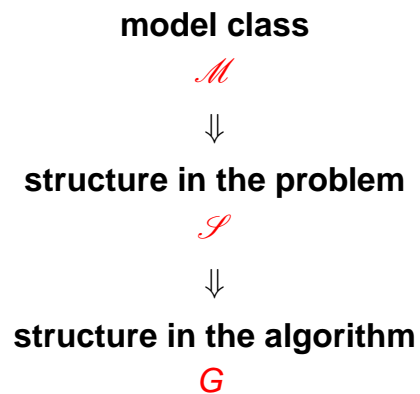
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What are the issues?



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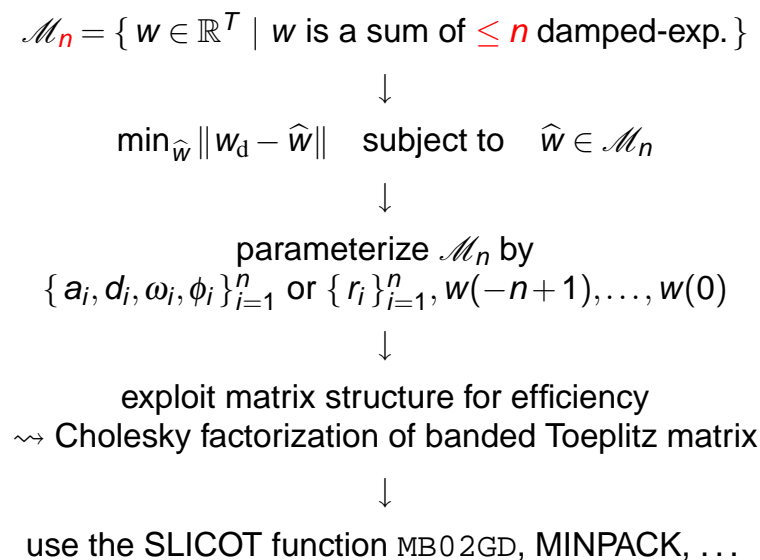
The sequence



is common.

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For examples ...



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Main point: $w \in \mathcal{M}_n \iff \text{rank}(\mathcal{S}(w)) \leq n$

An modeling problem

$$\min_{\hat{w}} \|w_d - \hat{w}\| \quad \text{subject to} \quad \hat{w} \in \mathcal{M}_n$$

is equivalent to structured low-rank approximation problem

$$\min_{\hat{w}} \|w_d - \hat{w}\| \quad \text{subject to} \quad \text{rank}(\mathcal{S}(w)) \leq n$$

for certain structure \mathcal{S} that depends on \mathcal{M} .

Often \mathcal{S} is composed of Hankel/Toeplitz, Hankel+Toeplitz, and unstr. blocks ↪ an algorithm with comput. complexity $O(T)$

⇒ one algorithm solves efficiently a variety of problems

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Thank you